## Lecture 10

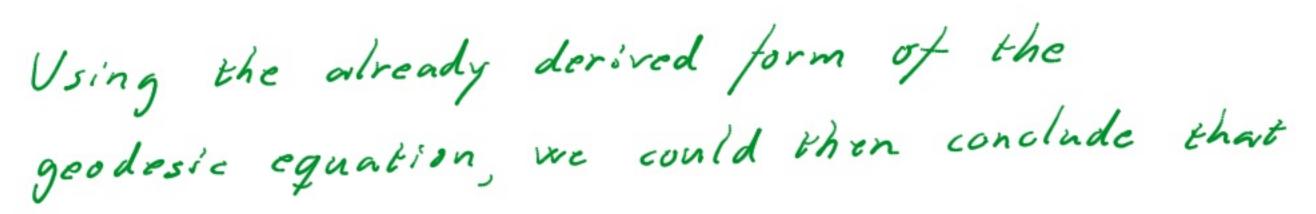
Measure of curvature: the result of p.t. around small loops - Derivation of  $R^{S}$  apr

Expressing R in terms of T.

Last time we defined the covariant derivative through the notion of parallel transport:

$$\nabla_{\overline{\xi}} \overline{v}(p) = \lim_{\epsilon \to 0} \frac{\overline{v}(q)/_{p.t.\,top} - \overline{v}(p)}{\epsilon}$$

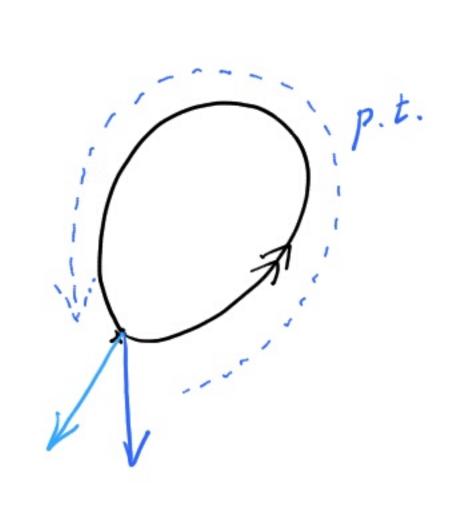
For the tangent of a geodesic we know that



where T is an expression containing the first partial derivatives of the metric.

We can now use this to define an invariant measure of curvature for generally curved spaces or spacetimes.

Qualitatively, this is how our measure will work:



P. t. a vector around a closed loop.

If space is curved the vector will not be the same when it returns:

it will be rotated (or boosted) with respect to the original vector.

