

$$1. a) \frac{\partial E}{\partial H} = \frac{\partial}{\partial H} \sum_{i=1}^m \|x'_i - Hx_i - t\|^2$$

$$= \sum_{i=1}^m \frac{\partial}{\partial H} \|x'_i - Hx_i - t\|^2$$

$$\|x'_i - Hx_i - t\|^2 = (X'_i - HX_i - t)^T (X'_i - HX_i - t)$$

$$= X'^T X' - 2X'^T HX + X^T H^T HX - 2X'^T t + 2t^T HX + t^T t$$

$$\frac{\partial E}{\partial H} = \sum_{i=1}^m (-2X'_i X_i^T + 2HX_i X_i^T + 2t X_i^T)$$

$$\frac{\partial E}{\partial t} = \sum_{i=1}^m (-2X'_i + 2HX_i + 2t)$$

$$b) \quad H \quad 2 \times 2 \quad t \quad 2 \times 1$$

$$\begin{pmatrix} m_1 & m_2 \\ m_3 & m_4 \end{pmatrix} \quad \begin{pmatrix} t_1 \\ t_2 \end{pmatrix}$$

$$X' = HX + t \quad (s) \quad \begin{pmatrix} x'_1 \\ x'_2 \end{pmatrix} = \begin{pmatrix} m_1 & m_2 \\ m_3 & m_4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} t_1 \\ t_2 \end{pmatrix}$$

$$x'_1 = m_1 x_1 + m_2 x_2 + t_1$$

$$x'_2 = m_3 x_1 + m_4 x_2 + t_2$$

For each point we have these 2 transformations equations

For m points, will have $2m$ equations

We can rewrite the equation in matrix form

$$A_i = \begin{pmatrix} x_{i1} & x_{i2} & 0 & 0 & 1 & 0 \\ 0 & 0 & x_{i1} & x_{i2} & 0 & 1 \end{pmatrix}$$

and $h = \begin{pmatrix} m_1 \\ m_2 \\ m_3 \\ m_4 \\ t_1 \\ t_2 \end{pmatrix}$ 6×1

So for m points we will have matrix $A = \begin{pmatrix} A_1 \\ A_2 \\ \dots \\ A_m \end{pmatrix}$ $2m \times 6$

$$(2m \times 6) (6 \times 1) = (2m \times 1)$$
$$A h = b$$

Normal equations: least squares solution to

$$A h = b$$

\downarrow

$$A^T A h = A^T b$$

$$(6 \times 2m) (2m \times 6) (6 \times 1) = (6 \times 2m) (2m \times 1)$$

$$\underbrace{\hspace{1cm}}_{(6 \times 6)}$$

S

$$\underbrace{\hspace{1cm}}_{(6 \times 1)}$$

h

$$S \begin{pmatrix} \sum_{i=1}^m x_{i1}^2 & \sum x_{i1} x_{i2} & 0 & 0 & \sum x_{i1} & 0 \\ \sum x_{i1} x_{i2} & \sum x_{i2}^2 & 0 & 0 & \sum x_{i2} & 0 \\ 0 & 0 & \sum x_{i1}^2 & \sum x_{i1} x_{i2} & 0 & \sum x_{i1} \\ 0 & 0 & \sum x_{i1} x_{i2} & \sum x_{i2}^2 & 0 & \sum x_{i2} \\ \sum x_{i1} & \sum x_{i2} & 0 & 0 & m & 0 \\ 0 & 0 & \sum x_{i1} & \sum x_{i2} & 0 & m \end{pmatrix}$$

$$u \begin{pmatrix} \sum x_{i1} x_{i1}' \\ \sum x_{i2} x_{i1}' \\ \sum x_{i1} x_{i2}' \\ \sum x_{i2} x_{i2}' \\ \sum x_{i1}' \\ \sum x_{i2}' \end{pmatrix}$$

$$c) \quad x_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rightarrow x'_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$x_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightarrow x'_2 = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$

$$x_3 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \rightarrow x'_3 = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

