

#### **Statistical Machine Learning**

Lecture 2 - Linear regression, regularization



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# Summary of Lecture 1 (I/III)

#### What is this course about? Supervised machine learning

In one sentence:

Methods for automatically learning (training, estimating, ...) a model for the relationship between

- the input x, and
- the output y

from observed training data

$$\mathcal{T} := \{(y_1, \mathbf{x}_1), (y_2, \mathbf{x}_2), \dots, (y_n, \mathbf{x}_n)\}.$$



#### Summary of Lecture 1 (II/III)

#### Regression vs. classification

- Numerical variables take on numerical values (real numbers, integer values, . . . ).
- Categorical variables take on values in one of K distinct classes,
   e.g. "true or false", "disease type A, B or C".

**Regression** is when the output y is numerical.

**Classification** is when the output y is categorical.



#### **Summary of Lecture 1 (II/III)**

#### What maths do we need.

- Calculus Finding a parameter which minimizes the distance between two points.
- Matrix algebra For keeping track of sum of squares.
- Probability theory Estimating paramaters. Normal distribution important

One key idea that brings these together is maximum likelihood. Finding the model that is maximally likely (closest to data).



#### Where are we now?



#### Outline – Lecture 2

Aim: To introduce linear regression and its regularized version.

#### **Outline:**

- 1. Summary of Lecture 1
- 2. Linear regression models
- 3. Maximum likelihood and least squares
- 4. Regularization
  - Ridge regression
  - LASSO

Linear regression is the foundation of statistics and (supervised) machine learning.



#### The course book

We have developed this course over the last 4 years.

A book based on these notes will soon be published as a textbook with Cambridge University Press.

Please read in parallel to your studies.

Book website:

smlbook.org

Help us by reporting errors via practical GitHub interface:

qithub.com/uu-sml/sml-book-page/issues



### Regression



- Input variable X
- Output variable Y

**Regression:** learning a model explaining Y from X, when Y is numerical.

$$Y = f(X; \beta) + \epsilon$$

 $\beta$  are the **parameters** of the model

 $(Y \text{ categorical} \rightarrow \text{classification})$ 



#### Numerical or categorical?

17.31 kg, 22.37 kg, 51.34 kg 1 = brown hair, 2 = red hair, 3 = blonde hair Adenine, Thymine, Cytosine, Guanine 1 bike, 2 bikes, 5 bikes



#### Numerical or categorical?

17.31 kg, 22.37 kg, 51.34 kg 1 = brown hair, 2 = red hair, 3 = blonde hair Adenine, Thymine, Cytosine, Guanine 1 bike, 2 bikes, 5 bikes Numerical



#### Numerical or categorical?

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Numerical Categorical



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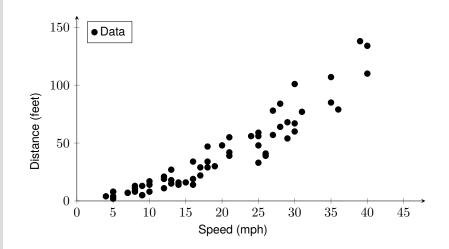
Numerical

Categorical output variable?  $\rightarrow$  classification. (But can be done with regression!)

Categorical input variable? Still regression!

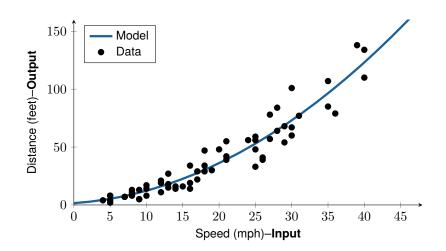


## Regression example: car stopping distances



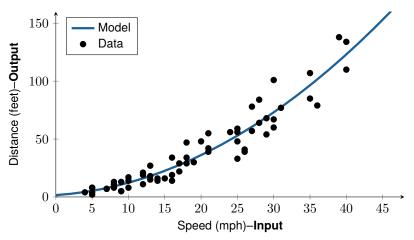


# Regression example: car stopping distances





### Regression example: car stopping distances



(in fact a linear regression model with nonlinear transformation of the input variables)



#### Regression example: Alpha Go zero





### Regression example: Alpha Go zero



- Input: State of the game ( $19 \times 19$  grid, either black, white or blank)
- Output: Probability for the current player to win the game
- + reinforcement learning

Silver et al. Mastering the game of Go with deep neural networks and tree search, Nature 529, 484-489, 2016.





