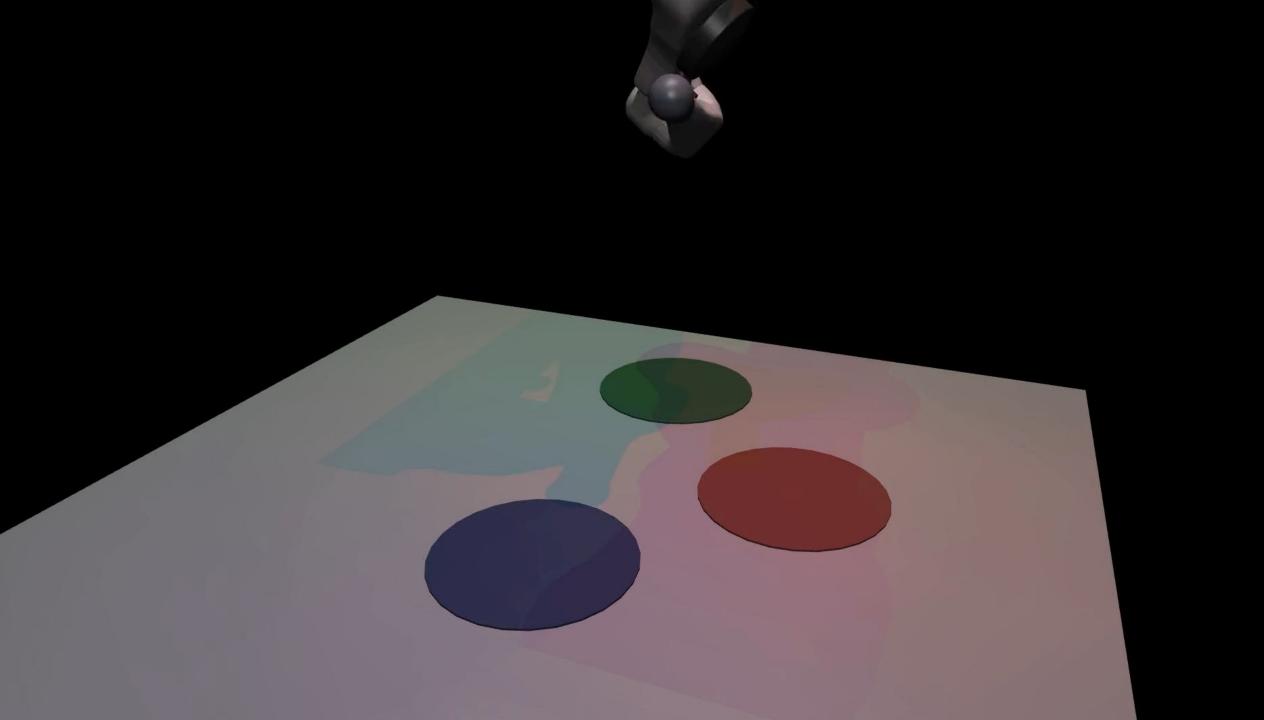
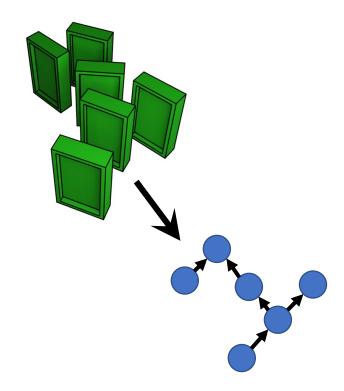


Weakly supervised causal representation learning

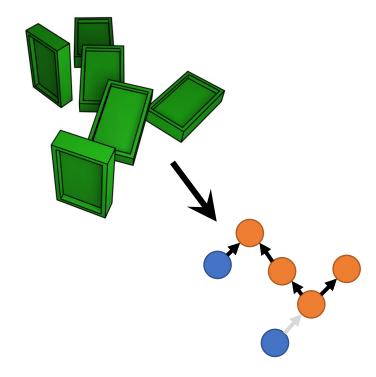
Johann Brehmer

Qualcomm Technologies Netherlands B. V.

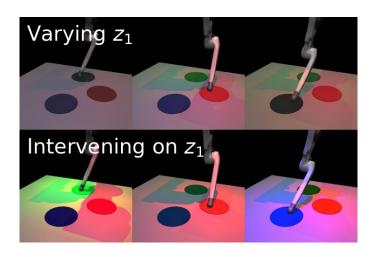




Can we **learn causal variables & causal structure from pixels**, without labels?



