

# ACO & GA @TSP

EDAA 23/24



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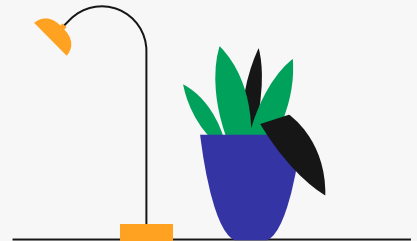
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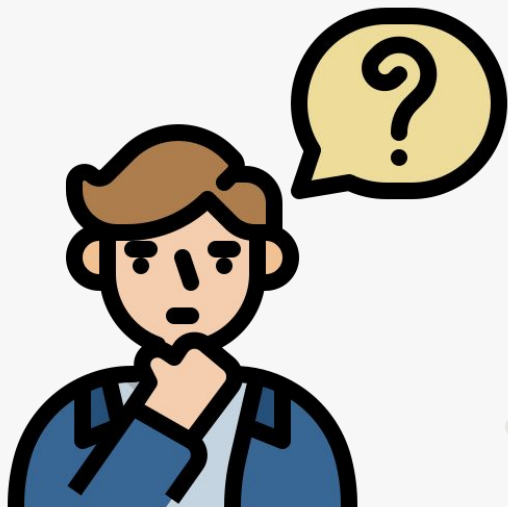
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01

# The Problem





# Traveling Salesman Problem (TSP)



## Shortest Path

Given a graph, what's the shortest possible path visiting each city exactly once and returning to the origin.



## NP-Hard

If there's a solution to the problem, it can't be found in polynomial time.



# Naive Approach...



- For a simple instance with 10 cities, we would have to calculate 3,628,800 possible permutations.
- To address this challenge, various heuristic and approximation algorithms have been developed to find near-optimal solutions for the TSP without exhaustively searching through all possible permutations.
- These algorithms aim to efficiently explore the solution space and find good solutions without the need to consider every possible permutation.

02



# Ant Colony Optimization Approach

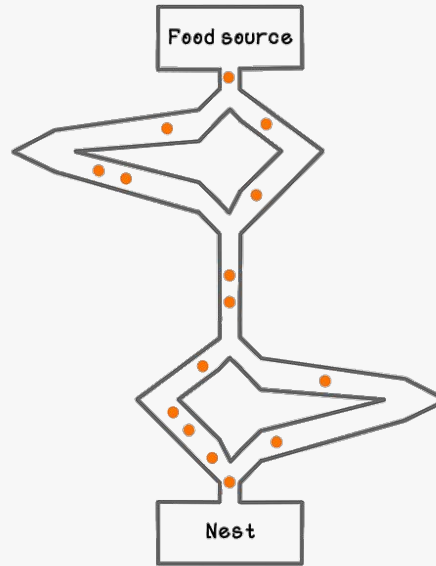


# Finding the best route... Pheromones

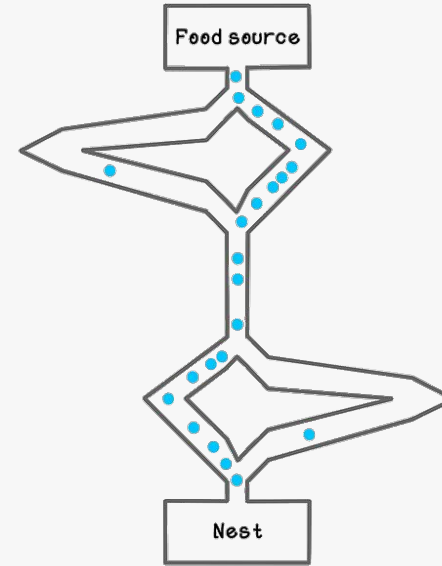


Taking in note:

- Ants are blind;
- Each ant moves at random;
- Pheromone is deposited on path;
- More pheromone on path increases probability of being followed.