### Regression example: Alpha Go zero





- Input: State of the game ( $19 \times 19$  grid, either black, white or blank)
- Output: Probability for the current player to win the game
- + reinforcement learning

Silver et al. Mastering the game of Go with deep neural networks and tree search, *Nature* 529, 484–489, 2016.

- Input: Same
- Output: Probability for the current player to win the game and what move to make

Silver et al. **Mastering the game of Go without human knowledge**, *Nature* 550, 354–359, 2017.

Silver et al. A general reinforcement learning algorithm that masters chess, shogi, and Go through self-play, *Science*, 362(6419): 1140–1144, 2018.



### **Linear regression**



"Linear regression = Regression with a linear model",

Output Y is linear combination of k inputs  $X_1, \ldots, X_k$  plus some noise/error  $\epsilon$ ,

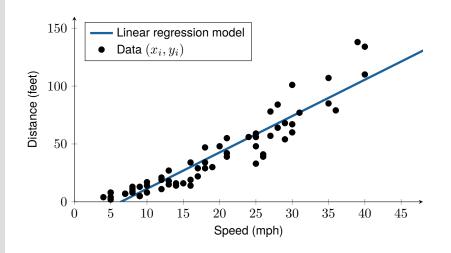
$$Y = \underbrace{\beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k}_{f(X;\beta)} + \epsilon.$$

Workflow (for most methods, not only linear regression):

- 1. Learn/train/estimate model from training data  $\mathcal{T}$ : find  $\widehat{\beta}_0, \widehat{\beta}_1, \dots, \widehat{\beta}_k$
- 2. Predict output for new test input using the model  $\widehat{Y} = \widehat{\beta}_0 + \widehat{\beta}_1 X_1 + \widehat{\beta}_2 X_2 + \cdots + \widehat{\beta}_k X_k$

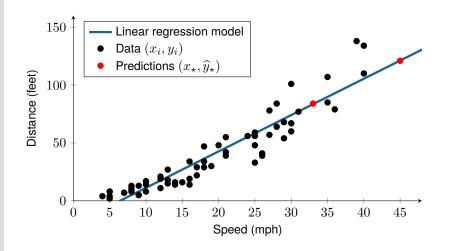


## Linear regression (k = 1)





## Linear regression (k = 1)





### Learning the model from data



Linear regression model:

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_k X_k + \epsilon$$

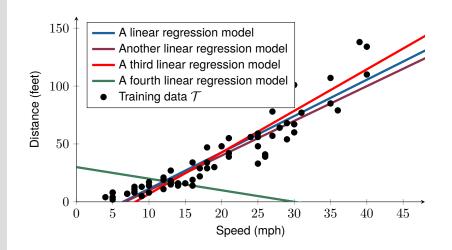
How to choose  $\beta_0, \beta_1, \dots, \beta_k$  (= $\beta$ , column vector)?

Use training data  $\mathcal{T} = \{(y_i, x_i)\}_{i=1}^n!$ 

$$x_i = \begin{bmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_t \end{bmatrix}, \quad \mathbf{X} = \begin{bmatrix} 1 & -x_1^\mathsf{T} - \\ 1 & -x_2^\mathsf{T} - \\ \vdots & \vdots \\ 1 & -x^\mathsf{T} - \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_t \end{bmatrix}.$$

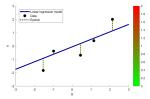


#### What is a good model?



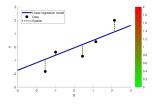


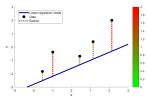
Learning a model from data is a matter of looking at the errors  $\varepsilon!$ 

