

Simulating the Ising model using the Metropolis algorithm

Johan Nereng

Department of Physics, University of Oslo, Norway

Nov 21, 2018

1 Abstract

The scope of this project is to examine a numerical simulation of the Ising model, implemented into a program through use of the the Metropolis algorithm. Specifically, this project aims to evaluate the ability of said program to simulate the expected ferromagnetic behaviour for spin lattices of up to 40×40 , and it's aptitude for applications in the studies of phase transitions for lattices up to 100×100 .

The main finding of this project is that a high resolution in temperature ($\Delta T \leq 0.005$) is needed to draw definite conclusions on program aptitude in studies on phase transitions. Due to the the resolution used in this project, $\Delta T = 0.05$, it may only be stated that the algorithm appears to produce results similar to the expected trends with respect to the expectation values of the energy ($\langle E \rangle$) and absolute magnetization ($\langle |M| \rangle$), the magnetic susceptibility (χ) and the specific heat capacity C_V . Further more, this project establishes that the Metropolis algorithm may be used to simulate an Ising model lattice - producing results with a relative tolerance of 10^{-3} for all previously mentioned quantities except C_V , for an $L = 2$ lattice, after $3 \cdot 10^6$ equilibrium cycles. Lastly, examinations of lattices up to $L = 100$ carried out in this project, show reliably low fluctuations for $\langle E \rangle$, $\langle |M| \rangle$, χ , and C_V after $3 \cdot 10^6$ equilibrium cycles.

2 Introduction

Authors' comment: *I was, as mentioned in the abstract, unable to procure sufficient resolution for the data used in the study of phase transitions. Expecting that the computations using $\Delta T = 0.05$ would take the entire night (turns out that this only took about an hour), I went to bed. By the time I realized I had to guesstimate using that resolution, there were no more nights available for the*

computer to work while I slept - lesson learned; when expecting long run times, test run with a print of the time about 1/10'th into the program. Also, during this project I have realized that I needed to learn how to use subplots, which I found the time to implement in most of the figures, but not all. I will definitely make better use of this function in the future.

In general, magnets are objects which produce a magnetic field. Such fields arise from net magnetic moment and induction from electric currents [1]. In the case of the strong magnetic fields observed in ferromagnets, the spin configuration of electrons in neighboring atoms largely decides the net magnetic moment [2]. This means that there is a connection between the microstate of the object and it's magnetic properties. These microstates are quantum states, and are therefore of a stochastic nature. The probability of a system occupying a specific microstate, may therefore be described in the canonical ensemble by the Boltzmann distribution (1) where k_B is the Boltzmann constant, T the temperature, and Z (2) the canonical partition function, which sums over the energy, E , of all possible states [3].

$$P_i(\beta) = \frac{e^{-\beta E_i}}{Z}, \text{ where } \beta = 1/k_B T \quad (1)$$

$$Z = \sum_{i=1}^M e^{-\beta E_i} \quad (2)$$

The properties of the canonical ensemble is used to find the expectation value of the energy, $\langle E \rangle$ which is subject to both the principle of energy minimization and the principle of maximum entropy, S . At the equilibrium point between these principles, the Helmholtz' free energy, $F = \langle E \rangle - TS$, is minimized [ibid]. In addition, a ferromagnetic object loses it's magnetic properties at a certain critical temperature known as the Curie Temperature, T_C , which may also be used to describe phase transition between ferromagnetism and paramagnetism [2]. Thus, in order to examine such phase transitions in ferromagnets, this project empathizes mean energy, temperature, and net magnetization, as well as two additional parameters; specific heat capacity at constant volume, C_V , which are related to the derivative of the Helmholtz's free energy [3], and the magnetic susceptibility, χ , which quantifies the material's response to an external magnetic field.

This projects start by describing the [thermodynamic properties](#) of a magnetic system through the canonical ensemble, and expressions for $\langle E \rangle$, C_V , $\langle M \rangle$, and χ presented. Next, the mathematical model known as the [the Ising model](#), utilizing a two dimensional lattice of size $L \times L$, is introduced and briefly explained. Then, this model is [applied to a magnetic system](#) of atomic spins, and analytical expressions for $\langle E \rangle$, $\langle M \rangle$, χ and C_V as functions of the temperature, T , are derived for an $L = 2$ lattice, using the mean absolute value

of the magnetic moment $\langle |M| \rangle$ in addition to the previously mentioned properties.

Having outlined the mathematical basis for the project, a Markov Chain Monte Carlo method known as the [Metropolis algorithm](#) is applied to the system in order to simulate the magnetic properties described by the Ising model. This algorithm is subsequently [implemented](#) in a *C++* program, and the simulation results for an $L = 2$ lattice [compared](#) with the analytical values for $T = 1$, which indicate that sufficiently accurate expectation values (within 10^{-3} of analytical values, except for C_V) may be produced after an equilibrium time of, $t_{eq} \approx 3 \cdot 10^6$ Monte Carlo cycles. C_V had a relative accuracy of 0.1 in relation to the other parameters). A [re-examination of \$C_V\$](#) however, showed sufficiently stable C_V for larger lattices ($L = 20$) after t_{eq} .

Upon having established algorithm integrity through the initial test described above, [t_{eq} is further examined](#), and the effects of initial spin configuration (random or ordered) looked into. After which, the ordered initial configuration is [assumed to be more suited](#) for this project. In addition, the examination of t_{eq} and parameter offset indicated that mean values should predominantly be sampled after t_{eq} . Using the results above, an $L = 40$ lattice is examined with respect to the variance in energy for $T = 1$ and $T = 2.3$. During which, the total energy of the lattice is recorded after each spin flip, and the probability distribution, $P(E)$, estimated - showing a tendency towards a Gaussian bell shape for $T = 2.3$.

Lastly, phase transitions in the Ising model are described, and power law estimates of the Curie Temperature presented. Then, the ability of the algorithm to [simulate phase transitions](#) tested, and compared to an analytical value for T_C . Here, a lack of data resolution and number of cycles yielded [no definite conclusions](#).

Throughout this project, $k_B T$ is often simply written as T , and other similar relaxations taken with respect to units. All programs, results and files used in this project may be found on the author's [Github repository](#).

