```
Exit[]
         PrependTo [$Path, "D:\\Users\\Johannes\\Promotion\\SVN Rep\\Mathematica\\Packages"];
        n = 1;
         dS[i_] := r S[i] dt + \sigma[i] S[i] dB[i];
         Q[i_] := q[i] P/S[i];
        dP = Expand \left[ \sum_{i=1}^{n} Q[i] dS[i] + \left( P - \sum_{i=1}^{n} Q[i] S[i] \right) r dt \right]
         coef = CoefficientArrays[dP, Prepend[Table[dB[i], {i, n+1}], dt]][[2]];
        S[n+1] := P;
        mm = MMc[{coef[[1]]}, {coef[[2;;n+2]]}];
        Print["Resulting system of SDEs:", MatrixForm /@ mm];
        mmlogd = MMdisc[mm];
         dfk = Simplify [DFK [V, mmlogd]]
         dt P r + P dB[1] q[1] \sigma[1]
Resulting system of SDEs: \left\{ \begin{pmatrix} r S[1] \\ P r \end{pmatrix}, \begin{pmatrix} S[1] \sigma[1] & 0 \\ P q[1] \sigma[1] & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right\}
The resulting system of SDEs: \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} S[1] \sigma[1] & 0 \\ Pq[1] \sigma[1] & 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right\}
        \frac{1}{2} \sigma[1]^{2} \left(P^{2} q[1]^{2} V^{(0,0,2)}[t,S[1],P] + \right.
               S[1] (2 P q[1] V^{(0,1,1)}[t, S[1], P] + S[1] <math>V^{(0,2,0)}[t, S[1], P]) + V^{(1,0,0)}[t, S[1], P]
        MatrixForm /@ CoefficientArrays[dfk, Table[q[i], {i, n}], Symmetric → True]
        \left\{\frac{1}{2}S[1]^2\sigma[1]^2V^{(0,2,0)}[t,S[1],P]+V^{(1,0,0)}[t,S[1],P],\right.
          \left( PS[1] \sigma[1]^2 V^{(0,1,1)}[t,S[1],P] \right), \left( \frac{1}{2} P^2 \sigma[1]^2 V^{(0,0,2)}[t,S[1],P] \right) \right\}
```

## constant volatility

The option value will be independent of the asset prices, as can be veryfied by the absence of S terms in the following equation:

```
 \begin{aligned} &\text{V2}:=\text{ToExpression}[\text{StringJoin}["V[\sharp 1,\sharp ",\text{ToString}[n+2],"]\&"]];\\ &\text{dfkC}=\text{Simplify}[\text{DFK}[V2,\text{mmlogd}]]\\ &\frac{1}{2}\text{ P}^2\text{ q}[1]^2\text{ }\sigma[1]^2\text{ }V^{\left(0,2\right)}[\text{t,P}]+V^{\left(1,0\right)}[\text{t,P}]\\ &\text{coef}=\text{CoefficientArrays}[\text{dfkC,Table}[\text{q}[\text{i}],\{\text{i,n}\}],\text{Symmetric}\rightarrow\text{True}];\text{MatrixForm}/@\text{ coeff}\\ &\left\{V^{\left(1,0\right)}[\text{t,P}],\left(0\right),\left(\frac{1}{2}\text{ P}^2\text{ }\sigma[1]^2\text{ }V^{\left(0,2\right)}[\text{t,P}]\right)\right\} \end{aligned}
```

## autonomous volatility

$$\begin{split} &\mathbf{S[1]} = \mathbf{P;S[2]} = \sigma; \\ &\mathbf{coefSDE} = \{\{0, \mathbf{a}\}, \{\{P\ \sigma\ \mathbf{q}, 0\}, \{0, \mathbf{b}\}\}, \{\{1, \rho\}, \{\rho, 1\}\}\}; \ \mathbf{MatrixForm}\ /@\ \mathbf{coefSDE} \\ &\mathbf{dfkA} = \mathbf{DFK}\ [\mathbf{V}, \mathbf{coefSDE}] \\ &\left\{\begin{pmatrix} 0 \\ \mathbf{a} \end{pmatrix}, \begin{pmatrix} P\ \mathbf{q}\ \sigma\ 0 \\ 0 & \mathbf{b} \end{pmatrix}, \begin{pmatrix} 1\ \rho \\ \rho\ 1 \end{pmatrix}\right\} \\ &\mathbf{a}\ \mathbf{V}^{\left(0,0,1\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] + \\ &\frac{1}{2}\ \left(\mathbf{b}^2\ \mathbf{V}^{\left(0,0,0,2\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] + 2\ \mathbf{b}\ \mathbf{P}\ \mathbf{q}\ \rho\ \sigma\ \mathbf{V}^{\left(0,1,1\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] + \mathbf{P}^2\ \mathbf{q}^2\ \sigma^2\ \mathbf{V}^{\left(0,2,0\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma]\right) + \\ &\mathbf{V}^{\left(1,0,0\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] \end{split}$$
 
