

In search of **structure** in the age of **scale**

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Two stories of deep learning

A story of structure

ICML 2016

Group Equivariant Convolutional Networks

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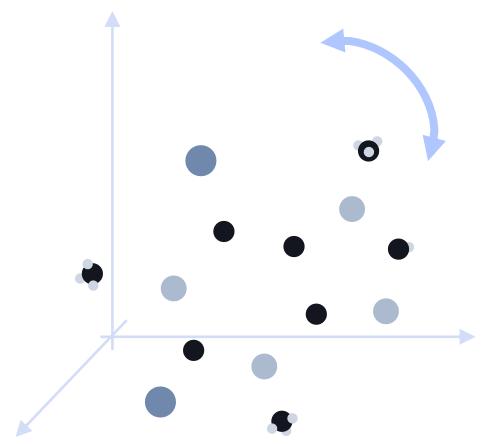
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Abstract

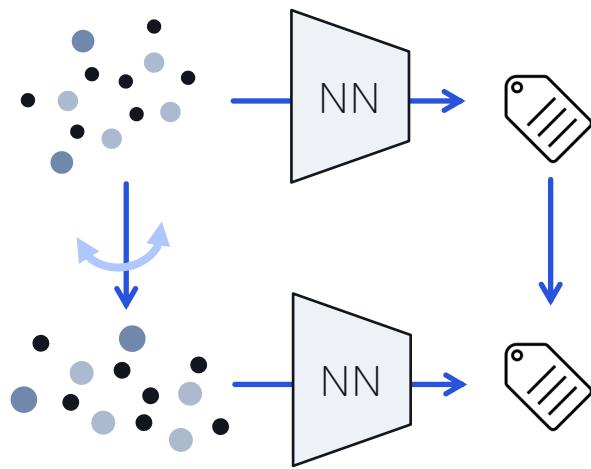
We introduce Group equivariant Convolutional Neural Networks (G-CNNs), a natural generalization of convolutional neural networks that reduces sample complexity by exploiting symmetries. G-CNNs use G-convolutions, a new type of layer that enjoys a substantially higher degree of weight sharing than regular convolution layers. G-convolutions increase the expressive capacity of the network without increasing the number of parameters. Group convolution layers are easy to use and can be implemented with negligible computational overhead for discrete groups generated by translations, reflections and rotations. G-CNNs achieve state of the art results on CIFAR10 and rotated MNIST.

Convolution layers can be used effectively in a *deep* network because all the layers in such a network are *translation equivariant*: shifting the image and then feeding it through a number of layers is the same as feeding the original image through the same layers and then shifting the resulting feature maps (at least up to edge-effects). In other words, the symmetry (translation) is preserved by each layer, which makes it possible to exploit it not just in the first, but also in higher layers of the network.

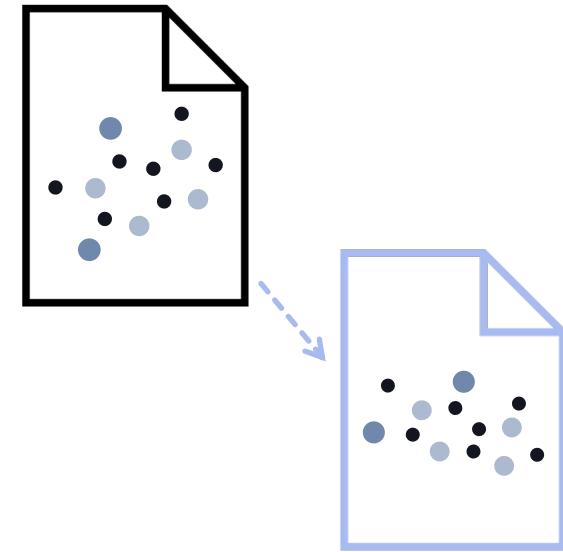
In this paper we show how convolutional networks can be generalized to exploit larger groups of symmetries, including rotations and reflections. The notion of equivariance is key to this generalization, so in section 2 we will discuss this concept and its role in deep representation learning. After discussing related work in section 3, we recall a number of mathematical concepts in section 4 that allow us to define and analyze G-convolutions in more detail.



