

COMPULSORY EXERCISE 3

JOHAN ÅMDAL ELIASSEN

1. EXERCISE 8.10: FITTING A CIRCLE TO POINTS

Given points $\{t_i, y_i\}_{i=1}^m \subset \mathbb{R}^2$, $m \geq 3$, we wish to fit a circle to these points. That is, we wish to satisfy

$$(*) \quad (t_i - c_1)^2 + (y_i - c_2)^2 = r^2, \quad 1 \leq i \leq m,$$

hence c_1 , c_2 and r are the unknowns to be solved for.

a. We have

$$(1.1) \quad (*) = t_i^2 + y_i^2 + c_1^2 + c_2^2 - 2c_1t_i - 2c_2y_i,$$

or equivalently,

$$(1.2) \quad 2c_1t_i^2 + 2c_2y_i^2 - c_1^2 - c_2^2 + r^2 = t_i^2 + y_i^2.$$

Set $x_1 = 2c_1$, $x_2 = 2c_2$, and $x_3 = -c_1^2 - c_2^2 + r^2$, and this becomes

$$(1.3) \quad t_ix_1 + y_ix_2 + x_3 = t_i^2 + y_i^2,$$

or in abbreviated matrix form,

$$(1.4) \quad \underbrace{\begin{pmatrix} t_i & y_i & 1 \end{pmatrix}}_{=: \mathbf{A}} \begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix}^T = \underbrace{(t_i^2 + y_i^2)}_{=: \mathbf{b}}, \quad 1 \leq i \leq m.$$

If we can solve the linear system above, it is trivial to derive the original unknowns. We have $c_1 = x_1/2$, $c_2 = x_2/2$ and $r^2 = c_1^2 + c_2^2 + x_3$.

b. LSQ: minimize E given by

$$\begin{aligned} E(\mathbf{x}) &= \|\mathbf{A}\mathbf{x} - \mathbf{b}\|_2^2 = \sum_{i=1}^m \left((t_ix_1 + y_ix_2 + x_3) - (t_i^2 + y_i^2) \right)^2 \\ &= \sum_{i=1}^m (t_i(x_1 - t_i) + y_i(x_2 - y_i) + x_3)^2. \end{aligned}$$

While it's by far the most unwieldy way to solve this problem, one way to proceed is to set the gradient of E to zero.

$$(1.5) \quad \frac{\partial E}{\partial x_j} = \sum_{i=1}^m 2q_{i,j}(t_i(x_1 - t_i) + y_i(x_2 - y_i) + x_3) = 0,$$

with $q_{i,j} = t_i, y_i$ or 1 for $j = 1, 2, 3$ respectively. Rewritten, we obtain the three equations

$$(1.6) \quad x_1 \sum_{i=1}^m t_i^2 + x_2 \sum_{i=1}^m t_i y_i + x_3 \sum_{i=1}^m t_i = \sum_{i=1}^m (t_i^3 + y_i^2 t_i),$$

$$(1.7) \quad x_1 \sum_{i=1}^m t_i y_i + x_2 \sum_{i=1}^m y_i^2 + x_3 \sum_{i=1}^m y_i = \sum_{i=1}^m (t_i * 2y_i + y_i^3),$$

$$(1.8) \quad x_1 \sum_{i=1}^m t_i + x_2 \sum_{i=1}^m y_i + m x_3 = \sum_{i=1}^m (t_i^2 + y_i^2).$$

In matrix form, $\mathbf{B}\mathbf{x} = \mathbf{c}$.

c. Two more or less obvious conditions are sufficient to ensure that \mathbf{A} has full column rank: first, there must be at least three distinct points (t_i, y_i) , and secondly, these three points must not all lie on the same line $y(t) = \alpha t$, for some $\alpha \in \mathbb{R}$. If these conditions are met, \mathbf{A} is guaranteed to have three linearly independent rows, i.e. a row rank of 3, which implies full column rank. These conditions are necessary even if the system is otherwise overdetermined.

d. Let $\{(t_i, y_i)\}_{i=1}^m = \{(1, 4), (3, 2), (1, 0)\}$, for $m = 3$. Three points on a circle uniquely determines it, so we may simply plug the points into \mathbf{A} to obtain $\mathbf{x} = (2, 4, -1)^T$, or $c_1 = 1, c_2 = 2, r = 2$.

To verify that the calculations in (b) were correct, inserting the numbers into \mathbf{B} and \mathbf{c} as obtained there, I get

$$(1.9) \quad \begin{pmatrix} 11 & 10 & 5 \\ 10 & 20 & 6 \\ 5 & 6 & 3 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 57 \\ 94 \\ 31 \end{pmatrix},$$

which yields the same results.