We prove: this is possible with weak supervision, when observing effects of interventions

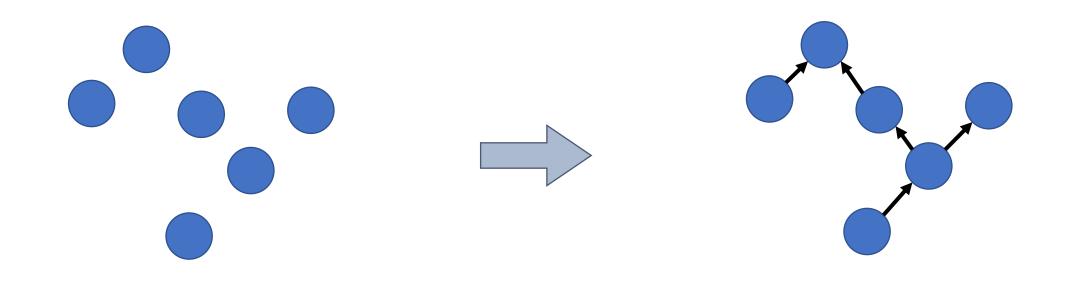


In practice, implicit latent causal models can identify the causal structure in image datasets

Problem

Can we learn causal representations from pixels?

Causal discovery / inference

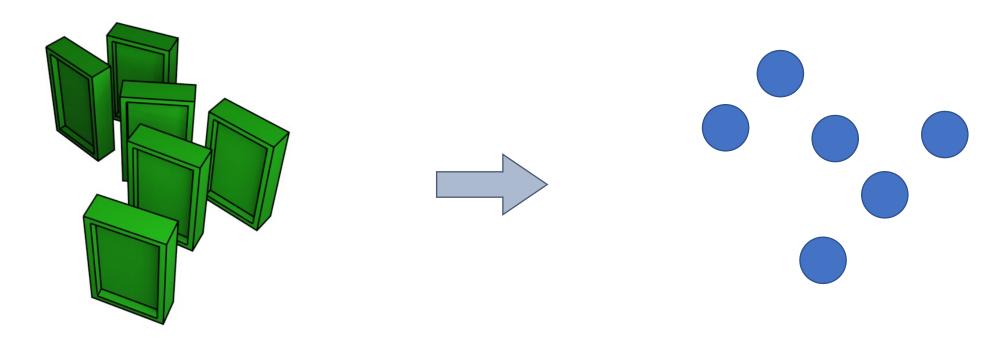


Given: dataset in terms of high-level causal variables

Goal: learn the causal structure

But: what if we don't observe the causal variables?

Disentangled representation learning

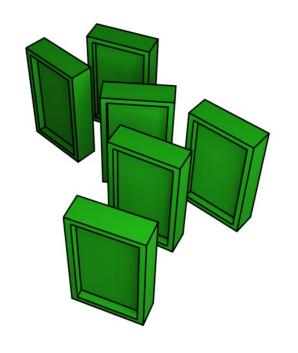


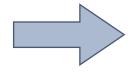
Given: **low-level, unstructured data representation**(e.g. pixels)

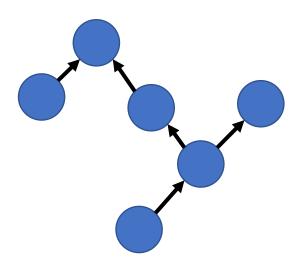
Goal: learn encoder to
high-level variables
(e.g. object positions, states, ...),
usually assuming independence

But: useful high-level concepts are rarely independent

Causal representation learning



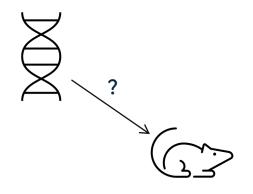


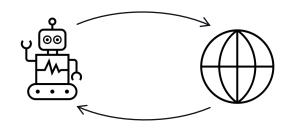


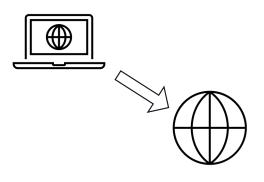
Given: low-level, unstructured data representation (e.g. pixels)

Goal: learn encoder to
high-level variables
(e.g. object positions, states, ...)
and their relations /
causal structure

Why learn causal representations?







Causal structure may be of **scientific interest**

Causal representations are **abstractions** that may be **useful for planning**

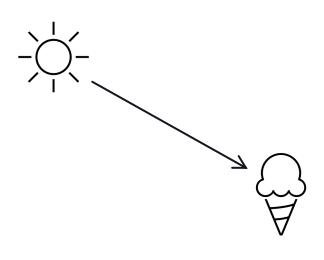
Causal models may be more **robust to changes**

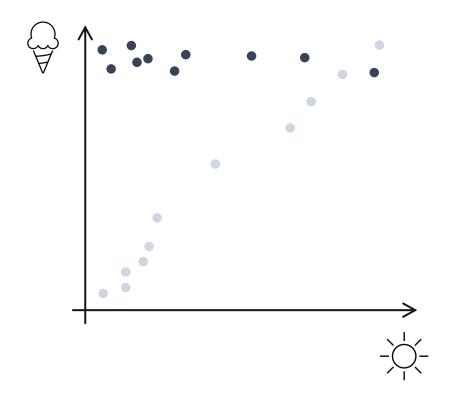
Arguably, these potential benefits have not yet been clearly demonstrated

Background

Causality and identifiability

Causality



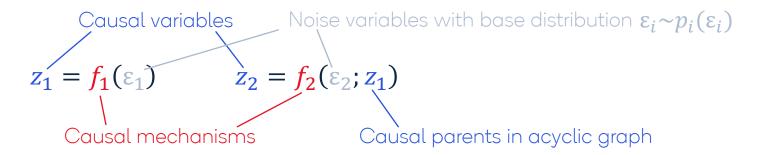


Semantically, causal models label relations between random variables as **cause-effect relations**