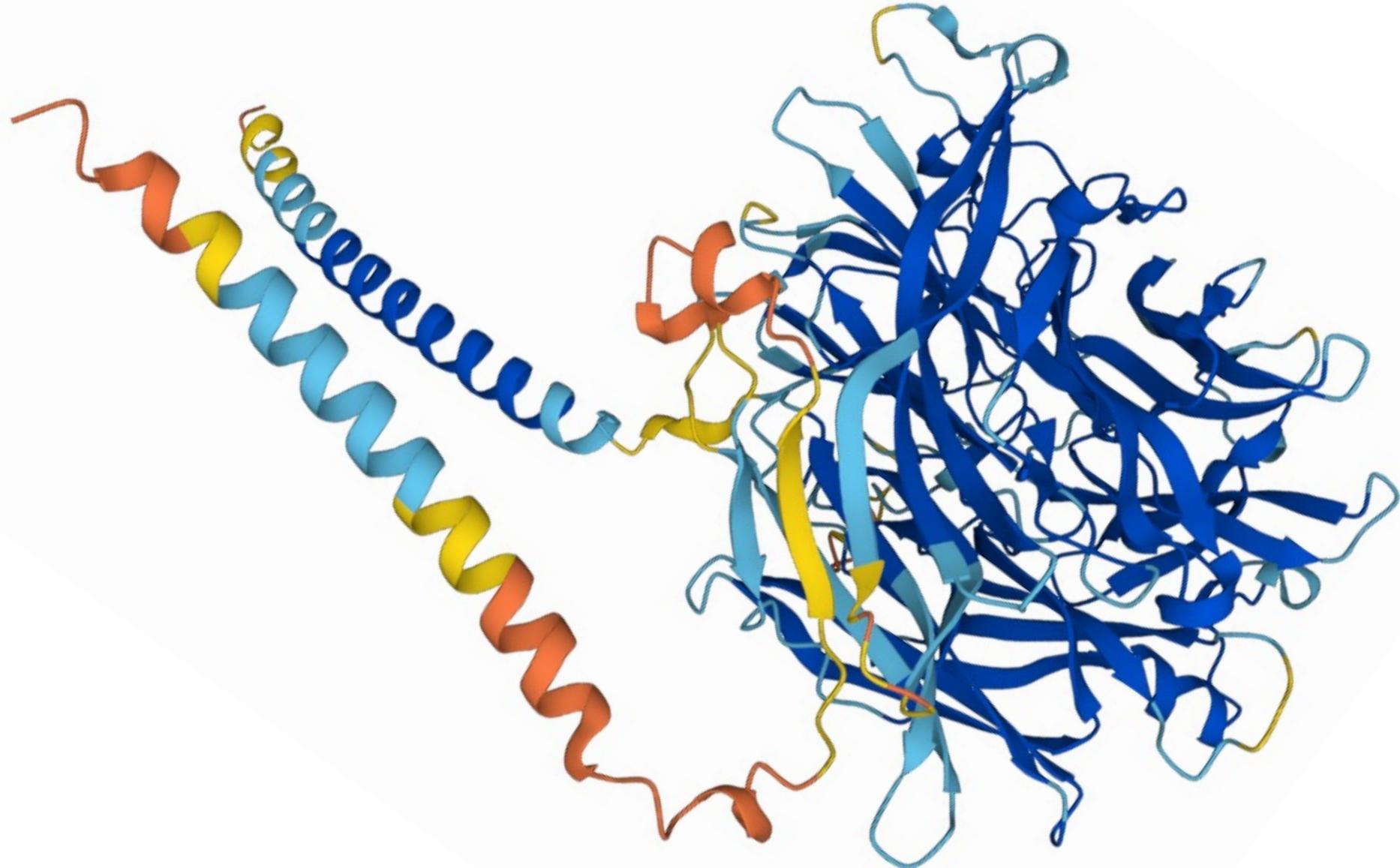
1. Identify structure:
spaces and symmetries



