

Lecture 1

9.9.

连续函数

$$S: \{F(x, y, z) = c\}$$

$$\frac{\partial F}{\partial z}(x_0, y_0, z_0) \neq 0 \quad (x_0, y_0, z_0) \in S.$$

$$\exists U \ni (x_0, y_0) \quad U \subseteq \mathbb{R}^2 \quad g: U \rightarrow \mathbb{R}$$

s.t. $F(x, y, g(x, y)) = c \quad \forall (x, y) \in U$

local \rightarrow global.

Topological space

- X topological space \mathcal{T} topology
① $\emptyset, X \in \mathcal{T}$
② finite Λ $\bigcap_{i=1}^n A_i \in \mathcal{T}$
③ contains U $\bigcup_{i=1}^n A_i \in \mathcal{T}$

Basis: \mathcal{B} is a basis of (X, \mathcal{T})
if \mathcal{B} generates \mathcal{T}

$$U \cup V \in \mathcal{T} \quad U = \bigcup_{i=1}^n A_i; \bigcap_{i=1}^m B_i$$

Secondary countable. (X, \mathcal{T}) if $\exists \mathcal{B}$ is countable.

Hausdorff: X is called Hausdorff

$$\forall p, q \in X \quad \exists U^{\text{open}} \ni p, \quad \exists V^{\text{open}} \ni q \quad U \cap V = \emptyset$$



Example:

$$\mathbb{R}^n / \{B_r(p) / p \in \mathbb{Q}^n, r \neq 0\}$$

$$B_r(p) = \{q \in \mathbb{R}^n / |q-p| < r\}$$

Continuous map: \rightarrow function.

$f: X \rightarrow Y$ is continuous if $f^{-1}(V)$ is open in X $\forall V$ open in Y

Homeomorphism: $f: X \rightarrow Y$ is a homeomorphism

同胚

f^{-1} to 1 on to.
 f, f^{-1} both continuous

Manifolds:

M is topological space is called n-d manifold if

① Hausdorff

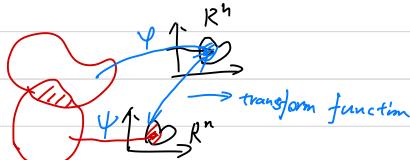
② 2-countable.

③ $\forall p \in M, \exists$ chart (U, φ) - $p \in U$
 U is open

$\varphi: U \rightarrow \varphi(U)^{\text{open}} \subseteq \mathbb{R}^n$ is a homeomorphism

*smooth

moreover if $\forall U \cap V \neq \emptyset$



red \rightarrow blue $\psi \circ \phi^{-1}$ is smooth

Smooth structure: collections

maximal choice of smooth compatible.

charts. of is atlas cover the manifolds and $\{(U_i, \varphi_i)\} \in A$

Rank: 3 more than one smooth structure

$(V, \psi) \in A$, (U, φ) is not compatible

$\exists TM$ with no smooth structure.

check:

1. U_i is open, $\bigcup_{i=1}^{n+1} U_i = \mathbb{R}P^n$, Tri.

2. φ_i is homeomorphism.

Example:

$$S^n = \{x_1^2 + \dots + x_{n+1}^2 = 1\} \subset \mathbb{R}^{n+1}$$

$$U_i^+ = \{\vec{x} \in S^n \mid x_i > 0\} \quad \varphi_i^+(\vec{x}) = (x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_{n+1})$$



Manifolds with boundary:

① Hausdorff

② 2-countable. (U, φ)

③ $\forall p \in M$, \exists local charts s.t. $\varphi : U \rightarrow \varphi(U)$ is a homeomorphism.

where $\varphi(U)$ is either an open set in \mathbb{R}^n or \mathbb{R}_+

$$U_i^- = \{\vec{x} \in S^n \mid x_i < 0\} \quad \varphi_i^- = (x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_{n+1})$$

$$\varphi_j^+ \circ (\varphi_i^-)^{-1}(w_1, \dots, w_n)$$

$$\begin{matrix} / \\ (\varphi_i^-)^{-1} \end{matrix}$$

$$(w_1, \dots, w_{i-1}, \sqrt{1-w_i^2}, w_i, \dots, w_n)$$

$$\begin{matrix} / \\ \varphi_j^+ \end{matrix}$$

$$w_1, \dots, w_{i-1}, -\sqrt{1-w_i^2}, w_i, \dots, w_{i+1}, w_i, \dots)$$

$$2. \mathbb{RP}^n = (\mathbb{R}^{n+1} \setminus \{0\}) / \sim$$

$$(x_1, \dots, x_{n+1}) \sim (y_1, \dots, y_{n+1})$$

$$\Leftrightarrow (x_1, \dots, x_n) = \lambda(y_1, \dots, y_n), \lambda \neq 0$$

$$[x_1, \dots, x_{n+1}]$$

$$U_i = \{[x_1, \dots, x_{n+1}] \mid x_i \neq 0\}$$

$$\varphi_i : \mathbb{RP}^n \rightarrow \mathbb{R}^n \quad \varphi_i([x_1, \dots, x_{n+1}]) = \left(\frac{x_1}{x_i}, \frac{x_2}{x_i}, \dots, \frac{x_{n+1}}{x_i} \right)$$

Lecture 2. 9.11 / All smooth manifolds

1. Smooth function

Defn: $f: M \rightarrow \mathbb{R}$ is smooth if

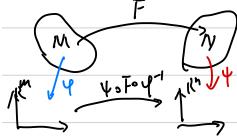
$\forall p \in M, \exists (U, \varphi), p \in U$, s.t. $f \circ \varphi^{-1}$ is smooth

Prop. if f is smooth, $\forall (U, \varphi)$, $f \circ \varphi^{-1}$ is smooth

$f \circ \varphi^{-1}$ is smooth. $f \circ \varphi^{-1} \circ \varphi^{-1}$ is smooth because M is smooth.

$$\begin{cases} S^2 \setminus \{x^2 + y^2 + z^2 = 1\} & f(x, y, z) = z \\ (U_x^+, \varphi_x^+) \quad \varphi_x^+(x, y, z) = (y, z) & f \circ \varphi_x^+ = z \\ (U_z^+, \varphi_z^+) \quad \varphi_z^+(x, y, z) = (x, y) & f \circ \varphi_z^+ = \sqrt{1-x^2-y^2} \end{cases}$$

Smooth map:



$F: M \rightarrow N$ is smooth map if $\forall p \in M$,

$$\exists (U, \varphi), (V, \psi) \quad p \in U, \quad f(p) \in V$$

s.t. $\varphi \circ F \circ \varphi^{-1}$ is smooth

diff homeo: F is $\begin{cases} 1 \text{ to } 1 & \text{onto} \\ & (\text{bijection}) \\ F, F^{-1} & \text{is smooth.} \end{cases}$

Tangent space and vector

tangent vector views as linear maps on smooth function near p

$$C_p^\infty = \{ f \mid \exists U \ni p, f|_U \text{ is smooth} \}$$

Defn: a linear map $v: C_p^\infty \rightarrow \mathbb{R}$ satisfy:

$$v(fg) = f(p)v(g) + g(p)v(f) \quad \text{if } v(\text{constant}) = 0$$

$$v \in T_p M$$

$$(U, \varphi) \quad \varphi(p) = 0 \quad C_p^\infty = \{ f, \dots \} \quad C_0^\infty = \{ f \mid F = f \circ \varphi^{-1}, f \in C_p^\infty \}$$

define $(\partial x_i)_p: C_0^\infty \rightarrow \mathbb{R}$

$$(\partial x_i)_p f = \frac{\partial f}{\partial x_i}|_{x=\vec{x}}$$

Prop: $T_p M \cong \text{Span} \{ (\partial x_i)_p \}$

proj: define $(\partial x_i)_p: C_p^\infty \rightarrow \mathbb{R}$ by

$$(\partial x_i)_p f = \frac{\partial (f \circ \varphi^{-1})}{\partial x_i}|_p$$

obviously $(\partial x_i)_p \leftrightarrow (\partial x_i)_p$

claim: $v = \sum_i v_i (\partial x_i)_p$. Lemma.

