

# Learning in System F (Synthesis Pearl)

Program synthesis, type inhabitation, inductive programming, and theorem proving. Different names for the same problem: learning programs from data. Sometimes the programs are proofs, sometimes they're terms. Sometimes data are examples, and sometimes they're types. Yet the aim is the same. We want to construct a program which satisfies some data. We want to learn a program.

What might a programming language look like, if its programs could also be learned? We give it data, and it learns a program from it. This work shows that System F yields a simple approach for learning from types and examples. Beyond simplicity, System F gives us a guarantee on the soundness and completeness of learning. We learn correct programs, and can learn all observationally distinct programs in System F. Unlike previous works, we don't restrict what examples can be. As a result, we show how to learn eventually arbitrary higher-order programs in System F from types and examples.

Additional Key Words and Phrases: Program Synthesis, Type Theory, Inductive Programming

## 1 Introduction

### 1.1 A tricky learning problem

Imagine we're teaching you a program. Your only data is the type  $\text{nat} \rightarrow \text{nat}$ . It takes a natural number, and returns a natural number. Any ideas? Perhaps a program which computes...

$$f(x) = x, \quad f(x) = x + 1, \quad f(x) = x + 2, \quad f(x) = x + \dots$$

The good news is that  $f(x) = x + 1$  is correct. The bad news is that the data let you learn a slew of other programs too. It doesn't constrain learning enough if we want to teach  $f(x) = x + 1$ . As teachers, we can provide better data.

Round 2. Imagine we're teaching you a program. But this time we give you an example of the program's behavior. Your data are the type  $\text{nat} \rightarrow \text{nat}$  and an example  $f(1) = 2$ . It takes a natural number, and seems to return its successor. Any ideas? Perhaps a program which computes...

$$f(x) = x + 1, \quad f(x) = x + 2 - 1, \quad f(x) = x + 3 - 2, \quad \dots$$

The good news is that  $f(x) = x + 1$  is correct. And so are all the other programs, as long as we're agnostic to some details. Types and examples impose useful constraints on learning. It's the data we use when learning in System F [Girard et al. 1989].

Existing work can learn successor from similar data [Osera 2015; Polikarpova et al. 2016]. But suppose  $\text{nat}$  is a church encoding. For some base type  $A$ ,  $\text{nat} := (A \rightarrow A) \rightarrow (A \rightarrow A)$ . Natural numbers are then higher-order functions. They take and return functions. In this context, existing work can no longer learn successor.

### 1.2 A way forward

The difficulty is with how to handle functions in the return type. The type  $\text{nat} \rightarrow \text{nat}$  returns a function, a program of type  $\text{nat}$ . To learn correct programs, you need to ensure candidates are the correct type or that they obey examples. Imagine we want to verify that our candidate program  $f$  obeys  $f(1) = 2$ . With the church encoding,  $f(1)$  is a function, and so is 2. To check  $f(1) = 2$  requires that we decide function equality—which is undecidable in a Turing-complete language [Sipser et al. 2006]. Functions in the return type create this issue. There are two ways out.

- (1) Don't allow functions in the return type, keep Turing-completeness.

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2018. 2475-1421/2018/1-ART1 \$15.00  
<https://doi.org/>

(2) Allow functions in the return type, leave Turing-completeness.

Route 1 is the approach of existing work. They don't allow functions in the return type, but keep an expressive Turing-complete language for learning. This can be a productive move, as many interesting programs don't return functions.

Route 2 is the approach we take. We don't impose restrictions on the types or examples we learn from. We instead sacrifice Turing-completeness. We choose a language where function equality is decidable, but still expressive enough to learn interesting programs. Our work shows that this too is a productive move, as many interesting programs return functions. This route leads us to several contributions:

- Detail how to learn arbitrary higher-order programs in System F.
- Prove the soundness and completeness of learning.
- Provide an implementation of learning, extending strong theoretical guarantees in practice.

## 2 System F

We assume you are familiar with System F, the polymorphic lambda calculus. You should know its syntax, typing, and evaluation. If you don't, we co-opt its specification in [Pierce 2002]. For a comprehensive introduction we defer the confused or rusty there. Additionally, we provide the specification and relevant theorems in the appendix.

Our focus in this section is to motivate System F: its syntax, typing, and evaluation. And why properties of each are advantageous for learning. Treat this section as an answer to the following question:

*Why learn in System F?*

### 2.1 Syntax

System F's syntax is simple. There aren't many syntactic forms. Whenever we state, prove, or implement things in System F we often use structural recursion on the syntax. A minimal syntax means we are succinct when we state, prove, or implement those things.

While simple, the syntax is still expressive. We can encode many staples of typed functional programming: algebraic data types, inductive types, and more [Pierce 2002]. For example, consider this encoding of products:

$$\begin{aligned}\tau_1 \times \tau_2 &::= \forall \alpha. (\tau_1 \rightarrow \tau_2 \rightarrow \alpha) \rightarrow \alpha \\ \langle e_1, e_2 \rangle &::= \Lambda \alpha. \lambda f : (\tau_1 \rightarrow \tau_2 \rightarrow \alpha). f e_1 e_2\end{aligned}$$

### 2.2 Typing

System F is safe. Its typing ensures both progress and preservation, i.e. that well-typed programs do not get stuck and that they do not change type [Pierce 2002]. When we introduce learning, we lift this safety and extend it to programs we learn. Because we use this safety in later proofs, we state the progress and preservation theorems in the appendix.

### 2.3 Evaluation

System F is strongly normalizing. All its programs terminate. As a result, we can use a simple procedure for deciding equality of programs (including functions).

- (1) Run both programs until they terminate.
- (2) Check if they share the same normal form, up to alpha-equivalence (renaming of variables).
- (3) If they do, they are equal. Otherwise, unequal.

For example, this decision procedure renders these programs equal:

$$\lambda x:\tau.x =_{\beta} (\lambda y:(\tau \rightarrow \tau).y)\lambda z:\tau.z$$

The decision procedure checks that two programs exist in the transitive reflexive closure of the evaluation relation. This only works because programs always terminate, a property we formally state in the appendix.