2. Design architectures that take
structure into account
through equivariance / weight sharing



3. Fill in the gaps from data



A story of scale

NeurIPS 2017

Attention Is All You Need

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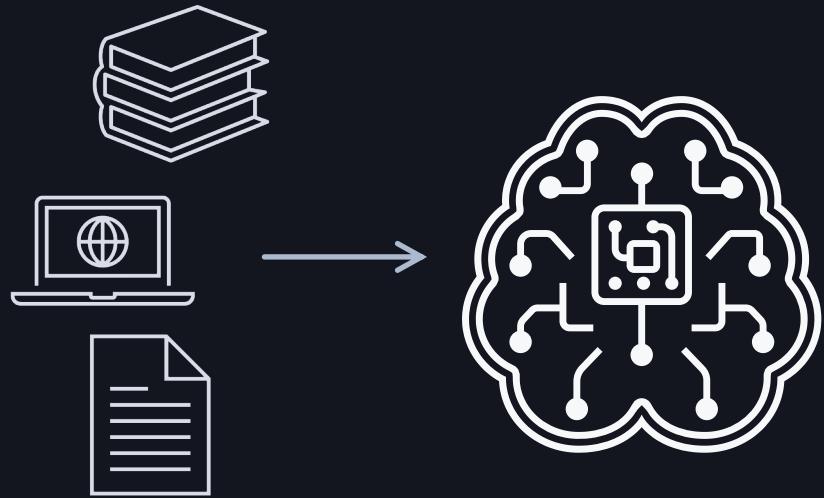
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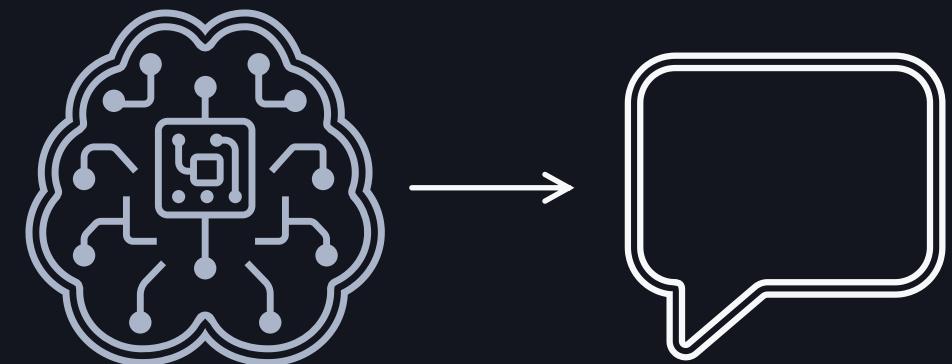
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Abstract

The dominant sequence transduction models are based on complex recurrent or convolutional neural networks that include an encoder and a decoder. The best performing models also connect the encoder and decoder through an attention mechanism. We propose a new simple network architecture, the Transformer, based solely on attention mechanisms, dispensing with recurrence and convolutions entirely. Experiments on two machine translation tasks show these models to be superior in quality while being more parallelizable and requiring significantly less time to train. Our model achieves 28.4 BLEU on the WMT 2014 English-to-German translation task, improving over the existing best results, including ensembles, by over 2 BLEU. On the WMT 2014 English-to-French translation task,



1. Train big transformer on lots of data



2. Finetune for specific problems

Do strong inductive biases
have a future?