$$\textcircled{1} \quad v(F \circ \varphi) \quad \forall F: \varphi(U) \rightarrow \mathbb{R} \quad - F \circ \varphi = F \circ \varphi + \sum_i h_i(x) \cdot x_i$$

$$v(F \circ \varphi) = v(F \circ \varphi) + \sum_i v_i (h_i(x) \circ \varphi) \cdot (x_i \circ \varphi)$$

$$\text{constant.} = \sum_i v_i (h_i(x) \circ \varphi) \cdot (x_i \circ \varphi)(p) + v(x_i \circ \varphi) \cdot (h_i(x) \circ \varphi)(p)$$

$$= \sum_i v_i (x_i \circ \varphi) \cdot h_i(p)$$

$$v = \sum_i v_i (\partial x_i)_p$$

$$v(f) = \sum_i v_i \left. \frac{\partial (f \circ \varphi^{-1})}{\partial x_i} \right|_p$$

$$= \sum_i v_i \left. \frac{\partial F}{\partial x_i} \right|_p$$

$$= \sum_i v_i h_i(p)$$

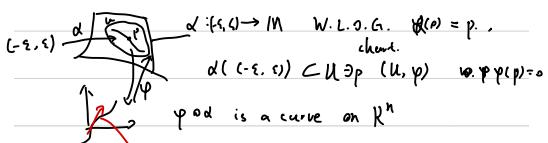
$$F(x) = F(0) + \sum_i h_i(x) x_i$$

$$\frac{\partial F}{\partial x_i} = h_i(x) + \sum_j \frac{\partial h_i}{\partial x_j}(x) x_j$$

$$\text{So } v_i = v(x_i \circ \varphi)$$

$$\frac{\partial F}{\partial x_i}|_0 = h_i(0)$$

Tangent vector of curve



$$v: C_p^\infty \rightarrow \mathbb{R}$$

$$v(f) \stackrel{\text{defn}}{=} \left. \frac{d}{dt} [f \circ \alpha(t)] \right|_{t=0} \quad v \in T_p M$$

$$= \left. \frac{d}{dt} (F \circ \varphi^{-1} \circ \varphi \circ \alpha) \right|_{t=0}$$

$$= \sum_i \left. \frac{\partial F}{\partial x_i} \right|_{\varphi(\alpha(t))} (\varphi \circ \alpha)'(t)$$

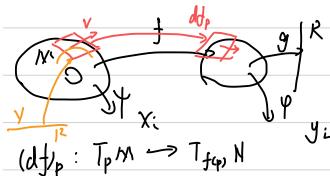
$$= \left[\sum_i (\varphi \circ \alpha)'(t) \frac{\partial}{\partial x_i} \right] f$$

Tangent vector of i .

$$v = \sum_i (\varphi \circ \alpha)'(t) \frac{\partial}{\partial x_i}$$

$$v \stackrel{\text{defn}}{=} \alpha'(t)$$

The differential of Smooth Maps



for $g \in C^\infty(N)$ equivalence: $(f \circ g)'(v)(h) = v(h \circ f)$

$$\text{or: } df_p(v) = (f \circ g)'(v) \quad y: R \rightarrow M \quad y'(v) = v \quad y(v) = p$$

$$\begin{aligned} \text{Check: } df_p(d_1 v_1 + d_2 v_2)(g) &= df_p(v)(g \circ f) \\ &= d_1 v_1(g \circ f) + d_2 v_2(g \circ f) \\ &= (d_1 df_p(v_1) + d_2 df_p(v_2))g \end{aligned}$$

$$df_p(d_1 v_1 + d_2 v_2) = d_1 df_p(v_1) + d_2 df_p(v_2) \quad \checkmark$$

df_p is linear!

f)

$$\begin{aligned} df_p(dX_i) &= \frac{\partial x_i}{\partial y_j} (g \circ f) \\ &= \left. \frac{\partial (g \circ f \circ \varphi^{-1})}{\partial x_i} \right|_p y_i \\ &= \left. \frac{\partial (g \circ \varphi^{-1} \circ \varphi \circ f \circ \varphi^{-1})}{\partial x_i} \right|_p y_i \\ &= \left. \frac{\partial (g \circ \varphi^{-1})}{\partial y_j} \frac{\partial x_i}{\partial y_j} \right|_p y_i \end{aligned}$$

$$\text{so: } df_p(dX_i) = \sum_j \frac{\partial y_i}{\partial x_j} dy_j$$

$$\begin{aligned} \text{so } df_p(y'(v)) &= df_p(\sum_i x'_i(v) dx_i) \\ &= \sum_i \sum_j \frac{\partial y_i}{\partial x_k} x'_k(v) dy_j \end{aligned}$$

$$\begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \cdots & \frac{\partial y_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_n}{\partial x_1} & \cdots & \frac{\partial y_n}{\partial x_n} \end{pmatrix} \begin{pmatrix} dx_1 \\ \vdots \\ dx_n \end{pmatrix} = \begin{pmatrix} dy_1 \\ \vdots \\ dy_n \end{pmatrix}$$

Jacob: $\cdot f$

Rank:

definition: We define rank of f is the rank of $(df_p)_p$ denote: $\text{rank}_f(p)$

if $\forall p \in M$, $\text{rank}_p = r$ denote $\text{rank}_f = r$

$f: M \rightarrow N$

Submersions: $\text{rank}_f = \dim N$ (surjective) ($n < m$)

Immersions: $\text{rank}_f = \dim M$ (injective) ($m < n$)

Embeddings: $\text{if } f \text{ is homeomorphism from } M \text{ to } f(M)$

\oplus : immersion

$$M \xrightarrow{\quad} \begin{array}{c} \nearrow \\ \curvearrowleft \end{array} \quad N \xrightarrow{\quad} \begin{array}{c} X \\ \nearrow \end{array}$$

Rank Theorem

$M^m, N^n \quad f: M \rightarrow N$ smooth, $\text{rank } f = k$

$\forall p \in M, \exists (U, \varphi) \ni p, (V, \psi) \ni f(p)$

$$F := \psi \circ f \circ \varphi^{-1} \quad F(x_1, \dots, x_m) = (x_1, \dots, x_r, 0, \dots, 0)$$

$$\begin{array}{ccc} \uparrow & \curvearrowright & \begin{array}{c} x_1, \dots, x_r \\ \hline x_{r+1}, \dots, x_n \end{array} \\ \text{---} & \nearrow & \text{---} \end{array}$$

$$(U, \varphi), (V, \psi) \text{ of } p, f(p)$$

$$\tilde{\varphi}(U) = (x_1, \dots, x_k; x_{k+1}, \dots, x_m) = (\bar{x}_1, \bar{x}_2)$$

$$\tilde{\psi}(V) = (y_1, \dots, y_k; y_{k+1}, \dots, y_n) = (Y_1, Y_2)$$

$$\tilde{F} := \tilde{\varphi} \circ f \circ \tilde{\psi}^{-1} = (Y_1, \bar{x}_1, \bar{x}_2, Y_2, \bar{x}_1, \bar{x}_2)$$

$$\tilde{F}(0, 0) = (0, 0)$$

since (df_p) is rank r .

(df_p) is not singular:

or $D\tilde{F}_{k \times k}$ is not singular

$$\text{inside: } G(\bar{x}_1, \bar{x}_2) = (Y_1, \bar{x}_1, \bar{x}_2, \bar{x}_1)$$

$$D G = \begin{pmatrix} \frac{\partial Y_1}{\partial \bar{x}_1} & \frac{\partial Y_1}{\partial \bar{x}_2} \\ \vdots & \vdots \\ 0 & 1 \end{pmatrix} \text{ is not singular.}$$

$$F \circ G^{-1}(W_1, W_2)$$

$$G: (\bar{X}_1, \bar{Y}_1) \rightarrow (W_1, W_2)$$

$$F: (\bar{X}_1, \bar{Y}_1) \rightarrow (Y_1, Y_2)$$

$$(W_1, W_2) \xrightarrow{G^{-1}} (\bar{Y}_1, \bar{Y}_2) \xrightarrow{F} (W_1, \tilde{Y}_2(W_1, W_2))$$

$$F \circ G^{-1}(W_1, W_2) = (W_1, \tilde{Y}_2(W_1, W_2))$$

$$\tilde{Y}_2(W_1, W_2) = Y_2(\bar{Y}_1(W_1, W_2), \bar{Y}_2(W_2))$$

$$D(F \circ G^{-1}) = \begin{pmatrix} \frac{\partial Y_1}{\partial W_1} & \cdots & \frac{\partial Y_1}{\partial W_2} \\ \vdots & \ddots & \vdots \\ \frac{\partial Y_k}{\partial W_1} & \cdots & \frac{\partial Y_k}{\partial W_2} \end{pmatrix}$$

and $F \circ G^{-1}$ rank k

$$\text{so } \frac{\partial Y_k}{\partial W_2} = 0$$

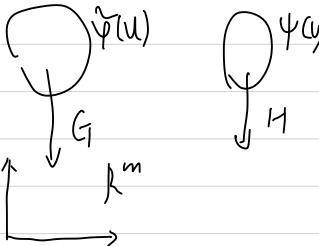
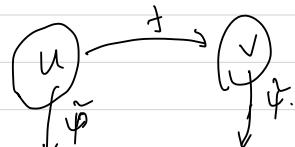
$$F \circ G^{-1}(W_1, W_2) = (W_1, \tilde{Y}_2(W_1))$$

defn $H: V \rightarrow \mathbb{R}^m$

$$H(Y_1, Y_2) = (Y_1, Y_2 - \tilde{Y}_2(Y_1))$$

$$DH = \begin{pmatrix} 1 & \cdots & -\frac{\partial \tilde{Y}_2}{\partial Y_1} \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \end{pmatrix} \text{ (der > smooth)}$$

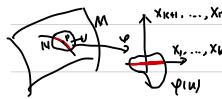
$$H \circ F \circ G^{-1}(W_1, W_2) = (W_1, 0)$$



Submanifolds:

$N \subset M^n$ is subset of $S \subset M$

if $\forall p \in N, \exists (U, \varphi) \ni p, \varphi(U \cap N) = \{x_1, \dots, x_k, x_{k+1} = \dots = x_n = 0\}$



Then, $(U \cap N, \varphi|_{U \cap N})$ given rise to a local chart of N

at p. and U is submanifold of M .

