

# Analysis of Partial Volume Correction on Quantification and Regional Heterogeneity in Cardiac PET

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## Abstract

*Background.* The partial volume correction (PVC) of cardiac PET datasets using anatomical side information during reconstruction is appealing but not straightforward. Other techniques, which do not make use of additional anatomical information, could be equally effective in improving the reconstructed myocardial activity.

*Methods.* Resolution modelling in combination with different noise suppressing priors was evaluated as a means to perform PVC. Anatomical priors based on a high-resolution CT are compared to non-anatomical, edge-preserving priors (relative difference and total variation prior). The study is conducted on *ex vivo* datasets from ovine hearts. A simulation study additionally clarifies the relationship between prior effectiveness and myocardial wall thickness.

*Results.* Simple resolution modelling during data reconstruction resulted in over- and under- estimation of activity, which hampers the absolute left-ventricular quantification when compared to the ground truth. Both the edge-preserving and the anatomy-based PVC techniques improve the absolute quantification, with comparable results (Student t-test,  $p = 0.17$ ). The

relative tracer distribution was preserved with any reconstruction technique (repeated ANOVA,  $p = 0.98$ ).

*Conclusions.* The use of edge-preserving priors emerged as optimal choice for quantification of tracer uptake in the left-ventricular wall of the available datasets. Anatomical priors visually outperformed edge-preserving priors when the thinnest structures were of interest.

*Keywords:* cardiac PET, system resolution, partial volume correction, quantification

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## List of abbreviations

PET	.....	Positron Emission Tomography
(HR)CT	...	(High Resolution) Computed Tomography
PVE	.....	Partial Volume Effect
PVC	.....	Partial Volume Correction
OSEM	....	Ordered Subsets Expectation Maximisation (reconstruction algorithm)
RR	.....	Resolution Recovery
MAP	.....	Maximum-a-Posteriori (reconstruction algorithm)
TV	.....	Total Variation (prior)
RD	.....	Relative Differences (prior)

### <sup>1</sup> 1. Introduction

<sup>2</sup> Positron emission tomography (PET) is a sensitive and quantitatively  
<sup>3</sup> precise preclinical and clinical tool for cardiovascular applications. <sup>18</sup>F-FDG  
<sup>4</sup> PET is nowadays the most sensitive method to identify myocardial viability  
<sup>5</sup> [1, 2]. Cardiac PET imaging leads to a panel of clinically relevant parameters  
<sup>6</sup> that can be interpreted visually (viability, tracer uptake in plaques or sar-  
<sup>7</sup> coid lesions, regional differences in tracer uptake) but some of these require  
<sup>8</sup> a quantitative analysis (absolute blood flow, function). Quantification im-  
<sup>9</sup> proves reproducibility, reduces inter-observer variability and might enhance  
<sup>10</sup> the diagnostic accuracy [3].

<sup>11</sup> Despite the wide range of applications for cardiac PET, the resulting im-  
<sup>12</sup> ages inherently suffer from severe blurring, due to both the finite resolution

13 of the imaging system (partial volume effect, PVE) and cardiac and respi-  
14 ratory motion during the entire PET examination [4], both of which hamper  
15 accurate quantification. The use of partial volume correction (PVC) tech-  
16 niques based on high resolution anatomical information to correct for this  
17 PVE has been successfully applied for PET brain imaging and to restore  
18 cardiac lesion uptake in a simulation study. In both cases, this resulted in  
19 improved quantitative information [5, 6, 7].

20 The main objective of this study is to evaluate the influence of two types  
21 of advanced reconstruction algorithms (anatomy-based and edge-preserving  
22 priors) on regional quantification of the left myocardial ventricle (LV) in  
23 comparison to the currently used clinical algorithms (with or without reso-  
24 lution modelling). All algorithms were applied on *ex vivo* datasets excised  
25 from sheep with asymmetric cardiac remodelling. The use of *ex vivo* (static)  
26 datasets allowed to rule out quantification errors caused by cardiac or res-  
27 piratory motion, and could therefore be considered as an ideal version of a  
28 single frame from a doubly gated *in vivo* study.

29 The animal model used in this work was an ovine model of dilated car-  
30 diomyopathy with asymmetric left ventricular remodelling due to a left-  
31 bundle branch block-like conduction delay. Some of the typical features of  
32 this pathology are a dilation of the LV chamber over time, together with  
33 a thinning of the septal wall and a thickening of the lateral wall of the LV  
34 during the progression of the disease. Such variations in the wall thicknesses  
35 were hypothesised to generate problems with relative tracer uptake quantifi-  
36 cation, due to the partial volume effects which are expected to mostly affect  
37 the thinned walls. The application of PVC techniques in hearts which un-  
38 derwent such kind of remodelling should best demonstrate the recovery of  
39 activity in the thinnest walls, provided that the final wall thinning is enough  
40 to cause severe PVEs.

