FYS3120 Classical Mechanics and Electrodynamics

Problem set 3

February 11, 2019

Problem 1 An object with mass m slides without friction on a plane inclined 30°. The plane is forced to move horizontally with a constant acceleration a. In this case a natural choice of generalized coordinate will be the displacement s of the object along the tilted surface. See Fig. 1 for an illustration.

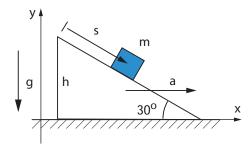


Figure 1: Motion on an inclined accelerated plane.

- a) Assume first the inclined plane to be at rest, with vanishing velocity and acceleration. Express the Cartesian coordinates x, y of the sliding object as functions of s. Find the Lagrangian expressed in terms of s and \dot{s} .
- $\bullet \ \ x = \frac{\sqrt{3}}{2}s$
- y = h s/2
- $K = \frac{1}{2}m\dot{s}^2$, V = mg(h-h-s/2), so $L = K-V = \frac{1}{2}m\dot{s}^2 mgh + mgs/2$
- **b)** Assume next the acceleration a to be constant and non-vanishing. Again find the Cartesian coordinates, and their time derivatives, expressed in terms of s and \dot{s} , and determine the Lagrangian.
 - $x = \frac{1}{2}at^2 + s\sqrt{3}/2, \dot{x} = at + \dot{s}\sqrt{3}/2$
 - $y = h s/2, \dot{y} = -\dot{s}/2$
- $K = \frac{1}{2}mv = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2) = \frac{1}{2}m(4a^2t^2 + \sqrt{3}at\dot{s} + \dot{s}^2), V = -mgh + mgs/2$, so $L = K V = \frac{1}{2}m(4a^2t^2 + \sqrt{3}at\dot{s} + \dot{s}^2) mgh + mgs/2$
- c) Find Lagrange's equation for the system, and solve the equation under the assumption that the body starts at time t=0 from the top of the inclined plane (s=0) with zero velocity relative to the plane.
- $\frac{d}{dt}(\frac{\partial L}{\partial \dot{q}_i}) \frac{\partial L}{\partial q_i} = 0 \rightarrow \frac{1}{2}m(\sqrt{3}a + 2\ddot{s}) mg/2 = 0 \rightarrow \ddot{s} = g \sqrt{3}a$

Problem 2 A rigid circular metal hoop rotates with constant angular velocity ω around an axis bisecting the hoop. A particle slides without friction along the hoop and there is no gravity. Use the angle θ with respect to the rotation axis as generalized coordinate (see Fig. 2).

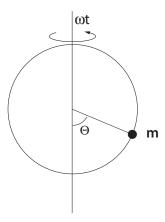


Figure 2: Rotating hoop.

- a) Find the Lagrangian expressed in terms of θ and $\dot{\theta}$, and derive Lagrange's equation for this variable.
- $K = \frac{1}{2}m(r^2\omega^2\sin^2\theta + \dot{\theta}^2)$
- V = 0
- $L = \frac{1}{2}m(r^2\omega^2\sin^2\theta + \dot{\theta}^2)$
- $\frac{d}{dt}\frac{\partial L}{\partial \dot{\theta}} \frac{\partial L}{\partial \theta} = m\ddot{\theta} mr^2\omega^2 sin(\theta)cos(\theta) = m\ddot{\theta} \frac{1}{2}mr^2\omega^2 sin(2\theta)$
- b) Show that the Lagrangian is the same as the Lagrangian of a particle moving in a time-independent, periodic potential $V(\theta)$, with two stable and two unstable equilibrium points (within a 2π interval).
 - If a particle of mass m and velocity $\dot{\theta}$, moves in a periodic potential $V(\theta)$ with two stable and two unstable equilibrium points on a 2π interval, it's kinetic energy may be written as $K=\frac{1}{2}m\dot{\theta}$, while it's potential energy may be written as $V=Asin^2(\theta)$. The Lagrangian is then $L=K-V=\frac{1}{2}m\dot{\theta}-Asin^2(\theta)$, where A is a constant. If $A=\frac{1}{2}mr^2\omega^2$, this formulation of the Lagrangian is the same as in the original problem.
- c) With θ_0 as one of the stable equilibrium points, introduce a small deviation, $\phi = \theta \theta_0$, and determine the small-angle form of the equation

of motion (keeping only the lowest order in θ and its derivative). What is the angular frequency of oscillations about the stationary point?

• Small angle $\phi \approx 0 \to \sin\phi \approx \phi$ (Taylor expansion lowest order and derivative), so: $\frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}} - \frac{\partial L}{\partial \phi} = m \ddot{\theta} - m r^2 \omega^2 \sin(\phi) \cos(\phi) \approx m \ddot{\theta} - 2\phi m r^2 \omega^2 \to \ddot{\theta} = 2\theta r^2 \omega^2$ Not sure about getting the angular freq from this. Solve as ODE then differentiate? Integrate directly? No matter which approach I use, the answer I get seems wrong.

Problem 3 Two bodies with the same mass, m, are connected with a massless rope through a small hole in a smooth horizontal plane. One body is moving on the plane, the other one is hanging at the end of the rope and can move vertically. At all instances the rope is tight. The acceleration due to gravity is g.

- a) Find Lagrange's equations of motion in polar coordinates (r, θ) .
- $K = m\dot{r}^2 + \frac{1}{2}mr^2\dot{\theta}^2, V = mgr \rightarrow L = m\dot{r}^2 + \frac{1}{2}mr^2\dot{\theta}^2 mgr$
- $\frac{dL}{dT}(\frac{\partial L}{\partial \dot{r}}) \frac{\partial L}{\partial r} = 2m\ddot{r} mr\dot{\theta}^2 + mg = 0 \rightarrow \ddot{r} = \frac{r}{2}\dot{\theta}^2 \frac{g}{2}$
- $\frac{dL}{dT}(\frac{\partial L}{\partial \dot{\theta}}) \frac{\partial L}{\partial \theta} = mr^2 \ddot{\theta} = 0 \rightarrow \dot{\theta} = constant$
- b) Reduce the equations of motion to a one dimensional problem in r and make a qualitative description of the motion. It can be helpful to solve the resulting differential equation numerically.
 - $\frac{\partial L}{\partial \theta} = 0$ means θ is a cycling coordinate. $\dot{\theta} = k/mr^2$, where k is a constant, so that $L(r,\dot{r}) = m\dot{r}^2 + \frac{1}{2}k^2/r^2 mgr$ and
 - $\frac{dL}{dT}(\frac{\partial L}{\partial \dot{r}}) \frac{\partial L}{\partial r} = 2m\ddot{r} + k^2/r + mg = 0 \rightarrow \ddot{r} = -\frac{k^2}{mr} \frac{g}{2}$.

Initially, r will decrease slowly while the ball on the plate is rotating with increasing speed. Eventually, r will decrease faster and faster, while speeding up the rotation.

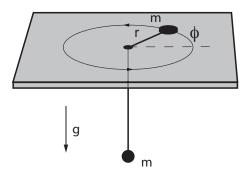


Figure 3: Two bodies connected by a rope through a small hole.