↑ equal)

Defn: Submanifolds

N^k is called (regular submanifolds of M) if

$N \subset M$ is an Embedding (see John Lee Thm. 5.14)
 $S = \Phi^{-1}(p)$, for $p \in N$

Thm: $\Phi: M^m \rightarrow N^n$ smooth map of constant rank

K: Then, each level set of Φ is a smooth submanifold with
 $\dim. m-k$ level set

Proof: $\forall q \in N, \Phi^{-1}(q) = S$

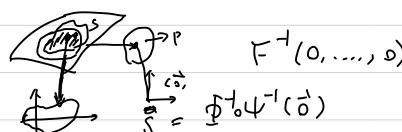


special case: Φ immersion $\dim = 0$

$\forall p \in S, \exists (U, \varphi) \ni p, (U, \varphi)$ of $\Phi(p)$

s.t. $\Phi \circ \varphi^{-1}(x_1, \dots, x_m) = (x_1, \dots, x_k, 0, \dots, 0) \quad H(x_1, \dots, x_m)$

so: $\varphi(S \cap U) = \{x_1 = 0, \dots, x_k = 0, x_{k+1}, \dots, x_m\}$



$$\varphi \circ \Phi^{-1} \circ \varphi^{-1}(\vec{o}) = (0, \dots, 0, x_{k+1}, \dots, x_m)$$

[Constant Rank Level set]

Defn: $f: M^m \rightarrow N^n$ map.

$$\text{rank}_f(p) = n$$

$p \in M$ is regular pt if $(df)_p$ is surjective

$p \in M$ is critical pt if $\not\sim$

$q \in N$ is regular value if $\forall p \in f^{-1}(q)$ is regular pts

critical value if . . .

$f^{-1}(q)$ is call regular level set

Thm. $\Phi: M^m \rightarrow N^n$ (not necessary to be CR)

regular level set is submanifolds.

Proof: $\tilde{M} = \{p \mid p \text{ is regular pt}\}$

* \tilde{M} is open in M ?

obviously: $\Phi^{-1}(q) \subseteq M$

$\Phi|_{\tilde{M}}$ is constant rank

$\Phi'(q) \hookrightarrow \tilde{M}$ accordly to last thm.

and $\tilde{M} \hookrightarrow M$?

so $\Phi^{-1}|_{\tilde{M}} \hookrightarrow M$

Example:

1. $M_n = \{n \times n \text{ matrices of } \mathbb{R}^n\}$ is a smooth manifold of $\dim(n^2)$

$$[a_{ij}] \cong \mathbb{R}^{n^2} \checkmark$$

2. $GL_n = \{A \in M_n \mid \det(A) \neq 0\}$ is a smooth ... of $\dim n^2$

3. $S_n = \{A \in GL_n \mid A = A^T\}$ of $\frac{n(n+1)}{2}$

4. $O_n = \{AA^T = Id\}$ dim?

$\Phi: GL_n \rightarrow S_n$

$$A \rightarrow AA^T$$

Proof: Id is regular value.

Vector Fields

Defn: $X: U \rightarrow TM$

$$(U, (x^i)) \ni p \quad p \rightarrow X_p$$

$$: X_p = \sum_i X^i(p) \frac{\partial}{\partial x^i}|_p \quad X^i: U \rightarrow \mathbb{R}$$

$\mathcal{X}_M = \{\text{collection of all smooth functions}\}$

X as: $C^\infty \xrightarrow{\text{a map}} C^\infty$ by define

$$Xf = \sum_i \frac{\partial(f \circ \Phi^{-1})}{\partial x^i} X^i$$

$$\text{or } (Xf)(p) = X_p f$$

Lie bracket

$[X, Y]: C^\infty \rightarrow C^\infty$

$$f \mapsto X(Yf) - Y(Xf).$$

Propo: ① $[\lambda_1 X_1 + \lambda_2 X_2, Y] = \lambda_1 [X_1, Y] + \lambda_2 [X_2, Y]$

$$\text{② } [X, Y] = -[Y, X]$$

$$\text{③ } [X, [Y, Z]] + \dots +$$

Integral curve of vector fields:

$X \in \mathfrak{X}(N)$ $\alpha: (-\varepsilon, \varepsilon) \rightarrow M$ is integral curve if

$$\text{if } \alpha'(t) = X_{\alpha(t)}$$

Under (U, φ) $\alpha([-\varepsilon, \varepsilon]) \subseteq U$

$$X_{\alpha(t)} = \sum_i X^i(\alpha(t)) \frac{\partial}{\partial x^i}$$

$$\alpha'(t) = \sum_i \dot{\alpha}^i \frac{\partial}{\partial x^i}$$

$$\dot{\alpha}^i = X^i(\alpha^1, \dots, \alpha^n)$$

Recall Thm: Local existence and unique.

(1) $\forall (\alpha^1(\cdot), \dots, \alpha^n(\cdot)), \exists \varepsilon > 0, \exists!$ solution define on $(-\varepsilon, \varepsilon)$

(2) if $\alpha^i(t_0) = \beta^i(t_0)$ at some point t_0 , they are same.

(3) $\forall \vec{x}_0 = (\alpha^1(\cdot), \dots, \alpha^n(\cdot)), \exists t_0 \in \mathbb{R}, \text{ s.t. } \exists \varepsilon > 0, \alpha^i((t_0, t)) \subset U_i \quad \exists B_i \ni 1$

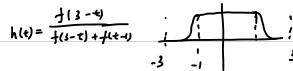
Properties of bump function:

$\exists f: \mathbb{R}^n \rightarrow \mathbb{R}$ Smooth

① $0 \leq f \leq 1 \quad B_r = \{x \mid |x| < r\}$.

② $\text{supp}(f) \subset B_1$

Proof: $f(x) = \begin{cases} e^{-\frac{1}{1-x}} & x \in (-\infty, 1) \\ 0 & \text{else} \end{cases}$



Defn: Vector Fields is complete if integral curve is defined on \mathbb{R} .

Anti-example: $X = x^3 \partial_x$ on \mathbb{R} $CX(p)(t)$ is

$$dx(t) = a^2(t)$$

$$a = -\frac{1}{t} \quad t=0 \text{ not defn}$$

if X is complete on M

we define $\varphi_t: M \rightarrow M$ by

$$\varphi_t(p) = \Phi(t, p) \quad \Phi(t, p) \text{ is integral curve start}$$

at p

$$\varphi_{-t} = \varphi_t^{-1}$$

| φ is smooth

| φ is one-to-one and onto.

Lemma:

X is TS,

$\{U_\alpha\}$ is covering of $X, \bigcup U_\alpha = X$

$\{U_\beta\}$ is refinement of $\{U_\alpha\}$ if $\bigcup U_\beta = X$
 $\{U_\beta\}$ is locally finite $\forall p \in X, \exists V_p \ni p, \text{ s.t. } V_p \cap U_\beta \neq \emptyset$
 finite

example: $U_\alpha = (0, 2^{-n})$

$$\bigcup_{k=-\infty}^{k=\infty} U_k = (0, +\infty)$$

$\exists n, x < 2^{-n}$.

X is paracompact

Thm: If M is closed/^{compact} no boundary.

$\forall X \in \mathcal{C}(M), X$ is complete.

Proof: $\forall p \in U_p$, we can find $(-\varepsilon_p, \varepsilon_p) \subset X(p)(t)$

$\{U_p\}_{p \in M}^{\text{open}}$ is open covering of M

$$\varepsilon = \sup \{\varepsilon_p\}$$

$\exists (\xi, \varepsilon), \forall p \in M, C_p(t)$ defined here.

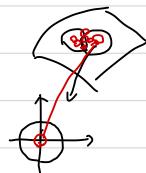
Lemma: $\{U_\alpha\}$ is open covering of M (Manifold)

\exists at most countable $\{V_\beta\}$ a refinement of $\{U_\alpha\}$ and is locally finite.

Let: (U_β, φ_β) is chart of M satisfy:

$$\varphi_\beta(U_\beta) = B_3$$

$$\left\{ \varphi_\beta^{-1}(B_i) \right\}_{i=1}^{\infty} \ni M$$



Secondary

Partition of Unity

1. bump-function (cut-off function)

support of f : $\text{supp}(f) = \overline{\{p \mid f(p) \neq 0\}}$

Defn:

$\{f_i\}_{i=1}^{\infty}$, $f_i \in C^{\infty}(M)$ is called partition of unity if

$$\text{① } \forall i \quad 0 \leq f_i \leq 1$$

② $\{\text{Supp}(f_i)\}_{i=1}^{\infty}$ is locally finite covering of M

$$\text{③ } \sum_{i=1}^{\infty} f_i(x) = 1$$

Defn: if $\{\text{Supp}(f_i)\}_{i=1}^{\infty}$ is refinement of U_d
then $\{f_i\}$ is said to be subordinate to $\{U_d\}$

Theorem:

M sm, $\{U_d\}$ open covering of M .