$$&\mathbf{coef} = \mathbf{CoefficientArrays}\ [\mathbf{dfkA},\ \mathbf{q},\ \mathbf{Symmetric} \to \mathbf{True}\ ]; \ \mathbf{MatrixForm}\ /@\ \mathbf{coef} \\ &\left\{\mathbf{a}\ \mathbf{V}^{\left(0,0,1\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] + \frac{1}{2}\ \mathbf{b}^2\ \mathbf{V}^{\left(0,0,2\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] + \mathbf{V}^{\left(1,0,0\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma] , \\ &\left(\mathbf{b}\ \mathbf{P}\ \rho\ \sigma\ \mathbf{V}^{\left(0,1,1\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma]\right), \left(\frac{1}{2}\ \mathbf{P}^2\ \sigma^2\ \mathbf{V}^{\left(0,2,0\right)}\ [\mathbf{t},\ \mathbf{P},\ \sigma]\right) \right\} \end{split}$$

## passport

$$\begin{split} &\mathbf{S[1]} = \mathbf{P; S[2]} = \mathbf{S} \\ &\mathbf{coefSDE} = \{\{0,0\}, \{\{S \ \sigma \ \mathbf{q},0\}, \{\sigma \ \mathbf{S},0\}\}, \{\{1,0\}, \{0,0\}\}\}; \ \mathbf{MatrixForm} \ / @ \ \mathbf{coefSDE} \\ &\mathbf{dfkA} = \mathbf{DFK[V, coefSDE]} \\ &\{\left(\begin{smallmatrix} 0\\0 \end{smallmatrix}\right), \left(\begin{smallmatrix} \mathbf{q} \ \mathbf{S} \ \sigma & 0\\ S \ \sigma & 0 \end{smallmatrix}\right), \left(\begin{smallmatrix} 1 & 0\\ 0 & 0 \end{smallmatrix}\right) \} \\ &\frac{1}{2} \left(S^2 \ \sigma^2 \ \mathbf{V}^{\left(0,0,2\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right] + 2 \ \mathbf{q} \ \mathbf{S}^2 \ \sigma^2 \ \mathbf{V}^{\left(0,1,1\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right] + \mathbf{q}^2 \ \mathbf{S}^2 \ \sigma^2 \ \mathbf{V}^{\left(0,2,0\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right] \right) + \\ &\mathbf{V}^{\left(1,0,0\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right] \\ &\mathbf{coef} = \mathbf{CoefficientArrays[dfkA,\mathbf{q},\mathbf{Symmetric} \rightarrow \mathbf{True]; \mathbf{MatrixForm}} \ / @ \ \mathbf{coef} \\ &\{\frac{1}{2} \ \mathbf{S}^2 \ \sigma^2 \ \mathbf{V}^{\left(0,0,2\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right] + \mathbf{V}^{\left(1,0,0\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right], \\ &\left(S^2 \ \sigma^2 \ \mathbf{V}^{\left(0,1,1\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right]\right), \left(\frac{1}{2} \ \mathbf{S}^2 \ \sigma^2 \ \mathbf{V}^{\left(0,2,0\right)} \left[\mathbf{t},\ \mathbf{P},\ \sigma\right]\right)\right\} \\ &\{\frac{1}{2} \ \mathbf{S}[1]^2 \ \sigma[1]^2 \ \mathbf{V}^{\left(0,2,0\right)} \left[\mathbf{t},\ \mathbf{S}[1],\ \mathbf{P}\right] + \mathbf{V}^{\left(1,0,0\right)} \left[\mathbf{t},\ \mathbf{S}[1],\ \mathbf{P}\right], \\ &\left(\mathbf{P} \ \mathbf{S}[1] \ \sigma[1]^2 \ \mathbf{V}^{\left(0,1,1\right)} \left[\mathbf{t},\ \mathbf{S}[1],\ \mathbf{P}\right]\right), \left(\frac{1}{2} \ \mathbf{P}^2 \ \sigma[1]^2 \ \mathbf{V}^{\left(0,0,2\right)} \left[\mathbf{t},\ \mathbf{S}[1],\ \mathbf{P}\right]\right)\right\} \end{aligned}$$