Functionally, causal models describe **probability distributions and how they change** under changing conditions

Structural causal models (SCMs)

• SCM:



Solution:

$$z = s(\epsilon) \Rightarrow z \sim p_z(z)$$
Solution function
(= successively applying causal mechanisms)

Observational distribution

Interventions:

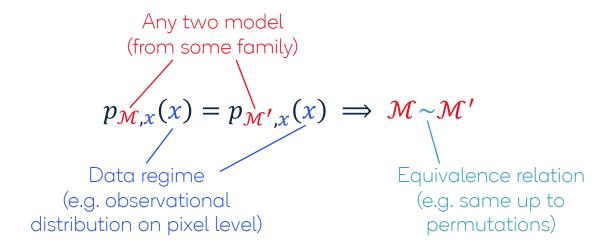
$$f_i(\varepsilon_i; z_{\text{parents}}) \to \tilde{f}_i(\varepsilon_i)$$
 $\Rightarrow z \sim \tilde{p}_z^i(z)$

New mechanism

(perfect intervention: no parents)

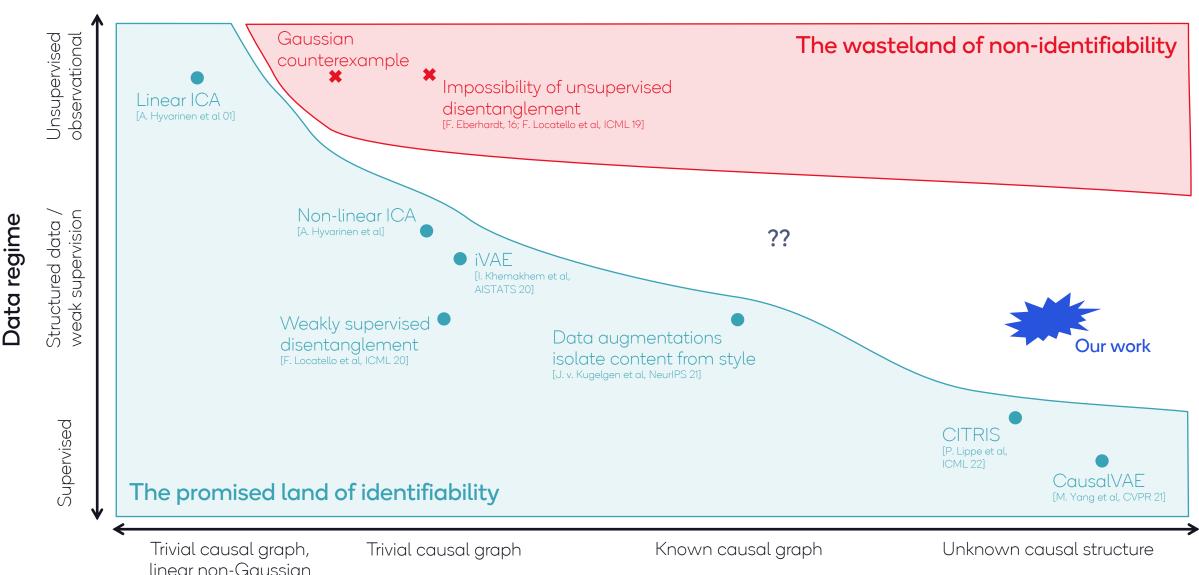
Identifiability

ullet An representation / SCM ${\mathcal M}$ is **identifiable** if



- Identifiability means we can **find ground-truth causal structure** through maximum-likelihood training
 - if it is within the specified model family
 - up to the equivalence relation
 - in the limit of infinite data
 - assuming perfect training

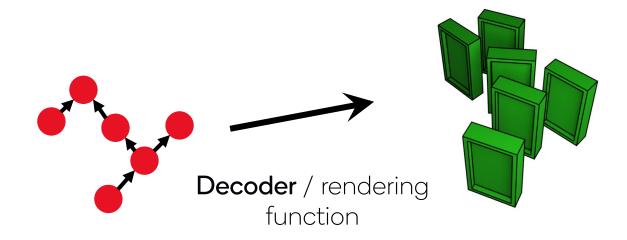
When are causal representations are identifiable?