### 3 Learning from Types

LEARNING		$\Gamma \vdash \tau \rightsquigarrow e$
$\frac{x : \tau \in \Gamma}{\Gamma \vdash \tau \rightsquigarrow x} \text{ (L-VAR)}$	$\frac{\Gamma, \alpha \vdash \tau \rightsquigarrow e}{\Gamma \vdash \forall \alpha.\tau \rightsquigarrow \lambda \alpha.e} \text{ (G-TABS)}$	
$\frac{\Gamma, x:\tau_1 \vdash \tau_2 \rightsquigarrow e_2}{\Gamma \vdash \tau_1 \rightarrow \tau_2 \rightsquigarrow \lambda x:\tau_1.e_2} \text{ (L-ABS)}$	$\frac{\Gamma \vdash \forall \alpha.\tau_1 \rightsquigarrow e}{\Gamma \vdash [\tau_2/\alpha]\tau_1 \rightsquigarrow e[\tau_2]} \text{ (L-TAPP)}$	
$\frac{\Gamma \vdash \tau_1 \rightarrow \tau_2 \rightsquigarrow e_1 \quad \Gamma \vdash \tau_1 \rightsquigarrow e_2}{\Gamma \vdash \tau_2 \rightsquigarrow e_1 e_2} \text{ (L-APP)}$		

Fig. 1. Learning from types in System F

## 4 Learning from Examples, Declaratively

### 4.1 What are examples?

Examples  $[\chi_1, \dots, \chi_n]$  are lists of tuples, containing the inputs and output to a program. For instance  $[\langle 1, 1 \rangle]$  describes an example whose input is 1 and output is 1. If I want to specify more than one example, I can package examples  $\chi$  into the list:  $[\langle 1, 1 \rangle, \langle 2, 2 \rangle]$ . Here I have two examples, each with one input and one output. In general, examples take the form

$$\chi ::= \langle e, \chi \rangle \mid \langle e, Nil \rangle$$

where  $e$  is an arbitrary program in System F and  $\chi$  is an example. This syntax for examples lets us construct examples with arbitrary numbers of inputs, e.g.  $\langle 10, 10, 20 \rangle \equiv \langle 10, \langle 10, \langle 20, Nil \rangle \rangle \rangle$ . Note that when examples have multiple inputs I use the short-hand notation for describing an  $n$ -tuple,  $\langle 10, 10, 20 \rangle$  in lieu of full notation  $\langle 10, \langle 10, \langle 20, Nil \rangle \rangle \rangle$ . Likewise when an example is merely  $\langle e, Nil \rangle$ , I use the short-hand  $\langle e \rangle$ —as  $Nil$  can be interpreted as the empty element.

For an example  $\chi \equiv \langle e_1, \dots, e_n \rangle$ , an ordered list of inputs is given by  $e_1, \dots, e_{n-1}$ . The last index always denotes an output. An example satisfies or describes a program, if when the ordered list of inputs  $e_1, \dots, e_{n-1}$  is applied to a program  $e$ , it is equivalent to the output  $e_n$ . That is,

$$(((e \ e_1)e_2) \dots e_{n-1}) =_{\beta} e_n$$

For instance,  $\chi \equiv \langle 1, 1 \rangle$  satisfies the identity program  $\lambda x:nat.x$  because

$$(\lambda x:nat.x)1 =_{\beta} 1$$

Similarly, a list of examples  $[\chi_1, \dots, \chi_n]$  satisfies some program if each example in the list satisfies the program. Note that with this notion of satisfaction, we can construct examples which satisfy

any program  $e$ , that is  $\langle e \rangle$ . It's an example with no input, and whose output is  $e$ . Because no inputs can be applied, and that  $e =_\beta e$ ,  $\langle e \rangle$  satisfies  $e$ .

With the learning relation, we can ask whether **IDENTITY** is learnable given a context, type, and examples. **IDENTITY** is a program which takes a natural number and returns it.

$$\cdot \vdash \text{nat} \rightarrow \text{nat} \triangleright \langle \langle 1, 1 \rangle, \langle 2, 2 \rangle \rangle \rightsquigarrow \blacksquare$$

Examples are stored as tuples. They describe possible worlds, one where our program's input is 1 and the other where our program's input is 2. Throughout learning we need a way to keep track of these distinct worlds. So our first step is always to duplicate  $\blacksquare$ , so that there is one per example.

$$\cdot \vdash \text{list nat} \rightarrow \text{nat} \triangleright \langle \langle 1, 1 \rangle, \langle 2, 2 \rangle \rangle \rightsquigarrow [\blacksquare, \blacksquare]$$

Let's refine these worlds, by applying them to their respective inputs. We extract the inputs from each example tuple.

$$1:\text{nat}, 2:\text{nat} \vdash \text{list nat} \triangleright \langle \langle 1 \rangle, \langle 2 \rangle \rangle \rightsquigarrow [(\blacksquare)1, (\blacksquare)2]$$

Because  $\blacksquare$  is applied to an argument, we know it must be an abstraction. Hence, we can also claim:

$$1:\text{nat}, 2:\text{nat} \vdash \text{list nat} \triangleright \langle \langle 1 \rangle, \langle 2 \rangle \rangle \rightsquigarrow [(\lambda x:\text{nat}.\blacksquare)1, (\lambda x:\text{nat}.\blacksquare)2]$$

Now that we've ran out of inputs in our examples, the problem becomes how to generate a program which satisfy the outputs left in the example tuples:

$$1:\text{nat}, 2:\text{nat} \vdash \text{list nat} \rightsquigarrow [(\lambda x:\text{nat}.\blacksquare)1, (\lambda x:\text{nat}.\blacksquare)2]$$

$$(\lambda x:\text{nat}.\blacksquare)1 =_\beta 1 \quad \wedge \quad (\lambda x:\text{nat}.\blacksquare)2 =_\beta 2$$

Given the constraints on well-typed terms, it's easy to find  $x$  to fill the body of the abstraction. This will become clear in the formal proof to follow.

$$1:\text{nat}, 2:\text{nat} \vdash \text{list nat} \rightsquigarrow [(\lambda x:\text{nat}.x)1, (\lambda x:\text{nat}.x)2]$$

$$(\lambda x:\text{nat}.x)1 =_\beta 1 \quad \wedge \quad (\lambda x:\text{nat}.x)2 =_\beta 2$$

Having satisfied the outputs from our examples, we've informally shown **IDENTITY**  $\equiv \lambda x:\text{nat}.x$  is learnable in System F. And all the machinery comes from types and operators we can encode in System F: list and product types along with their constructors and deconstructors.

The informal process of learning described can be made formal via the relation presented in Figure 2.