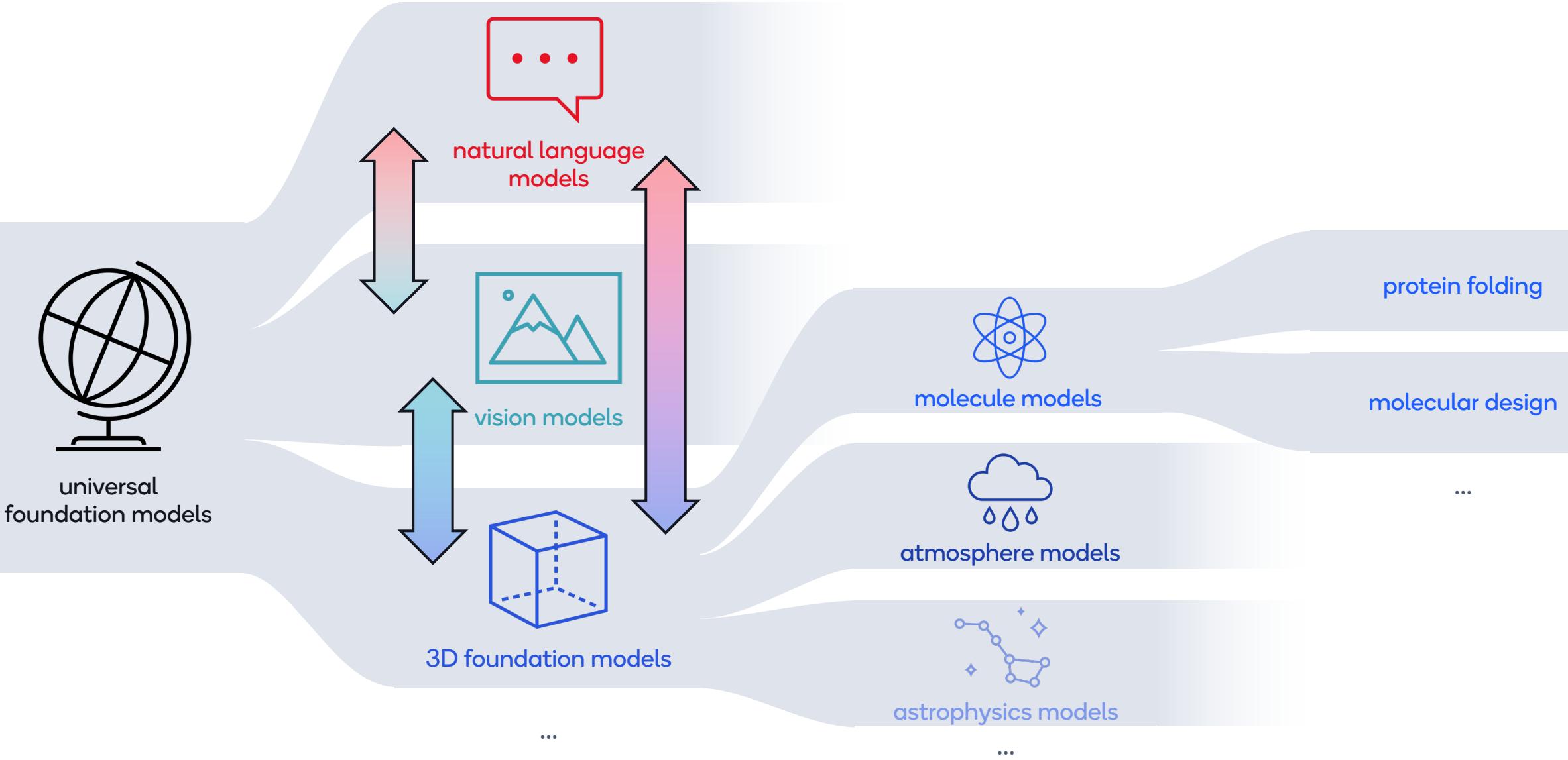
- There is **no clear evidence that LLMs can solve geometric problems** (yet?)
- **Strong inductive biases*** can help even when training on **100ks of samples** (AlphaFold, OpenCatalyst)
*Transformers have inductive biases, too – but here we mean domain-specific structure like equivariance
- Foundation models with strong inductive biases have not been studied in depth
- It's not a dichotomy! Let's find out what happens when we **combine scale and structure?**

