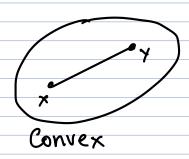
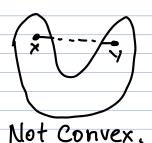
Math 6461 Lecture 5

Def: Let X be a vector space.

- (1) For $x,y \in X$, we denote $[x,y] = \{\lambda x + (1-\lambda)y : \lambda \in [0,1]\}$ the linear segment between x and y.
- (2) A subset A of X is called a convex set if for all $x_1y \in A$, $[x_1y] \subset A$. Equivalently, A is convex if for all $x_1y \in A$ and $\lambda \in [0,1], \lambda x + (1-\lambda)y \in A$.





Examples:

(1) If X is a vector space. Every singleton {X:\(\frac{1}{2}\) is convex.

Every subspace is Convex

(2) In IR. a subset is convex precisely

Notation: Let X be a vector space $x_1, ..., x_n \in X$ and $\lambda_1, ..., \lambda_n \in [0,1]$ and $\sum_{i=1}^n \lambda_i = 1$. Then $x = \sum_{i=1}^n \lambda_i x_i$ is called a convex combination of $x_1, ..., x_n$.

Proposition: Let X be a vector space and $A \subset X$ convex. Then for all $X_1, \dots, X_n \in A$ and $\lambda_1, \dots, \lambda_n \in [0,1]$ with

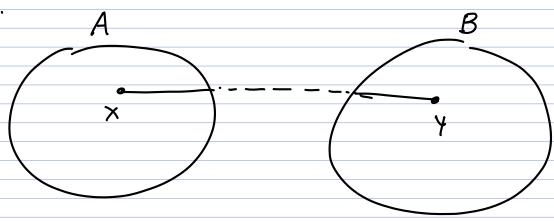
 $\sum_{i=1}^{n} \lambda_i = 1$, then $\sum_{i=1}^{n} \lambda_i \times_i \in A$.

Proof: by Induction (exercise)

Proposition: Let X be a vector space and $(Ai)_{i\in \mathbb{Z}}$ are convex. Subsets of X, then $A = \bigcap_{i\in \mathbb{Z}} A_i$ is convex.

Proof: exercise.

Remark: The union of convex subsets may not be convex.



Remark: Ø is convex.

Def: Let X be a vector space and ACX. The convex hull of A is the set

conv(A) = M&B: B is convex and ACB).

i.e. the set of all convex combinations of vectors of A.

Prop: Let X be a vector space and $A \subset X$. Then

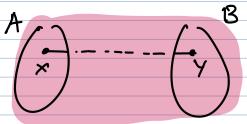
(i) Conv(A) is a Convex subset of X and $A \subset Conv(A)$ (ii) If B is a convex subset of X and $A \subset B$,

then $Conv(A) \subset B$.

That is, conv(A) is the smallest convex subset of X containing A.

Theorem: Let X be a vector space and $A \subset X$. Then $Conv(A) = \{\sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in [0,1], \sum_{i=1}^{n} \lambda_i x_i : n \in \mathbb{N}, x_1, \dots, x_n \in A, \lambda_1, \dots, \lambda_n \in A, \lambda_1, \dots, \lambda_$

 $conv(AUB) = \{ \lambda x + (1-\lambda)y : x \in A, y \in B, \lambda \in [0,1] \}$



See Robinson Ch. 3-7

Normed Spaces

Def: Let X be a vector space. A function $||\cdot||:X\to [0,\infty)$ is called a norm if the following hold:

- (i) $\forall x \in X$, $\|x\| = 0$ if and only if x = 0/ (ii) $\forall x \in X$ and $\lambda \in \mathbb{R}$, $\|\lambda x\| = \|\lambda\| \cdot \|x\|$
- (iii) ∀x,y ∈ X, ||x+y|| ≤ ||x|+ ||y||.