After 4 minutes



After 8 minutes

# Pseudo-Code



```
1: Begin ACO
2: Generate Random Population
3: While NOT stop DO:
    4: BEGIN
    5: Position Each Ant In Starting node
    6: Repeat
    7: For each Ant DO:
    8: Choose Next Node By Applying State Transition Rule
    9: Apply Step by Step Pheromone Update
    10: END For
    11: UNTIL every Ant has built a solution
    12: Update Best Solution
    13: Apply Offline pheromone update
    14: END
    15: Output the best solution
16: END
```



# Path construction

## How to select next node?



$$p_{ij} = \frac{[\tau_{ij}]^{\alpha} [\eta_{ij}]^{\beta}}{\sum_{h \in s} [\tau_{ij}]^{\alpha} [\eta_{ij}]^{\beta}}$$

i - origin

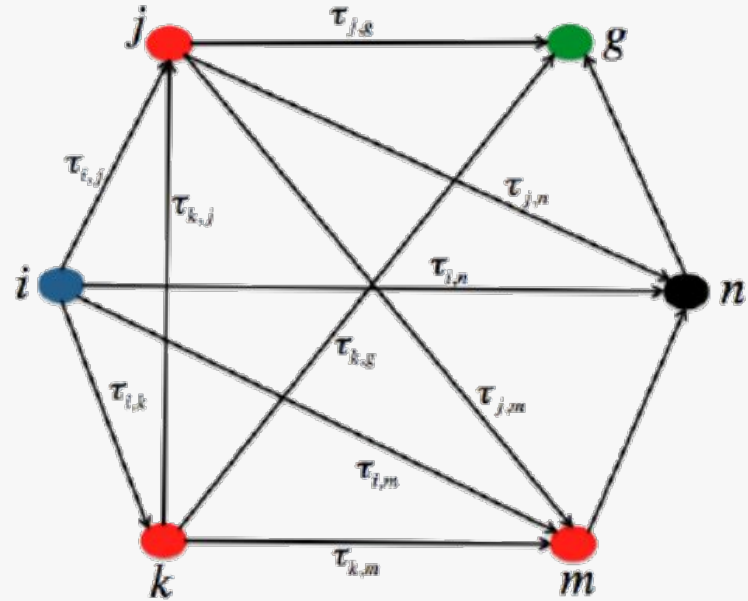
j - destination

$\tau$  - pheromone

$\eta$  - inverse of distance

$\alpha$  - weight (parameter)

$\beta$  - weight (parameter)



# Pheromones Update



i - origin  
j - destination  
 $\tau$  - pheromone  
 $\rho$  - evaporation constant  
t - time/length of path  
 $L^+$  - length of best path  
generated

Local Update

$$\tau_{ij}(t) = (1 - \rho) \cdot \tau_{ij}(t-1) + \rho \cdot \tau_0$$

Global Update

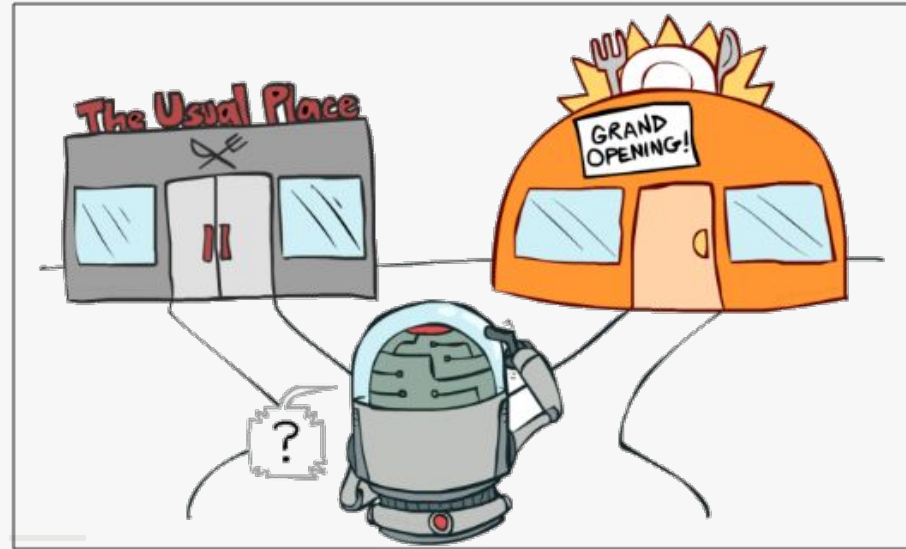
$$\tau_{ij}(t) = (1 - \rho) \cdot \tau_{ij}(t-1) + \frac{\rho}{L^+}$$