## 41 2. Methods

### 42 2.1. Animal model and experimental design

43 We used an ovine model of rapid pacing-induced dilated cardiomyopathy  
44 with left-bundle branch block-like morphology leading to asymmetric remod-  
45 ellng of the septal and lateral wall. All experiments and procedures were  
46 approved by the local ethical committee.

47 Each of the thirteen available sheep was sacrificed and their heart was  
48 excised. The excised, *ex vivo* hearts were filled with a non-attenuating, hard-

49 ening poly-urethane foam in order to ensure a stable shape of the heart in  
50 time. Each heart was filled once throughout the experiment, hence the heart  
51 shape was always the same throughout the *ex vivo* scans of the same ani-  
52 mal. A pilot *ex vivo* experiment had been previously carried out to confirm  
53 that the foam would not keep on expanding throughout the duration of the  
54 imaging process. The following *ex vivo* scans were performed:

- 55 • a 15-minute acquisition on a small-animal PET scanner (Siemens Fo-  
56 cuss220 microPET), which served as gold standard because of the high  
57 spatial resolution of this PET system (1.5 mm), resulting in images  
58 that are almost free from resolution-related blurring. A transmission  
59 scan with a rotating  $^{57}\text{Co}$  point source was also obtained for scatter  
60 correction.
- 61 • a 20-minute PET scan on the clinical PET/CT scanner (Siemens Bi-  
62 ograph 16, Hirez). These datasets were reconstructed with different  
63 algorithms and compared to the ground truth images provided by the  
64 microPET.
- 65 • a high-dose, high-resolution CT (HRCT) on the clinical PET/CT scanner.  
66 It was used for accurate attenuation correction and for PVC of  
67 both the clinical and the microPET datasets. In the *ex vivo* hearts the  
68 blood is removed from the ventricular cavities and the polyurethane  
69 foam is injected in their place. This allows a clear distinction of the  
70 myocardium, thus ensuring an efficient PVC. No contrast-enhanced CT  
71 is therefore needed in this case.

72 *2.2. Simulation study*

73 A simulation study was designed to clarify whether there is a relation-  
74 ship between the apparent thickness of the reconstructed structures and the  
75 different reconstruction algorithms.

76 For this purpose, several cylindrical phantoms resembling the shape of  
77 the left ventricle were designed, all with a height of 65 mm and an outer  
78 diameter of 30 mm. The cylindrical walls of each phantom had a uniform  
79 thickness, which was different for each phantom and ranged between 1 and 12  
80 mm (representative of the thicknesses that can be encountered in a cardiac  
81 setting). Figure 1 shows one of the designed phantoms.

82 The walls of the phantom were filled with a known and fixed activity  
83 concentration of 4 kBq/cc. A second identical phantom was then created

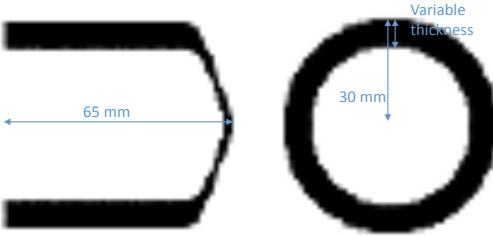


Figure 1: Transaxial (left) and axial (right) view of one of the phantoms simulated to demonstrate the effect of the reconstruction algorithms against different phantom thicknesses. The arrow with *Variable thickness* indicates the part of the phantom that was modified in the subsequent simulations to study the effect of different wall thicknesses (in this example, the wall thickness is 8 mm).

84 to simulate a uniform attenuation map and filled with a known and fixed  
 85 attenuation value of  $0.0999428$  ( $\text{attenuation} \times \text{cm}^{-1}$ ), which corresponds to  
 86 the mean attenuation value found for muscle at 511 keV [8]. A third copy of  
 87 the phantom was used to simulate the anatomical prior information, perfectly  
 88 aligned to the emission dataset.

89 A simulated acquisition of each of these numeric phantoms was performed,  
 90 modelling the physical phenomena of limited spatial resolution, attenuation  
 91 and detector normalization. Scatter and randoms were not modelled to ex-  
 92 clude their influence from the analysis. A noise-free sinogram was obtained  
 93 for each phantom. The resulting total sinogram counts are between 0.5 and  
 94 2.5 million counts, depending on the phantom thickness. This is in the  
 95 same order of magnitude as the total sinogram counts of the available heart  
 96 datasets with the lowest uptake and a 20 min data acquisition. One noisy  
 97 sinogram was generated for each thickness-phantom by adding Poisson noise  
 98 to the noise-free sinogram.