\exists partition of unity $\{f_i\}_{i=1}^{\infty}$ subordinate to $\{U_d\}$

by Lemma: $\exists \{U_p\}_{p \in \mathbb{N}}$ locally finite refinement of $\{U_d\}$

and $\{U_p, V_p\}, \psi_p: U_p \rightarrow V_p$ is open covering (also refinement)
 $f_p(x) = \begin{cases} h \circ \psi_p^{-1} & x \in U_p \\ 0 & x \notin U_p \end{cases}$



$F = \sum_{p=1}^{\infty} f_p$ ① F is smooth $\forall p$, only finite p , $p \in U_p$

② $F > 0$ $\{\psi_p^{-1}(B_p)\}_{p=1}^{\infty} = X$

$\forall p, \exists \beta \quad f_p(p) = 1 > 0$

and $f_p \geq 0$, so $F > 0$

$$f_p = \frac{f_p}{F}$$



w: a section of $\Lambda^k T^* M$



R-had.

Differential forms on \mathbb{R}^n

$$f \in C^\infty(\mathbb{R}) \quad df = \sum_i \frac{\partial f}{\partial x_i} dx_i$$

$$f \in C^k(\mathbb{R})$$

$$\Omega^k(\mathbb{R}) = \text{span}\{dx_{i_1} \wedge dx_{i_2} \wedge \dots \wedge dx_{i_k}\}_{1 \leq i_1 < \dots < i_k}$$

Exterior differentiation

$$d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$$

$$w \rightarrow dw$$

$$d(f_1 \wedge f_2 \wedge \dots \wedge f_k) = \sum_i (\frac{\partial f_i}{\partial x_i}) dx_i$$

$$df = 0:$$

$$df_i = \sum_j \frac{\partial f_i}{\partial x_j} dx_j$$

$$dw = \sum_i \sum_j \frac{\partial^2 f_i}{\partial x_i \partial x_j} dx_i \wedge dx_j$$

$$= \sum_i \sum_j \frac{\partial^2 f_i}{\partial x_i \partial x_j} (dx_i \wedge dx_j + dx_i \wedge dy_j) = 0$$

Exterior Algebra.

V n-dim vector space $V = \mathbb{R}^3$

e_1, \dots, e_n is a basis

we defn $\Delta^k V = \{a_1 x_1 y_1 z_1 + a_2 x_2 y_2 z_2 + \dots + a_n x_n y_n z_n\}$ $\dim(\Delta^k V) = \binom{n}{k}$

$$\Delta^k V := \text{span}\{e_1 \wedge e_2 \wedge \dots \wedge e_k\} \quad 1 \leq i_1 < \dots < i_k$$

$\Delta^* V := \bigoplus_{k=0}^n \Delta^k V$ \rightarrow external algebra of V. multiply was defined by

satisfy: $e_i \wedge e_j = -e_j \wedge e_i \quad (e_i \wedge e_i = 0)$

Algebra: Vector space + Ring

$$\forall u, v \in \Delta^* V \quad uv \in \Delta^* V.$$

$$\lambda(uv) = (\lambda u)v = u(\lambda v) \quad u \wedge v = (-1)^{kl} v \wedge u$$

Dual vector space:

V^* linear map for V to R $\dim(V^*) = n$

$$\{e_1^*, \dots, e_n^*\} \text{ and } e_i^*(e_j) = \delta_{ij};$$

k-alternating form

out one place

$$w: V \times V \times \dots \times V \rightarrow R$$

1. multilinear

$$w(aX_1 + bY_1, X_2, \dots, X_m) = aw(X_1, X_2, \dots, X_m) + bw(Y_1, \dots, X_m)$$

$$2. w(X_{(1)}, \dots, X_{(m)}) = \text{sgn}(\sigma) w(X_1, \dots, X_m)$$

② 由

exterior algebra on V^*

$$\Delta^* V^* = \bigoplus_{k=0}^n \Delta^k V^* \quad (k\text{-covector})$$

$w \in \Delta^k V^*$ assume $w = d_1 \wedge d_2 \wedge \dots \wedge d_n$.

$$\text{where } d_i = \sum_{j=1}^k \epsilon_{ij} e_j^* \in \Delta^1 V^* \quad (\text{or dual vector})$$

at M

Def. 1:

$$w: M \times \dots \times M \rightarrow \mathbb{R}$$

$$\text{with: } \circ w(X_1, \dots, X_k) = \text{sgn}(\sigma) w(X_{\sigma(1)}, \dots, X_{\sigma(k)})$$

③ multi-linear.

we can easily check w is k-alternating form

We define the tensor field of V is $\Omega^k M$ (under local chart)

$w \in \Omega^k M$ w_i is a continuous function on V.

and k is the order.

不一样 上面 dx_i 是 \mathbb{R}^n 中的基
下面 dx_i 是 $T_p M$ 的基, 形式一样
是因为我们自由选取了

Operators

$$1. d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$$

$$\omega \mapsto dw$$

$$dw(x_1, \dots, x_k) = \sum_{i=1}^k (-1)^{i+1} x_i (w(x_1, \dots, \hat{x}_i, \dots, x_k))$$

$$+ \sum_{i,j} (-1)^{i+j} w([x_i, x_j], x_1, \dots, \hat{x}_i, \dots, \hat{x}_j, \dots, x_k)$$

or $\omega \mapsto dw$

chart \downarrow

$$\sum f_i dx^i \mapsto \sum df_i \wedge dx^i$$

2. Push forward on vector field

$$f: M \rightarrow N \text{ smooth function}$$

\Downarrow induce a push forward of X by

$$f_* X \in \mathfrak{X}(N)$$

$$(f_* X)_{f(p)} = df_p(X_p)$$

$$f_*^{-1} = (\#)^{-1}$$

Cunne?

$$f_*: M \rightarrow N \quad (\#)_* = (\#)^{-1}$$

$$(\#)_* X = ([\#]_* X)_p = df_p^{-1} X_{f(p)}$$

3 Pull back on cotangent fields

$$f: M \rightarrow N \quad \downarrow \quad \omega \in \Omega^1(N)$$

$$(f^* \omega)(X) = \omega(f_* X) \quad f^* \omega \in \Omega^1(M)$$

$$(\#^* \omega)_p(X_p) = \omega([\#]_* X)_{f(p)}$$

$$= \omega(df_p(X_p))$$

$$= (\# f_p^{-1})^{-1} X_{f(p)}$$

$$= (\# f_p^{-1}) ([\#]_* X)_p$$

$$= X_{f(p)} \circ (\# f_p^{-1})$$

Push forward and Pull back on Tensor fields

$$\Gamma(T^{k,\ell}(M)) \quad \Gamma(T^{k,\ell}(N)) = \mathfrak{X}(N)$$

$$f_*: \Gamma(T^{k,\ell}(M)) \rightarrow \Gamma(T^{k,\ell}(N))$$

$$(\#_A)(x_1, \dots, x_k, w_1, \dots, w_\ell) = A(-f_*^{-1} x_1, \dots, f_*^{-1} x_\ell, f^* w_1, \dots, f^* w_\ell)$$

$$(\#^* A)(x_1, \dots, x_k, w_1, \dots, w_\ell) = A(f_* x_1, \dots, f_* x_\ell, f^{*\ell-1} w_1, \dots, f^{*\ell} w_\ell)$$

$$f_* (\#^* A)(x_1, \dots, x_k, w_1, \dots, w_\ell) = A(f_* x_1, \dots, f_* x_\ell, f_* w_1, \dots, f_* w_\ell)$$

$$= (\#^* A)(f_* x_1, \dots, f_* x_\ell, f^{*\ell-1} w_1, \dots, f^{*\ell} w_\ell)$$

$$= A(x_1, \dots, w_1, \dots, w_\ell, \dots, w_\ell)$$

$$f_* = f^{*-1}$$

$$f: M \rightarrow N$$

$$(\#_*)^{-1} = (\#)_*$$

5: Lie derivative: $\mathcal{L}_X X \in \mathfrak{X}(M)$ and complete

$$\theta_t: M \rightarrow M$$

$$\theta_t^*: \Gamma(T^{k,\ell}(M)) \rightarrow \Gamma(T^{k,\ell}(M))$$

$$\theta_{t*}: \quad \vdots$$

$$(F_{**} Y) F^{-1} *$$

$$\text{Define: } \mathcal{L}_X A = \frac{d}{dt} (\theta_t^* A)$$

for $Y \in \mathfrak{X}(N)$

$$\mathcal{L}_X Y = \frac{d}{dt} (\theta_t^* Y) = \frac{d}{dt} (\theta_t^{-1} Y) = \frac{d}{dt} (\theta_{-t} Y) = \lim_{t \rightarrow 0} \frac{\theta_{-t} Y - Y}{t} \xrightarrow{Y \in \mathfrak{X}(N)}$$

$$(\mathcal{L}_X Y)_p = \lim_{t \rightarrow 0} \frac{(\theta_{-t} Y)_p - Y_p}{t} = \frac{(d\theta_{-t})_{\theta_t(p)} Y_{\theta_{-t}(p)} - Y_p}{t}$$

$$(\mathcal{L}_X Y)_p = \frac{((d\theta_{-t})_{\theta_t(p)} Y_{\theta_{-t}(p)}) - Y_p)}{t} + dt_p \frac{(\#(Y))}{t}$$

$$= \frac{Y_{\theta_t(p)} (\# \circ \theta_{-t}) - Y_p}{t} + \frac{Y_{\theta_t(p)} (\# \circ \theta_{-t}) - Y_{\theta_{-t}(p)}}{t} + \frac{Y_{\theta_{-t}(p)} (\# \circ \theta_{-t}) - Y_{\theta_{-t}(p)}}{t}$$

$$= 2 Y_{\theta_t(p)} \left(\frac{\# \circ \theta_{-t} - \#}{t} \right) + Y_{\theta_{-t}(p)} Y_p$$

$$\mathcal{L}_X Y = [X, Y]$$

$$(J_x w) = \frac{d}{dt} (\theta_t^* w)$$

$$(J_x w)(x_1, \dots, x_k) = \frac{\underline{\theta_t^* w(x_1, \dots, x_k)} - w(x_1, \dots, x_k)}{t}$$