3 Methods

3.1 Thermodynamic properties

As the ferromagnetic system in this project is described through the canonical ensemble, the energy (3) and magnetization (4) of the ferromagnet are expectation values, the expressions of which are derived via the Helmholtz' free energy and entropy in the canonical ensemble [3].

$$\langle E \rangle = \sum_i^M E_i P_i(\beta) \quad (3)$$

$$\langle M \rangle = \sum_i^M M_i P_i(\beta) \quad (4)$$

Through the expectation values above, the specific heat capacity at constant volume, C_V (5), signifying the amount of heat needed to change the temperature of the system, and the magnetic susceptibility, χ (6), which quantifies the response to an external magnetic field, are defined.

$$C_V = \frac{1}{k_B T^2} (\langle E^2 \rangle - \langle E \rangle^2) \quad (5)$$

$$\chi = \frac{1}{k_B T} (\langle M^2 \rangle - \langle M \rangle^2) \quad (6)$$

3.2 The Ising model

In order to simulate ferromagnetic behaviour and properties, this project employs a theoretical description of ferromagnets known as the Ising model. This model consists of $L \times L$ binary variables on a two dimensional lattice, representing identical spin systems, with the energy of a specific spin configuration, or microstate, i defined as [5]:

$$E_i = -J \sum_{\langle kl \rangle} s_k s_l - B \sum_{i=k} s_k \quad (7)$$

Where, $J > 0$ is the exchange energy, B external magnetic field, and s_k, s_l , the k 'th and l 'th atomic spins of a total of N spins. The sum over $\langle kl \rangle$ is the sum over unique neighbouring spin pairs, while the spins are either spin up (\uparrow), $s = +1$, or spin down (\downarrow), $s = -1$ [ibid]. As this project aims to study phase transition in a ferromagnet without any external magnetic field, $B = 0$, so that:

$$E_i = -J \sum_{\langle kl \rangle} s_k s_l \quad (8)$$

In addition to the energy, the Ising model is defined through the magnetization of configuration i , defined as:

$$M_i = \sum_k s_k \quad (9)$$

In order to define the end points of the lattice, this project utilizes of periodic boundary conditions, which means that $s_{n(L+1)} = s_n$, where $n = 1, 2, \dots, L$, which is to say that the lattice may be viewed as the surface of a torus.

3.3 Model application - benchmarking

With the aim of obtaining evaluation parameters for the implementation of the later described Marcov Chain Monte Carlo method ([the Metropolis algorithm](#)), the analytical expressions for $\langle E \rangle$, the expectation value of the absolute magnetic moment $|M|$ ([10](#)), C_V , and χ , as functions of the temperature, T , are derived for a 2×2 lattice. This requires working out the partition function, Z , which depends on the number of spin configurations and their corresponding energy values. In addition, deriving the expression for χ hinges on knowing the magnetization of each spin configuration.

$$\langle M_i \rangle = \sum_k |s_k| P_i(\beta) \quad (10)$$

The spin configurations for the 2×2 Ising model lattice, and their energies and magnetization, are presented in table 1, where the degeneracy number signifies the number of spin configurations with the same energy and magnetization levels. Based on this table and equations (3), (10), 5, (2) the analytical expressions for the 2×2 lattice are presented below. Using these, the evaluation parameters (per spin) for $T = 1$ are presented in table 2, under [Algorithm implementation](#).

Table 1: Overview of microstates for a 2×2 lattice

Number of spins up	Degeneracy	Energy [J]	Magnetization
4	1	-8	4
3	4	0	2
2	4	0	0
2	2	8	0
1	4	0	-2
0	1	-8	-4

$$Z(T) = 12 + 2(e^{\frac{-8J}{k_B T}} + e^{\frac{8J}{k_B T}}) = 12 + 4 \cosh(\frac{8J}{k_B T}) \quad (11)$$

$$\langle E \rangle(T) = \frac{16}{Z}(e^{\frac{-8J}{k_B T}} - e^{\frac{8J}{k_B T}})J \quad (12)$$

$$\langle |M| \rangle(T) = \frac{8}{Z}(e^{\frac{8J}{k_B T}} + 1) \quad (13)$$

$$\chi(T) = \frac{1}{k_B T}(\frac{32}{Z}(e^{\frac{8J}{k_B T}} + 1)) \quad (14)$$

$$C_V(T) = \frac{1}{k_B T}(\frac{256}{Z} \cosh(\frac{8J}{k_B T}) - \frac{32^2}{Z^2} \cosh^2(\frac{8J}{k_B T})) \quad (15)$$

In order to obtain expectation values per spin, the equations above must be divided by L^2 .

3.4 The Metropolis algorithm

Calculating the partition function of a lattice of any significant size is impractical, bordering on the impossible, so in order to numerically model the ferromagnet, a Markov Chain Monte Carlo (MCMC) method is applied, namely the Metropolis algorithm. This method takes an initial spin configuration, proposes a new spin configuration, and either accepts or rejects the new configuration based on its sampling rule. By relying solely on the relative likelihood of a proposed configuration relative to the current configuration, the metropolis algorithm circumvents the partition function. Over the course of a large number of proposed configuration changes, the system reaches an equilibrium state - in which the spin configuration, energy and magnetization fluctuates around a mean as a function of temperature, enabling the study of the ferromagnetic properties without ever using the partition function. Below is a brief summery of the algorithm [3], and thereafter an augmenting description it.

MCMC: Metropolis algorithm

1. Initialize lattice
 - Set the spin orientation of starting configuration.
 - Calculate E and M
2. Propose new configuration (see comments below about lattice sweep)
 - Generate a random spin index k .
 - Set $s_k = -s_k$.
 - Calculate ΔE
3. Evaluate proposal
 - If $\Delta E \leq 0$, accept the new configuration (update E and M) and move to step 4.
 - Generate a random number r between 0 and 1.
 - If $r \leq e^{-\beta\Delta E}$, accept new configuration (update E and M).
 - If proposed configuration has not been accepted, reject proposal, and set $s_k = -s_k$ (dial-back configuration).
4. Update E_{total} , M_{total} , E_{total}^2 , M_{total}^2 , $|M|_{total}$
5. If the number of cycles from step 2 to 4 is less than the total number of MCC , go to step 2. Else calculate $\langle E \rangle$, $\langle E^2 \rangle$, $\langle M \rangle$, $\langle M^2 \rangle$, $\langle |M| \rangle$ and end simulation.

When initializing the lattice in step 1, this project employs both an ordered initial spin configuration (all spins \uparrow), and a randomized configuration, in which the orientation of each spin is randomized. Furthermore the metropolis algorithm

is applied with the use of lattice sweeps. This means that prior to step 4, $L \times L$ uniformly distributed spin indexes, k are generated. For each such index, the algorithm goes through step 2 and 3 for each such k , before moving on to step 4, where the change in each quantity is simply added to the corresponding sum. At step 5, in order to find E_{total} , M_{total} , E_{total}^2 , M_{total}^2 , $|M_{total}|$, and based on these, χ and C_V , E_{total} , M_{total} , E_{total}^2 , M_{total}^2 , $|M|_{total}$ are divided by the number of Monte Carlo cycles (lattice sweeps), and the number of spins. This means that all values extracted from the simulation are per spin.