Prop: Let X be a normed space. Then the function $d: X \times X \rightarrow [0, \infty)$ given by d(x,y) = ||x-y|| is a metric. That is,

(i) $\forall x, y \in X$, d(x,y) = 0 if and only if x = y(ii) $\forall x, y \in X$, d(x,y) = d(y,x)

(iii) ∀x,y,z ∈ X, d(x,z) ≤ d(x,y) + d(y,z).

Proof: (iii) For $x,y,z \in X$, $d(x,z) = ||x-z|| \le ||x-y|| + ||y-z|| = d(x,y) + d(y,z).$ This metric is called the induced metric on X.

Remark: If X is a normed space and $x,y \in X$, then $||||x|| - ||y||| \le ||x - y||$. (exercise)

Def: If X is a normed space and $(x_n)_{n=1}^{\infty} \in X$, $x_0 \in X$, then $\lim_{n\to\infty} x_n = x_0$ means $\lim_{n\to\infty} ||x_n - x_0|| = 0$.

Prop: Let X be a normed space,

(i) +: $X \times X \rightarrow X$ is continuous, i.e. $\forall (x_n)_{n=1}^{\infty}$, $(y_n)_{n=1}^{\infty}$, $x_0, y_0 \in X$ such that $\lim_{n\to\infty} x_n = x_0$, $\lim_{n\to\infty} y_n = y_0$. Then $\lim_{n\to\infty} (x_n + y_n) = x_0 + y_0$

(ii) •: $IR \times X \rightarrow X$ is continuous, i.e. $\forall (x_n)_{n=1}^{\infty}$, $x_0 \in X$ and $(\lambda_n)_{n=1}^{\infty}$, $\lambda_0 \in IR$ such that $(x_n) \rightarrow x_0$ and $\lambda_n \rightarrow \lambda_0$, then $(\lambda_n x_n) \rightarrow \lambda_0 x_0$.

(iii) ||·||: X→ X is continuous, i.e. \(\text{\kn}\)n\(\text{\mathbb{e}}\), \(\text{\section}\) \(\text{\kn}\)\(\text{\mathbb{e}}\), \(\text{\section}\)

Proof (ii): $\|\lambda_{n} x_{n} - \lambda_{o} x_{o}\| = \|\lambda_{n} x_{n} - \lambda_{o} x_{n} + \lambda_{o} x_{n} - \lambda_{o} x_{o}\|$ $\leq \|\lambda_{n} x_{n} - \lambda_{o} x_{n}\| + \|\lambda_{o} x_{n} - \lambda_{o} x_{o}\|$ $= \|x_{n}\| \|\lambda_{n} - \lambda_{o}\| + \|x_{n} - x_{o}\| \cdot \|\lambda_{o}\|$ $\longrightarrow 0.$

Notation: Let X be a normed space.

(i) For $x_0 \in X$ and $\varepsilon > 0$, denote $B(x_0, \varepsilon) = \{x \in X : ||x_0 - x|| < \varepsilon \}$ called the open ball at x_0 with radius ε .

(ii) For xo ex and E>0, denote

B[x0, E] = {x ∈ X : ||x0-x|| ≤ E}.

called the closed ball at xo with radius E.

(iii) 1Bx = {xeX: 11x11 = 1} called the closed unit ball on X

(iv) $S_x = \{x \in X : ||x|| = 1\}$ called the unit circle on X.

Prop: B(x, E) and IBx are convex sets,

Prop: Let X be a normed space and Y is a subspace of X

(i) $\overline{Y} = \{all | limit points of Y\}$ is a subspace of X

(ii) If $Y^o = \{union of all open balls contained in <math>Y^a = \{union of all open balls contained in Y^a \}$ is

Proof (i) Uses continuity of + and · (exercise)

(ii) If Y° ≠Ø then ∃y ∈ Y and €>0 such that B(y, €) < Y°

Fix x e X. 8how x e Y. Put z = y + E X

Then $z \in B(y, \varepsilon)$ because $||y-z|| = \frac{\varepsilon}{||x||+2} ||x|| < \varepsilon$. Then

 $z \in Y \Rightarrow x = \frac{||x||+2}{\varepsilon} (z-y) \in Y$

Exercise: let X be a normed space and $x_0 \in X$ and $\varepsilon > 0$

(i) B(xo, E) = B(xo, E)