(L-WRLD) says that if you can learn a list of programs  $[e_1, \dots, e_n]$ , where  $e_1, \dots, e_n$  are equivalent, then you can learn the program  $e_1$ . This rule is used to create  $n$  worlds for  $n$  examples at the start of learning.

$$\frac{\Gamma \vdash \text{list nat} \rightarrow \text{nat} \triangleright [\langle 1, 1 \rangle, \langle 2, 2 \rangle] \rightsquigarrow [\lambda x:\text{nat}.x, \lambda x:\text{nat}.x]}{\Gamma \vdash \text{nat} \rightarrow \text{nat} \triangleright [\langle 1, 1 \rangle, \langle 2, 2 \rangle] \rightsquigarrow \lambda x:\text{nat}.x} \quad (\text{L-WRLD})$$

(L-BASE) says that if you can learn a list of programs from its type and each  $e_i$  is equivalent to some  $\chi_i$  for  $0 \leq i \leq n$ , then we can use each  $\chi_i$  as an example output. For instance,  $(\lambda x:\text{nat}.x)1 =_\beta 1$ . This means we can use 1 as an example output for  $(\lambda x:\text{nat}.x)$ . When learning, this rule is the "base" case. After exhausting the example information, this rule turns the learning process into learning from types.

$$\frac{\Gamma, 1:\text{nat} \vdash \text{list nat} \rightsquigarrow [(\lambda x:\text{nat}.x)1] \quad (\lambda x:\text{nat}.x)1 =_\beta 1}{\Gamma \vdash \text{list nat} \triangleright [\langle 1 \rangle] \rightsquigarrow [(\lambda x:\text{nat}.x)1]} \quad (\text{L-BASE})$$

(L-EABS) says that if you can learn a list of applications  $[e_1\pi_1(\chi_1), \dots, e_n\pi_1(\chi_n)]$ , then you can learn a list of abstractions  $[e_1, \dots, e_n]$  from examples where each  $\pi_1\chi_i$  are inputs for  $0 \leq i \leq n$ . Note that  $\pi_1$  is the first projection of an example tuple.

## LEARNING

$$\boxed{\Gamma \vdash \tau \triangleright \chi \rightsquigarrow e}$$

$$\frac{\Gamma \vdash \text{list } \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n] \quad \bigwedge_{i=1}^n e_i =_{\beta} e_n}{\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e} \text{ (L-WRLD)}$$

$$\frac{\Gamma, \bigcup_{i=1}^n \chi_i : \tau \vdash \text{list } \tau \rightsquigarrow [e_1, \dots, e_n] \quad \bigwedge_{i=1}^n e_i =_{\beta} \chi_i}{\Gamma \vdash \text{list } \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n]} \text{ (L-BASE)}$$

$$\frac{\Gamma, \bigcup_{i=1}^n \pi_1(\chi_i) : \tau_a \vdash \text{list } \tau_b \triangleright [\pi_2(\chi_1), \dots, \pi_2(\chi_n)] \rightsquigarrow [e_1 \pi_1(\chi_1), \dots, e_n \pi_1(\chi_n)]}{\Gamma \vdash \text{list } \tau_a \rightarrow \tau_b \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n]} \text{ (L-EABS)}$$

$$\frac{\Gamma, \alpha \vdash \text{list } \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1[\alpha], \dots, e_n[\alpha]]}{\Gamma \vdash \text{list } \forall \alpha. \tau \triangleright [\Lambda \alpha. \chi_1, \dots, \Lambda \alpha. \chi_n] \rightsquigarrow [e_1, \dots, e_n]} \text{ (L-ETABS)}$$

$$\frac{\begin{array}{c} \Gamma \vdash \text{list } \tau_a \rightarrow \tau_c \triangleright [\chi_1, \dots, \chi_j] \rightsquigarrow [e_1, \dots, e_j] \\ \Gamma \vdash \text{list } \tau_b \rightarrow \tau_c \triangleright [\chi_1, \dots, \chi_k] \rightsquigarrow [e_1, \dots, e_k] \end{array}}{\Gamma \vdash \text{list } (\tau_a + \tau_b) \rightarrow \tau_c \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n]} \text{ (L-SUM)}$$

Fig. 2. Learning from examples in System F

$$\frac{\Gamma, 1:\text{nat}, 2:\text{nat} \vdash \text{list nat} \triangleright [\langle 1 \rangle, \langle 2 \rangle] \rightsquigarrow [(\lambda x:\text{nat}.x)1, (\lambda x:\text{nat}.x)2]}{\Gamma \vdash \text{list nat} \rightarrow \text{nat} \triangleright [\langle 1, 1 \rangle, \langle 2, 2 \rangle] \rightsquigarrow [\lambda x:\text{nat}.x, \lambda x:\text{nat}.x]} \text{ (L-EABS)}$$

(L-ETABS) says that if you can learn a list of applications  $[e_1[\alpha], \dots, e_n[\alpha]]$ , then you can learn a list of polymorphic abstractions  $[e_1, \dots, e_n]$  from examples where each  $\Lambda \alpha. \chi_i$  are inputs for  $0 \leq i \leq n$ .

$$\frac{\Gamma, \alpha \vdash \text{list } \alpha \rightarrow \alpha \triangleright [\langle z, z \rangle] \rightsquigarrow [(\Lambda \alpha. \lambda x:\alpha. x)[\alpha]]}{\Gamma \vdash \text{list } \forall \alpha. \alpha \rightarrow \alpha \triangleright [\Lambda \alpha. \langle z, z \rangle] \rightsquigarrow [\Lambda \alpha. \lambda x:\alpha. x]} \text{ (L-TABS)}$$

(L-SUM) says that if you can learn a list of programs whose input is type  $\tau_a$  and another list of programs whose input is type  $\tau_b$ , then you can learn a list of program whose input is the sum type  $\tau_a + \tau_b$  and whose examples contain inputs of both type  $\tau_a$  and type  $\tau_b$ . During learning, this rule is perhaps the most useful. It lets you distribute examples when encountering sum types as inputs, which ends up creating two sub-problems, each of which dealing with a smaller set of examples, which are easier to satisfy. In the example, let  $e \equiv \text{case}(b) \text{ of } \iota_1(\text{true}) \mapsto \text{false} \mid \iota_2(\text{false}) \mapsto \text{true}$

$$\frac{\begin{array}{c} \Gamma \vdash \text{list bool} \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle] \rightsquigarrow [\lambda x:\text{bool}. \text{false}] \\ \Gamma \vdash \text{list bool} \rightarrow \text{bool} \triangleright [\langle \text{false}, \text{true} \rangle] \rightsquigarrow [\lambda y:\text{bool}. \text{true}] \end{array}}{\Gamma \vdash \text{list } (\text{bool} + \text{bool}) \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle, \langle \text{false}, \text{true} \rangle] \rightsquigarrow [e, e]} \text{ (L-SUM)}$$

This new relation extends learning from types. Now System F can learn from examples too. So far, our presentation of learning is both sound and complete. You can learn every program in System F from types. We now show that these results hold when learning from examples too.