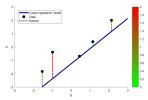




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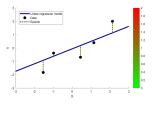


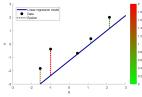


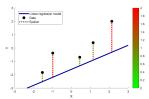


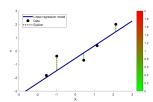


Learning a model from data is a matter of looking at the errors  $\varepsilon!$ 



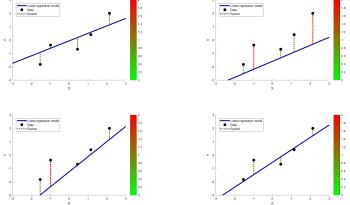








Learning a model from data is a matter of looking at the errors  $\varepsilon!$ 



**Maximum likelihood**: Think of  $\varepsilon$  (dotted) as random variables, and **choose the model** (solid) **such that the resulting**  $\varepsilon$  **are as likely as possible**.



#### Linear regression model in matrix form

Recall our linear regression model:

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}, \qquad \boldsymbol{\varepsilon} \sim \mathcal{N}(0, \sigma_{\varepsilon}^2 I).$$

Assumptions (for now):

- 1. y observed **random** variable.
- 2.  $\beta$  unknown **deterministic** variable.
- X known deterministic variable.
- 4.  $\varepsilon$  unknown random variable.
- 5.  $\sigma_{\varepsilon}$  unknown/known **deterministic** variable.





Using the maximum likelihood principle

$$\widehat{\beta} = \underset{\beta}{\operatorname{argmax}} \ P(\mathbf{y} \,|\, \mathbf{X}; \beta)$$

and assuming  $\epsilon \sim \mathcal{N}(0,\sigma_\epsilon^2)$  independently for each data point i

$$\Rightarrow P(y_i|x_i;\beta) = \frac{1}{\sqrt{2\pi\sigma_{\epsilon}^2}} \exp\left(-\frac{1}{2\sigma_{\epsilon}^2}(\beta_0 + \beta_1 x_{i1} + \dots + \beta_k x_{ip} - y_i)^2\right)$$
$$\Rightarrow P(\mathbf{y}|\mathbf{X};\beta) = \prod_{i=1}^n P(y_i|x_i;\beta) \propto \exp\left(-\frac{1}{2\sigma_{\epsilon}^2} \sum_{i=1}^n (\beta_0 + \dots + \beta_k x_{ip} - y_i)^2\right)$$

$$\Rightarrow \widehat{\beta} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^{n} (\beta_0 + \beta_1 x_{i1} + \dots + \beta_k x_{ip} - y_i)^2 = \underset{\beta}{\operatorname{argmin}} \ \underline{\|\mathbf{X}\beta - \mathbf{y}\|_2^2} \ ,$$

Loss function induced by maximum likelihood

the least squares problem is achieved.



### Least squares in matrix form

The least squares problem

$$\widehat{\beta} = \underset{\beta}{\operatorname{argmin}} \|\mathbf{X}\beta - \mathbf{y}\|_2^2$$



#### Least squares in matrix form

The least squares problem

$$V(\beta) = \|\mathbf{X}\beta - \mathbf{y}\|_2^2 = \beta^\mathsf{T} \mathbf{X}^\mathsf{T} \mathbf{X}\beta - 2\mathbf{y}^\mathsf{T} \mathbf{X}\beta + \mathbf{y}^\mathsf{T} \mathbf{y}$$

Minimize by differentiating and setting

$$\frac{\partial V(\beta)}{\partial \beta} = 2\mathbf{X}^\mathsf{T} \mathbf{X} \beta - 2\mathbf{X}^\mathsf{T} \mathbf{y}$$

Therefore,

$$\mathbf{X}^\mathsf{T}\mathbf{X}\widehat{\boldsymbol{\beta}} = \mathbf{X}^\mathsf{T}\mathbf{y}$$