# Exploration vs Exploitation

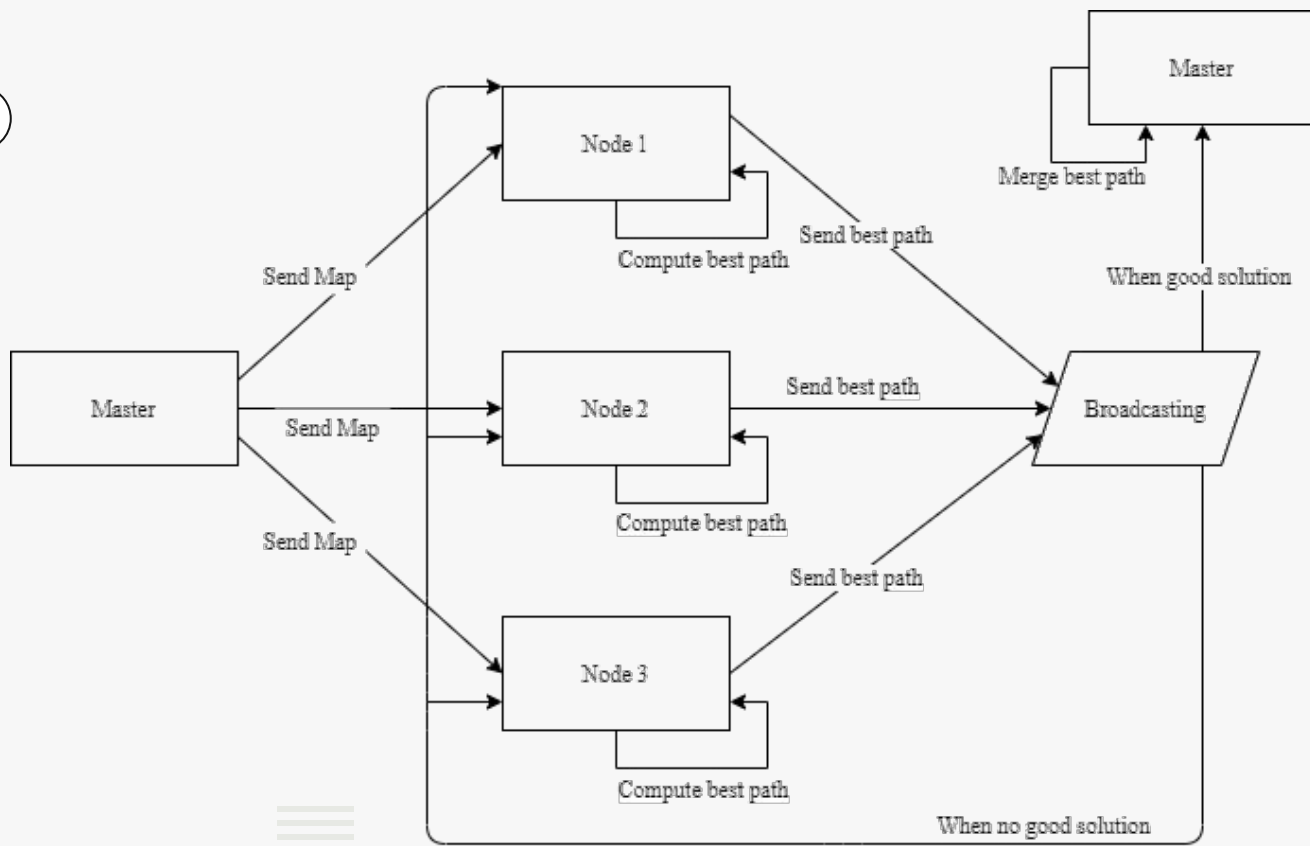


$$[\tau_{ij}]^{\alpha} [\eta_{ij}]^{\beta}$$

- $\alpha$  > exploration  
ant move is random
- $\beta$  > exploitation  
benefit shorter edges



