## Selective inference after cross-validation

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### RSS test error estimation

- For K-fold cv, data partitioned (randomly) into  $D_1, \ldots, D_K$ . For each  $k=1,\ldots,K$ , hold out  $D_k$  as a test set while training a model on the other K-1 folds. Form estimate  $RSS_k$  of out-of-sample prediction error. Average these estimates over test folds.
- Use to choose model complexity: evaluate  $RSS_{k,s}$  for various sparsity choices s. Pick s minimizing the cv-RSS estimate.

## **Examples**

### For each training set...

- Train LASSO models on a grid of  $\lambda$  values. Or fit sequentially with GLMNET. Choose  $\lambda^*$  minimizing cv-RSS. Finally, fit a LASSO model at  $\lambda^*$  on the whole data.
- Run forward stepwise with maxsteps S. For  $s=1,\ldots,S$  evaluate the test error  $RSS_{k,s}$ . Average to get  $RSS_s$ . Pick  $s^*$  minimizing this. Run forward stepwise on the whole data for  $s^*$  steps.

Can we do selective inference for the final models chosen this way?

# Quadratic constraints example: forward stepwise

### Key observation

The inequalities  $RSS(i_s) \leq RSS(j)$  characterizing the variable added at step s can all be written in the form

$$y^T(Q_{i_s}-Q_{j,s})y\geq 0 \quad \forall j\neq i_s$$

Define  $E_{s,j} := \{ y : y^T (Q_{i_s} - Q_{j,s}) y \ge 0 \}.$ 

#### Characterization of the selection event

The event E that forward stepwise chooses model m can be written

$$E = \bigcap_{s=1}^{S} \bigcap_{j \neq i_s, \dots, i_1} E_{s,j}$$

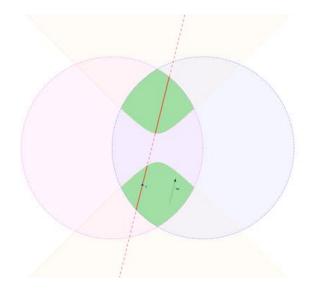
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### Reduction to one dimension

- The geometry of E (intersection of quadratics) is complicated. For example, verifying if an ellipsoid contains an intersection of ellipsoids is NP-complete (Boyd et. al. LMI book, Section 3.7.2). Our quadratics may not even be ≥ 0.
- To test for variable  $i_s$ , reduce to a one-dimensional problem. Define  $T\chi_{i_s} = \|Py\|_2$  for some projection P. Let U = Py/S and Z = y Py. Support of  $T\chi_{i_s}$

$$M_{i_s} = \{t \geq 0 : Ut + Z \in E\}$$

## Cartoon of selection event and one-dimensional slice



### Cross-validation

- Let f, g index CV test folds.
- On fold f, model  $m_f$  at step s, and -f denoting the training set for test fold f (complement of f).
- Define  $P_{f,s}:=X^f_{m_f,s}(X^{-f}_{m_f,s})^\dagger$  (not a projection)
- $s = \arg\min_{s} \sum_{f=1}^{K} \|y^f P_{f,s}y^{-f}\|_2^2$
- Sums of squares... maybe it's a quadratic form?

J. R. Loftus

# The key result

## Blockwise quadratic form of cv-RSS

Define  $Q^s_{ff} := \sum_{g \neq f} (P_{g,s})_f^T (P_{g,s})_f$  and

$$Q_{fg}^s := -(P_{f,s})_g - (P_{g,s})_f^T + \sum_{\substack{h=1\\h\notin \{f,g\}}}^K (P_{h,s})_f^T (P_{h,s})_g^T$$

Then with  $y_K$  denoting the observations ordered by CV-folds,

$$\text{cv-RSS}(s) = y_K^T Q^s y_K$$

#### Proof.

Algebra



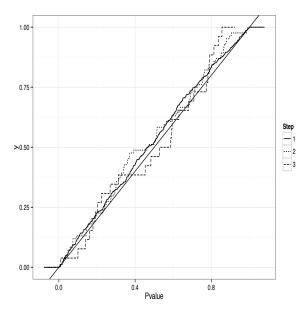
## Does it work?

Well yes, it's a theorem.

End of talk. Thank you for listening!

J. R. Loftus

# Global null, K = 5, n = 50, p = 100, steps = 10



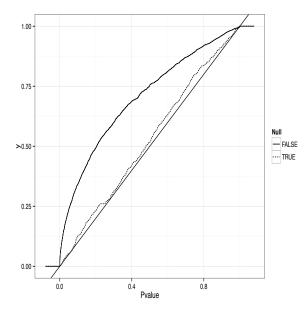
About 16% chose sparsity > 1

Less than 0.5% chose sparsity > 3

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J. R. Loftus CV inference

# 5-sparse, K = 5, SNR = 7, n = 50, p = 100, steps = 10



Screened 90%

Another 4% 4/5

# Limitations / ongoing work

- Forward stepwise used linearity  $\hat{y}^f = Py^{-f}$ . Ridge has same form. Lasso has additional constant terms, but works the same otherwise.
- Computationally expensive. Might be able to optimize a little more.
- Tuning parameters: K and maxsteps (or  $\lambda$  grid).
- Unknown  $\sigma$ . Estimate by CV / use selective F test.