#### Least squares in matrix form

The least squares problem

$$\widehat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \|\mathbf{X}\boldsymbol{\beta} - \mathbf{y}\|_2^2$$

is solved by the normal equations

$$\widehat{\beta} = \left( \mathbf{X}^\mathsf{T} \mathbf{X} \right)^{-1} \mathbf{X}^\mathsf{T} \mathbf{y}.$$

Remember (from lecture 1)  $\mathbf{X}^T\mathbf{X}$  is like sum of squares (similar to co-variances of input variables) and  $\mathbf{X}^T\mathbf{y}$  is similar to co-variance between input and output.

For k=1:

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x})((y_i - \bar{y}))}{\sum_{i=1}^n (x_i - \bar{x})^2}$$



# Linear regression: the key concepts

#### The linear regression model

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + \varepsilon$$

#### Maximum likelihood

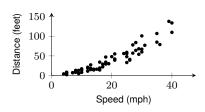
$$\varepsilon \sim \mathcal{N}(0, \sigma_{\varepsilon}^2)$$
 iid

**Our first** learning tool



### **Example**

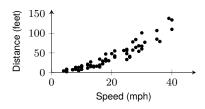
- $x = \mathsf{Speed}$
- y = Distance





- x = Speed
- y = Distance

$$y = \beta_0 + \beta_1 x + \varepsilon, \ \varepsilon \sim \mathcal{N}(0, \sigma_{\varepsilon}^2)$$



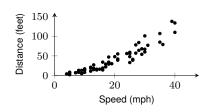


- x = Speed
- y = Distance

$$y = \beta_0 + \beta_1 x + \varepsilon, \ \varepsilon \sim \mathcal{N}(0, \sigma_{\varepsilon}^2)$$

$$\beta = \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix}$$

$$\mathbf{X} = \begin{bmatrix} 1 & 4 \\ 1 & 5 \\ 1 & 5 \\ 1 & 5 \\ 1 & 5 \\ 1 & 7 \\ 1 & 7 \\ 1 & 8 \\ \vdots & \vdots \\ 1 & 39 \\ 1 & 39 \\ 1 & 40 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 4 \\ 2 \\ 4 \\ 8 \\ 8 \\ 7 \\ 7 \\ 8 \\ \vdots \\ 138 \\ 110 \\ 134 \end{bmatrix}$$





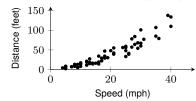
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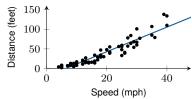
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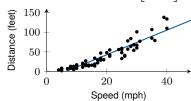
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The normal equations  $\Rightarrow \widehat{\beta} = \begin{bmatrix} -20.1 \\ 3.1 \end{bmatrix}$ 



Use the model for predictions!



# Transforming the inputs

"If the speed x is an input variable, why can't the kinetic energy  $(\propto x^2)$  be an input variable?"

We can make arbitrary nonlinear transformations to the input variables! The model is still a linear regression model, since

$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 \cos(x) + \beta_4 \arctan(x) + \varepsilon$$

is equivalent to

$$y=\beta_0+\beta_1x_1+\beta_2x_2+\beta_3x_3+\beta_4x_4+\varepsilon,$$
 with  $X_1=v$  
$$X_2=v^2$$
 
$$X_3=\cos(v)$$
 
$$X_4=\arctan(v)$$

x = original input variable,  $x_i$  transformed input variables (features).