## 5 Metatheory

Because our aim is to show every program in System F is learnable from examples, we want to show that learning is still equivalent to typing. As with learning from types, we show both completeness and soundness of learning with respect to typing—giving us the equivalence. These proofs entail a bit more work, but are far simpler than similar presentations of metatheory for languages which permit learning from examples, e.g. MYTH [Osera 2015]. The mathematical convenience is afforded by not introducing any machinery into System F for learning.

### 5.1 Typing and Learning are still equivalent

To show completeness, we need to show that for any program in System F there exists a list of examples from which it can be learned. This turns out to be trivial. Hence, a stronger statement we want is that we can learn any program which is satisfied by a list of examples. It would be problematic if we could learn any program in System F, but only from a particular subset of the examples which describe that program. Showing both of these gives strong guarantees on learning. If a list of examples describes a program, you can learn that program—and this list exists for every program in System F.

**Lemma 5.1** (COMPLETENESS<sub>a</sub> OF LEARNING).

*If  $\Gamma \vdash e : \tau$  then there exist some  $[\chi_1, \dots, \chi_n]$  such that  $\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e$*

*Proof.* For an arbitrary program  $e$  of type  $\tau$ , let  $[\langle e \rangle]$  constitute its example list. This example list has no input, only an output  $e$ . Hence the statement  $\Gamma \vdash \tau \triangleright [\langle e \rangle] \rightsquigarrow e$  asks whether we can learn a program  $e$  of type  $\tau$  whose output is  $e$ .

Now, note that for any program  $e =_\beta e$  by definition of the reflexive, transitive, and symmetric evaluation relation. Additionally, for any program  $e$  of type  $\tau$ , a list  $[e]$  can be learned from type list  $\tau$ . Because learning from types is complete, this works for any program.

Knowing this, we can apply the following learning rules:

$$\frac{\Gamma, x:\tau \vdash \text{list } \tau \rightsquigarrow [e] \quad e =_\beta e}{\Gamma \vdash \text{list } \tau \triangleright [\langle e \rangle] \rightsquigarrow [e]} \text{ (L-BASE)} \quad \frac{\Gamma \vdash \text{list } \tau \triangleright [\langle e \rangle] \rightsquigarrow [e] \quad e =_\beta e}{\Gamma \vdash \tau \triangleright [\langle e \rangle] \rightsquigarrow e} \text{ (L-WRLD)}$$

Hence for any program  $e$  in System F, it can be learned from examples when the example is  $[\langle e \rangle]$ .  $\square$

This is nice, but the less interesting completeness result. We want to make sure that a list of examples which describes a program can be used to learn it. An example list satisfies (or describes) a program, where if the program is applied to the inputs, the corresponding outputs are equivalent.

**Lemma 5.2** (COMPLETENESS<sub>b</sub> OF LEARNING).

*If  $\Gamma \vdash e : \tau$  and there exist some  $[\chi_1, \dots, \chi_n]$  which satisfies  $e$ , then  $\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e$ .*

*Proof.* There are two general cases to prove, when  $e$  has inputs and when  $e$  has no inputs. For programs without input, see previous lemma. For programs with input let  $\Gamma \vdash e : \tau$ , where  $[\chi_1, \dots, \chi_n]$  are examples which satisfy  $e$ . Because of Theorem ??, we also know  $\Gamma \vdash \tau \rightsquigarrow e$ . Because lists are learnable, we also know  $\Gamma \vdash \text{list } \tau \rightsquigarrow [e_1, \dots, e_n]$ , where  $\bigwedge_{i=1}^n e_i =_\beta e_n$ .

Now let's deconstruct each  $\chi_i$  into its input and output components:  $\langle \chi_i^{in}, \chi_i^{out} \rangle$ . Since each  $\chi_i$  satisfies  $e$ , it must be that  $\bigwedge_{i=1}^n e_i \chi_i^{in} =_\beta \chi_i^{out}$ . Due to satisfaction,  $e_i \chi_i^{in}$  is guaranteed to be well-typed. Hence  $\Gamma, \bigcup_{i=1}^n \chi_i^{out} : \tau^{out}, \bigcup_{i=1}^n \chi_i^{in} : \tau^{in} \vdash \text{list } \tau^{out} \rightsquigarrow [e_1 \chi_i^{in}, \dots, e_n \chi_n^{in}]$ . With this, we can apply the following rules:

$$\begin{array}{c}
\Gamma, \bigcup_{i=1}^n \chi_i^{out} : \tau^{out}, \bigcup_{i=1}^n \chi_i^{in} : \tau^{in} \vdash list \tau^{out} \rightsquigarrow [e_1 \chi_1^{in}, \dots, e_n \chi_n^{in}] \quad \bigwedge_{i=1}^n e_i \chi_i^{in} =_{\beta} \chi_i^{out} \\
\hline
\Gamma, \bigcup_{i=1}^n \chi_i^{in} : \tau^{in} \vdash list \tau^{out} \triangleright [\langle \chi_1^{out} \rangle, \dots, \langle \chi_n^{out} \rangle] \rightsquigarrow [e_1 \chi_1^{in}, \dots, e_n \chi_n^{in}] \quad (L-BASE) \\
\hline
\Gamma \vdash list \tau \triangleright [\langle \chi_1^{in}, \chi_1^{out} \rangle, \dots, \langle \chi_n^{in}, \chi_n^{out} \rangle] \rightsquigarrow [e_1, \dots, e_n] \quad (L-EABS)
\end{array}$$

Remembering that  $\chi_i \equiv \langle \chi_i^{in}, \chi_i^{out} \rangle$  and that  $\bigwedge_{i=1}^n e_i =_{\beta} e_n$ , we finally prove the necessary result.

$$\begin{array}{c}
\Gamma \vdash list \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n] \quad \bigwedge_{i=1}^n e_i =_{\beta} e_n \\
\hline
\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e \quad (L-WRLD)
\end{array}$$

Note that if there are  $n$  inputs to the examples which satisfy  $e$ , then (L-EABS) must be applied  $n$  times to fully reconstruct the examples.  $\square$

**Lemma 5.3 (SOUNDNESS OF LEARNING).**

If  $\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e$  then  $\Gamma \vdash e : \tau$

*Proof.* Case analysis on learning rules.