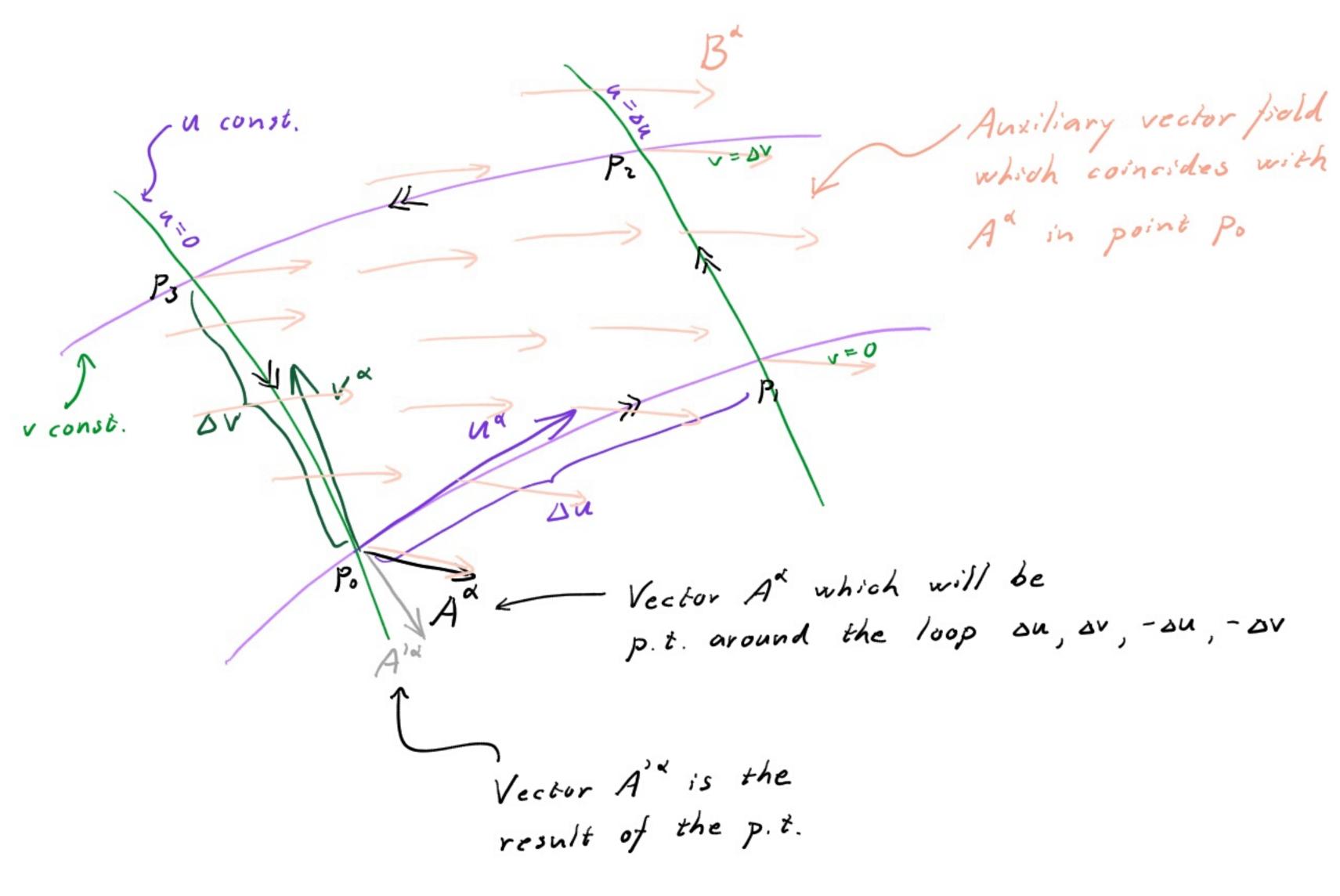
The kind of transformation (and its size) is a measure of the curvature in the directions spanned by the loop.

Since the covariant derivative quantifies the result of p.t., we can use it to make this measure of currature precise.

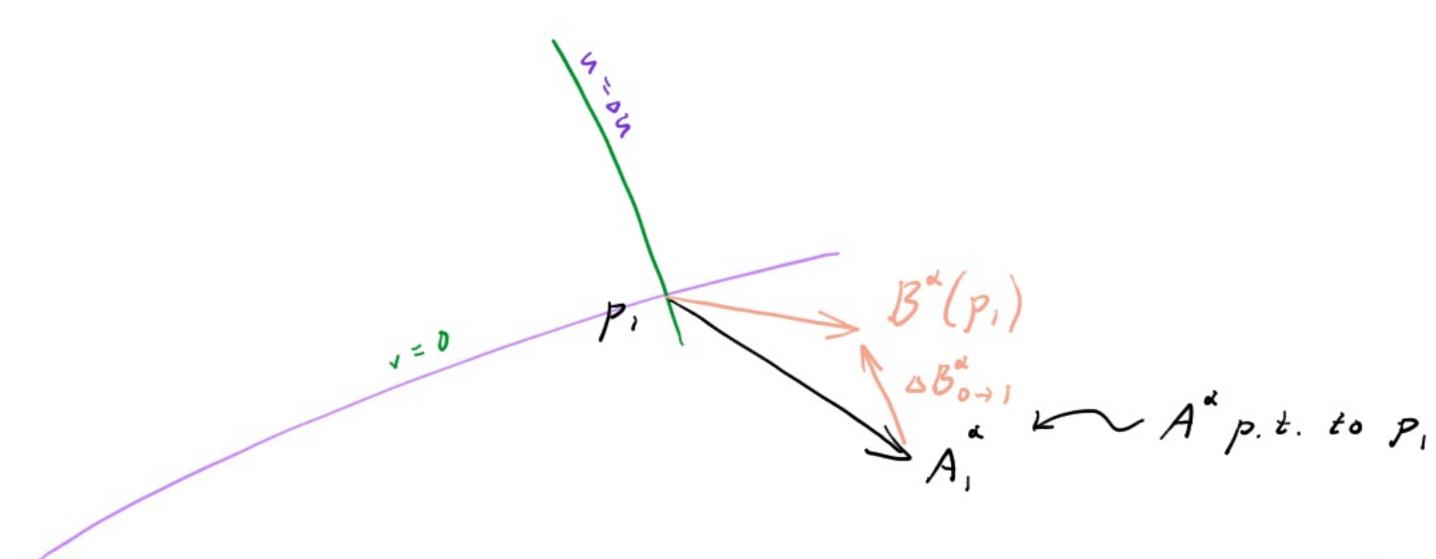
Consider a point  $p_0$  and a 2-dimensional surface (the one in which the p.t. will take place). Introduce coordinates u and v in that surface such that  $p_0^u = (0,0)$ .