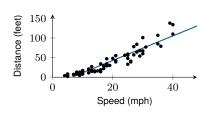
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$$y = \beta_0 + \beta_1 x + \varepsilon, \varepsilon \sim \mathcal{N}(0, \sigma_{\varepsilon}^2)$$

$$\beta = \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix}$$

$$\mathbf{X} = \begin{bmatrix} 1 & 4 \\ 1 & 5 \\ 1 & 5 \\ 1 & 5 \\ 1 & 5 \\ 1 & 7 \\ 1 & 7 \\ 1 & 8 \\ \vdots & \vdots \\ 1 & 39 \\ 1 & 39 \\ 1 & 40 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 4 \\ 2 \\ 4 \\ 8 \\ 8 \\ 7 \\ 7 \\ 8 \\ \vdots \\ 138 \\ 110 \\ 134 \end{bmatrix}$$

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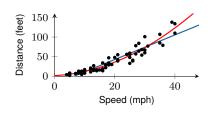
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$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + \varepsilon, \varepsilon \sim \mathcal{N}(0, \sigma_{\varepsilon}^2)$$

$$\beta = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 16 \\ 1 & 5 & 25 \\ 1 & 5 & 25 \\ 1 & 5 & 25 \\ 1 & 7 & 49 \\ 1 & 7 & 49 \\ 1 & 8 & 64 \\ \vdots & \vdots & \vdots \\ 1 & 39 & 1521 \\ 1 & 40 & 1600 \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 4 \\ 2 \\ 4 \\ 8 \\ 8 \\ 7 \\ 7 \\ 8 \\ \vdots \\ 138 \\ 110 \\ 134 \end{bmatrix}$$

The normal equations  $\Rightarrow \widehat{\beta} = \begin{bmatrix} 1.58 \\ 0.42 \\ 0.066 \end{bmatrix}$ 





# **Transforming the inputs**

If the original input variable is v, we can for instance use:

a polynomial in v

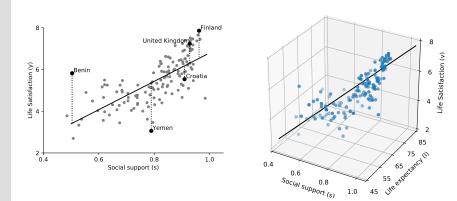
$$y = \beta_0 + \beta_1 \underbrace{v}_{x_1} + \beta_2 \underbrace{v^2}_{x_2} + \beta_3 \underbrace{v^3}_{x_3} + \dots + \beta_k \underbrace{v^k}_{x_k} + \varepsilon$$

- radial basis function kernels (see book draft)



# **Ex) Happiness**

Happiness is fitted as a function of Log GDP, Social Support, Life Expectency, Freedom, Generosity and Corruption.

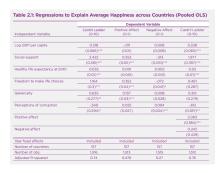


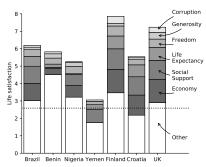
https://worldhappiness.report/ed/2019/



# Ex) Happiness

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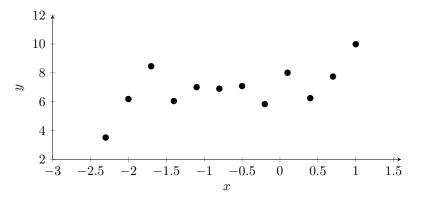




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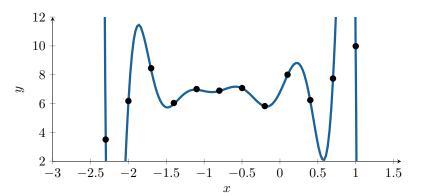


With a k=n-1 degree polynomial, we can fit n data points perfectly.





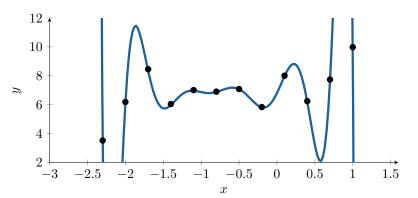
With a k=n-1 degree polynomial, we can fit n data points perfectly.



Is this desired?



With a k = n - 1 degree polynomial, we can fit n data points perfectly.



Is this desired? Overfit!