Case 1: (L-WRLD)

We know that we can learn from examples a list of length  $n$  where each entry is  $e$ .

$$\begin{array}{c}
\Gamma \vdash list \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n] \quad \bigwedge_{i=1}^n e_i =_{\beta} e_n \\
\hline
\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e \quad (L-WRLD)
\end{array}$$

After applying (L-EABS) and (L-BASE) it must be that  $\Gamma \vdash list \tau' \rightsquigarrow [e_1 \chi_1^{in}, \dots, e_n \chi_n^{in}]$ . The list is only learnable if each element is learnable, hence  $\Gamma \vdash \tau' \rightsquigarrow e_i \chi_i^{in}$ . And an application is only learnable if each side of the application is learnable, hence  $\Gamma \vdash \tau \rightsquigarrow e$  (noting  $e_i =_{\beta} e$ ). Because of the equivalence of learning from types and typing, we have  $\Gamma \vdash e : \tau$ .

Case 2: (L-BASE)

We know we can learn from types a list of length  $n$  where each entry is  $e$ .

$$\begin{array}{c}
\Gamma, \bigcup_{i=1}^n \chi_i : \tau \vdash list \tau \rightsquigarrow [e_1, \dots, e_n] \quad \bigwedge_{i=1}^n e_i =_{\beta} \chi_i \\
\hline
\Gamma \vdash list \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n] \quad (L-BASE)
\end{array}$$

The list is only learnable if each element is learnable, hence  $\Gamma \vdash \tau \rightsquigarrow e$ . Because of the equivalence of learning from types and typing, we have  $\Gamma \vdash e : \tau$ .

Case 3: (L-EABS)

We know we can learn from types a list of length  $n$  and type  $\tau_b$  where each entry is  $e \pi_1(\chi_i)$ .

$$\begin{array}{c}
\Gamma, \bigcup_{i=1}^n \pi_1(\chi_i) : \tau_a \vdash list \tau_b \triangleright [\pi_2(\chi_1), \dots, \pi_2(\chi_n)] \rightsquigarrow [e_1 \pi_1(\chi_1), \dots, e_n \pi_1(\chi_n)] \\
\hline
\Gamma \vdash list \tau_a \rightarrow \tau_b \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow [e_1, \dots, e_n] \quad (L-EABS)
\end{array}$$

After applying (L-BASE) it must be that  $\Gamma, \bigcup_{i=1}^n \pi_1(\chi_i) : \tau_a \vdash list \tau_b \rightsquigarrow [e_1 \pi_1(\chi_1), \dots, e_n \pi_1(\chi_n)]$ . The list is only learnable if each element is learnable, hence  $\Gamma, \bigcup_{i=1}^n \pi_1(\chi_i) : \tau_a \vdash \tau_b \rightsquigarrow e_1 \pi_1(\chi_1)$ . And an application is only learnable if each side of the application is learnable, hence  $\Gamma \vdash \tau_a \rightarrow \tau_b \rightsquigarrow e$  (noting  $e_i =_{\beta} e$ ). Because of the equivalence of learning from types and typing, we have  $\Gamma \vdash e : \tau_a \rightarrow \tau_b$ .

Case 4: (L-ETABS)

Same strategy as Case 3, except using type application.

Case 5: (L-SUM)

After assuming (L-SUM), reduces to proof of Case 3.  $\square$

**Theorem 5.4** (EQUIVALENCE OF TYPING AND LEARNING).

If and only if  $\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e$ , then  $\Gamma \vdash e : \tau$  and  $[\chi_1, \dots, \chi_n]$  satisfies  $e$ .

*Proof.* Directly from Lemmas 5.1, 5.2 and 5.3. □

Because we can only learn a program if and only if it is well typed, it follows that learned programs obey progress, preservation, and normalization. Each proof invokes the equivalence theorem between typing and learning, and then the respective progress, preservation, and normalization theorems for typing.

**5.2 Learned programs still don't get stuck****Corollary 5.5** (PROGRESS IN LEARNING).

If  $e$  is a learned program, then either  $e$  is a value or else there is some program  $e'$  such that  $e \rightarrow_\beta e'$ .

*Proof.* Directly from Theorems 5.4 and 10.1. □

We shouldn't be able to learn programs which get stuck during evaluation, same as with typing. If I learn a program, either its a value or it can be evaluated to another program. When learning from examples, learning still obeys progress.

**5.3 Learned programs still don't change type****Corollary 5.6** (PRESERVATION IN LEARNING).

If  $\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e$  and  $e \rightarrow_\beta e'$ , then  $\Gamma \vdash \tau \triangleright [\chi_1, \dots, \chi_n] \rightsquigarrow e'$ .

*Proof.* Directly from Theorems 5.4 and 10.2. □

We shouldn't be able to learn programs of a different type than the one provided. If I learn a program, and it evaluates to another program, then I should be able to learn that new program from the same type. When learning from examples, learning still obeys preservation.

**5.4 Learned programs still always halt****Corollary 5.7** (NORMALIZATION IN EVALUATION).

Learned programs in System  $F$  always evaluate to a value, to a normal form.

*Proof.* Directly from Theorems 5.4 and 10.3. □

We shouldn't be able to learn programs which never finish computing. They must halt. As with learning from types, learning from examples only lets you learn halting programs.

**6 Learning identity, not, and successor**

For examples, any program in System  $F$  can serve as input or output. There are no restrictions. In similar works which allow learning from examples, like MYTH [Osera 2015], there are restrictions on what examples can look like. Namely, functions cannot appear as output in an example. This makes it impossible to learn many higher-order programs. In fact, the motivation for this work started from observing this limitation in MYTH. It made it impossible to learn compilers, higher-order programs which specify programming languages.

Here we show how to learn several programs from examples before discussing further the prospect of learning not only programs, but programming languages.