$\in \Omega^k(M)$

$$\begin{cases} J_x = i_{x \odot d} - d \circ i_x & \text{Cartan.} \\ J_x \circ i_y - i_y \circ J_x = i_{[x, y]} \end{cases}$$

Exercise

Summary:

$$\begin{cases} i_Y : \Omega^k \rightarrow \Omega^{k+1} \\ d : \Omega^k \rightarrow \Omega^{k+1} \\ i_X : \Omega^k \rightarrow \Omega^k \\ j^* : \Omega^k(N) \rightarrow \Omega^k(M) \\ j_* : \Omega^k(N) \rightarrow \Omega^k(M) \end{cases} \Rightarrow \begin{array}{l} T^k TM \rightarrow T^{k+1} TM \\ T^k TN \rightarrow T^{k+1} TN \\ T^k TM \rightarrow T^{k+1} TN \end{array}$$

Integral of w :

$M^n \quad w \in \Omega^n(M)$ in $(U, \varphi), (V, \psi)$

$$w|_U = f(x_1, \dots, x_n) dx_1 \wedge dx_2 \wedge \dots \wedge dx_n$$

$$w|_V = g(y_1, \dots, dy_n) dy_1 \wedge \dots \wedge dy_n$$

DF of R^k DF of M DF of R^k

$$\text{define: } \int_U w = \int_{\varphi(U)} w|_U$$

$$w = \int_U f(x_1, \dots, x_n) dx_1 \wedge \dots \wedge dx_n$$

$$= \int_U f(x_1, \dots, x_n) dx_1 dx_2 \dots dx_n$$

Is that well defined???

$$g(y_1, \dots, y_n) dy_1 \wedge dy_2 \wedge \dots \wedge dy_n$$

$$y_i = y_i(x_1, \dots, x_n)$$

$$\frac{\partial y_i}{\partial x_j} = \sum \frac{\partial y_i}{\partial x_k} dx_k \wedge \sum \frac{\partial y_k}{\partial x_j} dx_k \wedge \dots$$

$$\det \left(\frac{\partial y_i}{\partial x_j} \right)$$

$$\therefore g \left(\begin{matrix} y_1(x_1, \dots, x_n) \\ \vdots \\ y_n(x_1, \dots, x_n) \end{matrix} \right) \det \left(\frac{\partial y_i}{\partial x_j} \right) = f(x_1, \dots, x_n)$$

well defined:

$$\left| \det \left(\frac{\partial y_i}{\partial x_j} \right) \right| = \det \left(\frac{\partial y_i}{\partial x_j} \right) \Rightarrow \det > 0.$$

paracompact is need! no, every manifold is paracompact

M call orientation if $\exists (U_\alpha, \varphi_\alpha)$

$$\forall U_\alpha = M \text{ and } \det(\varphi_\alpha \circ \varphi_\beta^{-1}) > 0$$

for orientation compatible covering $\{(U_\alpha, \varphi_\alpha)\}$ is

If $\text{supp}(w)$ is compact local finiteness

$$\text{supp}(w) = \overline{\{p \in M, w_p \neq 0\}}$$

partition of unity:

$$\begin{cases} \text{supp}(f_\alpha) \subseteq U_\alpha & \text{rechts} \\ \sum f_\alpha = 1 & \text{links} \\ \text{supp}(f_\alpha) \cap \text{supp}(f_\beta) = \emptyset & \text{middle} \end{cases} \Rightarrow \sum f_\alpha w = w$$

only finite sum is non-zero

$$= \sum_{\substack{\text{finite} \\ \text{compact}}} f_\alpha \underbrace{w}_{\text{finite}} = \sum_{\substack{\text{finite} \\ \text{compact}}} f_\alpha w$$

if $\sum f_\alpha$ is also $\alpha \models p \in V$

$$\sum_{\substack{\beta \\ \text{DF of } M}} f_\beta w = \sum_{\substack{\alpha \\ \text{DF of } R^k}} \sum_{\substack{\beta \\ \text{DF of } R^k}} f_\alpha w$$

$$\sum_{\substack{\alpha \\ \text{DF of } M}} f_\alpha w = \sum_{\substack{\beta \\ \text{DF of } M}} \sum_{\substack{\alpha \\ \text{DF of } R^k}} f_\alpha w g_\beta \quad \text{because } \sum_{\substack{\alpha \\ \text{DF of } R^k}} f_\alpha w \text{ is finite!}$$

Stokes

$w \in \Omega^{n-1}(M) \quad dw \in \Omega^n(M) \quad \text{and } \text{supp}(w)$ is compact,

Remark: ∂M is orientable, and we can define +

if V is vector space with $\dim(V) = n$

we call $(v_1, \dots, v_n) \sim (v'_1, \dots, v'_n)$ iff $\det(v_{ij}) > 0$

$$V/n = \{[v_1, \dots, v_n]\}$$

M orientable $\rightarrow \exists (U_\alpha, \varphi_\alpha) \quad \forall U_\alpha = M$ and

$$\det(\varphi_\alpha \circ \varphi_\beta^{-1}) > 0$$

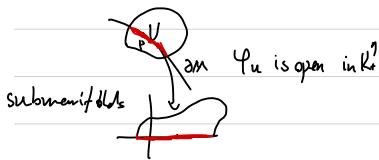
at every point p $d\varphi_1, \dots, d\varphi_n$ is an same orientation



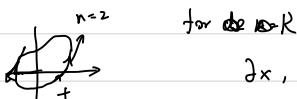
proof $\forall U_\alpha, \varphi_\alpha$, can we? $\{dx_1, \dots, dx_n\} \sim \{dx'_1, \dots, dx'_n\}$

define induced orientation of ∂M as

$$\forall p \in \partial M \quad \exists (U, \varphi)_p \text{ ori}$$



$T_p \partial M$ positive orientation define: $\{(-1)^n \partial_1, \dots, \partial_{n-1}\}$



for $\partial M \subset R^n$

$$dx, dy$$

Carry our proof on R^n or H^{n+1}

$$w = \sum_{i=1}^n f_i(x) dx_1 \wedge \dots \wedge \hat{dx_i} \wedge \dots \wedge dx_n$$

$$dw = \sum_{i=1}^n (-1)^{i-1} \frac{\partial f_i}{\partial x_i} dx_1 \wedge \dots \wedge dx_n$$

$$\int_M dw = \sum_{i=1}^n \int_{R^n} (-1)^{i-1} \int_0^\infty \frac{\partial f_i}{\partial x_i} dx_i \wedge dx^{n+1}$$

since $\text{supp } \{f_i(x)\}$ is compact.

$$\frac{\partial f_i}{\partial x_i} dx_i = f_i|_{\partial M} \quad \text{sin } f_i \text{ suppose compact}$$

$$\int_M w = 0. \quad \forall$$

$$\text{if } \int_{H^n} dw = \sum_{i=1}^n \int_{H^n} (-1)^{i-1} \frac{\partial f_i}{\partial x_i} dx_1 \wedge \dots \wedge dx_n$$

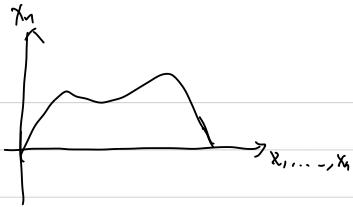
only when $i=n$

$$= (-1)^{n+1} \int_0^\infty \frac{\partial f_n}{\partial x_n} dx_n \cdot \int_{R^{n-1}} dx_1 \wedge \dots \wedge dx_{n-1}$$

$$= \int_{R^n} (x_1, \dots, x_{n-1}, \omega) - \int_{R^n} (x_1, \dots, x_{n-1}, 0)$$

$$= (-1)^n \int_{R^{n-1}} f_n(x_1, \dots, x_{n-1}, 0) dx_1 \wedge \dots \wedge dx_{n-1}$$

$$\int_M w = (-1)^n \sum_{i=1}^n \int_{R^{n-1}} f_i(x_1, \dots, x_{n-1}, 0) dx_1 \wedge \dots \wedge \overset{i}{dx_i} \wedge \dots \wedge dx_n$$



$$\int_{\partial H^n} w = (-1)^n \int_{\partial H^n} (\dots, 0)$$

$$dx_1 \wedge \dots \wedge dx_{n-1}$$

So; our result is right for $w \in \Lambda^k(H^n)$

and $w \in \Lambda^k(R^n) / \text{compact}$.