99 *2.3. Image reconstruction*

100 *Hirez PET/CT datasets*

101 Both simulated and real measured datasets were reconstructed using the  
 102 same iterative reconstruction scheme ([3,2,2] iterations  $\times$  [42,24,1] subsets).  
 103 A realistic, in-house developed model of the Hirez PET system was used both  
 104 for the simulated acquisition of the numeric phantoms and for the reconstruc-  
 105 tion of all the Hirez PET datasets. When requested, the spatial resolution  
 106 of the scanner was modelled as a Gaussian function whose full-width at half-  
 107 maximum corresponds to the spatial resolution of the scanner (4.3 mm and

108 4.5 mm in the transaxial and axial direction, respectively). The voxel size  
109 of the reconstructed PET images was set to  $1.35 \times 1.35 \times 1.35 \text{ mm}^3$  for all  
110 datasets.

111 An overview of the different algorithms used to reconstruct each of the  
112 available sinograms is listed below:

- 113 1. iterative reconstruction (ordered subsets expectation maximisation,  
114 **OSEM**) without resolution recovery (RR)
- 115 2. OSEM with RR (**OSEM + RR** in the rest of this work), which takes  
116 into account the resolution of the scanner during the PET reconstruc-  
117 tion.
- 118 3. iterative reconstruction with prior information (maximum-a-posteriori,  
119 MAP) with RR, with CT-based side anatomical information. The  
120 anatomical information was incorporated in the reconstruction process  
121 by means of the asymmetrical **Bowsher** prior [9, 10]. The Bowsher  
122 prior is parametrised by two values, namely the weight (w) and the  
123 number of neighbours (n), which define the strength of the prior and  
124 the size of its smoothing mask respectively.
- 125 4. MAP with RR in combination with a non-anatomy based prior (known  
126 as *relative differences* (**RD**) prior [11]), parametrised by a weight (w)  
127 and an edge-preserving parameter ( $\gamma$ ).
- 128 5. MAP with RR, in combination with a non-anatomy based prior (known  
129 as *isotropic total variation prior* (**TV**) [12]), parametrised by a weight  
130 (w).

131 A range of prior parameter values was chosen based on a simulation study,  
132 where reconstructions with a similar count level were compared to a ground  
133 truth dataset in terms of bias and noise. A visual inspection of the datasets  
134 confirmed that the chosen range was an appropriate compromise between  
135 noise reduction and excessive smoothing of the structures.

#### 136 *microPET datasets*

137 The microPET list-mode datasets of the *ex vivo* hearts were reconstructed  
138 using a MAP reconstruction algorithm (5 iterations  $\times$  28 subsets) with res-  
139 olution recovery [13] and asymmetrical Bowsher prior ( $w = 50$ ,  $n = 9$ ). We  
140 chose to apply a prior because resolution recovery alone is known to reduce  
141 the apparent thickness of the structures and to possibly hamper quantifica-  
142 tion [14]. Moreover, Bowsher reconstructions have been shown to improve the  
143 recovery of activity concentrations in previous studies, e.g. in [6]. In order to

144 corroborate such findings and choose which microPET reconstruction to use  
145 as ground truth, we performed a preliminary simulation study. The Bowsher  
146 reconstruction with the aforementioned parameters was found to minimise  
147 the bias and the noise when compared to a simulated ground truth. It was  
148 therefore chosen as the reconstruction method for the microPET datasets in  
149 this study.

150 Attenuation correction of the microPET was based on the HRCT and  
151 performed, together with scatter and sensitivity correction, during recon-  
152 struction. The data were also precorrected for randoms and deadtime. The  
153 microPET images were reconstructed with a voxel size of  $0.4745 \times 0.4745 \times$   
154  $0.796 \text{ mm}^3$ . For comparison to the Hirez datasets, they were rigidly aligned  
155 and resampled to match the Hirez.

#### 156 *2.4. Image post-processing*

157 A polar map (or bull's eye) representation of the simulated and *ex vivo*  
158 reconstructions was chosen to illustrate the regional and absolute differences  
159 within the myocardium. To create the bull's eye plots, the software must  
160 compute a single value for each longitudinal and angular position within the  
161 LV. This value must represent the activity over the LV wall thickness at each  
162 of those positions. To do so, the LV wall portion enclosed by the endocardial  
163 and the epicardial contours is considered for each angular and longitudinal  
164 position. The definition of the endocardial and epicardial contours is done  
165 automatically using a model-based approach, as described in [15]. The maxi-  
166 mum activity value or the mean activity value along each of those portions is  
167 computed (see [7] for further details on the process). This value is then used  
168 to represent the activity value over the myocardial thickness. Both types of  
169 polar maps were created in this work, by taking the maximum or the mean  
170 count over the LV thickness (*max-count* and *mean-count* polar maps in the  
171 rest of this work, respectively).