**6.1 Learning polymorphic identity****Lemma 6.1** (POLYMORPHIC IDENTITY IS LEARNABLE).

$\cdot \vdash \forall \alpha. \alpha \rightarrow \alpha \triangleright [\Lambda \alpha. \langle z, z \rangle] \rightsquigarrow \Lambda \alpha. \lambda x: \alpha. x$



*Proof.*

(i)  $\alpha, z:\alpha \vdash \alpha \rightarrow \alpha \rightsquigarrow (\Lambda\alpha.\lambda x:\alpha.x)[\alpha]$

$$\frac{\frac{\frac{x:\text{nat} \in \alpha, z:\alpha, x:\alpha}{\alpha, z:\alpha, x:\alpha \vdash \alpha \rightsquigarrow x} \text{ (L-VAR)}}{\alpha, z:\alpha \vdash \alpha \rightarrow \alpha \rightsquigarrow \lambda x:\alpha.x} \text{ (L-ABS)}}{\alpha, z:\alpha \vdash \forall \alpha.\alpha \rightarrow \alpha \rightsquigarrow \Lambda\alpha.\lambda x:\alpha.x} \text{ (L-TABS)} \quad \frac{\alpha, z:\alpha \vdash \alpha \rightsquigarrow \alpha}{\alpha, z:\alpha \vdash \alpha \rightarrow \alpha \rightsquigarrow (\Lambda\alpha.\lambda x:\alpha.x)[\alpha]} \text{ (L-APP)}$$

(ii)  $\alpha, z:\alpha \vdash \alpha \rightsquigarrow (\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z$

$$\frac{\frac{(i)}{\alpha, z:\alpha \vdash \alpha \rightarrow \alpha \rightsquigarrow (\Lambda\alpha.\lambda x:\alpha.x)[\alpha]} \quad \frac{z:\alpha \in \alpha, z:\alpha}{\alpha, z:\alpha \vdash \alpha \rightsquigarrow z} \text{ (L-VAR)}}{\alpha, z:\alpha \vdash \alpha \rightsquigarrow (\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z} \text{ (L-APP)}$$

(iii)  $\alpha, z:\alpha \vdash \text{list } \alpha \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z]$

$$\frac{(ii)}{\alpha, z:\alpha \vdash \alpha \rightsquigarrow (\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z} \quad \frac{\alpha, z:\alpha \vdash \text{list } \alpha \rightsquigarrow []}{\alpha, z:\alpha \vdash \text{list } \alpha \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z]} \text{ (L-CONS)}$$

(iv)  $\cdot \vdash \forall \alpha.\alpha \rightarrow \alpha \triangleright [\Lambda\alpha.\langle z, z \rangle] \rightsquigarrow \Lambda\alpha.\lambda x:\alpha.x$

$$\frac{(iii)}{\alpha, z:\alpha \vdash \text{list } \alpha \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z]} \quad \frac{(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z =_{\beta} z}{\alpha, z:\alpha \vdash \text{list } \alpha \triangleright [\langle z \rangle] \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z]} \text{ (L-BASE)}$$

$$\frac{\alpha, z:\alpha \vdash \text{list } \alpha \triangleright [\langle z \rangle] \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]z]}{\alpha \vdash \text{list } \alpha \rightarrow \alpha \triangleright [\langle z, z \rangle] \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]]} \text{ (L-EABS)}$$

$$\frac{\alpha \vdash \text{list } \alpha \rightarrow \alpha \triangleright [\langle z, z \rangle] \rightsquigarrow [(\Lambda\alpha.\lambda x:\alpha.x)[\alpha]]}{\cdot \vdash \text{list } \forall \alpha.\alpha \rightarrow \alpha \triangleright [\Lambda\alpha.\langle z, z \rangle] \rightsquigarrow [\Lambda\alpha.\lambda x:\alpha.x]} \text{ (L-ETABS)}$$

$$\frac{\cdot \vdash \text{list } \forall \alpha.\alpha \rightarrow \alpha \triangleright [\Lambda\alpha.\langle z, z \rangle] \rightsquigarrow [\Lambda\alpha.\lambda x:\alpha.x]}{\cdot \vdash \forall \alpha.\alpha \rightarrow \alpha \triangleright [\Lambda\alpha.\langle z, z \rangle] \rightsquigarrow \Lambda\alpha.\lambda x:\alpha.x} \text{ (L-WRLD)}$$

□

## 6.2 Learning boolean not

**Lemma 6.2** (NOT IS LEARNABLE).

$\cdot \vdash (\text{bool} + \text{bool}) \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle, \langle \text{false}, \text{true} \rangle] \rightsquigarrow e$

NOTE:  $e \equiv \text{case}(b) \text{ of } \iota_1(\text{true}) \mapsto \text{false} \mid \iota_2(\text{false}) \mapsto \text{true}$ . Additionally, that *true* and *false* are learnable from any context.

*Proof.*

(i)  $\text{true}:\text{bool} \vdash \text{bool} \rightsquigarrow (\lambda x:\text{bool}.\text{false})\text{true}$

$$\frac{\frac{\text{true}:\text{bool}, x:\text{bool} \vdash \text{bool} \rightsquigarrow \text{false}}{\text{true}:\text{bool} \vdash \text{bool} \rightsquigarrow \lambda x:\text{bool}.\text{false}} \text{ (L-ABS)} \quad \frac{\text{true}:\text{bool} \in \text{true}:\text{bool}}{\text{true}:\text{bool} \vdash \text{bool} \rightsquigarrow \text{true}} \text{ (L-VAR)}}{\text{true}:\text{bool} \vdash \text{bool} \rightsquigarrow (\lambda x:\text{bool}.\text{false})\text{true}} \text{ (L-APP)}$$

(ii)  $\cdot \vdash \text{list } \text{bool} \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle] \rightsquigarrow [\lambda x:\text{bool}. \text{false}]$

$$\frac{\frac{(i) \quad \text{true}:\text{bool} \vdash \text{list } \text{bool} \rightsquigarrow []}{\text{true}:\text{bool} \vdash \text{list } \text{bool} \rightsquigarrow [(\lambda x:\text{bool}. \text{false})\text{true}]} \text{ (L-CONS)} \quad (\lambda x:\text{bool}. \text{false})\text{true} =_{\beta} \text{false}}{\frac{\text{true}:\text{bool} \vdash \text{list } \text{bool} \triangleright [\langle \text{false} \rangle] \rightsquigarrow [(\lambda x:\text{bool}. \text{false})\text{true}]}{\Gamma \vdash \text{list } \text{bool} \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle] \rightsquigarrow [\lambda x:\text{bool}. \text{false}]} \text{ (L-EABS)}} \text{ (L-SUM)}$$

