

Solutions to exam in General Relativity, May 31, 2018

① Line element for Schwarzschild geometry in Eddington-Finkelstein coordinates: $ds^2 = -\left(1 - \frac{2M}{r}\right)dv^2 + 2dvdr + r^2 d\Omega^2$
 where $v = t + r + 2M \ln\left|\frac{r}{2M} - 1\right|$

a) $\xi^\alpha = (1, 0, 0, 0)$ in Schwarzschild coord (t, r, θ, φ)
 General transformation formula: $\xi^{\beta'} = \frac{\partial x^{\beta'}}{\partial x^\alpha} \xi^\alpha = \frac{\partial x^{\beta'}}{\partial x^t} \xi^t$

Only v depends on t and $\frac{\partial v}{\partial t} = 1$.

Hence $\xi^{\beta'} = (1, 0, 0, 0)$ also in EF-coord.

b) In order to find K from $\xi^\alpha \nabla_\alpha \xi^\beta = K \xi^\beta$ we need

$$\begin{aligned} \xi^\alpha \nabla_\alpha \xi^\beta &= \nabla_v \xi^\beta = \underbrace{\partial_v \xi^\beta}_{=0} + \Gamma^\beta_{\nu\sigma} \xi^\sigma = \Gamma^\beta_{vv} = \\ &= \frac{g^{\beta\delta}}{2} \left(\underbrace{\partial_v g_{\nu\delta}}_{=0} + \underbrace{\partial_\nu g_{v\delta}}_{=0} - \underbrace{\partial_\delta g_{vv}}_{\substack{\delta=r \\ \text{since } g_{vv} \text{ only} \\ \text{depends on } r}} \right) = -\frac{g^{\beta r}}{2} \underbrace{\partial_r g_{vv}}_{=-\frac{2M}{r^2}} \end{aligned}$$

We need the inverse metric for the v, r -components:

$$g_{\alpha\beta} = \begin{pmatrix} -(1 - \frac{2M}{r}) & 1 \\ 1 & 0 \end{pmatrix} \quad g^{\alpha\beta} = (g_{\alpha\beta})^{-1} = \begin{pmatrix} 0 & 1 \\ 1 & 1 - \frac{2M}{r} \end{pmatrix}$$

$$\text{Hence } \beta = v \Rightarrow g^{vr} \frac{M}{r^2} = \frac{M}{r^2}$$

$$\beta = r \Rightarrow g^{rr} \frac{M}{r^2} = \left(1 - \frac{2M}{r}\right) \frac{M}{r^2}$$

$$\beta = \theta, \varphi \Rightarrow 0$$

$$\text{So } \xi^\alpha \nabla_\alpha \xi^\beta = \frac{M}{r^2} \left(1, 1 - \frac{2M}{r}, 0, 0 \right)$$

Insert $r = 2M$:

$$\left. \xi^\alpha \nabla_\alpha \xi^\beta \right|_{r=2M} = \frac{1}{4M} \underbrace{\left(1, 0, 0, 0 \right)}_{\text{should be } K \xi^\beta} \Rightarrow K = \frac{1}{4M}$$

② General expressions:

$$R^{\alpha}_{\beta\gamma\delta} = \partial_{\gamma} \Gamma^{\alpha}_{\beta\delta} - \partial_{\delta} \Gamma^{\alpha}_{\beta\gamma} + \Gamma^{\alpha}_{\gamma\epsilon} \Gamma^{\epsilon}_{\beta\delta} - \Gamma^{\alpha}_{\delta\epsilon} \Gamma^{\epsilon}_{\beta\gamma}$$

$$\Gamma^{\alpha}_{\beta\gamma} = \frac{g^{\alpha\delta}}{2} (\partial_{\gamma} g_{\delta\beta} + \partial_{\beta} g_{\delta\gamma} - \partial_{\delta} g_{\beta\gamma})$$

Consider a local inertial frame (LIF) at point p :

$$g_{\alpha\beta} \Big|_p = \eta_{\alpha\beta}$$

$$\partial_{\gamma} g_{\alpha\beta} \Big|_p = 0$$

Since $\Gamma^{\alpha}_{\beta\gamma}$ consists of first derivatives of $g_{\alpha\beta}$, it follows that

$$\Gamma^{\alpha}_{\beta\gamma} \Big|_p = 0$$

Hence the third and fourth terms in $R^{\alpha}_{\beta\gamma\delta}$ vanish.