The energy change, ΔE in it's easiest form simply takes the difference between current energy from (8) and proposed energy. However, as the spins are only changed on at the time, there is no need to keep track of the energy of the current state in order to work out ΔE - it may after all only take on five possible values: $-8J, -4J, 0J, 4J, 8J$ [3] - which means that the temperature really only affect the sampling rule $r \leq e^{-\beta \Delta E}$. Lastly, it's worth mentioning that this Metropolis algorithm set up ensures ergodicity and detailed balance, which may be read about in more detail in "An introduction to Monte Carlo methods" by J.C.Waltera and G.T.Barkema[8].

3.5 Algorithm implementation

The MCMC algorithm is now implemented into program through code written in *C++* with the *armadillo* library [7], using the template for the Ising model with the Mersenne twister random number engine from the Github page of the course Computational Physics at the University of Oslo [4].

In order to test the integrity of the algorithm in the program implementation, the program is run with $L = 2$, initial configuration as all spins up, $T = 1$, and $MCc = 10^8$. The results for $\langle E \rangle$, $\langle |M| \rangle$, χ , and C_V are then plotted as functions of the number Monte Carlo cycles, and compared to the analytical values obtained from (11) through (15) presented in table 2, with the intention of establishing the magnitude of the number of cycles needed to obtain a tolerable precision. The results are expected to fluctuate and deviate less from the analytical values as the number of Monte Carlo cycles approaches the required number to obtain a stable equilibrium state.

Table 2: Analytical values for 2×2 lattice for $T = 1$

$\langle E \rangle$	$\langle M \rangle$	χ	C_V
-1.9960	0.9987	3.9933	0.0321

3.6 Equilibrium time

The program is now more closely examined with respect to equilibrium time - the number of cycles needed to reach stable expectation values. After [establishing an initial estimate](#) of the equilibrium time of $3 \cdot 10^6$ cycles, the first step is evaluating the equilibrium time of C_V for a larger lattice ($L = 20, T = 1$), as C_V had one order of magnitude larger relative error than χ the initial tests. After this, the effects of initial spin configuration on equilibrium time is examined by comparing a random initial orientation versus an ordered orientation (all spins \uparrow). This is done by evaluating the time/cycle evolution of $\langle E \rangle$ and $\langle |M| \rangle$ for a $L = 20$ lattice over $4 \cdot 10^6$ cycles, examining both $T = 1$ and $T = 2.3$ - the lowest and highest temperatures used later in this project - with emphasis on convergence to equilibrium means.

The initially estimated equilibrium time is based on the stability of the expectation values for $L = 2$, which means that it should be more than sufficient for larger lattices. A confirmation of this is however needed before moving on to phase transitions. Lastly, the effects of temperature on the number of accepted spin configurations is looked into. As the sampling rule yields increased acceptance rate for increased temperatures, the number of accepted configurations is expected to exponentially increase with $k_b T$.

3.7 Variance in energy

Having established an equilibrium time of $3 \cdot 10^6$, the algorithm implementation is now tested with respect to the variance of energy, σ_E^2 . This is done by setting up a $L = 40$ lattice, and counting the number of energies of the system after equilibrium state is achieved. Based on the distribution of energies, $P(E)$ is calculated, and the results compared to the standard deviation, σ_E , which is more easily interpreted intuitively than the variance when comparing values to a graphical presentation of a distribution. These calculations are carried out using both $T = 1$ and $T = 2.3$. With the findings described under [Equilibrium time](#) in the discussion of results section in mind, σ_E^2 is expected to increase significantly for $T = 2.3$ in comparison to $T = 1$.

Having tested behavior found eq time, check expectation values against as expected: phase transition Ising model

3.8 Phase transitions

Phase transitions are in general terms changes in physical properties of a material due changes in for example temperature or pressure. In the case of the Ising model, a phase transition signifies the transition between ferromagnetic properties and paramagnetic properties, which manifests at a certain critical temperature T_C , also known as the Curie temperature. For temperature below T_C , the mean magnetization, $\langle M \rangle \neq 0$, while for $T > T_C$, the magnetization goes towards zero. Around the critical temperature, the model undergoes what is known as a

second order phase transition, or a continuous phase transition. $\langle M \rangle$, the order parameter, maintains continuity during the transition, while the susceptibility exhibits divergent behaviour [5]. As the temperature increases towards T_C , the susceptibility reaches a peak value, and for temperatures above T_C , the susceptibility decreases. The sharpness of this peak is directly related to the lattice size. For an $L \rightarrow \infty$ lattice, the susceptibility at T_C becomes discontinuous, while finite sized lattices have an increasingly sharp peak in χ for higher lattice sizes [3].

For temperatures close to T_C , properties of the Ising model may be expressed through power laws, which relates $\langle M(T) \rangle$, C_V and $\chi(T)$ to T_C through the critical components $\beta = 1/8$, $\alpha = 0$, $\gamma = 7/4$ as follows [6]:

$$\begin{aligned}\langle M(T) \rangle &\sim (T - T_C)^\beta \\ C_V(T) &\sim |T_C - T|^\alpha \\ \chi(T) &\sim |T_C - T|^\gamma\end{aligned}$$

The divergent behaviour of the susceptibility near T_C is usually described through the correlation length, ξ , which is a measure of how strongly distant spins on the lattice are correlated. Near T_C the spins become more correlated, which means that ξ increases: $\xi \sim |T - T_C|^{-\nu}$. This relationship defines the critical component ν [3], and through finite scaling relations [6], relates the behaviour of finite sized lattices to the discontinuity associated with infinite sized lattices in the Ising model by

$$T_C(L) - T_C(L = \infty) \propto aL^{-1/\nu} \quad (16)$$

, where a is a proportionality constant. This means that by using this relationship, a realistic T_C may be estimated though the use lattice models such as the ones employed in this project.

3.9 Estimating the Curie temperature

By applying (16), T_C in the thermodynamic limit $L \rightarrow \infty$ is now estimated using lattice sizes $L = 40, 60, 80, 100$. ν is set to 1. The exact results for kT_C/J is ≈ 2.269 [6]. As the run time of each Monte Carlo cycle drastically increases with higher values of L , parallelization methods using Message Passing Interface (MPI) for *C++*. This enables the use of multiple logical cores, thus speeding up the simulations. The Github page of the course Computational Physics at the University of Oslo [4] provides a readily built Ising program with MPI utility - which in this project is modified to only sample expectation values after a given equilibrium time t_{eq} . Using this modified program, lattices of size $L = 40, 60, 80, 100$ are simulated for temperatures in the range $[2.0, 2.3]$ and $\Delta = 0.05$, over a total of $3.3 \cdot 10^6$, with $t_{eq} = 3 \cdot 10^6$. As the magnetization around T_C is expected to decrease towards zero, change of spin configuration quite suddenly alter the sign of $\langle M \rangle$. Due to this, $\langle |M| \rangle$ is instead examined in

these large lattice simulations.