Theory

Causal representations can be identified from weak supervision

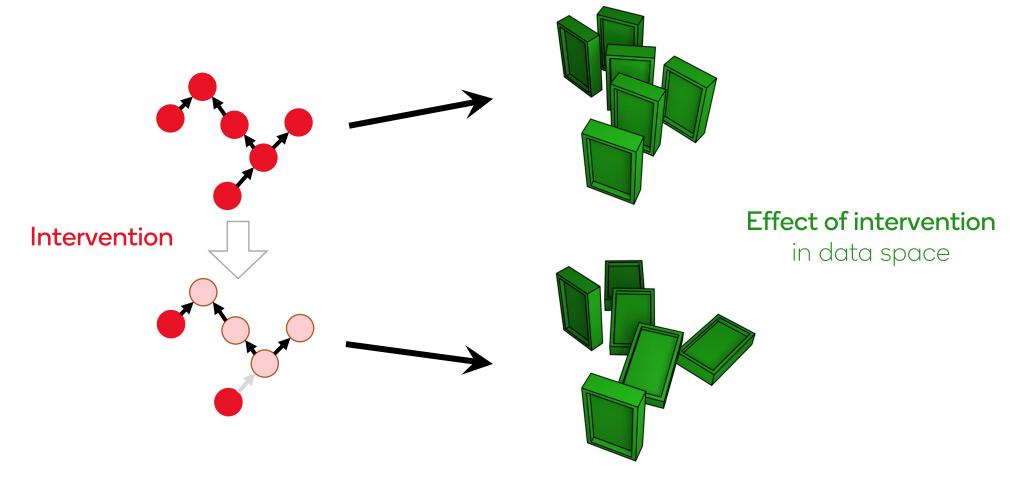
Latent causal model



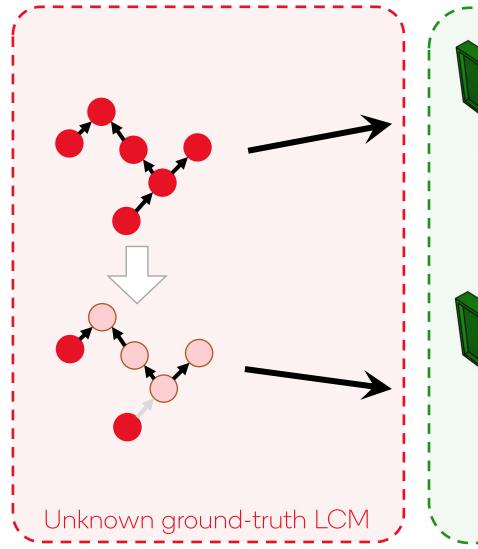
High-level variables with a structural causal model between them

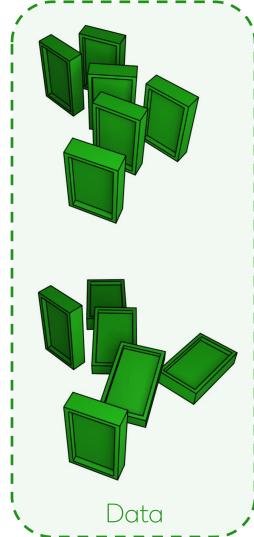
Low-level data (pixels)

Interventions



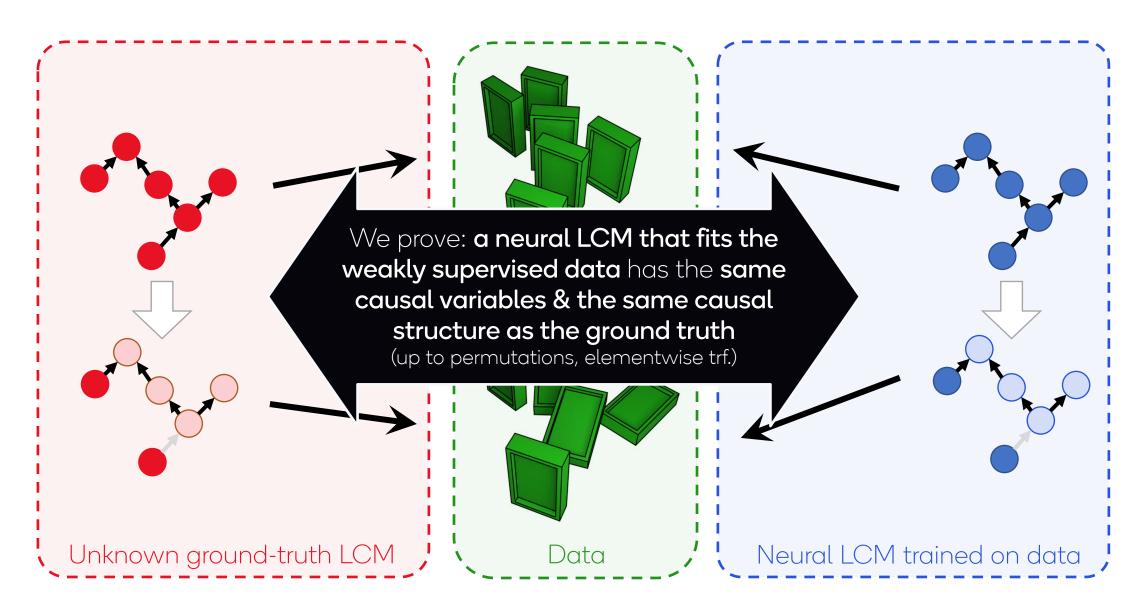
Weakly supervised data setting





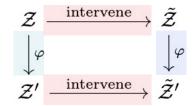
- We assume access to data pairs of the system before and after interventions
 - Equivalent to counterfactuals
 - Causal abstraction of time-series data
- Otherwise, **no labels**
 - Only pixel-level data is observed
 - Intervention targets are unknown