The first and second terms (the first derivatives of Γ) contain both first and second derivatives of $g_{\alpha\beta}$. Only those terms containing no first derivative survives in the LIF.

Hence:

$$\begin{aligned} R^{\alpha}_{\beta\gamma\delta} \Big|_p &= \partial_{\gamma} \Gamma^{\alpha}_{\beta\delta} - \partial_{\delta} \Gamma^{\alpha}_{\beta\gamma} = \\ &= \frac{g^{\alpha\epsilon}}{2} \left(\underbrace{\partial_{\gamma} \partial_{\delta} g_{\epsilon\beta} + \partial_{\gamma} \partial_{\beta} g_{\epsilon\delta} - \partial_{\gamma} \partial_{\epsilon} g_{\beta\delta}}_{\text{vanishes since sym. in } \gamma, \delta} \right) - \left[\text{same with } \gamma \leftrightarrow \delta \right] = \end{aligned}$$

$$= \frac{g^{\alpha\epsilon}}{2} \left(\partial_{\gamma} \partial_{\beta} g_{\epsilon\delta} - \partial_{\gamma} \partial_{\epsilon} g_{\beta\delta} - \partial_{\delta} \partial_{\beta} g_{\epsilon\gamma} + \partial_{\delta} \partial_{\epsilon} g_{\beta\gamma} \right)$$

$$\text{So } R_{\alpha\beta\gamma\delta} \Big|_p = \frac{1}{2} \left(\partial_{\gamma} \partial_{\beta} g_{\alpha\delta} - \partial_{\gamma} \partial_{\alpha} g_{\beta\delta} - \partial_{\delta} \partial_{\beta} g_{\alpha\gamma} + \partial_{\delta} \partial_{\alpha} g_{\beta\gamma} \right)$$

$$(3) \quad a) \quad T_{\alpha\beta} = \begin{pmatrix} g & 0 & 0 & 0 \\ 0 & p & 0 & 0 \\ 0 & 0 & p & 0 \\ 0 & 0 & 0 & p \end{pmatrix}$$

Consider an arbitrary observer with 4-velocity

$$u^\alpha = \gamma_v (1, v_x, v_y, v_z)$$

This observer will measure the energy density

$$\varepsilon = T_{\alpha\beta} u^\alpha u^\beta = \gamma_v^2 (g + p v^2) \quad \text{where } v^2 = v_x^2 + v_y^2 + v_z^2$$

Require $\varepsilon > 0$

$$\Rightarrow g + p v^2 > 0$$

$$g > -p v^2$$

v^2 can of course be anything between 0 and 1.

If $p > 0$ this requirement is strongest when $v=0$.

Then it says that $g > 0$

If $p < 0$ this requirement is strongest when $v=1$.

Then it says that $g + p > 0$

Hence we must require $g > 0$ and $g + p > 0$.

b) Vacuum energy:

$$T_{\alpha\beta} = \begin{pmatrix} g & 0 & 0 & 0 \\ 0 & -g & 0 & 0 \\ 0 & 0 & -g & 0 \\ 0 & 0 & 0 & -g \end{pmatrix} = -g \eta_{\alpha\beta}$$

Energy density as measured by observer u^α :

$$\varepsilon = T_{\alpha\beta} u^\alpha u^\beta = -g \underbrace{\eta_{\alpha\beta} u^\alpha u^\beta}_{= \vec{u} \cdot \vec{u} = -1} = g$$

So all observers measures the same energy density g .