if w support on single chart (U, φ)

$$\int_M dw = \int_{H^n} \frac{(\varphi^{-1})^* dw}{\text{compact.}} = \int_{H^n} d((\varphi^{-1})^* w)$$

$$\text{curl } = \int_{\partial M} w \quad (\varphi^{-1})(\partial M) = \partial M$$

$$w = \sum_{\alpha} f_{\alpha} w \quad \int_M \sum_{\alpha} f_{\alpha} w = \sum_{\alpha} \int_M f_{\alpha} w = \sum_{\alpha} \int_M df_{\alpha} \wedge w$$

$$\sum_{\alpha} df_{\alpha} \wedge w = \sum_{\alpha} f_{\alpha} dw + \sum_{\alpha} df_{\alpha} \wedge dw$$

$$= dw + d(\sum_{\alpha} f_{\alpha}) \wedge dw = dw$$

$$\therefore \int_M dw$$

de Rham Cohomology:

$$d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$$

$$Z^k := \ker(d: \Omega^k(M) \rightarrow \Omega^{k+1}(M)) \Rightarrow \text{closed form}$$

$$B^k := \ker(d: \Omega^{k-1}(M) \rightarrow \Omega^k(M)) \Rightarrow \text{exact form}$$

Obviously $B^k \subset Z^k$ since $d^2 = 0$

$$\text{define: } H_{\text{DR}}^k(M) := Z^k / B^k \leftarrow M \text{ 的 } k \uparrow \text{ dR 上}$$

In general:

$$\begin{array}{ccccccc} \text{chain complex: } & 0 & \xrightarrow{d} & A^0 & \xrightarrow{d} & A^1 & \rightarrow \dots \rightarrow A^n \rightarrow 0 \\ & & & \text{if } d^2 = 0 & & & \end{array}$$

$$H^k = \frac{\ker(d: k \rightarrow k+1)}{\text{Im}(d: k-1 \rightarrow k)}$$

de Rham:

$$[\omega] \in H^k(M) \quad d\omega = 0$$

$$[\omega] = [\omega'] \iff \omega - \omega' = df \Rightarrow \omega \text{ cohomology to } \omega'$$

$$\text{Ex: } w = \frac{xdy - ydx}{x^2 + y^2} \quad M = \mathbb{R}^2 \setminus \{0\}$$

Induced Cohomology maps: (Functional.)

$$F: M \rightarrow N \quad F^*: \Omega^k(N) \rightarrow \Omega^k(M) \Rightarrow F^* H_{\text{DR}}^k(N) \rightarrow H_{\text{DR}}^k(M)$$

① if w is closed in N

$$d(F^*w) = F^*(dw) = 0.$$

② if w is exact in N

$$F^*(dw) = d(F^*w)$$

$$\text{define } F^*: H_{\text{DR}}^k(N) \rightarrow H_{\text{DR}}^k(M)$$

$$F^*[\omega] = [F^*\omega]$$

$$\text{if } [\omega] = [\omega'] \quad \omega' = \omega + dy$$

$$\begin{aligned} [F^*\omega] &= [F^*\omega + F^*dy] = [F^*\omega + d(F^*y)] \\ &= [F^*\omega] \end{aligned}$$

well defined.

Homotopy and Fundamental Group.

X, Y TSs $F_0, F_1: X \rightarrow Y$ continuous

a homotopy from F_0 to F_1 is a continuous map

$$\begin{cases} H(x, 0) = F_0 \\ H(x, 1) = F_1 \end{cases}$$

homotopic relation, \sim

path-homotopic $f_0 \sim f_1$, if

$$I \times I$$

↓
path-homotopic

$$H(s, 0) = f_0(s)$$

$$H(s, 1) = f_1(s)$$

$$H(0, t) = f_0(t) = f_1(t)$$

$$H(1, t) = f_0(1) = f_1(1)$$

$f_1 \sim f_2$ equivalence relation so

$[f]$ ⇒ path class

$$f, g: I \rightarrow X \quad f(s) = g(s)$$

$$\begin{matrix} f \\ + \\ g \end{matrix} \circ \begin{matrix} g \\ + \\ f \end{matrix}$$

$$\text{product: } f \cdot g(s) = \begin{cases} f(2s) & 0 \leq s \leq \frac{1}{2} \\ g(2s-1) & \frac{1}{2} \leq s \leq 1 \end{cases}$$

$$\begin{matrix} f \\ + \\ g \end{matrix} \circ \begin{matrix} g \\ + \\ f \end{matrix}$$

$$[f+g] = [f \cdot g] \Rightarrow \text{a group}$$

2. Homotopy equivalence:

$F: X \rightarrow Y$ smooth maps, if $\exists G: Y \rightarrow X$ cont...

and $G \circ F \simeq \text{Id}_X$ $F \circ G \simeq \text{Id}_Y \Rightarrow F$ is homotopy equivalent
and X, Y homotopy equivalent.

$$S^{n-1} \cong \mathbb{R}^n \setminus \{0\}$$

$$\begin{aligned} L: S^{n-1} &\hookrightarrow \mathbb{R}^n & t \circ L &= \text{Id}_{\mathbb{R}^n} \\ t: \mathbb{R}^n &\rightarrow \mathbb{R}^n & t(x) &= \epsilon \frac{x}{|x|} + (1-\epsilon) \frac{x}{|x|} \end{aligned}$$

① de Rham is homotopy invariant.

If

$M \xrightarrow{\sim} N$ is homotopy equivalent., $H_{\text{de}}^k(M) \cong H_{\text{de}}^k(N)$

$$\begin{aligned} 1. \text{ Star shape: } & I : \{I\} \hookrightarrow U \\ & f : U \rightarrow I \cup J, \quad f|_I = \text{Id}_I \\ & f|_J = \text{id}_{I \cap J} \\ & H^k(U) \cong H^k(I \cup J) \end{aligned}$$

$$H^k(U) \cong 0 \text{ for } k \geq 1$$

$$② H^0_{\text{de}}(M) \cong \mathbb{R} \text{ for connected } M.$$

$$\begin{cases} \mathbb{Z}^0 = f \quad df = 0 \Rightarrow f = C \\ \mathbb{Z}^0 = \{0\} \quad \mathbb{Z}^0 / \mathbb{Z}^0 \cong \mathbb{R} \end{cases}$$

$$\begin{array}{c} \text{Fundamental group based} \\ \text{and } q \\ \text{pt} \end{array} \begin{array}{l} H_{\text{de}}^1(M) \rightarrow \text{Hom}(\pi_1(M, q), \mathbb{R}) \\ \downarrow \\ [w] \end{array}$$

$$\Phi[w]: \pi_1(M, q) \rightarrow \mathbb{R}$$

$$\Phi[w](y) = \int_y w \quad \text{not enough tools.}$$

well defined and injective (Surject)

$$\int_{w+dw} w = \int_y w = 0$$

$$\int_y w = \int_y w \quad \boxed{\text{homom}}$$

Injective

$$\begin{aligned} \text{If: } 0 &= \int_y w \\ &= \int_\alpha w + \int_\beta w - \int_\delta w \\ &= \int_\beta w \quad \text{so: } \int_y w = 0 \quad \forall y \text{ is closed.} \\ &\quad \boxed{w = dy = 0} \end{aligned}$$

The MV Thm:

$$M = U^{\text{open}} \cup V^{\text{open}} \text{ and } U \cap V \neq \emptyset$$

$$\begin{array}{ccc} & \begin{matrix} i & j & k \\ U & V & M \end{matrix} & \text{i, j, k, l induce map} \\ \begin{matrix} \text{UNV} \\ \downarrow \\ \text{j} \end{matrix} & \begin{matrix} \downarrow \\ \text{i} \end{matrix} & \begin{matrix} \downarrow \\ \text{k} \end{matrix} \\ \Omega^k(M) & \xrightarrow{i^*} & \Omega^k(U) \\ \downarrow & & \downarrow \\ \Omega^k(V) & \xrightarrow{j^*} & \Omega^k(U \cap V) \end{array}$$

$$\begin{array}{c} \Omega^k(M) \xrightarrow{i^* \oplus j^*} \Omega^k(U) \oplus \Omega^k(V) \xrightarrow{k^*} \Omega^{k+1}(U \cap V) \\ \downarrow \\ (i^* \oplus j^*)(w, y) = (w|_U, w|_V) \\ \boxed{\text{Exact sequence: } U^{p-1} \xrightarrow{F^{p-1}} U^p \xrightarrow{F^p} U^{p+1} \dots} \\ \ker(F^p) = \text{Im } F^{p-1} \end{array}$$

MV state: $\exists \delta_k: \Omega^k(U \cap V) \rightarrow \Omega^{k+1}(U \cap V)$

and sequence if exact

$$\begin{array}{ccccc} \delta_{k-1} & \Omega^k(M) & \rightarrow & \rightarrow & \Omega^{k+1}(M) \\ \downarrow & & & & \downarrow \delta_k \end{array}$$

Short exact:

$$0 \xrightarrow{\psi} A \xrightarrow{\phi} B \xrightarrow{\psi} C \rightarrow 0 = \begin{cases} \psi \text{ is injective.} \\ \ker(\psi) = J_-(\psi) \\ \phi \text{ is surjective.} \\ \ker(\phi) = 0 \quad \text{Im } \phi = C \end{cases}$$