Identifiability theorem

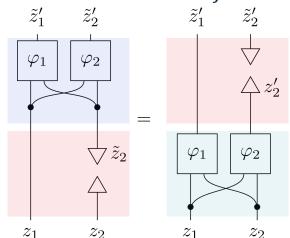


Proof sketch

- 1. Consider two LCMs with causal variables z and z', both matching the data. Define $\varphi: z \to z'$.
- 2. Interventions commute with φ :



3. We assume perfect interventions. Then then \tilde{z}_i' is independent of z_i . For 2 variables:



- 4. We assume \mathbb{R} -valued variables. Statistical independence then implies functional independence. Thus, $\varphi_i(z_i, z_j)$ must be constant in z_j .
- 5. Since this holds for any i, φ must be a permutation plus elementwise transformations.
- 6. Finally, we can show that the causal graphs and intervention targets in the two models are consistent with this transformation.
- 7. Thus the two models are isomorphic.

Assumptions

Assumption

Weakly supervised data is available

Causal variables are \mathbb{R} -valued

Causal mechanisms are diffeomorphic

No hidden confounders

Decoder is deterministic

Interventions are perfect

(Post-intervention values of intervention targets are independent of pre-intervention state)

Interventions are complete

(The dataset contains interventions on any single causal variable)

Possible relaxation

Maybe (work in progress)

Maybe (work in progress)

Difficult

Difficult

Plausible (as in iVAE)

Difficult (counterexamples)

Relaxation to n-target interventions plausible (incomplete interventions → partial identifiability)

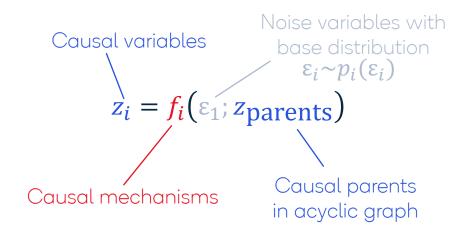
Practice

Implicit is better than explicit

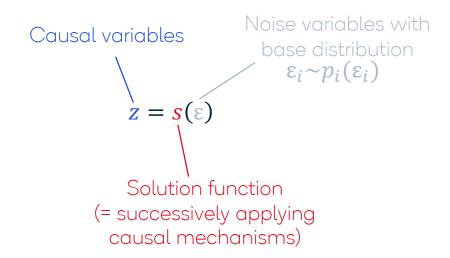
Explicit and implicit representations of causal structure

Explicit representation

through graph & causal mechanisms:

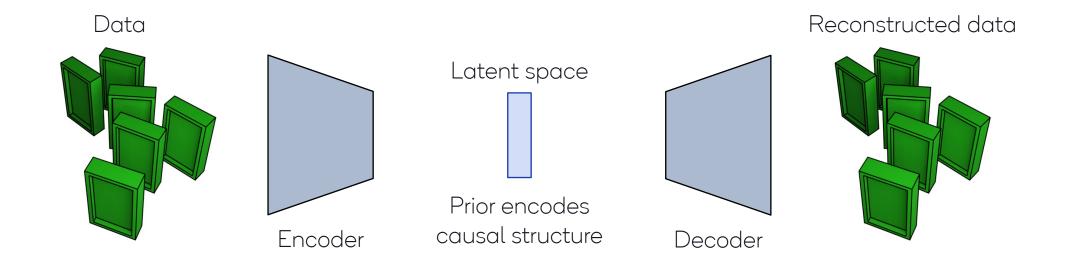


Implicit representation through solution function:

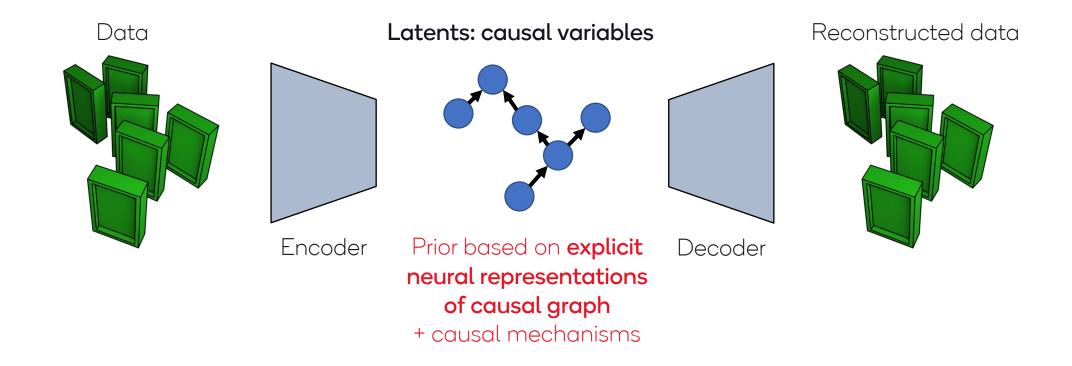


Under our assumptions, explicit and implicit representation **contain the same information**