Following the simulations, a sequence of similar simulations over a smaller range of T up to $T = 2.3$ with $\Delta t = 0.005$ are carried out, using the same lattice sizes, but with $1.1 \cdot 10^6$ cycles, and $t_{eq} = 1 \cdot 10^6$. This reduction in cycles is due to time constraints, and is a necessary but unfortunate discrepancy in this project.

4 Results

4.1 Initial evaluation of Metropolis implementation

Figure 1 shows the results from initial tests of the program implementation of Ising model using Metropolis algorithm, with $L = 2$ and a total of 10^7 cycles for $T = 1$. The resolution of the graphs is 10000 cycles. The figures clearly show that all four parameters ($\langle E \rangle$, $\langle |M| \rangle$, χ , V_C), deviate significantly from the analytical values for low numbers ($< 2 \cdot 10^6$) of Monte Carlo cycles. In addition, the fluctuations in the expectation values are all relatively strong for all parameters for $< 2 \cdot 10^6$ cycles. After $3 \cdot 10^6$ cycles however, the $\langle E \rangle$, $\langle |M| \rangle$ and χ all appear to stabilize, with minor fluctuations around a fixed mean value. C_V however, appears to fluctuate with higher amplitude up to about $6 \cdot 10^6$. The maximum relative error (ϵ) are presented in table 3 for all parameters after $3 \cdot 10^6$ cycles.

Table 3: Maximum relative error after $3 \cdot 10^6$ cycles, with 10^4 cycles per data point - 2×2 lattice for $T = 1$

$\epsilon(\langle E \rangle)$	$\epsilon(\langle M \rangle)$	$\epsilon(\chi)$	$\epsilon(C_V)$
$9.04 \cdot 10^{-5}$	$9.55 \cdot 10^{-5}$	$1.19 \cdot 10^{-3}$	$4 \cdot 10^{-2}$

4.2 Equilibrium time

Augmentation of initial tests

Figure 2 shows C_V over $7 \cdot 10^6$ cycles - which upon inspection has a clear stable trend after $3 \cdot 10^6$ cycles - more under discussion of results.

Initial configuration

Figure 3 shows the time evolution of $\langle E \rangle$ for both a random and an ordered initial spin configuration for $T = 1$. The first cycles have been omitted from the figure, as the random spin configuration starts with a very large deviation from its equilibrium value (undesirable graph scaling). In the case of the ordered spin configuration, the expectation value fluctuates in the vicinity of -1.99715

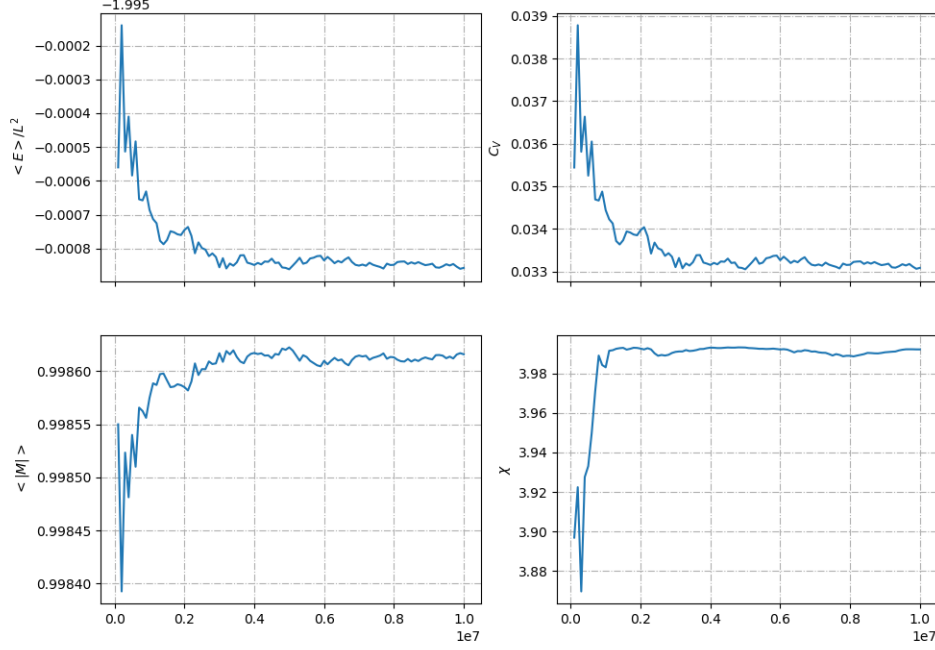


Figure 1: Initial test results with $L = 2$, over 10^7 cycles, with 10^4 cycles per data point

for the entire duration of the simulation, with strong fluctuations before $1 \cdot 10^6$ cycles. The random configuration however produces an expectation value with a (decreasing) downwards sinking trend throughout the simulation - and with a clear offset to the ordered spin mean after $3 \cdot 10^6$ cycles. Similarly, $\langle E \rangle$ for $T = 2.3$ is presented in 4 - which a somewhat larger initial deviation on $\langle E \rangle$ for the ordered initial configuration than the random initial configuration, with convergence to equilibrium values offset by ≈ 0.003 J.

In figure 5 initial spin configuration on equilibrium time is examined by comparing the convergence of $\langle E \rangle$ to $\langle E \rangle_{eq}$ for each initial configuration using temperatures $T = 1$ and $T = 2.3$, $L = 20$. $\langle E \rangle_{eq}$ is calculated by taking the average mean of the $\langle E \rangle$ from cycle number $3 \cdot 10^6$ to $4 \cdot 10^6$. As in figure 3, the first cycles have been omitted. $T = 1$ has a faster convergence than $T = 2.3$, with the ordered configuration of $T = 1$ being faster than the random configuration. For $T = 2.3$, the two configurations appear to have approximately the same convergence rate, with higher fluctuations after equilibrium time than in the $T = 1$ case. The configurations' effects on $\langle |M| \rangle$ follows the same trends, as is

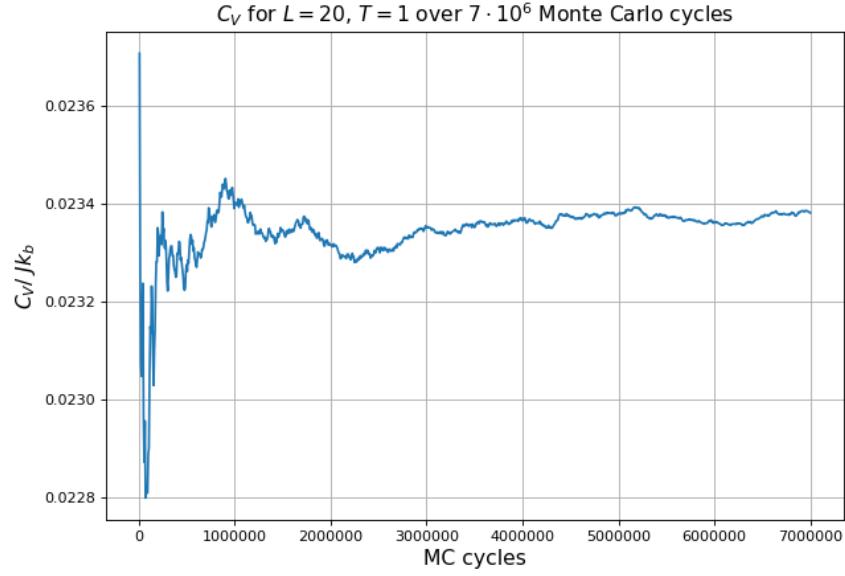


Figure 2: Augmentation to initial test: C_V using $L = 20$. 10^4 cycles per data point

evident by figure 6.