#### 172 *2.5. Image analysis*

##### 173 *Measured ex vivo datasets*

174 The **absolute** values of the *ex vivo* reconstructions were compared. The  
175 mean difference between the microPET polar map and the *ex vivo* Hirez  
176 polar maps, relative to the mean activity of the microPET polar map, was  
177 computed and plotted, for each animal. The values extracted from the mean-  
178 count polar maps were compared to the values extracted from the max-count  
179 polar maps.

180 For every polar map, the S/L ratio was additionally calculated by divid-  
181 ing the mean activity in the free septal wall (segments 8, 9 in a conventional  
182 17-segment polar map [16]) by the mean activity in the free lateral wall (seg-  
183 ments 11, 12). This analysis aimed to quantify whether the prior-based re-  
184 constructions improve or preserve the **regional variations** of activity within  
185 the heart, when compared to the S/L ratio computed on the polar map of  
186 the corresponding ground truth reconstructions.

187 Although the analysis of the septal vs lateral walls is commonly performed  
188 to describe regional inhomogeneity in the heart function and metabolism [17],  
189 a more general overview of the inhomogeneities was also provided. To this  
190 end, each of the available *ex vivo* max-count polar maps was considered, and  
191 divided by its maximum to obtain a *normalized* polar map (unit-less, ranging  
192 between 0 and 1). For each sheep, all the normalized polar maps from the  
193 Hirez scanner, obtained with the different reconstruction techniques, were  
194 compared to the normalized polar map of the ground truth. The resulting  
195 percentage bias was computed, per segment. The mean of the segmental bi-  
196 ases was computed over all the sheep, together with the segmental standard  
197 deviation of the bias over all sheep. Two corresponding polar maps were  
198 generated for each reconstruction algorithm, whose segmental values repre-  
199 sent the mean bias and the mean standard deviation of the normalized polar  
200 maps of the Hirez against the ground truth.

201 *Simulated datasets*

202 The mean activity in the middle ring of each max-count polar map of  
203 the simulated phantoms was plotted for the different phantom thicknesses in  
204 comparison to the activity expected in that region ( $4 \text{ kBq/cc}$ ).

205 Additionally, profiles through the wall were taken in the cylindrical part  
206 of the heart phantom (Figure 1). An average of the 20 central subsequent  
207 axial profiles was considered, to minimise the contribution of noise to the  
208 profiles. These mean profiles were plotted for all different reconstruction  
209 algorithms.

210 *2.6. Statistical methods*

211 A repeated ANOVA between the different reconstructions of the mea-  
212 sured datasets was performed, to establish whether a statistical difference in  
213 the mean absolute activity differences could be found, and the resulting p  
214 and F values were reported (significance level: 0.05). An additional Student  
215 t-test with posthoc Bonferroni correction helped to point out the algorithms