(ii) $(B[x_0, \varepsilon])^3 = B(x_0, \varepsilon)$

(iii) yo + B(x0, E) = B(x0+y0, E)

(iv) $(\lambda x_0)\lambda B(x_0, \varepsilon) = B(\lambda x_0, |\lambda|, \varepsilon)$

Examples of Normed Spaces

(i) IR with 1.1

(ii) IR^n with $\|\cdot\|_{L^1}$ and $\|\cdot\|_{\infty}$, i.e. $\|x\|_{L^1} = \sum_{i=1}^n |x_i|$ and

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\|x\|_{\infty} = \max_{1 \leq i \leq n} |x_i|
(iii) 1 (IN) = {xe |RIN : $\frac{2}{n} |xn| < \infty \} with ||x||\(\ell_1 = \frac{\infty}{n} |xn|\)
(iv) Consider
   Coo (IN) = { xe IRIN : INEIN sit xn=0 +n=N}
   Co((N) = { x ∈ (R 1N : xn→0 as n→∞?
   Lo (IN) = { x ∈ IR N : Sup | Xn | < ∞ }
    with ||x||e = sup |xn|
 (v) C([0,1]) with
\|f\|_{\infty} = \sup_{x \in \mathcal{B}_{r,\eta}} |f(x)|, \quad \|f\|_{L^{1}} = \int_{\Omega}^{r} |f(x)| dx.
(vi) C'([0,1]) then IIf ||c| = ||f||_ + ||f'||_.
Exercise: Show above are normed spaces.
Additional Normed Spaces
(i) IRn with II·llp for 1≤p<∞ where
        \|x\|_{P} = \left(\frac{M}{2} \|x_{i}\|^{P}\right)^{P}
(ii) lP(IN) = 3 x ∈ IR IN: 2 |xn|P < ∞ { with ll·llyp for 1 ≤ p < ∞
   where \|x\|_{P} = \left(\sum_{n=1}^{\infty} |x_n|^p\right)^p
(iii) C([o1]) with
   \|f\|_{L^p} = \left(\int_0^1 |f(x)|^p dx\right)^{\frac{1}{p}} \text{ for } 1 \leq p < \infty.
Hölder and Minkowski Inequalities
Notation: Let 1 \le p \le \infty. We denote the conjugate exponent
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l≤q≤∞ of p as follows:

(i) If $1 then <math>q = \frac{p}{p-1}$

(ii) If
$$p=1$$
, then $q=\infty$
(iii) If $p=\infty$, then $q=1$.

Remark: For 1 \le p, q \le \infty, \frac{1}{p} + \frac{1}{q} = 1

Theorem: let $1 < p, q < \infty$ such that $p + \frac{1}{q} = 1$, (i) (Hölder) For all $x, y \in \mathbb{R}^n$,

$$\sum_{i=1}^{n} |x_{i}y_{i}| \leq \left(\sum_{i=1}^{n} |x_{i}|^{p}\right)^{\frac{1}{p}} \left(\sum_{i=1}^{n} |y_{i}|^{q}\right)^{\frac{1}{q}}$$

$$\Rightarrow ||x_{i}y_{i}|| \leq ||x_{i}||^{p} ||y||_{q}$$

(ii) $\forall x \in \mathbb{R}^n \exists y \in \mathbb{R}^n \text{ s.t. } ||y||_q = 1 \implies \sum_{i=1}^n x_i y_i = ||x||_p$

(iii) (Minkowski) for all
$$x,y \in \mathbb{R}^n$$

$$\left(\sum_{i=1}^n |x_i + y_i|^p\right)^{\frac{1}{p}} \leq \left(\sum_{i=1}^n |x_i|^p\right)^{\frac{1}{p}} + \left(\sum_{i=1}^n |y_i|^p\right)^{\frac{1}{p}}$$

$$\Rightarrow |x_i + y_i|^p \leq |x_i|^p + |x_i|^p.$$

Note: There are similar formulations for lp(IN) and C(LO117).