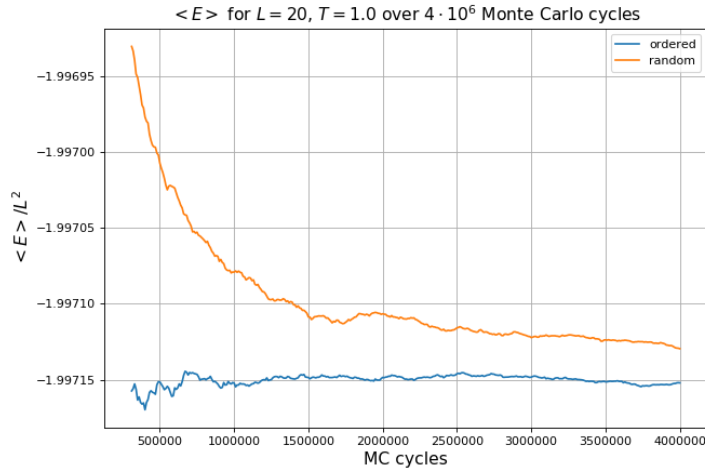


Figure 3: $\langle E \rangle$ for $T = 1$ - ordered vs random initial configuration

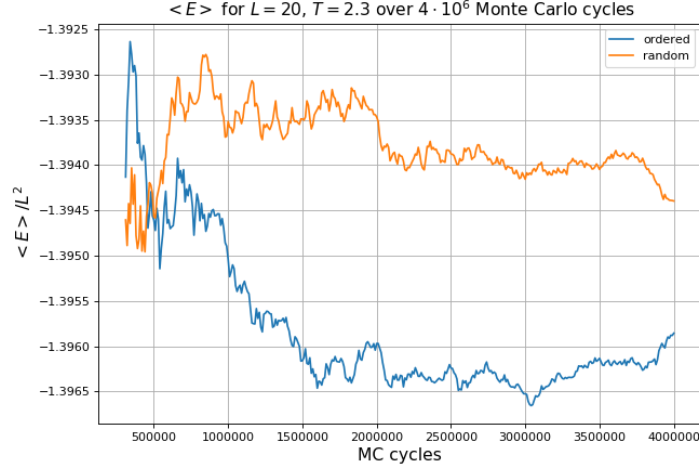


Figure 4: $\langle E \rangle$ for $T = 2.3$ - ordered vs random initial configuration

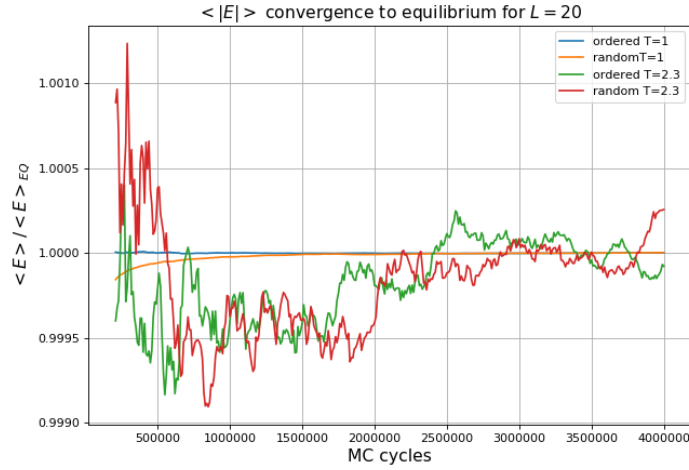


Figure 5: Comparison of convergence to $\langle |E| \rangle_{eq}$ for ordered and random initial configuration, with $T = 1$ and $T = 2.3$

Figures 7 and 8, show the average number of accepted spins per lattice sweep as a function of the number of cycles is presented for $T = 1$, $T = 2.3$ and both initial spin configurations. For $T = 1$, the number of accepted configurations per sweep is significantly higher for the random spin configuration than for the ordered configuration - especially at the start of the simulation (first values are

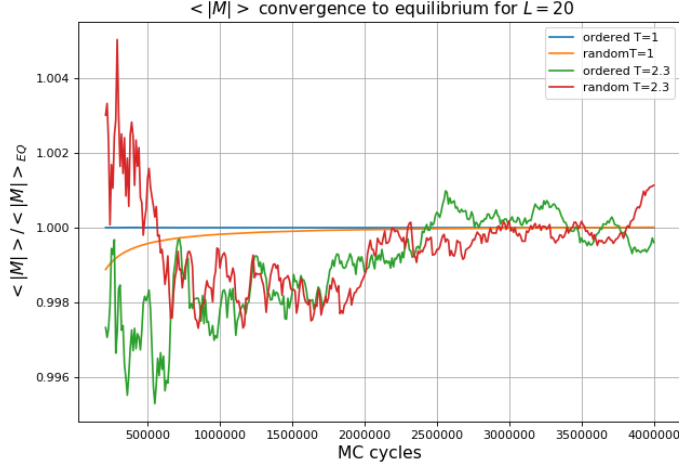


Figure 6: Comparison of convergence to $\langle |M| \rangle_{eq}$ for ordered and random initial configuration, with $T = 1$ and $T = 2.3$

again omitted due to scaling). Both configurations stabilize after $\approx 2 \cdot 10^6$ cycles. In the case of $T = 2.3$, the number of accepted spins per sweep is approximately the same for both configurations, and two orders of magnitudes larger than in the $T = 1$ case. This fits the trend that may be seen in figure 9, which shows a clear exponential increase in average cycles per sweep after equilibrium time as a function of temperature.