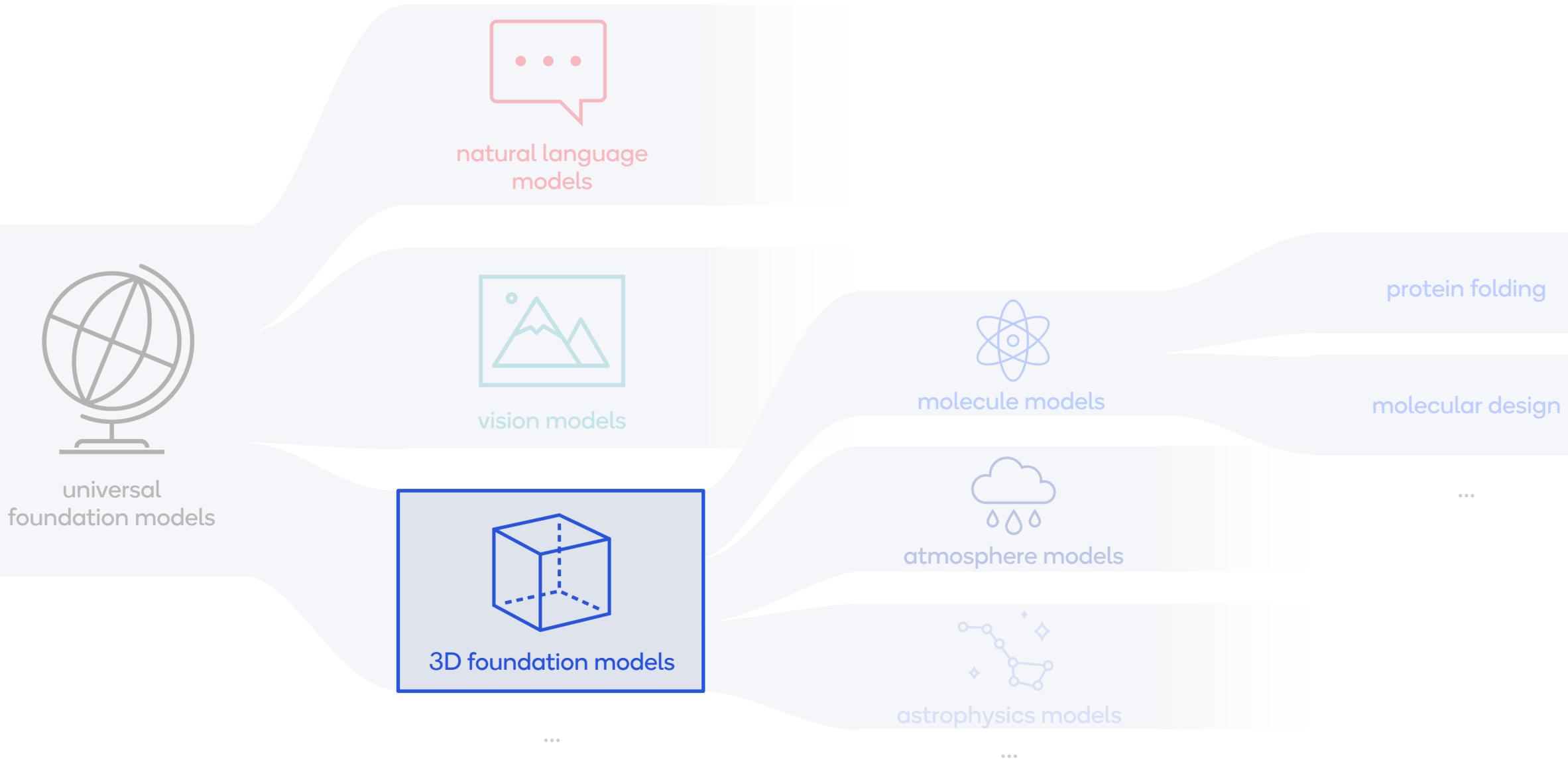
Ali Borji et al, "A Categorical Archive of ChatGPT Failures", arXiv:2302.03494