(iii)  $\text{false}:\text{bool} \vdash \text{list } \text{bool} \rightsquigarrow (\lambda y:\text{bool}. \text{true})\text{false}$

$$\frac{\frac{\text{false}:\text{bool}, y:\text{bool} \vdash \text{bool} \rightsquigarrow \text{true}}{\text{false}:\text{bool} \vdash \text{bool} \rightsquigarrow \lambda y:\text{bool}. \text{true}} \text{ (L-ABS)} \quad \frac{\text{false}:\text{bool} \in \text{false}:\text{bool}}{\text{false}:\text{bool} \vdash \text{bool} \rightsquigarrow \text{false}} \text{ (L-VAR)}}{\text{false}:\text{bool} \vdash \text{bool} \rightsquigarrow (\lambda y:\text{bool}. \text{true})\text{false}} \text{ (L-APP)}$$

(iv)  $\cdot \vdash \text{list } \text{bool} \rightarrow \text{bool} \triangleright [\langle \text{false}, \text{true} \rangle] \rightsquigarrow [\lambda y:\text{bool}. \text{true}]$

$$\frac{\frac{(iii) \quad \text{false}:\text{bool} \vdash \text{list } \text{bool} \rightsquigarrow []}{\text{false}:\text{bool} \vdash \text{list } \text{bool} \rightsquigarrow [(\lambda y:\text{bool}. \text{true})\text{false}]} \text{ (L-CONS)} \quad (\lambda y:\text{bool}. \text{true})\text{false} =_{\beta} \text{true}}{\frac{\text{false}:\text{bool} \vdash \text{list } \text{bool} \triangleright [\langle \text{true} \rangle] \rightsquigarrow [(\lambda y:\text{bool}. \text{true})\text{false}]}{\cdot \vdash \text{list } \text{bool} \rightarrow \text{bool} \triangleright [\langle \text{false}, \text{true} \rangle] \rightsquigarrow [\lambda y:\text{bool}. \text{true}]} \text{ (L-EABS)}} \text{ (L-SUM)}$$

(v)  $\cdot \vdash (\text{bool} + \text{bool}) \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle, \langle \text{false}, \text{true} \rangle] \rightsquigarrow e$

$$\frac{\frac{(ii) \quad (iii)}{\cdot \vdash \text{list } (\text{bool} + \text{bool}) \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle, \langle \text{false}, \text{true} \rangle] \rightsquigarrow [e, e]} \text{ (L-SUM)}}{\cdot \vdash (\text{bool} + \text{bool}) \rightarrow \text{bool} \triangleright [\langle \text{true}, \text{false} \rangle, \langle \text{false}, \text{true} \rangle] \rightsquigarrow e} \text{ (L-WRLD)}$$

□

### 6.3 Learning church successor

**Lemma 6.3** (SUCCESSOR IS LEARNABLE).

Let  $\text{church} \equiv \forall \alpha. (\alpha \rightarrow \alpha) \rightarrow \alpha \rightarrow \alpha$ ,  $\bar{0} \equiv \Lambda \alpha. \lambda f:\alpha \rightarrow \alpha. \lambda x:\alpha. x$ ,  $\bar{1} \equiv \Lambda \alpha. \lambda f:\alpha \rightarrow \alpha. \lambda x:\alpha. fx$ , and  $\text{succ} \equiv \lambda n:\text{church}. \Lambda \alpha. \lambda f:\alpha \rightarrow \alpha. \lambda x:\alpha. f(n[\alpha]fx)$ . And assume that  $\bar{0}$ ,  $\bar{1}$ , and  $\text{succ}$  can be learned from any context.

Show  $\cdot \vdash \text{church} \rightarrow \text{church} \triangleright [\langle \bar{0}, \bar{1} \rangle] \rightsquigarrow \text{succ}$ .

*Proof.*

(i)  $\bar{0}:\text{church} \vdash \text{church} \rightarrow \text{church} \rightsquigarrow \text{succ}$

NOTE: Can be learned from any context.

(ii)  $\cdot \vdash \text{church} \rightarrow \text{church} \triangleright [\langle \bar{0}, \bar{1} \rangle] \rightsquigarrow \text{succ}$

$$\begin{array}{c}
\frac{\bar{0}:\text{church} \in \bar{0}:\text{church}}{(i) \quad \bar{0}:\text{church} \vdash \text{church} \rightsquigarrow \bar{0}} \\
\frac{\bar{0}:\text{church} \vdash \text{church} \rightsquigarrow (\text{succ})\bar{0} \quad \bar{0}:\text{church} \vdash \text{list church} \rightsquigarrow []}{\bar{0}:\text{church} \vdash \text{list church} \rightsquigarrow [(\text{succ})\bar{0}]} \quad (\text{succ})\bar{0} =_{\beta} \bar{1} \quad (\text{L-BASE}) \\
\frac{\cdot \vdash \text{list church} \triangleright [\langle \bar{1} \rangle] \rightsquigarrow [(\text{succ})\bar{0}]}{\cdot \vdash \text{list church} \rightarrow \text{church} \triangleright [\langle \bar{0}, \bar{1} \rangle] \rightsquigarrow [\text{succ}]} \quad (\text{L-EABS}) \\
\frac{\cdot \vdash \text{list church} \rightarrow \text{church} \triangleright [\langle \bar{0}, \bar{1} \rangle] \rightsquigarrow [\text{succ}]}{\cdot \vdash \text{church} \rightarrow \text{church} \triangleright [\langle \bar{0}, \bar{1} \rangle] \rightsquigarrow \text{succ}} \quad (\text{L-WRLD})
\end{array}$$

□

## 7 Learning from Examples, Practically

We have implemented a proof-of-concept prototype, with promising results. (Reviewers: see the artifact attached.)

The implementation of learning from types is in the function `genTerms` in `learning.hs`. All the code in this section is in Haskell and runs in `ghci`:

```
genTerms TyBool [] 5
```

That generates all terms of type `Bool` from the empty context, up to an AST size 5.

The implementation of learning from examples is in the function `lrnTerms` in `learning.hs`.

```
lrnTerms (TyAbs TyBool TyBool) [InTm TmTrue (Out TmTrue)] [] [] 3
```

That generates all terms of type `Bool → Bool` from the empty context, up to an AST size 3 and which satisfy the example `< tt, tt >`.

To generate polymorphic terms, our examples include types. These types are used to instantiate an example at a particular base type. For example, run the following in `ghci` to learn at type  $(\forall X.X \rightarrow X)$  with examples `< Bool, tt, tt >`:

```
lrnTerms (TyAbs "X" (TyAbs (TyVar "X") (TyVar "X")))
  [InTy TyBool (InTm TmTrue (Out TmTrue))]
  [] [] 4
```

This will produce the polymorphic identity function.

