# FYS3120 Classical Mechanics and Electrodynamics

Problem set 2

January 30, 2019

## **Problem 1**

#### 1.a)

 $\frac{\partial L}{\partial t}$  is the expression for the explicit time dependence of the Lagrangian with respect to time - where all other variables than time is fixed.  $\frac{dL}{dt}$  is, in contrast, the total (explicit and implicit) dependence of the Lagrangian on time, which includes the dependence of all variables in the Lagrangian with respect to time - for example how a spatial coordinate (in the Lagrangian) varies with respect to time.

1.b)

# **Problem 2**

#### 2.a)

 $q = \{q_i\}_{i=1}^{i=2}, q_1 = \theta, q_2 = \phi$ , where  $\theta$  is the angle between the uppermost rod (rod 1) and the vertical plane, and  $\phi$  is the angle between the other rod (rod 2) and the horizontal plane.

Taking the moment of inertia of rod 1 about it's fixed end,  $I_1=ml^2/3$ , the speed of the center of mass of rod 2,  $v_2$ , and the moment of inertia about the center of mass of rod 2,  $I_{2,CM}$ :  $K=\frac{1}{2}I_1\dot{\theta}^2+\frac{1}{2}mv_2^2+\frac{1}{2}I_{2,CM}\dot{\phi}^2=\frac{1}{6}ml^2\dot{\theta}^2+\frac{3}{6}ml^2\dot{\theta}^2+\frac{1}{24}ml^2\dot{\phi}^2=\frac{2}{3}ml^2\dot{\theta}^2+\frac{1}{24}ml^2\dot{\phi}^2$ .

Taking the distance from the fixed surface to the center of mass of each rod,  $y=-l\cos\theta$ :  $V=mgy_1+mgy_2=-mg\frac{l}{2}cos\theta-mglcos\theta=-\frac{3}{2}mglcos\theta$ . Thus:  $L=K-V=\frac{2}{3}ml^2\dot{\theta}^2+\frac{1}{24}ml^2\dot{\phi}^2+\frac{3}{2}mglcos\theta$ 

### 2.b)

Lagrange's equations for the system:

$$\begin{split} \frac{dL}{dt}(\frac{\partial L}{\partial \dot{q}_i}) - \frac{\partial L}{\partial q_i} &= 0 \implies \\ \frac{dL}{dt}(\frac{\partial L}{\partial \dot{\theta}}) - \frac{\partial L}{\partial \theta} &= \frac{4}{3}ml^2\ddot{\theta} + \frac{3}{2}mglsin\theta = 0 \\ \frac{dL}{dt}(\frac{\partial L}{\partial \dot{\phi}}) - \frac{\partial L}{\partial \phi} &= \frac{1}{12}ml^2\ddot{\phi} = 0 \end{split}$$

For small oscillations about equilibrium position ( $\theta = 0$ ),  $\sin \theta \approx \theta$ , so:

$$\frac{4}{3}ml^2\ddot{\theta} + \frac{3}{2}mglsin\theta \approx \frac{4}{3}ml^2\ddot{\theta} + \frac{3}{2}mgl\theta = 0 \implies \\ \ddot{\theta}(\theta) = -\frac{9}{8}\frac{g}{l}\theta \implies \dot{\theta} = -\frac{9}{8}\frac{g}{l}\theta t + c, c = \theta_0 = 0 \rightarrow \dot{\theta} = -\frac{9}{8}\frac{g}{l}\theta t$$

# Problem 3

3.a)