Zigzag Lemma: (and commutative)

$$\text{If: } 0 \rightarrow A^p \xrightarrow{F} B^p \xrightarrow{G} C^p \rightarrow 0 \quad \text{short exact}$$

$$\begin{array}{ccccccc} \psi_p, \exists \delta: H^p(C) & \xrightarrow{\text{R}} & H^{p+1}(A) & \text{s.t.} \\ \rightarrow H^k(A) & \xrightarrow{F^k} & H^k(B) & \xrightarrow{G^k} & H^k(C) & \xrightarrow{\delta} & H^{k+1}(A) \end{array}$$

is exact

$$\begin{array}{ccccccc} 0 & \rightarrow & A^k & \xrightarrow{F} & B^k & \xrightarrow{G} & C^k \rightarrow 0 \\ & & \downarrow d & & \downarrow d & & \downarrow d \\ 0 & \rightarrow & A^{k+1} & \xrightarrow{F} & B^{k+1} & \xrightarrow{G} & C^{k+1} \rightarrow 0 \\ & & \downarrow d & & \downarrow d & & \downarrow d \\ 0 & \rightarrow & A^{k+2} & \xrightarrow{F} & B^{k+2} & \xrightarrow{G} & C^{k+2} \rightarrow 0 \end{array}$$

F, G, d is commute

$$\ker(G) = \text{Im}(F)$$

~~Since~~ \downarrow since G is surjective.

$$0 \rightarrow A^k \xrightarrow{F} B^k \xrightarrow{G} C^k \rightarrow 0$$

$$dC^k = 0 \text{ by defn}$$

$$0 \rightarrow A^{k+1} \xrightarrow{F} B^{k+1} \xrightarrow{G} C^{k+1} \rightarrow 0$$

$$0 \rightarrow A^{k+2} \xrightarrow{F} B^{k+2} \xrightarrow{G} C^{k+2} \rightarrow 0$$

F, G, d is commute

$$\exists a^{k+1}$$

$$db^k =$$

$$1. = db^k.$$

$$d(F(a^{k+1})) = d(F$$

$$\text{So } da^{k+1} = 0$$

$$8: C^k \rightarrow a^{k+1}$$

$$\text{define } \delta: [C^k] \rightarrow [a^{k+1}]$$

Proof MV:

①

$$0 \rightarrow \Omega^k(M) \xrightarrow{k^* \oplus i^*} \Omega^k(U) \oplus \Omega^k(V) \xrightarrow{i^* - j^*} \Omega^k(U \cup V) \rightarrow 0$$

short

③

② $k^* \oplus i^*$ is injective:

$$\begin{aligned} & i^*(w|_U, w|_V) = (0, 0) \\ & \Downarrow \\ & w = 0 \end{aligned}$$

$$③ (k^* - j^*)(w|_U, w|_V) = w|_{U \cup V} - w|_{U \cup V} = 0$$

$$u. \text{Im}(k^* \oplus i^*) \subseteq \ker(i^* - j^*)$$

$$0 = (i^* - j^*)(y, y') = y|_{U \cup V} - y'|_{U \cup V}$$

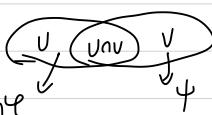
$$\text{So } y = y' \text{ on } U \cup V$$

$$\text{So: } \delta = \begin{cases} y & \text{on } U \\ y' & \text{on } V \end{cases} \quad \delta \text{ is smooth every where}$$

$$\text{And } (\delta, \delta) = (k^* \oplus i^*) \in$$

$$\forall w \in \Omega^k(U \cup V) \exists w_1 \in U, w_2 \in V$$

$$w = w_1 - w_2$$



$$w_1 = \begin{cases} \psi w & U \cap V \\ 0 & U \setminus \text{supp } \psi \end{cases}$$

$$w_2 = \begin{cases} -\psi w & U \cap V \\ 0 & V \setminus \text{supp } \psi \end{cases}$$

$$w_1 - w_2 = \psi(\psi + \phi)w = w.$$

3. Degree theory:

M, N : compact, orientable, connected, smooth ...

of dimensions n

④ $\forall w \in \Omega^n(N)$

$$\int_M F^* w = k \int_N w$$

2) If q is regular value

$$k = \sum_{p \in F^{-1}(q)} \text{sgn}(p)$$

$$\det(dF_p) > 0.$$

$$\text{sgn}(p) = \begin{cases} + & dF_p \text{ preserve orientation} \\ - & \det(dF_p) < 0. \end{cases}$$

Riemannian metric:

Vector space:

Inner product: $V \times V \rightarrow \mathbb{R}$

$$u, v \mapsto (u, v)$$

$$\textcircled{1} \text{ bilinear } (\lambda u + \lambda' v, w) = \lambda_1(u, w) + \lambda_2(v, w)$$

$$\textcircled{2} \text{ Symmetric } (u, v) = (v, u)$$

$$\textcircled{3} \text{ positive definite: } (u, u) \geq 0 \text{ and } (u, u) = 0 \text{ iff } u = 0$$

M , SM , g is called Riemannian metric on M if it assigns to each $T_p M$ and inner product which is various

$$\text{Smooth: } g: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathbb{C}^\infty$$

$$g_p: T_p M \times T_p M \rightarrow \mathbb{R} \quad g_p^*$$

local chart of p $(U, \varphi(x_1, \dots, x_n))$

$$g_{ij} = g(\partial x_i, \partial x_j) \quad \{\partial x_1, \dots, \partial x_n\}$$

$$g = g_{ij} dx^i dx^j \quad \{dx^1, \dots, dx^n\} \text{ dual basis}$$



$$g_{ij} = g(\partial x_i, \partial x_j)$$

$$\begin{aligned} g_{ij} &= g(\partial y_i, \partial y_j) = g\left(\frac{\partial x_i}{\partial y_i} \partial x_i, \frac{\partial x_j}{\partial y_j} \partial x_j\right) \\ &= \left(\frac{\partial x_i}{\partial y_i}\right) g_{kl} \left(\frac{\partial x_l}{\partial y_j}\right) \end{aligned}$$

$$\widehat{g}_{ij} = g_{kl} \left(\frac{\partial x_k}{\partial y_i}\right) \left(\frac{\partial x_l}{\partial y_j}\right)$$

Hodge *:

Orthogonal basis: $\{e_1, \dots, e_n\}$ on $T_p M$ (GS-orth)

$$g_{ij} = \delta_{ij}$$

$\{e_1^*, \dots, e_n^*\}$ dual basis and set $*$ it to orth by defn

$\widehat{g}^{ij} = \text{independent of } \{e_1, \dots, e_n\}$

$$\langle e_1^*, \dots, e_n^* \rangle = \langle \widehat{g}^{ij}, e_1, \dots, e_n \rangle$$

$$\Lambda^k T_p^* M = \text{span}\{e_1^* \wedge \dots \wedge e_n^* \mid i_1 < \dots < i_n\} = \det(\langle e_i^*, e_j^* \rangle)$$

$$\langle a, b \rangle_p = \sum_I a^I b^I \quad \text{orthonormal}$$

$$a = \sum_I a^I e^*$$

$$b = \sum_I b^I e^*$$

Hodge *

$$*: \Lambda^k T_p^* M \rightarrow \Lambda^{n-k} T_p M$$

$$e_I^* \rightarrow e_J^* \text{ sgn}(I, J)$$

$$I \cup J = \{1, \dots, n\}$$

$$\text{sgn}(I, J) = \text{sgn}(i_1, \dots, i_k, j_1, \dots, j_{n-k})$$

↓

Varying p

$$*: \Omega^k(M) \rightarrow \Omega^{n-k}(M)$$

$$*1 \in \Omega^n(M) := V_M \text{ Volume form on } M$$

2 Lagrange:

Frame work: on each $p \in M$ we find an orthonormal

$$\text{basis: } \{e_1, \dots, e_n\}$$

or on local chart:

$$V_M = \sqrt{\det(g_{ij})} dx_1 \wedge dx_2 \wedge \dots \wedge dx_n$$

$$\textcircled{1} * (f w + g y) = f * w + g * y$$

$$\textcircled{2} * w = (-1)^{k(n-k)} w$$

$$\textcircled{3} w \wedge *y = y \wedge w = \langle w, y \rangle V_M$$

$$\textcircled{4} * \langle w, y \rangle = \langle w, *y \rangle$$

$$\textcircled{5} \langle *w, *y \rangle = \langle w, y \rangle$$

③ $w_p = \sum_I e_I$ we just proof $w_p = e_1$ for linearity

$$*e_1 = \text{sgn}(I, J) e_J \quad *e_2 = \text{sgn}(I, J) \text{ sgn}(J, K) e_K$$

$$*e_3 = \text{sgn}(J, I) e_I \quad \text{sgn}(J, I) = (-1)^{k(n-k)}$$

$$\text{sgn}(3, 2) = (-1)^{3(2-3)} = -1$$

$$\text{sgn}(2, 1) = (-1)^{2(1-2)} = 1$$

$$\text{sgn}(4, 1) = (-1)^{4(1-4)} = 1$$

$$w_p = \sum_I e_I \quad I = \{e_1, \dots, e_n\}$$

$$j_p = \sum_I e_I$$

$$w_p \wedge y_p = e_1 \wedge e_2 \neq 0 \quad \text{if } \{i, j\} = \{1, 2\}$$

$$\text{so } w_p \wedge *y_p = \sum_I e_I \wedge e_J \text{ sgn}(I, J)$$

$$\frac{e_1 \wedge e_2 \wedge \dots \wedge e_n}{e_1 \wedge e_2 \wedge \dots \wedge e_n} = V_M$$