The implementation “works” minus a programs which require multiple type applications. There’s also a bottleneck in performance that becomes apparent when synthesizing programs at around AST depth 20, because of the way the type application rule is currently implemented for learning.

## 8 Related Work

The literature on synthesis is both vast and rapidly expanding. Therefore, we inevitably cherry-pick among approaches that have inspired us while covering a varied landscape as well.

### 8.1 Type-driven synthesis

The seminal works on type-driven synthesis by Osera [2015]. demonstrates that you can have none-“magical” approaches to synthesis: everything is predictable, such as for instance, needing trace-complete examples. We take inspiration from this work, and suggest a way forward for examples with higher-order functions in the input/output exammples. We do not require trace completeness for System F is strongly normalizing.

Polikarpova et al. [2016] have extended the typed-driven approach to refinement types. This is interesting because refinement types, such as Liquid Types [?] are rather expressive and the types can act as rich specification. The idea of liquid types has been researched in many languages beyond the initial ML-style setting: for example, Javascript [Chugh et al. 2012] and Haskell [Vazou et al. 2014]. Our work extends the type-driven approach in an orthogonal direction.

## 8.2 Other approaches to synthesis

Program Sketching [Solar-Lezama 2008] has been a promising approach to synthesis. It relies on specification and holes. We rely on types instead of full-blown specifications.

Microsoft Prose [Research [n.d.]] has enabled the program demonstration of Excel. The Microsoft team has packaged the lessons learned from FlashFill [Gulwani 2011] into a generic framework Flash Meta [Polozov and Gulwani 2015]. The key insight is that witness functions (also known as reverse semantics) are enough to speed up synthesis for a domain-specific language. In Prose, the synthesizer author defines a grammar for the language, the semantics and the inverse semantics, and the framework automatically creates the synthesizer.

Rosette [Torlak and Bodik 2014] is a solver-aided language framework that similarly enables a separation of concern between domain and generic solving, based on satisfiability modulo theory underneath the hood. In Rosette, one can write a vanilla interpreter and get a synthesizer.

Another term for synthesis used in the learning community is program induction. Differentiable programming such as for Forth [Bosnjak et al. 2017] and Datalog [Raghothaman et al. 2019] use relaxation techniques to go from symbol to neural. Neural-Guided Search [Ellis et al. 2020; Zhang et al. 2018] uses neural networks *not* for creating programs but for guiding the search on the symbolic possibilities.

Inductive logic programming [Muggleton 1991] provides a classical avenue for synthesis in Prolog and related programming languages. An exciting recent development is the work of Cropper and Morel [2020] in which programs are learned through failures.

## 9 Conclusion

We offer a promising route to type-driven synthesis through learning in System F. Our main insight is that System F provides a fruitful ground for further synthesis work. In addition to a declarative theory, we developed a small implementation to testbed our ideas.

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## 10 Appendix

### 10.1 Specification of System F

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SYNTAX			
$e ::=$	TERMS:	$\tau ::=$	TYPES:
$x$	<i>variable</i>	$\tau_1 \rightarrow \tau_2$	<i>function type</i>
$e_1 e_2$	<i>application</i>	$\forall \alpha. \tau$	<i>polymorphic type</i>
$\lambda x:\tau. e$	<i>abstraction</i>	$\alpha$	<i>type variable</i>
$e[\tau]$	<i>type application</i>	$\Gamma ::=$	CONTEXTS:
$\Lambda \alpha. e$	<i>type abstraction</i>	$\cdot$	<i>empty</i>
$v ::=$	VALUES:	$x:\tau, \Gamma$	<i>variable</i>
$\lambda x:\tau. e$	<i>abstraction</i>	$\alpha, \Gamma$	<i>type variable</i>
$\Lambda \alpha. e$	<i>type abstraction</i>		

---

Fig. 3. Syntax in System F

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TYPING	$\boxed{\Gamma \vdash e : \tau}$
$\frac{x : \tau \in \Gamma}{\Gamma \vdash x : \tau} \text{ (T-VAR)}$	$\frac{\Gamma, \alpha \vdash e : \tau}{\Gamma \vdash \Lambda \alpha. e : \forall \alpha. \tau} \text{ (T-TABS)}$
$\frac{\Gamma, x:\tau_1 \vdash e_2 : \tau_2}{\Gamma \vdash \lambda x:\tau_1. e_2 : \tau_1 \rightarrow \tau_2} \text{ (T-ABS)}$	$\frac{\Gamma \vdash e : \forall \alpha. \tau_1}{\Gamma \vdash e[\tau_2] : [\tau_2/\alpha]\tau_1} \text{ (T-TAPP)}$
$\frac{\Gamma \vdash e_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma \vdash e_2 : \tau_1}{\Gamma \vdash e_1 e_2 : \tau_2} \text{ (T-APP)}$	

---

Fig. 4. Typing in System F

**Theorem 10.1** (PROGRESS IN TYPING).

If  $e$  is a closed, well-typed program, then either  $e$  is a value or else there is some program  $e'$  such that  $e \rightarrow_\beta e'$ .

**Theorem 10.2** (PRESERVATION IN TYPING).

If  $\Gamma \vdash e : \tau$  and  $e \rightarrow_\beta e'$ , then  $\Gamma \vdash e' : \tau$ .

**Theorem 10.3** (NORMALIZATION IN EVALUATION).

Well-typed programs in System F always evaluate to a value, to a normal form.

EVALUATING

 $e \rightarrow_{\beta} e'$ 

$$\frac{e_1 \rightarrow_{\beta} e'_1}{e_1 e_2 \rightarrow_{\beta} e'_1 e_2} \text{ (E-APP1)}$$

$$\frac{e \rightarrow_{\beta} e'}{e[\tau] \rightarrow_{\beta} e'[\tau]} \text{ (E-TAPP)}$$

$$\frac{e_2 \rightarrow_{\beta} e'_2}{e_1 e_2 \rightarrow_{\beta} e_1 e'_2} \text{ (E-APP2)}$$

$$(\Lambda \alpha. \lambda x: \alpha. e)[\tau] \rightarrow_{\beta} (\lambda x: \alpha. e)[\tau/\alpha] \text{ (E-TSUB)}$$

$$(\lambda x: \tau. e)v \rightarrow_{\beta} e[v/x] \text{ (E-SUB)}$$

Fig. 5. Evaluating in System F