## Final Assignment -- Target Code Generation

The final part of the compiler is the back end which generates assembly language from quads, with some help from the symbol table. Since we have covered the X86 architecture in class, that is the recommended one to use. You could do either X86-32 or X86-64.

Since quads are theoretically independent of the source language, there are no more requirements and exemptions having to do with the C language. Whatever you had to support in Assignment 5 you need to support in Assignment 6.

When you have successfully completed this assignment, your compiler should be able to accept a simple test program (as usual, OK to use cpp to pre-process the source) which demonstrates:

- \* Reading and writing local and global variables
- \* Declarative pseudo-opcodes for global declarations
- \* Computation of expressions
- \* Reading and writing array elements
- \* Creating and dereferencing pointer values
- \* String constants
- \* Control flow (if statements and at least one type of loop)
- \* Calling external function, with arguments (int or pointer)

The result of your program (on stdout or to a file specified on the command line) is a .s file. You should then be able to run

```
cc -m32 file.s
OR
cc -m64 file.s
```

which will run the system's assembler on your output, invoke the system linker to link in the standard C library and run-time startup code, and produce an executable a.out which, when run, should produce correct output! Call the standard C printf() function to generate run-time output. Since your compiler will probably not be able to deal with the system header files (which may contain constructs that are optional), just create a simple prototype declaration such as int printf(); someplace in your test C source, prior to calling printf. Or, if you supported implicit declaration of functions, you'll be fine.

The -m32 flag is to be used for X86 32 bit code. If you have generated 64-bit assembly code, use -m64. Because the function calling APIs are different between the 32 and 64 architecture, it is important that you select the correct flag!

As discussed in class, it is not required that your assembly code be "optimal" in any way, but it must be correct.

## **Instruction Selection**

Instruction selection is a hard problem. The recommended approach is to write a very simple instruction selector which looks at the quad opcode and the addressing modes in an ad-hoc fashion, one quad at a time, and generates a sequence of one or more assembly instructions per quad.

X86 is generally a 2-address architecture, and has additional address mode combination restrictions which are mentioned in the lecture notes. You might want to reserve one or two of the "scratch" registers for dealing with situations where the quad is too rich to express in one step. E.g.

```
i{lvar}=ADD j{lvar},k{lvar}
```

```
movl (-16)%ebp,%eax #j is at offset -16 in stack frame movl (-20)%ebp,%edx #k is at offset -20
```

addl	%edx,%eax	#add, res	sult in eax
movl	%eax,(-24)%ebp		#move result to i at offset -24
##Optimal	sequence:		
movl	(-16)%ebp,%eax		#j is at offset -16 in stack frame
addl	(-20)%ebp,%eax		#k is at offset -20
movl	%eax, (-24)%ebp		#move result to i at offset -24

## **Register Allocation**

As discussed in lecture notes, register allocation can be a very difficult problem, far beyond our ability to tackle in the limited time left in the course.

The most primitive yet still functional approach to register allocation is to use the same scratch registers each time to bring memory operands into registers as needed to perform operations. There is no attempt to have local variables reside in registers in between quads, and even temporary values (such as arise in complicated expressions) would be considered "phantom" local variables and would own a specific stack frame slot for the duration of the function, even after the temporary is no longer live.

Alternatively, you can attempt to do a primitive register allocator with the temporals by making some assumptions based on how you generated quads. If you only assign to a temporary value once and only use it once, you do not need to worry about live value analysis. You can just assume that the temporary is dead after its first and only use as a source operand. But of course if you don't generate quads this way, don't expect it to work!

The most robust register allocator which you could accomplish would be full local register allocation (within a basic block) using a "scoreboard" type approach. Here most temporary variables would be satisfied with a register, and you would only need to assign stack slots to those temporaries that overflowed the register pool.

## **General Hints**

If you are unsure of what opcode to pick, or how the instruction works, the best approach is to create a tiny test program which exercises the operation under consideration (e.g. integer division), run it through gcc -S to see what gcc picks, then look up the opcode and addressing mode in the assembly language reference manual for the architecture in which you are working (manuals for SPARC and X86 have been placed on the course web site). You may need to give gcc the -O0 flag to turn off the optimizer, otherwise your entire test program may get optimized away because the compiler is smarter than you anticipated.

When looking at GCC output, do not be concerned with comment directives, or sections other than text, data and bss (.comm). You may see some very confusing gcc output which is intended for debugging, exception handling, etc. In the Unit 6 notes, this extraneous output was sanitized for your protection.

You might also find that running GCC on some of the test cases from Unit 6 generates different sequences of instructions and/or registers than the examples showed. Different versions of GCC produce different code. You can assume that both the examples and the code that your GCC generates are correct (i.e. that there are no bugs in GCC). And of course, a compiler such as clang might produce significantly different code.