4.3 Variance in energy

In figure 10, the probability of each total energy level for the $L = 40$ lattice with $T = 1$ and $T = 2.3$ is presented, based on 5000 energy samplings in equilibrium state. It is evident that $T = 2.3$ features a much wider range of temperatures than $T = 1$. For $T = 1$, the energies are mainly spread out in the range $\sim [-3200, -3180]J$, with more than half of the data points around $-3200J$, which is $\approx -2J$ per spin. In the case of $T = 2.3$ the data points are roughly spread out over the range $\sim [-2300, -1900]J$, in a bell shape around $\approx -2210J$, corresponding to $\approx -1.38J$ per spin. The standard deviations, σ_E (scaled for total energy, instead of per spin) based on the variances, σ_E^2 , calculated over the equilibrium states by the program over $3 \cdot 10^5$ equilibrium cycles, are 5.47 J and 130.6 J, respectively for $T = 1$ and $T = 2.3$.

The bell shape observed for $T = 2.3$ roughly corresponds to the general shape expected of a Gaussian distribution. A fit to Gaussian distribution is shown in figure 11, based on $\sigma_E = 131.347$ J and the mean energy, $\bar{E} = -2158.34$ J

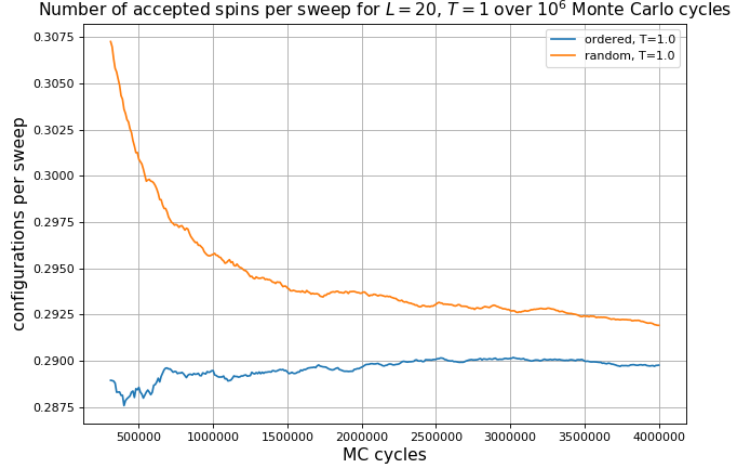


Figure 7: Average (over 10^4 cycles) number of accepted configurations per sweep for $T = 1$, $L = 20$, using both initial configurations

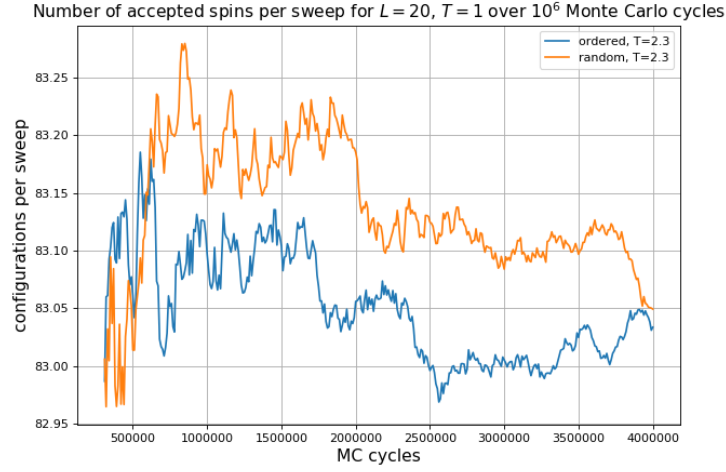


Figure 8: Average (over 10^4 cycles) number of accepted configurations per sweep for $T = 2.3$, $L = 20$, using both initial configurations

(calculated on the energy samplings).

Lastly, in order to compare the observations above with $\langle E \rangle$ for $T = 2.3$, a simulation using $L = 20$, $T = 2.3$ and

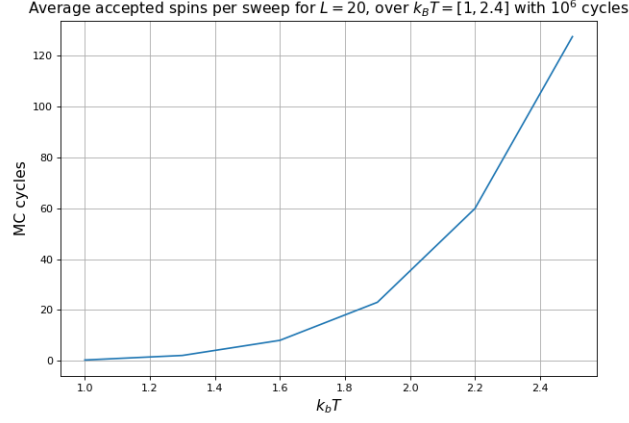


Figure 9: Average number of accepted configurations per sweep for $T = [1, 2.4]$ after eq. time with a resolution of $0.3k_B T$, $L = 20$, $1 \cdot 10^6$ cycles after eq. time ($3 \cdot 10^6$) per data point.

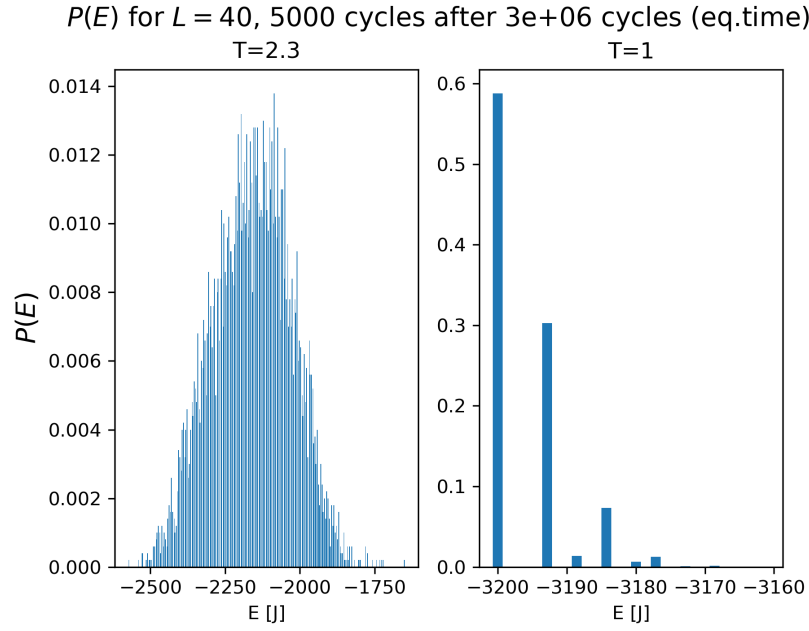


Figure 10: Probability distribution, $P(E)$ for $T = 2.3$ and $T = 1$ on a 40×40 lattice, based on samplings from $5 \cdot 10^3$ cycles after equilibrium time