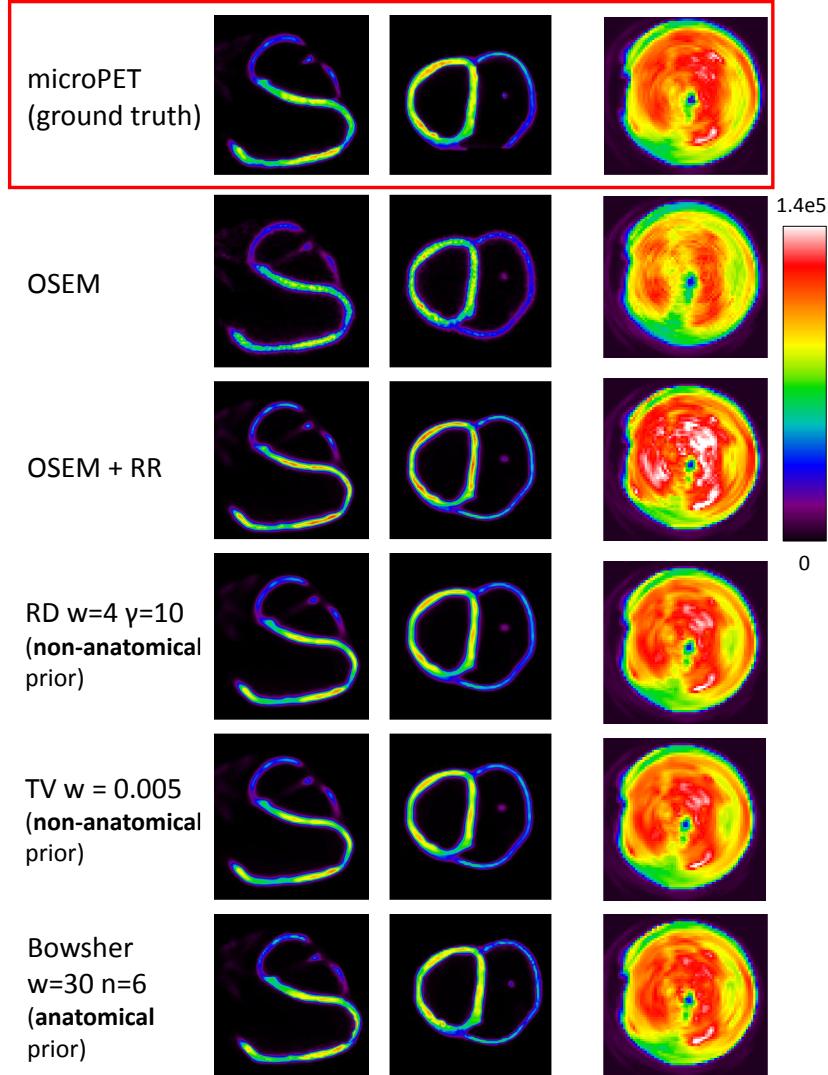


Figure 2: Representative images of an *ex vivo* sheep heart (sheep4238) reconstructed with different algorithms. On the right, the corresponding max-count polar maps for the same sheep are shown. The red box highlights the ground truth dataset (microPET). Color scale in Bq/cc. OSEM: ordered-subsets expectation-maximization (iterative reconstruction) algorithm, RR: resolution recovery, RD: relative differences prior, TV: total variation prior.

216 which significantly differed from the state-of-the-art reconstruction technique  
217 (OSEM + RR). A repeated ANOVA test between the mean S/L ratios com-  
218 puted from the various reconstructions was also performed, and the resulting  
219 p and F values were reported (significance level: 0.05).

220 **3. Results**

221 ***Measured ex vivo datasets***

222 A representative dataset with a selection of the performed reconstructions  
223 is shown in Figure 2. The use of well tuned edge-preserving priors (RD, TV)  
224 seems to work as well as a (well tuned) Bowsher prior, even though the  
225 Bowsher reconstructions show moderately sharper edges. In all cases, the  
226 visual assessment of the different reconstructions did not reveal dramatic  
227 changes in the relative activity distribution. The polar maps obtained for all  
228 the ex vivo datasets were also compared visually (right column of Figure 2)  
229 and confirmed the previous observations.

230 The accurate **absolute recovery** of the activity concentrations within  
231 the LV was then considered (Figure 3), which confirms an overall underes-  
232 timation of the mean LV activity when no resolution recovery is modelled  
233 and a significant mean overestimation of the LV activity for the reconstruc-  
234 tions with resolution recovery alone (repeated ANOVA: F-value=150, p-value  
235 < 0.001 (significant)). The T-test between TV and the latter (OSEM+RR)  
236 gives a p-value < 0.001 (significant), whereas the same test between TV and  
237 Bowsher w=30,n=9 has a p-value of 0.17 (not significant). This ranking  
238 holds true when the mean-count polar maps are used (bottom pane of Fig-  
239 ure 3), but the differences between the different algorithms are more subtle.  
240 However, we can clearly appreciate the stabilizing role of the regularization  
241 included during the reconstruction process.

242 The **S/L ratios** were further calculated for the polar maps of each of  
243 the clinical reconstructions. They were compared to the ground truth S/L  
244 ratio extracted from the corresponding microPET reconstruction. Within  
245 each animal, the S/L ratios do not significantly change with different recon-  
246 struction algorithms, further supporting our visual evaluation of the polar  
247 maps. The ANOVA test showed no significant differences in the mean S/L  
248 ratios recovered from the different reconstruction algorithms ( $F = 0.25$ ,  $p =$   
249 0.98).

250 The polar maps describing the mean bias and the mean standard de-  
251 viation of the bias, over all sheep, are reported in Figure 4 for 4 selected