Consider a vector A at po. We will p.t. this around a small rectangular loop consisting of segments of the coordinate lines of a and v.

We also need to introduce an auxiliary rector field B".



As the first step, p.t. A along the u-coord. line a coordinate distance on to point P.:



Now, note that the difference between  $A_i^{\alpha}$  and the auxiliary field  $B^{\alpha}(p_i)$  is the same as the covariant change in  $B^{\alpha}$  when moving from  $p_i$  to  $p_i$  (since  $B^{\alpha}(p_i) = A^{\alpha}$  at  $p_i$ ):  $\Delta B_{0 \to i}^{\alpha} = \Delta u u^{\beta} \nabla_{\beta} B^{\alpha}|_{v=0}$ 

$$A_{i}^{\alpha} = B^{\alpha}(p_{i}) - \Delta B^{\alpha}_{0\rightarrow 1} = B^{\alpha}(p_{i}) - \Delta u u^{\beta} \nabla_{\beta} B^{\alpha}|_{v=0}$$

By definition of covariant derivative!

Let us continue step by step along the remaining segments of the loop:

$$\Delta \mathcal{B}_{1\to 2}^{\alpha} = \Delta v v^{\beta} \nabla_{\beta} \mathcal{B}_{u=\Delta u}^{\alpha}$$

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$$\Delta B_{2\rightarrow 3}^{\alpha} = -\Delta u u^{\beta} \nabla_{\beta} B_{|\nu=a\nu}^{\alpha}$$
and 
$$A_{3}^{\alpha} = B^{\alpha}(P_{3}) - \Delta B_{0\rightarrow 1}^{\alpha} - \Delta B_{1\rightarrow 2}^{\alpha} - \Delta B_{2\rightarrow 3}^{\alpha}$$

$$\Delta B_{3\rightarrow 0}^{\alpha} = -\Delta V V^{B} \nabla_{B} B^{\alpha} \Big|_{u=0}$$
and 
$$A'^{\alpha} = B'(p_{0}) - \Delta B_{0\rightarrow 1}^{\alpha} - \Delta B_{1\rightarrow 2}^{\alpha} - \Delta B_{2\rightarrow 3}^{\alpha} - \Delta B_{3\rightarrow 0}^{\alpha}$$

$$= A^{\alpha} \qquad \qquad Back at the starting point!$$

Hence we can express the result of the p.t., that is,  $\Delta A^{\alpha} = A^{i\alpha} - A^{\alpha}$ 

in terms of the covariant derivatives of the auxiliary field B2!

Let us put all the pieces together:
$$\Delta A^{\alpha} = A^{i\alpha} - A^{\alpha} = -\Delta B^{\alpha}_{0 \to 1} - \Delta B^{\alpha}_{1 \to 2} - \Delta B^{\alpha}_{2 \to 3} - \Delta B^{\alpha}_{3 \to 0} =$$

$$= \Delta u \Delta v \left[ \frac{u^{o} \nabla_{o} B^{\alpha} /_{v=av} - u^{o} \nabla_{o} B^{\alpha} /_{v=o}}{\Delta v} - \frac{v^{o} \nabla_{o} B^{\alpha} /_{v=o}}{\Delta u} - \frac{v^{o} \nabla_{o} B^{\alpha} /_{u=o}}{\Delta u} \right]$$