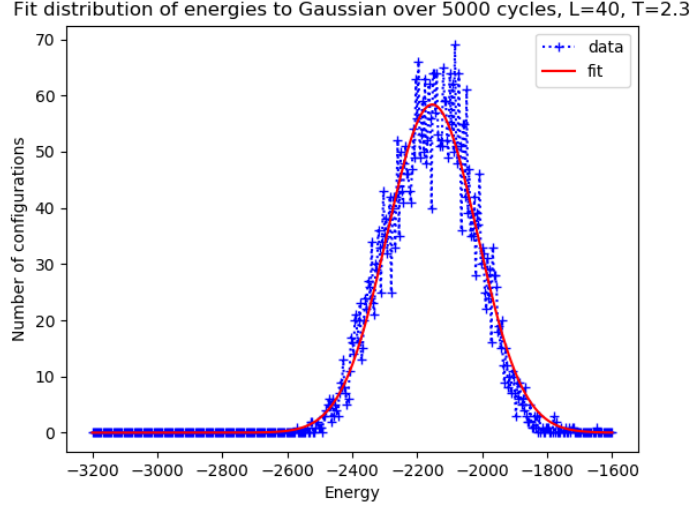


Figure 11: Energy sampling for $T = 2.3$ fit to Gaussian distribution

4.4 Estimating the Curie temperature

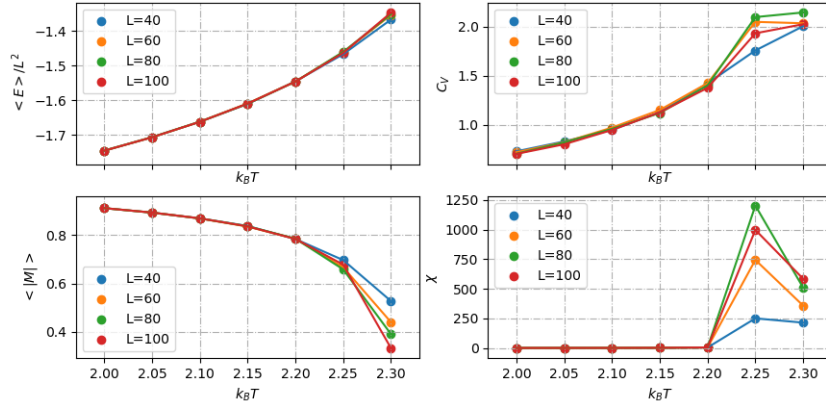


Figure 12: $\langle E \rangle, C_V, \langle |M| \rangle, \chi$ as functions of T , with $\Delta = 0.05$, for $L = 40, 60, 80, 100$ using $3.3 \cdot 10^6$ cycles per temperature, with $t_{eq} = 3 \cdot 10^6$.

Figure 12 shows a clear tendency for $\langle |M| \rangle$ to decrease towards as T increases, and appears to decrease faster for higher values of L around $T = 2.25$. Furthermore, χ increases drastically after $T = 2.20$, and again especially so for higher values of L , where $L = 80$ has the highest peak at $\chi \approx 1200$. More on

this under discussion of results. As has been observed previously, $\langle E \rangle$ increases with temperature, as does C_V , which for higher values of L increases more after $T \approx 2.2$. See [discussion of energy variance](#) for more on this.

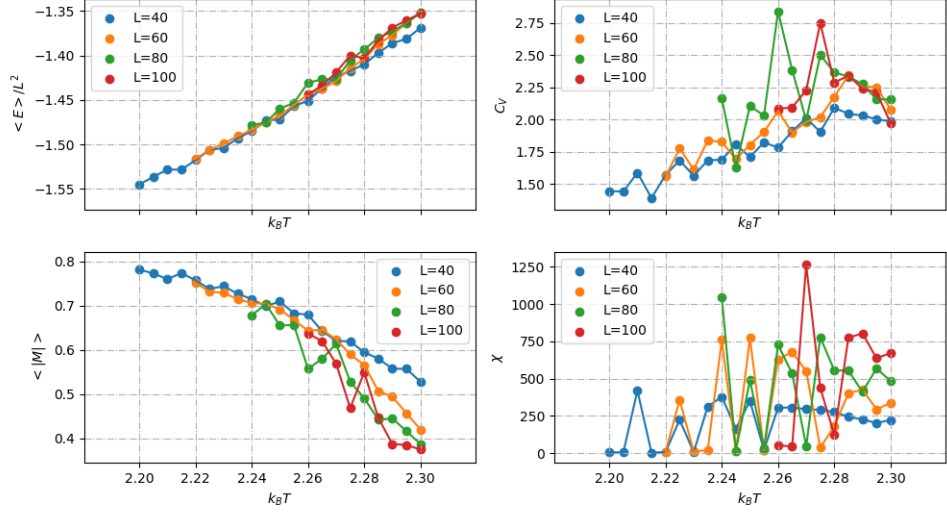


Figure 13: $\langle E \rangle, C_V, \langle |M| \rangle, \chi$ as functions of T , with $\Delta = 0.005$, for $L = 40, 60, 80, 100$ using $1.1 \cdot 10^6$ cycles per temperature, with $t_{eq} = 1 \cdot 10^6$.

Figure 13 shows the results for the second large lattice simulations on a narrow range of T , with higher resolution, albeit with a reduced number of cycles. There are significant fluctuations in both χ and $\langle |M| \rangle$, especially in terms of χ for $L = 80$ and 60 , and $\langle |M| \rangle$ for $L = 100$. Due to this, the following values of $T_C(L)$ are based on assumptions and should be recalculated for confirmation. See discussion of results.

Based on the expected behaviours of $\langle |M| \rangle, \chi$, and C_V near T_C , $T_C(L)$ for $L = 40, 60, 80, 100$ are estimated by eye, and presented in table 4. Solving (16) for T_C , and taking the average over the value corresponding to each $T_C(L)$ in the table yields $T_C = 2.2390 J/k_B$. More under discussion of results.

Table 4: By-eye estimates of $T_C(L)$

$T_C(40)$	$T_C(60)$	$T_C(80)$	$T_C(100)$
2.24	2.25	2.26	2.27

5 Discussion of results

5.1 Initial evaluation of Metropolis implementation

The initial tests of the algorithm implementation indicates that the program simulates the 2×2 lattice successfully. All parameters except C_V are within a relative tolerance of 10^{-3} from the analytical values after $3 \cdot 10^6$ cycles. The mean of C_V however is relatively inaccurate compared with the other values - whether this is due to some discrepancy in algorithm development, a consequence of the choice of mathematical model, or a statistical phenomenon is unclear.