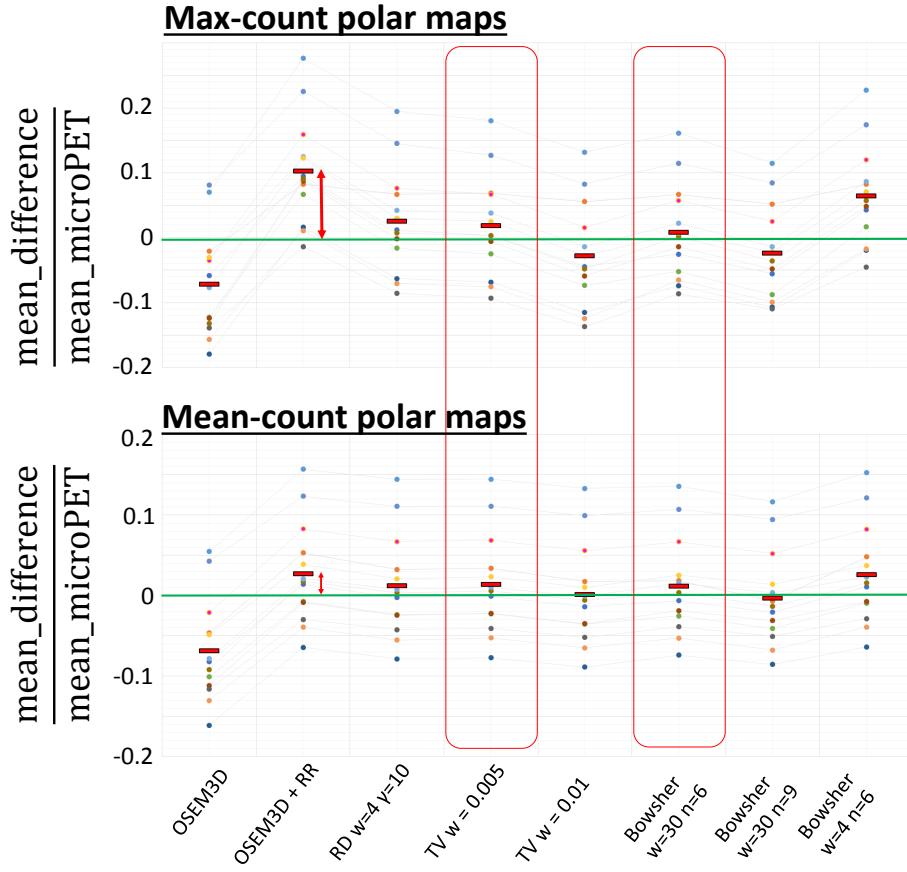


Figure 3: Mean difference between the polar maps of the ground truth (microPET) and the polar maps of the *ex vivo* Hirez images, reconstructed with the various algorithms, relative to the mean activity of the polar map of the corresponding microPET. Connected dots of the same color represent individual animals. The red solid bar is the mean value over all animals for each of the considered algorithms. The use of a different way to obtain the polar maps (max-count (top) or mean-count (bottom) polar maps) changes the amount of error that is computed, especially for OSEM+RR (red arrows). The use of edge-preserving or anatomical priors leads to a more accurate and more stable absolute quantification of the activity in the LV, regardless of the type of polar map that is used. The red boxes highlight this behaviour for two representative cases.

algorithms: Bowsher (weight=30, n=9), TV (weight=0.005) and for the iterative reconstruction with and without resolution recovery. Most of the individual biases are within the  $\pm 0.1$  threshold, thus indicating very small differences (up to 10%) in the reconstructed LV homogeneity.

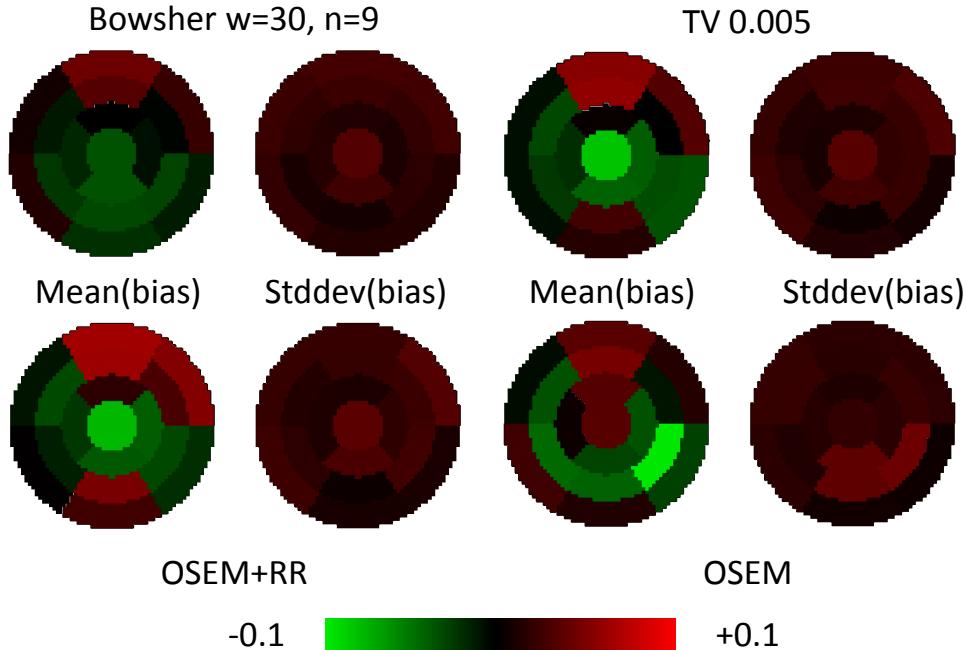


Figure 4: Mean bias (left side of each quadrant) and mean standard deviation of the bias (right side in each quadrant) over all animals, extracted from the normalized max-count polar maps of the reconstructions using a selection of the different algorithms. OSEM: iterative reconstruction, with or without resolution recovery (RR); TV: non-anatomical prior, Bowsher: anatomical prior. The bias is a fraction of the maximum of the normalized polar maps, i.e. a fraction of 1.