Operationalizing latent causal models



Explicit latent causal models



Explicit latent causal models in practice



 \Longrightarrow Easy to learn graph given representations



Easy to learn representations given graph

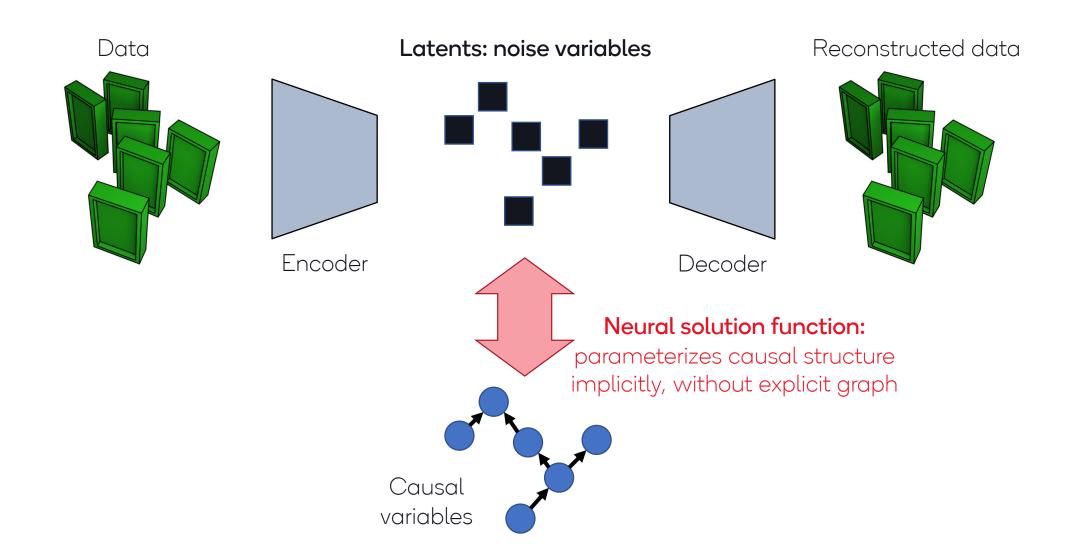


+ () Difficult to learn graph and representation simultaneously

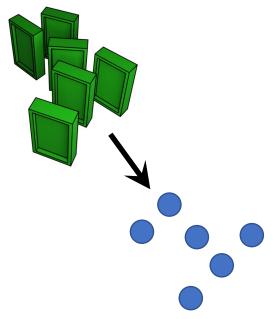
(Evidence for local minima in the loss landscape corresponding to wrongly oriented graph edges)

⇒ don't learn explicit graphs if you don't have to

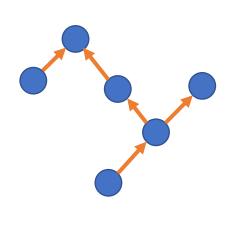
Implicit latent causal models



What can you do with ILCMs?

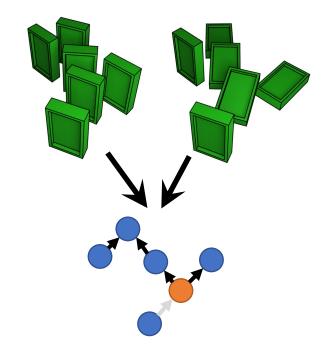


Map pixels to causal variables

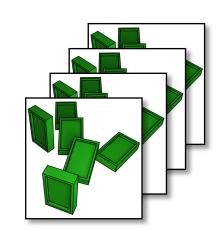


Find the causal graph

- ILCM-E: with off-theshelf causal discovery algorithm ENCO
- ILCM-H: with our new heuristic