$$\langle \# w, *y \rangle \neq$$

$$w = \sum_i g_i e_i$$

$$y = \sum_j g_j e_j$$

$$*w = \sum_i g_i e_j \text{ sgn}(i,j)$$

$$*y = \sum_i g_i e_j$$

$$\langle \# w, *y \rangle = \sum_i g_i \quad \checkmark$$

Inner product on $\Omega^k(M)$

$$w, y \in \Omega^k(M) \quad M \dots$$

$$(w, y) := \int_M \langle w, y \rangle \nu_M$$

$$= \int_M w \wedge y$$

$$\delta: \Omega^k \rightarrow \Omega^{k-1} \quad w \in \Omega^{k-1}(M) \quad y \in \Omega^k(M)$$

$$(dw, y) = (w, dy)$$

$$= \int_M dw \wedge y \quad w \in \Omega^k(M)$$

$$= \int_M d(w \wedge y) = dw \wedge y + (-1)^k w \wedge dy$$

$$= \int_M d(w \wedge y) - \int_M (-1)^{k-1} w \wedge d(y)$$

$$= (-1)^k \int_M w \wedge d(y)$$

$$= (-1)^k \int_M w \wedge * * d(y) \quad (-1)^{(k-k+1)(k-1)}$$

$$= \int_M w \wedge *(*d(y)) (-1)^{(k-k+1)(k-1)+k} \quad n(k+1)+k/$$

$$= n(k-1) - \frac{(k-1)^2 + k}{2}$$

$$n(k-1) - \frac{k+1+k}{2}$$

$$= n(k-1)+1 = n(k+1)+$$

$$\delta = (-1)^{n(k+1)+} * d *$$

$$\Delta = d\delta + \delta d : \Omega^k \rightarrow \Omega^k$$

$$\Delta: \Omega^1(R^n) \rightarrow \Omega^1(R^n)$$

$$w = \sum dx^i$$

$$dw = \frac{\partial^2}{\partial x^i} dx^i \wedge dx^j \quad i < j$$

$$*dw = -\frac{1}{2} \frac{\partial^2}{\partial x^i \partial x^j} dx^i \wedge dx^j \quad i < j$$

$$*dw = -\frac{1}{2} \frac{\partial^2}{\partial x^i \partial x^j} dx^i \wedge dx^j \wedge \dots \wedge dx^n \quad (-1)^{i+j}$$

$$d + dw = f \left(\frac{\partial^2}{\partial x^i \partial x^j} dx^i \wedge \dots \wedge dx^n \right)$$

$$= (-1)^{i+1} \frac{\partial^2}{\partial x^i \partial x^j} dx^i \wedge \dots \wedge dx^n \wedge \dots \wedge dx^n$$

$$+ (-1)^{i+1} \frac{\partial^2}{\partial x^i \partial x^j} dx^i \wedge \dots \wedge dx^n \wedge \dots \wedge dx^n$$

$$= \frac{\partial^2}{\partial x^i \partial x^j} dx^i \wedge \dots \wedge dx^n$$

$$*d *dw = (-1)^{k+1} \frac{\partial^2}{\partial x^i \partial x^j} dx^i + (-1)^{k+1} \frac{\partial^2}{\partial x^i \partial x^j} dx^i$$

$$d *d *w = \frac{\partial^2}{\partial x^i \partial x^j} dx^i + \frac{\partial^2}{\partial x^i \partial x^j} dx^i$$

$$d\delta + \delta d = w$$

$$\delta: \Omega^1 \rightarrow \Omega^0 \quad (-1)^{2n+1} d * dt + (-1)^{3n+1} dt * d.$$

$$- \frac{\partial^2}{\partial x^i \partial x^j} dx^i - \frac{\partial^2}{\partial x^i \partial x^j} dx^i$$

$$\Delta = d\delta + \delta d$$

$$\textcircled{1} \quad \delta^* = *\Delta$$

$$\textcircled{2} \quad (\delta w, y) = (w, \delta y)$$

$$\textcircled{3} \quad \delta w = 0 \text{ iff } dw = 0 \quad \delta w = 0$$

$$\begin{aligned} (\delta w, y) &= (dw, \delta y + d\theta, y) \\ &= (\delta w, \delta y) + (dw, d\theta) \\ &= (w, \delta y) \quad \checkmark \end{aligned}$$

$$0 = (dw, w) = (\delta w + \delta w, dw + dw) = 0$$

$$\underline{\delta w = 0 \text{ and } dw = 0.}$$

$$\Delta^k = H^k \oplus dA^{k-1} \oplus \delta A^{k-1}$$

$$\text{if so } w = Hw + dy + \delta \theta \text{ uniquely}$$

$$\text{then } dw = 0 \Rightarrow d\delta \theta = 0$$

$$0 = (\theta, d\delta \theta) = (\delta \theta, \delta \theta) \Rightarrow \delta \theta = 0$$

$$\Rightarrow w = Hw + dy \quad \checkmark$$

$$\text{Hodge } H^k(\Lambda) = \{w \mid \Delta w = 0\}$$

$$H^k(\Lambda) \cong H_{\text{Dol}}^k(\Lambda)$$

$$f: w \leftrightarrow [w]$$

\textcircled{1} Injection

$$\text{if } f w = [0] \text{ then } w = 0$$

$$\text{if } w = dy \text{ then } w = 0$$

$$(w, w) = (dy, w) = (y, \delta w) = \cancel{0} \cancel{= 0},$$

$$w = 0$$

$$\textcircled{2} \quad \forall w, dw = 0 \quad \exists! w' \quad w - w' = dy$$

$$\text{then } \Delta w' = 0$$

Choosing a basis of $H^k(\Lambda)$ β_1, \dots, β_r

$$H: \Omega^k(\Lambda) \rightarrow H^k(\Lambda)$$

$$Hw = \sum_{i=1}^r (w, \beta_i) \beta_i$$



Hodge decomposition:

$$Hw \in \Omega^k(\Lambda)$$

$$w = Hw + dy$$

$$\text{since } dA^{k-1} \perp \delta A^{k-1} \perp H^k$$

Proof: if: $\Delta w = 0$

$$(w, dy) = (\delta w, y) = 0$$

$$(w, \delta \theta) = (\delta w, \theta) = 0$$

$$(\delta y, d\theta) = (y, d\theta) = 0.$$

Riemannian Geometry:

(M, g)

① Affine Connection:

$$\nabla: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$$

$$\nabla_X Y \xrightarrow{\text{def}} \nabla_X Y$$

$$1) \quad \nabla_{f_1 X + f_2 Y} Z = f_1 \nabla_X Z + f_2 \nabla_Y Z \quad (\text{linearity})$$

$$2) \quad \nabla_X (f Y) = f \nabla_X Y + X(f) Y$$

$$3) \quad \nabla_X (\lambda_1 Y_1 + \lambda_2 Y_2) = \lambda_1 \nabla_X Y_1 + \lambda_2 \nabla_X Y_2$$

$$(\partial_k, \nabla_{\partial_j} \partial_i) = \frac{1}{2} (g_{ik,j} + g_{jk,i} - g_{ij,k})$$

$$\nabla_{\partial_j} \partial_i = \tilde{\Gamma}_{ij}^k \partial_k$$

$$g_{kl} \tilde{\Gamma}_{ij}^l = \frac{1}{2} (g_{ik,j} + g_{jk,i} - g_{ij,k})$$

$$\tilde{\Gamma}_{ij}^k = \frac{1}{2} g^{kl} (g_{ik,j} + g_{jk,i} - g_{ij,k})$$

$$(g^{kl})^{-1} = g_{kl}$$

Thm: (Levi-Civita) (M, g) Riemannian M

exists ∇

$$1) \quad X(Y, Z) = (\nabla_X Y, Z) + (Y, \nabla_X Z)$$

$$2) \quad \nabla_X Y - \nabla_Y X = [X, Y]$$

LC-connection

Proof:

$$X(Y, Z) = (\nabla_X Y, Z) + (Y, \nabla_X Z)$$

$$Y(Z, X) = (\nabla_Y Z, X) + (Z, \nabla_Y X)$$

$$Z(X, Y) = (\nabla_Z X, Y) + (X, \nabla_Z Y)$$

① + ② - ③

$$\begin{aligned} & ([Y, Z], X) + ([X, Z], Y) + 2(\nabla_X Y, Z) \\ & \quad - (\nabla_X Y, Z) \\ & \quad + (Z, \nabla_X X) \end{aligned}$$

$$\begin{aligned} (\nabla_X Y, Z) &= \frac{1}{2} (X(Y, Z) + Y(Z, X) - Z(X, Y)) \\ &\quad - (X, [Y, Z]) - (Y, [X, Z]) \\ &\quad - (Z, [Y, X]) \end{aligned}$$

base 2 basis $\Rightarrow \nabla_X$

$\partial_i, \partial_j, \partial_k$ local chart