# ACO Parallel





03

# Genetic Algo. Approach

# Terminology



## Gene

It's basically a unit/element of a chromosome



## Chromosome

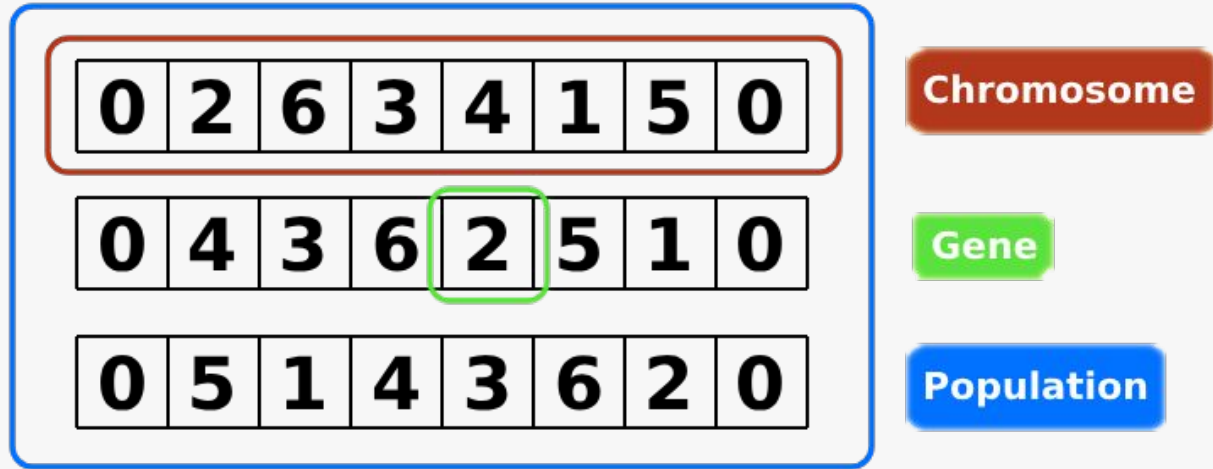
It's a solution to a given problem. It's an ensemble of genes.



## Population

It's a subset of feasible solutions to a given problem. Basically, it's a set of chromosomes.

# What does it mean...



Representation of the  
terminology regarding the TSP  
Problem

# Genetic Operators



## Mutation

Used to maintain diversity & avoid local minima. Does some change within a chromosome.



## Crossover

Combines genetic information of two parents to generate new offsprings.



## Tournament

Method of selecting an individual from the population. N elements are chosen at random -> the fittest wins.

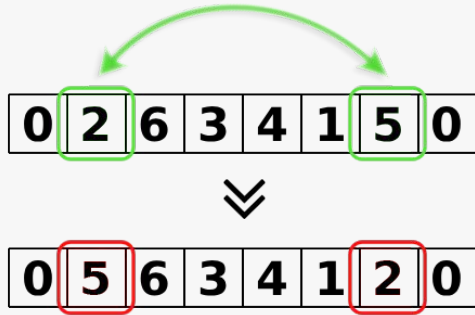


## Roulette

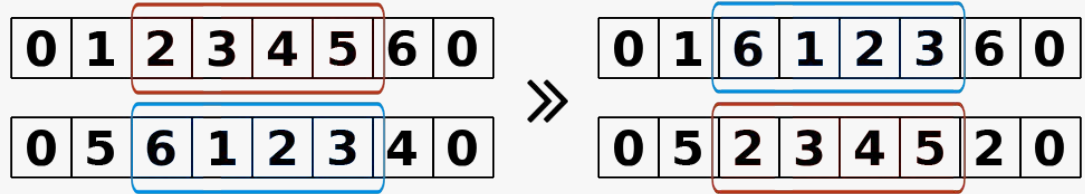
Method of selecting an individual from the population. Each chromosome has a probability linearly correlated to its fitness level.



# What does it mean...



Example of  
Mutation Function



Example of  
Crossover Function

# Pseudo-Code



```
1: Begin GA
2: Generate Random Population
3: While NOT stop DO:
4:   BEGIN
5:     Tournament Selection
6:     Roulette Selection
7:     Generate CrossOvers
8:     Mutate Children
9:     Extend Population by Reproducing
10:    Remove Least Fitted
11:   END
12: Output the best solution
13: END
```