Infer interventions from data pairs

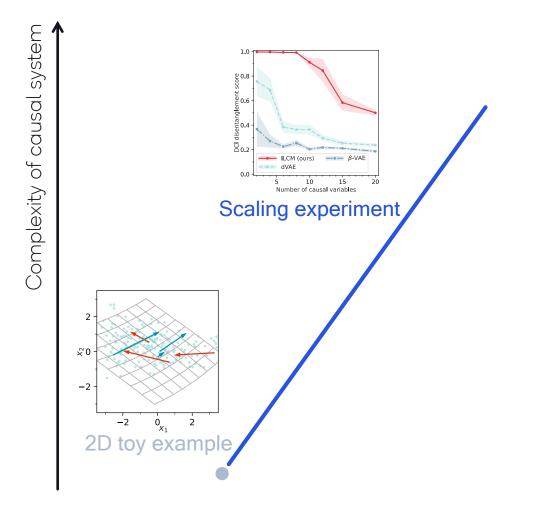


Generate observational, interventional, and counterfactual data

Experiments

Things work, mostly

Experiments

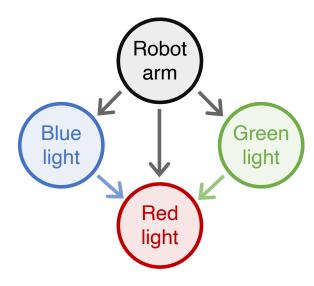


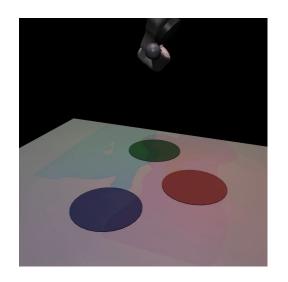




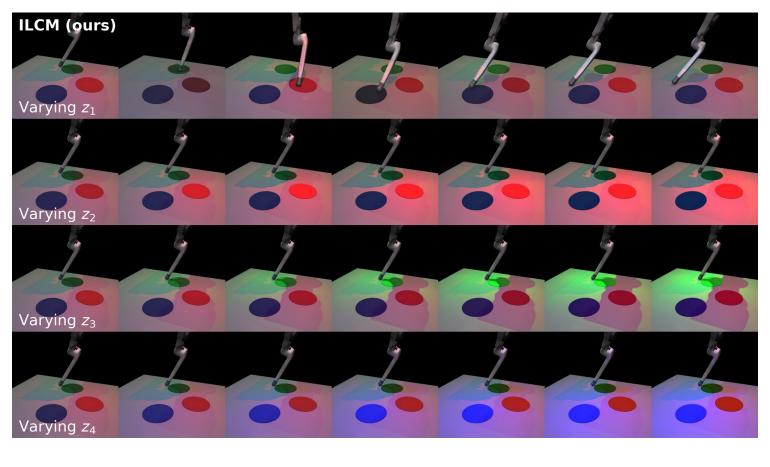
CausalCircuit

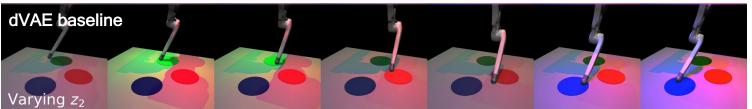
- New dataset with more intuitive causal structure
- Robot arm interacts with touch-sensitive lights, which are connected with a circuit
 - Robot arm movement based on inverse kinematic model
 - Physics + rendering with MuJoCo
 - 4 continuous causal variables: robot arm restricted to 1D arc + 3 light states
 - 512x512 images from fixed camera position
- ILCMs are trained on pre- and post-intervention data