#### 256 ***Simulated datasets***

257 The analysis of the mean reconstructed activity at different phantom  
 258 thicknesses is in Figure 5. As hypothesized, the thinnest phantoms benefit  
 259 more from the additional use of anatomical information (black line), while  
 260 the non-anatomical priors – or the anatomical priors where the number of  
 261 neighbours over which the smoothing is performed is too large – blur over the  
 262 edges and therefore struggle to fully restore the activity within the walls of  
 263 the thinnest phantoms. The iterative reconstruction with resolution recovery

264 alone displays the typical overestimation of activity at a thickness of 6-8 mm  
 265 (roughly double the spatial resolution of the system), which becomes less  
 266 apparent with increasing wall thickness of the cardiac phantom ( $\geq 10$  mm).

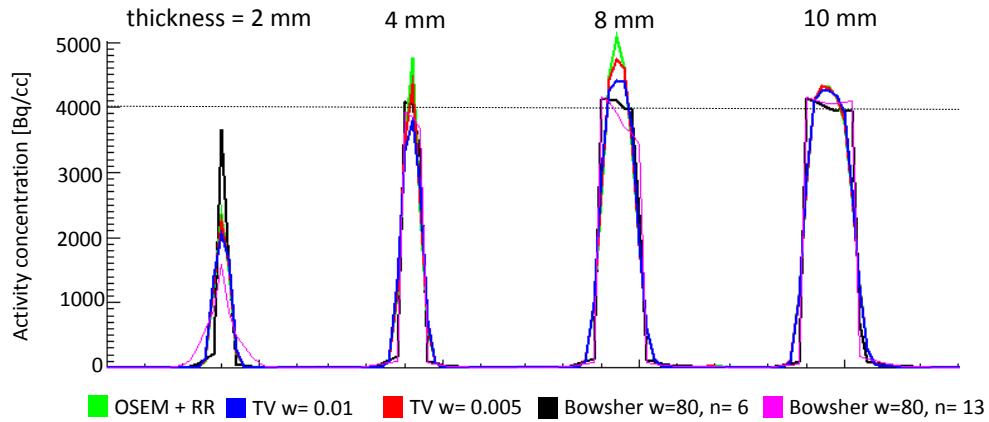


Figure 5: Profiles over one wall of the heart phantom (simulated homogeneous activity of 4  $kBq/cc$ ), for a selection of phantom thicknesses. To emphasize the effect of the parameter choice in the Bowsher reconstructions, especially at small thicknesses, a high weight and two very different numbers of neighbours ( $n$ ) are shown.

267 The analysis of the mean recovered value in the max-count bull's eye plots  
 268 of the heart phantom at different thicknesses (Figure 6) confirms the findings  
 269 of the profile analysis and of the analysis of the *ex vivo* measured datasets.

270 The visual inspection of the thinnest structures of the sheep datasets (e.g.  
 271 right ventricle) confirms the improved reconstruction of such areas when an  
 272 adequately chosen anatomical prior is used. Figure 7 shows a comparison  
 273 between the short-axis slices of two Bowsher and two TV reconstructions.

#### 274 4. Discussion

275 The use of anatomical side information for the improved quantification  
 276 of cardiac PET datasets stemmed from previous, successful experiences in  
 277 brain PET imaging, where similar techniques have been applied during the  
 278 reconstruction of PET datasets [6]. The results obtained in the current study  
 279 are in line with previous findings and add interesting insights into the dis-  
 280 criminating factors for choosing an anatomy-based prior.

281 The modelling of the resolution during reconstruction is essential for deal-  
 282 ing with the PVE. However, our findings confirm that the resolution recovery