So
$$SA^{\alpha} = du \, dv \left( v^{\tau} (\nabla_{r} u^{\beta}) (\nabla_{\alpha} B^{\alpha}) + v^{\tau} u^{\alpha} \nabla_{r} \nabla_{\beta} B^{\alpha} + u^{\tau} (\nabla_{r} v^{\beta}) (\nabla_{\alpha} B^{\alpha}) - u^{\tau} v^{\beta} \nabla_{r} \nabla_{\beta} B^{\alpha} \right) - u^{\tau} v^{\beta} \nabla_{r} \nabla_{\beta} B^{\alpha} \right)$$

The first and third term vanish, since
$$v^{*}(\nabla_{y}u^{s}) = v^{*}(\partial_{y}u^{s} + \Gamma^{s}_{ss}u^{s}) = \frac{\partial}{\partial v}\frac{\partial x^{s}}{\partial u} + v^{*}u^{s}\Gamma^{s}_{rs} = \frac{\partial}{\partial u}\frac{\partial x^{s}}{\partial v} + u^{*}v^{s}\Gamma^{s}_{rs} = u^{*}(\partial_{y}v^{s} + v^{s}\Gamma^{s}_{rs}) = u^{*}\nabla_{y}v^{s}$$

$$= u^{*}\nabla_{y}v^{s}$$

So what remains is

$$SA^{\alpha} = du \ dv \ u^{\alpha}v^{\gamma} \left( \nabla_{v} \nabla_{o} - \nabla_{o} \nabla_{o} \right) B^{\alpha}$$

can be replaced by

 $\frac{1}{2} \cdot du \ dv \left( u^{\beta}v^{\gamma} - u^{\gamma}v^{\beta} \right) \equiv SS^{\beta\gamma}$ 

Remember that the vector field was arbitrary. We only with something that demanded that it should is anti-sym. in  $\beta$ ,  $\delta$ .

 $egunl A^{\alpha}$  at point  $p_{o}$ .

Mystery: How can the change in the vector Addepend on an arbitrary field Bd?

To solve the mystery, let us evaluate the anti-sym. second covariant derivative on Ba.

$$\nabla_{s}\nabla_{s}B^{\alpha} = \nabla_{s}\left(\partial_{s}B^{\alpha} + \Gamma_{ss}^{\alpha}B^{s}\right) =$$

$$= \partial_{r}\partial_{s}B^{\alpha} - \Gamma_{sr}^{s}\partial_{s}B^{\alpha} + \Gamma_{sr}^{\alpha}\partial_{s}B^{s} +$$

$$+ \partial_{r}\left(\Gamma_{ss}^{\alpha}B^{s}\right) + \Gamma_{rs}^{\alpha}\Gamma_{ps}B^{s} - \Gamma_{rs}^{r}\Gamma_{rs}^{\alpha}B^{s}$$

The terms marked x are all symmetric in 8, B, so they will cancel against similar terms in V, Bx.

The forth term:

$$\supset_{\sigma} \left( \mathcal{T}_{SS}^{\times} \mathcal{B}^{s} \right) = \left( \mathcal{J}_{\sigma} \mathcal{T}_{SS}^{\times} \right) \mathcal{B}^{s} + \mathcal{T}_{SS}^{\times} \mathcal{B}^{s}$$

This is symmetric together with the third term above.

Thus they will also cancel similar terms in  $\nabla_{s} \nabla_{s} \mathcal{B}^{\alpha}$ .

We are left with two terms only. Hence:

$$\left( \nabla_{s} \nabla_{s} - \nabla_{s} \nabla_{s} \right) B^{\alpha} =$$

$$= \left( \partial_{s} \Gamma^{\alpha}_{os} - \partial_{o} \Gamma^{\alpha}_{ss} + \Gamma^{\alpha}_{ps} \Gamma^{p}_{os} - \Gamma^{\alpha}_{ps} \Gamma^{r}_{ss} \right) B^{s}$$

R SOB

So what looks like a second derivative operator acting on a field, actually just is a rank 4 tensor multiplying the vector at a point!

This is the Riemann tensor!

Hence we have shown:

$$SA^{\alpha} = -R^{\alpha}_{SB^{\alpha}} SS^{\beta^{\alpha}} A^{\delta}$$

Note that the area does not have to be rectangular.