By substitution

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 3 & 0 & 0 & 5 \\ 0 & 0 & 1 & 1 & 0 & 3 & 0 & 8 \end{pmatrix} \begin{array}{l} S \\ h \\ u \\ m_1 \\ m_2 \\ m_3 \\ m_4 \\ t_1 \\ t_2 \end{array}$$

$$S \quad h \quad u$$

$$\begin{cases} m_1 + t_1 = 3 \\ m_2 + t_1 = 1 \\ m_3 + t_2 = 2 \\ m_4 + t_2 = 4 \\ m_1 + m_2 + 3t_1 = 5 \\ m_3 + m_4 + 3t_2 = 8 \end{cases}$$

$$(i) \quad \begin{cases} m_1 = 2 \\ t_1 = 1 \\ m_3 = 0 \\ t_2 = 2 \\ m_2 = 0 \\ m_4 = 2 \end{cases} \quad \begin{pmatrix} 2 \\ 0 \\ 0 \\ 2 \\ 1 \\ 2 \end{pmatrix} \quad h$$

COMPUTER VISION HW 06

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Exercise 2.

$$x' = SRx + t \quad (\Rightarrow) \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = S \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \end{pmatrix}$$

$$a) \quad v' = x'_2 - x'_1 = \begin{pmatrix} x'_{2x} - x'_{1x} \\ x'_{2y} - x'_{1y} \end{pmatrix}$$

$$v = x_2 - x_1 = \begin{pmatrix} x_{2x} - x_{1x} \\ x_{2y} - x_{1y} \end{pmatrix}$$

The angle θ can be calculated using dot product and the cross product of the unit vectors:

$$\vec{v} \cdot \vec{v}' = \|\vec{v}\| \|\vec{v}'\| \cos \theta \quad (\Rightarrow) \quad \left. \begin{array}{l} \text{Unit vectors} \\ \vec{v} = \frac{\vec{v}}{\|\vec{v}\|} \end{array} \right\}$$

$$(\Rightarrow) \cos \theta = \frac{\vec{v} \cdot \vec{v}'}{\|\vec{v}\| \|\vec{v}'\|}$$

$$(\Rightarrow) \theta = \cos^{-1} \left(\frac{\vec{v} \cdot \vec{v}'}{\|\vec{v}\| \|\vec{v}'\|} \right) \quad \text{where} \quad \left\{ \begin{array}{l} \vec{v} = \frac{\vec{v}}{\|\vec{v}\|} \\ \vec{v}' = \frac{\vec{v}'}{\|\vec{v}'\|} \end{array} \right.$$

$$b) \quad \|\vec{v}\| = \sqrt{(x_{2x} - x_{1x})^2 + (x_{2y} - x_{1y})^2}$$

$$\|\vec{v}'\| = \sqrt{(x'_{2x} - x'_{1x})^2 + (x'_{2y} - x'_{1y})^2}$$

the scale factor Δ can be calculated through the ratio of the norms of \vec{v} and \vec{v}' :