"Keep eta small unless the data really convinces us otherwise"

Least squares

$$\widehat{\boldsymbol{\beta}} = \mathop{\rm argmin}_{\boldsymbol{\beta}} \lVert \mathbf{X} \boldsymbol{\beta} - \mathbf{y} \rVert_2^2$$





"Keep eta small unless the data really convinces us otherwise"

Least squares with Ridge regression

$$\widehat{\boldsymbol{\beta}} = \mathop{\mathrm{argmin}}_{\boldsymbol{\beta}} \lVert \mathbf{X}\boldsymbol{\beta} - \mathbf{y} \rVert_2^2 + \gamma \lVert \boldsymbol{\beta} \rVert_2^2$$





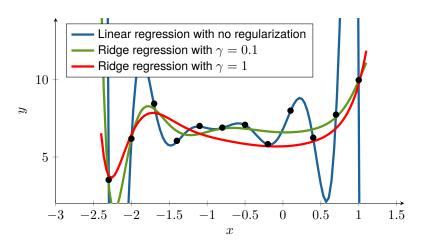
"Keep eta small unless the data really convinces us otherwise"

Least squares with Ridge regression

$$\begin{split} \widehat{\boldsymbol{\beta}} &= \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \|\mathbf{X}\boldsymbol{\beta} - \mathbf{y}\|_2^2 + \gamma \|\boldsymbol{\beta}\|_2^2 \\ \Rightarrow (\mathbf{X}^\mathsf{T}\mathbf{X} + \gamma\mathbf{I}_{p+1})\widehat{\boldsymbol{\beta}} &= \mathbf{X}^\mathsf{T}\mathbf{y} \end{split}$$

 $\gamma$  regularization parameter





Regularization can help us to avoid overfitting!



#### Ridge regression

$$\widehat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \|\mathbf{X}\boldsymbol{\beta} - \mathbf{y}\|_2^2 + \gamma \|\boldsymbol{\beta}\|_2^2$$

(has a closed-form solution for  $\widehat{\beta}$ )

#### LASSO

$$\widehat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \|\mathbf{X}\boldsymbol{\beta} - \mathbf{y}\|_2^2 + \gamma \|\boldsymbol{\beta}\|_1$$

(lacks a closed-form solution for  $\widehat{\beta}$ )

Regularization can be used in many methods, not only linear regression!



# **Dummy variables for categorical inputs**

For a categorical input with 2 different classes/levels/labels A and B: Create a dummy variable

$$\begin{split} x &= \begin{cases} 0 & \text{if A} \\ 1 & \text{if B} \end{cases} \\ \Rightarrow y &= \beta_0 + \beta_1 x + \varepsilon = \begin{cases} \beta_0 + \varepsilon & \text{if A} \\ \beta_0 + \beta_1 + \varepsilon & \text{if B} \end{cases} \end{split}$$



# **Dummy variables for categorical inputs**

For a categorical input with a=4 different classes/levels/labels A, B, C, D: Create a-1=3 dummy variables

$$x_1 = \begin{cases} 1 & \text{if B} \\ 0 & \text{if not B} \end{cases}, \quad x_2 = \begin{cases} 1 & \text{if C} \\ 0 & \text{if not C} \end{cases}, \quad x_3 = \begin{cases} 1 & \text{if D} \\ 0 & \text{if not D} \end{cases}$$

$$\Rightarrow y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \varepsilon = \begin{cases} \beta_0 + \varepsilon & \text{if A} \\ \beta_0 + \beta_1 + \varepsilon & \text{if B} \\ \beta_0 + \beta_2 + \varepsilon & \text{if C} \\ \beta_0 + \beta_3 + \varepsilon & \text{if D} \end{cases}$$



### A few concepts to summarize lecture 2

**Regression** is about learning a model that describes the relationship between an input variable  $\mathbf x$  (both numerical and categorical) and a numerical output variable y.

**Linear regression** corresponds to regression with a linear model.

**Maximum likelihood** with Gaussian iid assumption on  $\varepsilon$ 

 $\Rightarrow$  least squares and normal equations

Nonlinear transformations can be applied to the input variables

Overfit is when the model adapts (too much) to noise in the data

Regularization can help against overfitting

Categorical variables are handled by dummy variables