④ The Friedman equation: $\dot{a}^2 - \frac{8\pi g}{3} a^2 = -k$ (*)

a) Suppose that the energy density g is any combination of matter and radiation:

$$g = g_m + g_r = b_m a^{-3} + b_r a^{-4} \quad \text{where } b_m > 0, b_r > 0$$

from (18.25) and (18.26)

Then (*) gives

Choose positive sign

$$\dot{a} = \left(\frac{8\pi g}{3} a^2 - k \right)^{1/2} = \left(\frac{8\pi}{3} (b_m a^{-1} + b_r a^{-2}) - k \right)^{1/2}$$

$$\begin{aligned} \frac{d^2 a}{dt^2} &= \frac{d}{dt}(\dot{a}) = \frac{1}{2} \dot{a}^{-1} \frac{8\pi}{3} (-b_m a^{-2} - 2b_r a^{-3}) \cdot \dot{a} = \\ &= -\frac{4\pi}{3} (b_m a^{-2} + 2b_r a^{-3}) \end{aligned}$$

< 0 for all positive b_m and b_r ,
that is, the expansion slows down.

b) Now, suppose that we also have vacuum energy:

$$g = g_m + g_r + g_v = b_m a^{-3} + b_r a^{-4} + \frac{\Lambda}{8\pi}$$

from (18.28)

Then (*) gives

$$\dot{a} = \left(\frac{8\pi}{3} \left(b_m a^{-1} + b_r a^{-2} + \frac{\Lambda}{8\pi} a^2 \right) - k \right)^{1/2}$$

$$\text{and } \frac{d}{dt}(\dot{a}) = -\frac{4\pi}{3} \left(b_m a^{-2} + 2b_r a^{-3} - \frac{\Lambda}{4\pi} a \right)$$

For b_m and b_r small enough, the Λ -term will dominate. Then $\frac{d}{dt}(\dot{a}) > 0$, so that the expansion speed will increase.

⑤ a) The longest time must be the time along a geodesic.
Then (9.26) is applicable:

$$\frac{e^2 - 1}{2} = \frac{1}{2} \left(\frac{dr}{d\tau} \right)^2 + \frac{1}{2} \left[\left(1 - \frac{2M}{r} \right) \left(1 + \frac{l^2}{r^2} \right) - 1 \right]$$

$$\Rightarrow \frac{d\tau}{dr} = - \left(e^2 - \underbrace{\left(1 - \frac{2M}{r} \right) \left(1 + \frac{l^2}{r^2} \right)}_{< 0} \right)^{-1/2}$$

ingoing geodesic means $\frac{d\tau}{dr} < 0$

$$\text{So } \tau = \int d\tau = - \int_{r=2M}^{r=0} \left(e^2 - \underbrace{\left(1 - \frac{2M}{r} \right) \left(1 + \frac{l^2}{r^2} \right)}_{< 0} \right)^{-1/2} dr =$$

$$= \int_0^{2M} \left(e^2 + \left(\frac{2M}{r} - 1 \right) \left(1 + \frac{l^2}{r^2} \right) \right)^{-1/2} dr$$

The largest possible τ is obtained for $e=0$ and $l=0$:

$$\tau_{\max} = \int_0^{2M} \left(\frac{2M}{r} - 1 \right)^{-1/2} dr = \left[\begin{array}{l} x = \frac{r}{2M} \\ dx = \frac{dr}{2M} \end{array} \right] = 2M \int_0^1 \left(\frac{1}{x} - 1 \right)^{-1/2} dx =$$

$$= 2M \underbrace{\int_0^1 \left(\frac{x}{1-x} \right)^{1/2} dx}_{= \frac{\pi}{2}} = \pi M$$

b) Changing to standard units: $c \tau_{\max} = \frac{\pi M G}{c^2}$

$$\tau_{\max} = \frac{\pi M G}{c^3}$$

$$M = 4 \cdot 10^6 M_{\odot} \approx 8 \cdot 10^{36} \text{ kg}$$

$$\Rightarrow \tau_{\max} \approx \frac{\pi \cdot 8 \cdot 10^{36} \cdot 6.67 \cdot 10^{-11}}{(3 \cdot 10^8)^3} \approx 62 \text{ s}$$