After approximately $6 \cdot 10^6$ cycles, C_V appears to stabilize - albeit around a value 0.001 higher than the analytical value. It is not unlikely that such an offset is a consequence of summing up from the beginning of the simulation - which may lead to an accumulation of unrepresentative values during the first cycles - and may very well have affected all parameters to one degree or another. Increasing the total number of cycles will result in a gradual decrease of this offset. Another solution is to not record any mean values prior to the equilibrium time. In addition, a higher L is expected to increase stability of all expectation values after equilibrium time. Thus, despite the larger relative error in C_V for this number of cycles, the equilibrium time is initially estimated to $\sim 3 \cdot 10^6$ cycles, based on figure 1 and table 3 - pending further testing of the time evolution of the system.

5.2 Equilibrium time

C_V had a relative error 10 times larger than χ during the initial tests, and significantly stronger fluctuations after the estimated equilibrium time of $3 \cdot 10^6$. Comparison with analytical values for an $L = 20$ lattice is however not possible, or at least feasible, so evaluation relies on stability of mean and magnitude of fluctuations alone. This is also why the augmentation test was carried out using $T = 1$, as this temperature should have a relatively low variance. Upon examining C_V 's fluctuations for an $L = 20$ lattice, it appears that the initial equilibrium time estimation is sufficient with regards to variance for equilibrium cycles. Thus, $3 \cdot 10^6$ cycles is kept as the estimate for the number of cycles needed to obtain an equilibrium state.

For the comparison of initial spin configurations on equilibrium time, it is clear that in the case of $T = 1$ random initial configuration requires a significantly higher number of cycles to reach expectation values in the vicinity of those pertaining to an equilibrium state. On the other hand, this is not the case for $T = 2.3$ - where both configurations have approximately the same number of sweeps per cycle and convergence rate to $\langle E \rangle_{eq}$ and $\langle M \rangle_{eq}$. For $T = 1$, the two configurations are offset after $3 \cdot 10^6$ cycles, which is likely to be the result of the relatively high start values of the random configuration. This may however be overcome by discarding values generated prior to the equilibrium state. As

$T = 2.3$ is the highest temperature used in this project, the ordered initial spin configuration is maintained as the standard initialized configuration in this project. Lastly, the mean number configurations per sweep (after equilibrium time) increases exponentially with T , as is to be expected - a natural consequence of the sampling rule mentioned under [Equilibrium time in the Methods section](#).

5.3 Variance in energy

Based on the observations in Variance in energy under the Results section, it is evident that the energy is generally much higher for the $T = 2.3$ case. This fits well with earlier observed difference in $\langle E \rangle$ for the two temperatures based on figures 3 and 4 for the $L = 20$ lattice. The approximate ranges of values, $[-3200, -3180]$ and $[-2300, -1900]$ for $T = 1$ and $T = 2.3$, corresponds well to the simulation returns for σ_E - 5.47 J and 130.6 J, considering that 2σ should cover about .68 of the data points.

$T = 2.3$ has, as previously mentioned, a significantly larger variance in energy than $T = 1$. This is directly related to the already observed tendency for higher higher energies to accept a larger number of configurations, which means that a wider range of energies is stochastically feasible as the temperature increases. Lastly, the Gaussian distribution fit may indicate that the energy of the ferromagnet, using the Ising model, goes towards a Gaussian distribution for high temperatures. More testing is however needed in order establish this with any certainty.

5.4 Estimating the Curie temperature

As described under the presentation of results, after $T = 2.25$, a distinct decrease in $\langle |M| \rangle$ decreases, and a distinct increase in χ , may be observed. The fact that higher values of L exhibit this behaviour more strongly may indicate phase transitions in the range $T = [2.2, 2.3]$. χ spikes at approximately $T = 2.25$ for all values of L . However, this does not necessarily mean that $T_C \approx T = 2.25$, due to the temperature resolution of the graph ($\Delta T = 0.05$).

The results from the $\Delta t = 0.005$ simulations fluctuate more than expected. This is most likely due to t_{eq} being only $1 \cdot 10^6$ and the total number of cycles $1.1 \cdot 10^6$. This means that any conclusions drawn from the data will be speculative and prone to errors - a future rerun of the simulations with a high ΔT and $t_{eq} \geq 3 \cdot 10^6$ should be carried out in order to verify or correct the following assumptions:

Based on the estimated values of $T_C(L)$ for $L = 40, 60, 80, 100$, $T_C = 2.2390 J/k_B$, which is $0.0300 J/k_B$ from the analytical value. This is a significant deviation, and the estimated values for $T_C(L)$, on which the calculation is based, are highly speculative. Therefore, no conclusions on the Metropolis algorithm's ability to reproduce the analytical Curie temperature may be made, other than

that the simulations appear to show trends in $\langle|M|\rangle$, χ and C_V associated with the expected behaviour of the model near the Curie temperature.

6 Conclusions

This project concludes that the Metropolis algorithm may be used to simulate the ferromagnetic properties modelled by the Ising model. For an $L = 2$ lattice, three of four parameters ($\langle E \rangle$, $\langle|M|\rangle$, χ) are within a relative tolerance of 10^{-3} from the analytical values after $3 \cdot 10^6$ cycles. C_V on the other hand requires $6 \cdot 10^6$ cycles for sufficient stability in the $L = 2$ case. After $3 \cdot 10^6$ cycles on an $L = 20$ lattice however, also C_V exhibits sufficiently small fluctuations. Thus, the equilibrium time, t_{eq} , is established as $3 \cdot 10^6$, under the assumption that larger lattices do not decrease the stability of the mean. In addition, in order to remove initial expectation value offset, these values should only be sampled from cycles after t_{eq} .

For low temperatures, random initial spin configuration is concluded to result in higher stabilization time for mean values - thus ordered initial spin is to be preferred in general. The Metropolis algorithm implementation appears to produce some of the expected behaviour near the Curie temperature for lattices up to $L = 100$. Discrepancies in data resolution and number of cycles before and after t_{eq} means that no definite conclusions may be drawn with regards to applications in the study of phase transitions. However, this project finds that a temperature step of $\Delta T = 0.05$ is too large to properly evaluate program aptitude for the studies of phase transitions. A definite conclusion to this question may be obtained through re-evaluation of the program, using for example cluster computing.

References

- [1] Sands Feynman, Leighton. The feynman lectures on physics, 34: The magnetism of matter, 2013.
- [2] Sands Feynman, Leighton. The feynman lectures on physics, 36: Ferromagnetism, 2013.
- [3] Morten Hjorth-Jensen. Computational physics lectures: Statistical physics and the ising model, Aug 23 2017.
- [4] Morten Hjorth-Jensen. Repository containing material pertinent to fys3150 at the university of oslo, 2018.
- [5] Ross Moore. The ising model, 1999.
- [6] Computational Physics. Project 4 assignment paper, Fall 2018.
- [7] Conrad Sanderson and Ryan Curtin. Armadillo: a template-based c++ library for linear algebra., 2016.

- [8] Walter and Barkema. An introduction to monte carlo methods., 2015.