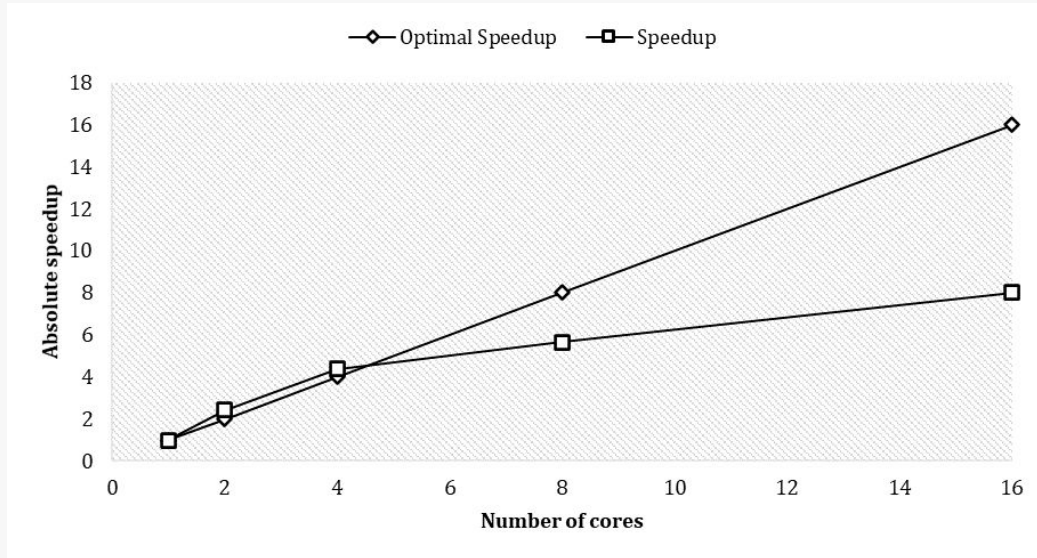
Pseudo-Code for the GA

04

# Results

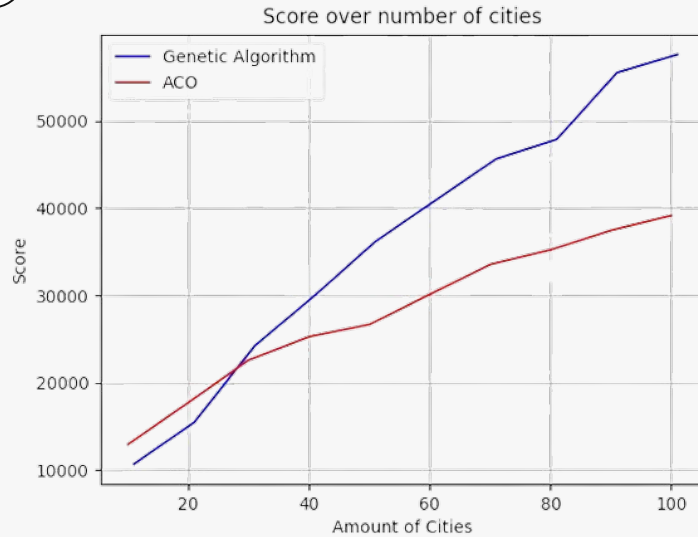


# ACO Serial vs Parallel



Although there is an absolute speed increase, the significant cost of node-to-node transmission makes this not so beneficial. The communication time between nodes rises with node count, which results in a drop in speedup relative to ideal speedup.

# ACO vs GA





05

# Conclusions

# ACO Approach Trade-Off



- Inherent parallelism & scalability;
- Ability to find near-optimal solutions;
- Adaptability to dynamic environments (to different problems & constraints);
- Balance exploration and exploitation, allowing for effective exploration of the solution space.



- Theoretical analysis is difficult;
- Sensitive to parameter settings;
- Research is experimental rather than theoretical;
- Time to convergence uncertain (but convergence is guaranteed!)

# Genetic Algorithm Trade-Off



- GAs can handle a wide range of optimization problems.
- Considerably easier to code when compared to other approaches.



- Computationally expensive, especially for complex problems or large solution spaces;
- Very sensitive to parameter tuning & choice of mutation and crossover functions;
- May converge to a suboptimal solution very early on & get stuck on a local minima.



# Conclusions & Remarks



- According to our results, the ACO approach performed better overall than the GA one.
- The GA achieved better results when the number of cities was lower, but was outperformed in higher inputs.
- Does it mean that the ACO approach is better than GA ?
- Perhaps for this specific problem it could be, but it all depends on various factors such as problem complexity, input size and specific requirements or constraints and even the coding approach itself.

# References

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