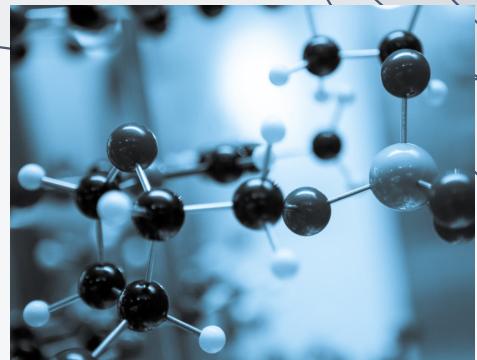
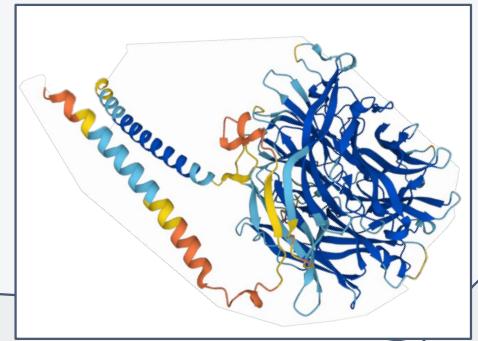
Nouha Dziri et al, "Faith and Fate: Limits of Transformers on Compositionality", arXiv: 2305.18654;

Karthik Valmeekam et al, "Large Language Models Still Can't Plan (A Benchmark for LLMs on Planning and Reasoning about Change)", arXiv:2206.10498

Lawrence Zitnick et al, "An Introduction to Electrocatalyst Design using Machine Learning for Renewable Energy Storage", arXiv:2010.09435

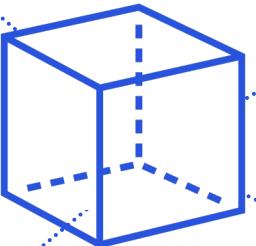
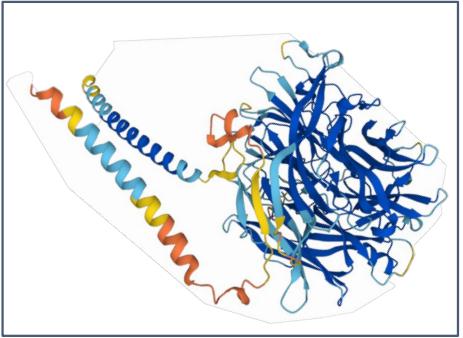




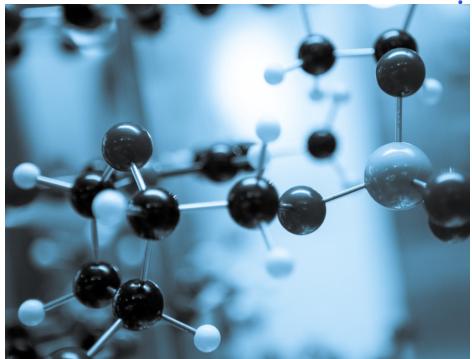


3D space
Positions
Distances
Orientations
Movement
Distance-dependent forces
Collisions
Spatial symmetries





One foundation model
for any 3D system?



Foundation model checklist

In language / vision foundation models

- Lots of **data** the internet
- Universal **representations** tokenizers and embeddings
- A scalable, expressive **architecture** transformers
- Self-supervised **training** protocol max likelihood, classification
- Multiple **downstream tasks** with shared structure chatbots, ...
- Bonus points for **predictable scaling** neural scaling laws

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Geometric foundation model

- the data is out there (?)
- ?
- ?
- ?
- ?
- ?

