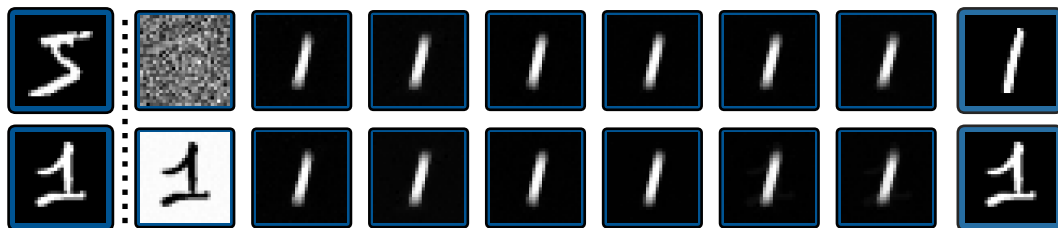
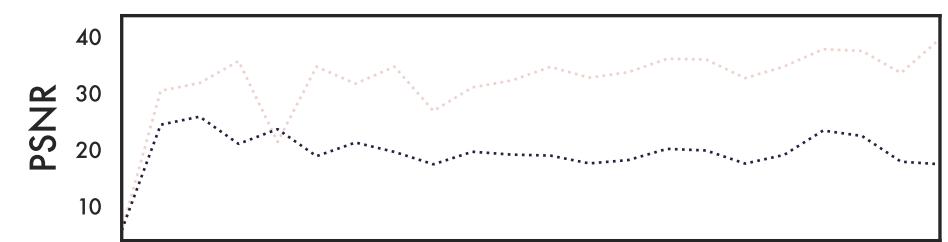
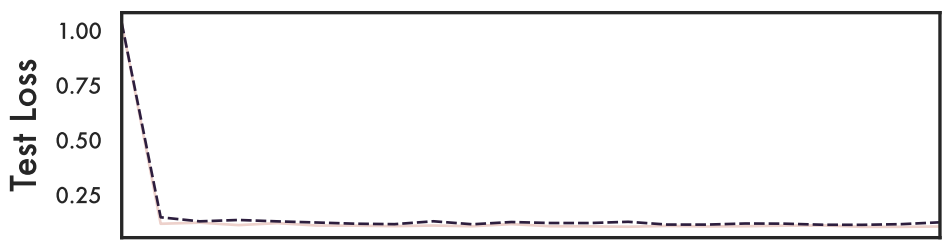
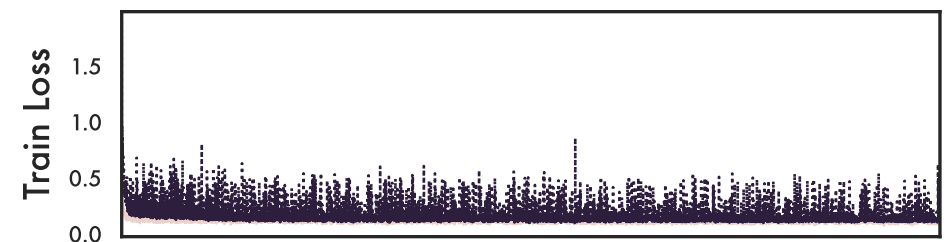


Debugged learning dynamics

Output (D)



Output (F)



Steps