EXERCISE 8.24

Given $\mathbf{A} \in \mathbb{C}^{m \times n}$, from previous exercises (8.17, 8.18), we have that \mathbf{A}^\dagger is the unique matrix satisfying the following:

- (1) $(\mathbf{A}\mathbf{A}^\dagger)^* = \mathbf{A}\mathbf{A}^\dagger$,
- (2) $(\mathbf{A}^\dagger\mathbf{A})^* = \mathbf{A}^\dagger\mathbf{A}$,
- (3) $\mathbf{A}^\dagger\mathbf{A}\mathbf{A}^\dagger = \mathbf{A}^\dagger$,
- (4) $\mathbf{A}\mathbf{A}^\dagger\mathbf{A} = \mathbf{A}$.

Hence, for a matrix \mathbf{B} , to show that a matrix \mathbf{C} is the generalized inverse of \mathbf{B} is to show that \mathbf{B} and \mathbf{C} together satisfy the four identities above.

a. Show that $(\mathbf{A}^*)^\dagger = (\mathbf{A}^\dagger)^*$: For notational simplicity, let $\mathbf{B} = \mathbf{A}^*$, $\mathbf{C} = (\mathbf{A}^\dagger)^*$.

(1) and (2) trivially hold; for (3) we have

$$\mathbf{CBC} = ((\mathbf{CBC})^*)^* = (\mathbf{C}^*\mathbf{B}^*\mathbf{C}^*)^* = (\mathbf{A}^\dagger\mathbf{A}\mathbf{A}^\dagger)^* = (\mathbf{A}^\dagger)^* = \mathbf{C},$$

and likewise for (4),

$$(1.10) \quad \mathbf{BCB} = ((\mathbf{BCB})^*)^* = (\mathbf{A}\mathbf{A}^\dagger\mathbf{A})^* = \mathbf{A}^* = \mathbf{B}.$$

Hence $\mathbf{C} = (\mathbf{A}^\dagger)^*$ is indeed the generalized inverse of $\mathbf{B} = \mathbf{A}^*$. \square

b. Show that $(\mathbf{A}^\dagger)^\dagger = \mathbf{A}$.

(3) and (4) follow from (4) and (3) for \mathbf{A} . For (1) we have:

$$(\mathbf{A}^\dagger\mathbf{A})^* = \mathbf{A}^*(\mathbf{A}^\dagger)^*.$$

Now, from (a) this becomes

$$(\dots) = \mathbf{A}^*(\mathbf{A}^*)^\dagger = (\mathbf{A}^*(\mathbf{A}^*)^\dagger)^* = \mathbf{A}^\dagger\mathbf{A}.$$

again using (a).

The procedure for showing (2) is practically identical:

$$(\mathbf{A}\mathbf{A}^\dagger)^* = (\mathbf{A}^\dagger)^*\mathbf{A}^* = (\mathbf{A}^*)^\dagger\mathbf{A}^* = ((\mathbf{A}^*)^\dagger\mathbf{A}^*)^* = \mathbf{A}\mathbf{A}^\dagger, .$$

\square

c. Show: $(\alpha\mathbf{A})^\dagger = \frac{1}{\alpha}\mathbf{A}^\dagger$, $\alpha \in \mathbb{C} \setminus \{0\}$.

This is more or less trivial. For (1), we have $(\alpha\mathbf{A}\frac{1}{\alpha}\mathbf{A}^\dagger)^* = (\mathbf{A}\mathbf{A}^\dagger)^* = \mathbf{A}\mathbf{A}^\dagger = \alpha\mathbf{A}\frac{1}{\alpha}\mathbf{A}^\dagger$, and similarly for (2), and for (3) and (4),

$$(1.11) \quad \frac{1}{\alpha}\mathbf{A}^\dagger\alpha\mathbf{A}\frac{1}{\alpha}\mathbf{A}^\dagger = \frac{1}{\alpha}(\mathbf{A}^\dagger\mathbf{A}\mathbf{A}^\dagger) = \frac{1}{\alpha}\mathbf{A}^\dagger,$$

and

$$(1.12) \quad \alpha\mathbf{A}\frac{1}{\alpha}\mathbf{A}^\dagger\alpha\mathbf{A} = \alpha\mathbf{A}\mathbf{A}^\dagger\mathbf{A} = \frac{1}{\alpha}\mathbf{A}.$$

\square