GATr: a versatile architecture for geometric data



=

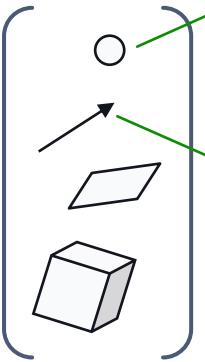
Geometric **A**lgebra
Transformer



Geometric Algebra
Transformer

16-dim vector space

=



Embeddings for
primitive 3D objects
(points, planes, ...)

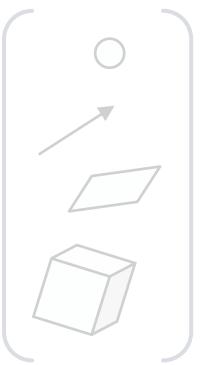
Embeddings for 3D
transformations
(shifts, rotations, ...)

Geometric algebra
representations



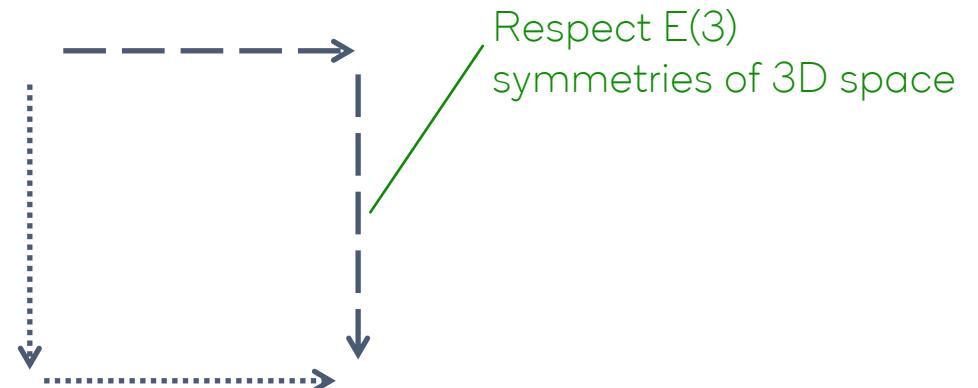
Geometric Algebra
Transformer

=



Geometric algebra
representations

+

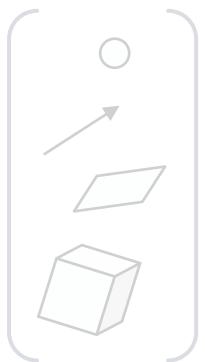


Equivariant
layers



Geometric **A**lgebra
Transformer

=



Geometric algebra
representations

+

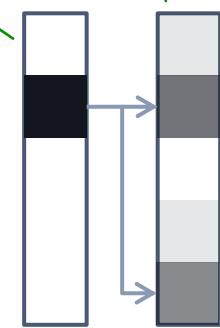
Scalable to thousands of tokens
(unlike many previous geometric
architectures)