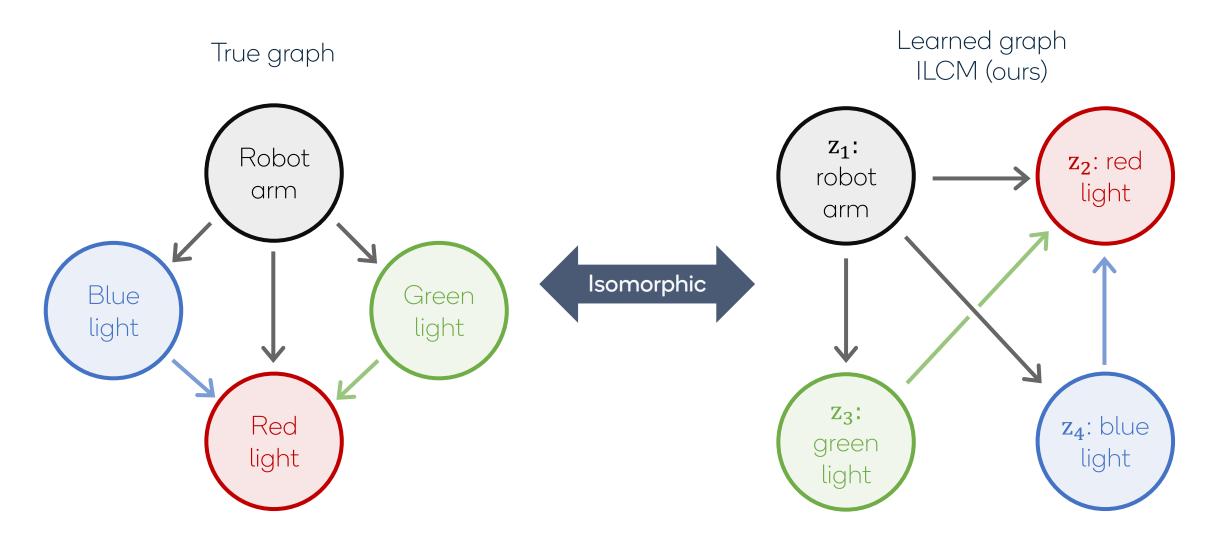


LCMs disentangle the causal variables



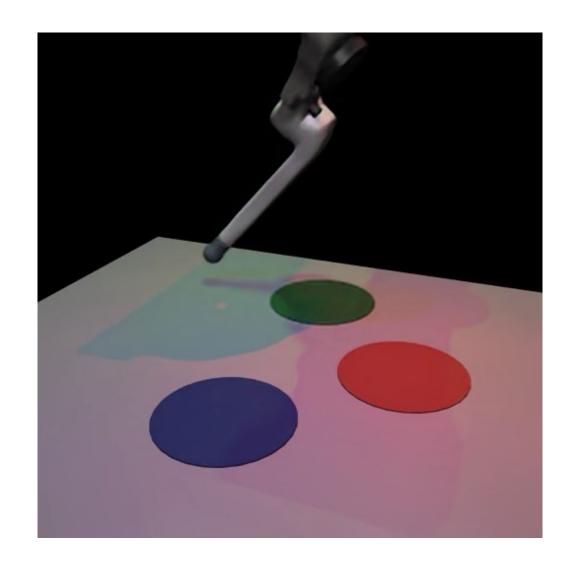


LCMs learn the correct graph



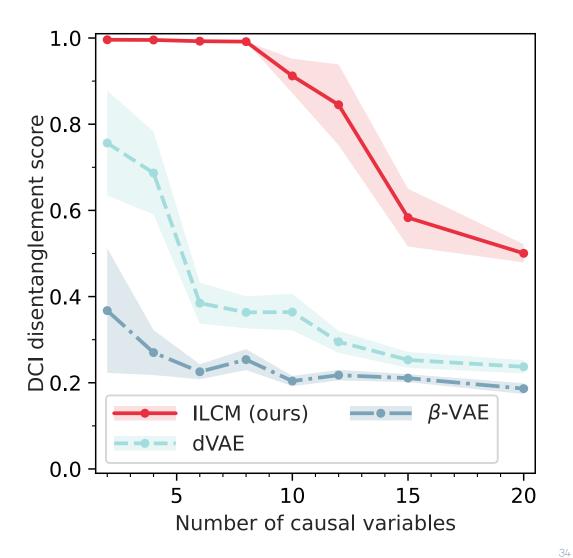
ILCMs let us reason causally

ILCM samples, **intervening** on a single latent (including causal effects)



Do ILCMs scale?

- Toy experiment:
 - n causal variables
 - linear causal effects
 - SO(n) decoder
- ILCM results robust up to ~10 variables without additional tuning



Outlook

Towards useful causal representation learning

A long way to go

Where we are

Where we need to get

Identifiability theorems

Demonstrate usefulness on downstream tasks

Pre- & post-intervention data

Realistic data regimes:

observational & interventional data, video data, ...

God-given interventions

Learning intervention policies

Fixed causal variables

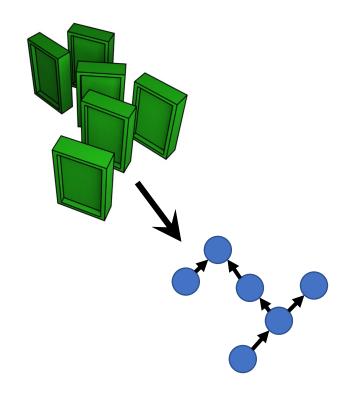
Variable scene composition

Strict **DAG-based causality**

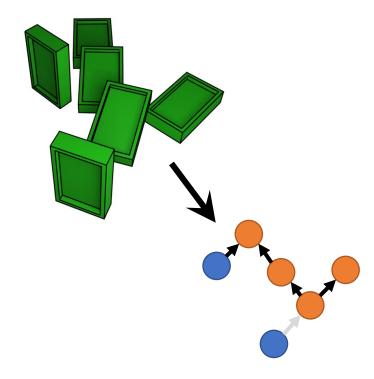
Weaker relational structures

Toy experiments (up to O(10) variables)

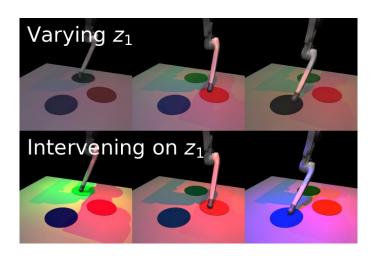
Realistic experiments



Can we **learn causal variables** & causal structure from pixels, without labels?

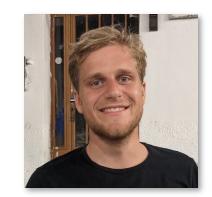


We prove: this is possible with weak supervision, when observing effects of interventions

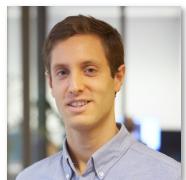


In practice, implicit latent causal models can identify the causal structure in image datasets

Weakly supervised causal representation learning JB, Pim de Haan, Phillip Lippe, Taco Cohen NeurIPS 2022 arXiv:2203.16437







Pim de Haan

Phillip Lippe

Taco Cohen

Towards causal representation learning

Bernhard Schölkopf, Francesco Locatello, Stefan Bauer, Nan Rosemary Ke, Nal Kalchbrenner, Anirudh Goyal, Yoshua Bengio IEEE Advances in Machine Learning and Deep Neural Networks 2021 arXiv:2102.11107

Weakly-supervised disentanglement without compromises

Francesco Locatello, Ben Poole, Gunnar Rätsch, Bernhard Schölkopf, Olivier Bachem, Michael Tschannen ICML 2020 arXiv:2002.02886

Self-supervised learning with data augmentations provably isolates content from style

Julius von Kügelgen, Yash Sharma, Luigi Gresele, Wieland Brendel, Bernhard Schölkopf, Michel Besserve, Francesco Locatello NeurlPS 2021 arXiv:2106.04619

CITRIS: Causal identifiability from temporal intervened sequences
Phillip Lippe, Sara Magliacane, Sindy Löwe, Yuki M. Asano, Taco
Cohen, Efstratios Gavves
ICML 2022
arXiv:2202.03169

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