$$\Delta = \frac{\|\vec{v}'\|}{\|\vec{v}\|}$$

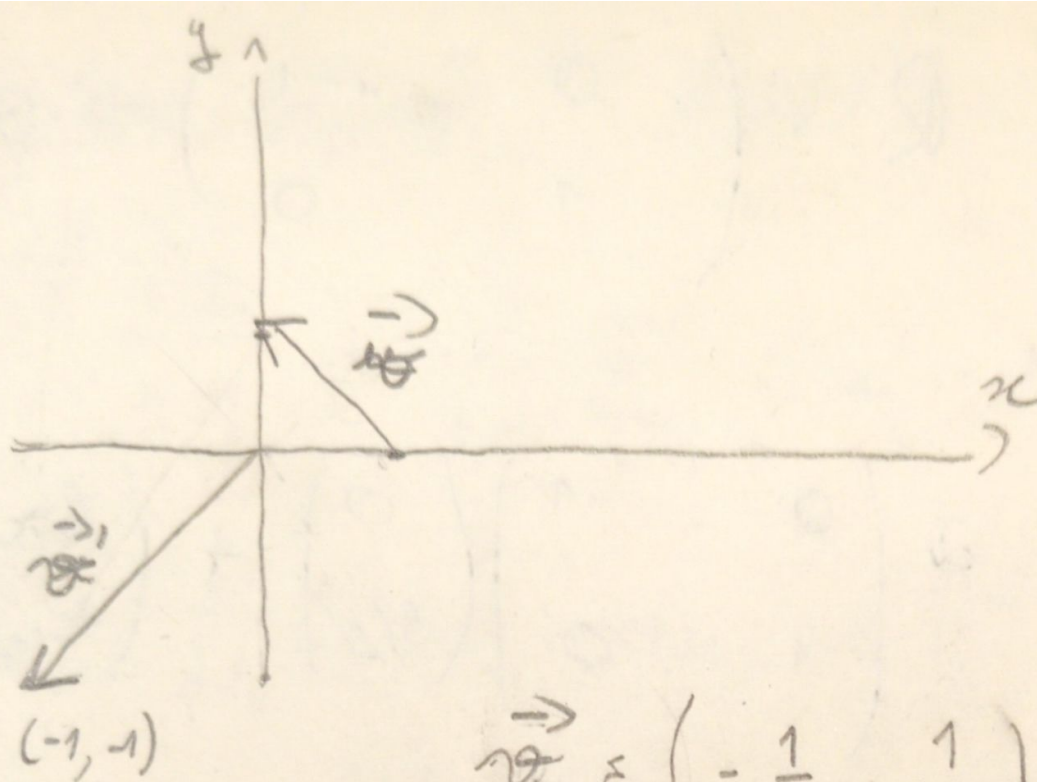
$$c) \quad t = x'_1 - \Delta R x_1 \quad (*)$$

$$(*) \quad t = x'_1 - \frac{\|x_1\|}{\|x'_1\|} R x_1$$

$$(*) \quad t = x'_1 - \frac{\|x_1\|}{\|x'_1\|} \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} x_1$$

$$\text{where } \theta = \cos^{-1} \left(\frac{\frac{x}{\|x\|} \cdot \frac{x'}{\|x'\|}}{\|x\| \|x'\|} \right)$$

d)



$$\vec{u} = \left(-\frac{1}{2}, \frac{1}{2} \right)$$

$$\vec{v} = \left(-1, -1 \right)$$

$$\Delta = \frac{||\vec{u}'||}{||\vec{v}'||} = \frac{\sqrt{2}}{\sqrt{1}} = \frac{\sqrt{2}}{1} = 2$$

$$\frac{\sqrt{2}}{2} \cdot \frac{\sqrt{2}}{2}$$

$$\Theta = \cos^{-1} \left(\frac{\left(-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2} \right) \cdot \left(-\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2} \right)}{\sqrt{2} \cdot \frac{1}{\sqrt{2}}} \right)$$

$$\cos^{-1} \left(\frac{1}{2} + \left(-\frac{1}{2} \right) \right) = \cos^{-1}(0)$$

$$= 90^\circ = \Theta$$

$$\cos(90) = 0$$

$$\sin(90) = 1$$

$$\Delta = 2 \quad R = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} + \theta = 90^\circ$$

$\frac{\pi}{2}$

$$\begin{pmatrix} -1 & -1 \end{pmatrix} = 2 \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1/2 \end{pmatrix} + \begin{pmatrix} t_x \\ t_y \end{pmatrix}$$

$$(c) \begin{pmatrix} t_x \\ t_y \end{pmatrix} = \begin{pmatrix} -1 & -1 \end{pmatrix} - \begin{pmatrix} 0 & -2 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1/2 \end{pmatrix}$$

$$(d) \begin{pmatrix} t_x \\ t_y \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$