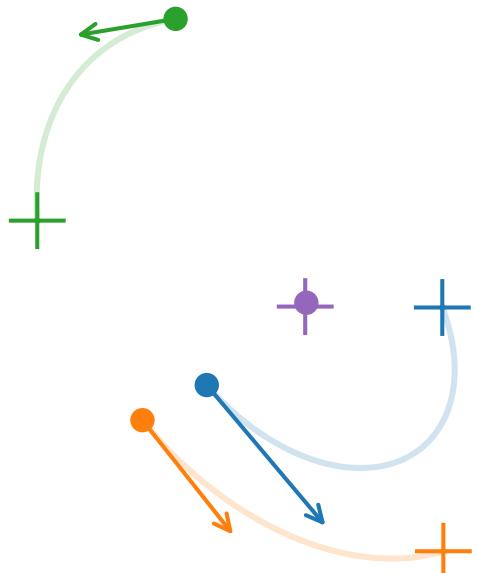
+

Transformer
architecture

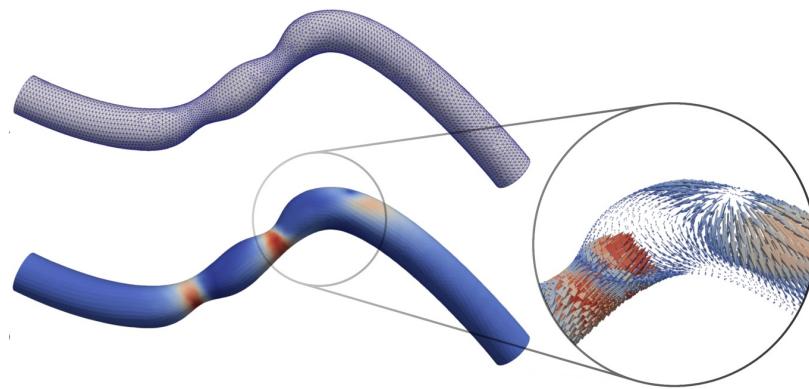
Expressive and versatile



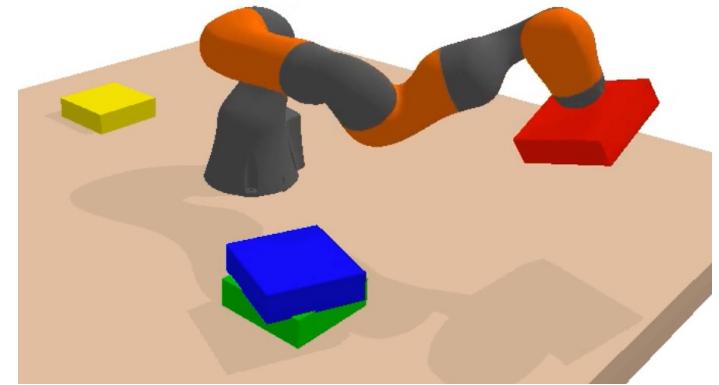
GATr outperforms baselines across domains



n-body modeling



predicting wall shear stress
in arteries



robotic motion planning

Towards geometric foundation models?

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- ?
- ?
- ?

Scaling works.

Structure works.

Structure at scale is exciting, and there's lots we don't know yet.



Pim de Haan



Sönke Behrends



Taco Cohen



Ekdeep Singh Lubana

Geometric Algebra Transformer

Johann Brehmer*, Pim de Haan*, Sönke Behrends, Taco Cohen *equal contribution

NeurIPS 2023, [arXiv:2305.18415](https://arxiv.org/abs/2305.18415)

Surveying the Swamp: Choosing a Geometric Algebra for your Equivariant Transformer

Pim de Haan, Taco Cohen, Johann Brehmer

Under review

A Guided Tour to the Plane-Based Geometric Algebra PGA

Leo Dorst, Steven De Keninck
bivector.net/PGA4CS.pdf

Clifford group equivariant neural networks

David Ruhe, Johannes Brandstetter, Patrick Forré
NeurIPS 2023, [arXiv:2305.11141](https://arxiv.org/abs/2305.11141)

Language models in molecular discovery

Nikita Janakarajan, Tim Erdmann, Sarath Swaminathan, Teodoro Laino, Jannis Born
[arXiv:2309.16235](https://arxiv.org/abs/2309.16235)

Multiple Physics Pretraining for Physical Surrogate Models

Michael McCabe et al.
[arXiv:2310.02994](https://arxiv.org/abs/2310.02994)

xVal: A Continuous Number Encoding for Large Language Models

Siavash Golkar et al.
[arXiv:2310.02989](https://arxiv.org/abs/2310.02989)

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Thank you



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