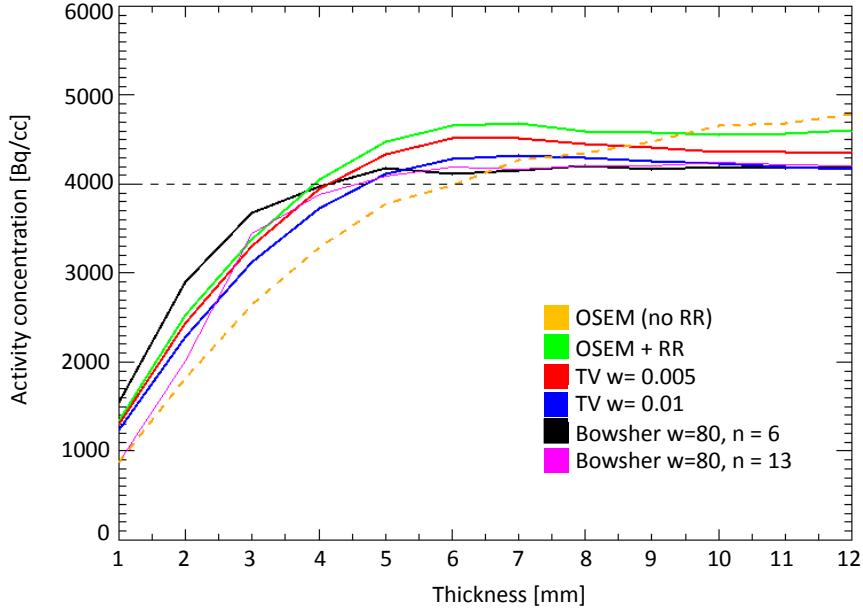


Figure 6: Mean value in the max-count polar maps of the heart phantoms, at increasing phantom thicknesses. The Bowsher algorithm, with a well chosen neighborhood, is the one that best improves the recovery of the mean activity concentration starting from a thickness of 2 mm.

is an ill-posed problem [18] and, alone, is not sufficient for accurate image quantification. Some kind of regularization is additionally needed to produce more quantitatively accurate results. In this study, the use of priors proves to improve the absolute quantification of the left ventricles, when compared to the state-of-the-art iterative reconstruction algorithms (with or without resolution recovery). This paper highlights the role of both anatomical (Bowsher) and non-anatomical edge-preserving priors (RD, TV) applied during the reconstruction of the datasets in stabilizing the resulting images. Even when the weights or the number of neighbours chosen are not fully optimized for the structures of interest (e.g. too many neighbours, or too bland prior weight), the error calculated in the enhanced reconstructions is milder than the one obtained in the reconstructions where no priors are used.

For regional analysis and relative quantification of the activity distribution within the left ventricle, on the other hand, the use of either reconstruction algorithm (with or without prior information) was sufficient and provided similar information. The S/L ratios are equally well resolved when



Figure 7: Comparison between non-anatomical (TV) and CT-based Bowsher reconstructions, for three different sheep datasets (from left to right column: sheep4238, sheep1869 and sheep1132). For both algorithms, the same short-axis slice and the same maximum is shown (they differ for the different animals, to maximize visibility).

299 compared to the ground truth ratio, no matter the reconstruction algorithm  
 300 that is chosen for reconstructing the datasets obtained on the clinical scanner.

301 It is worth mentioning that the Bowsher priors presented in the study on  
 302 the wall thickness for demonstrative purposes use a considerably high weight  
 303 to achieve such results. In a more realistic scenario where these techniques  
 304 would be applied, i.e. a motion-corrected acquisition with the use of anatom-  
 305 ical information obtained from a dedicated scanner, the use of a high weight  
 306 would be risky and could cause artefacts if the alignment between the PET  
 307 and the anatomical dataset is not accurate. To present, the prior param-  
 308 eters need to be tuned in a case-by-case fashion to obtain optimal results,  
 309 which can be a limiting factor for a realistic clinical workflow. A way to  
 310 automatically select the best prior parameters was out of the scope of this  
 311 work and should be subject of further investigation. Additionally, it is nec-  
 312 essary to underline the importance of a correct image alignment and motion  
 313 correction, before proceeding to anatomy-based PET reconstruction. With  
 314 these regards, truly simultaneous PET/MR systems might represent a great  
 315 improvement in the direction of accurate alignment, provided that the tech-  
 316 nical advances in MRI imaging will reduce the geometrical distortions and  
 317 artefacts that nowadays still affect the gated MR measurements [19].

318 A limitation of this study is the sole use of *ex vivo*, static cardiac datasets  
319 for the assessment of the usefulness of partial volume correction techniques.  
320 In patients, the motion of the heart due to the beating and the breathing  
321 during the scan can create additional blurring of the PET datasets and needs  
322 to be taken into account and fully corrected if accurate quantification is  
323 aimed at. We expect a worsening of the quantification performances of any  
324 of the presented algorithms in the case where the correction of the motion is  
325 inaccurate or missing. The use of *in vivo* datasets, which we acquired within  
326 the same study as the *ex vivo* datasets, should help to shed further light into  
327 the applicability of the presented techniques to images of the beating heart.  
328 The analysis of the *in vivo* datasets is ongoing. Particularly, given that no  
329 partial volume correction technique should be applied to datasets that are  
330 not corrected for motion, we are investigating on the applicability of partial  
331 volume correction techniques in combination with dual-gating techniques.  
332 The results of the *in vivo* study will be made available upon completion.  
333 A particularly important conclusion from the present *ex vivo* study, where  
334 no motion is present and alignment with anatomical data is perfect, is that  
335 non-anatomical priors and anatomical, CT-based priors perform equally well  
336 for the quantification of LV activity. As the current *ex vivo* experiment can  
337 be considered as an ideal dual-gated *in vivo* experiment – where the scatter,  
338 attenuation and motion correction have been perfectly accounted for–, we  
339 believe that the application of non-anatomy based priors is a good starting  
340 point for truly dual-gated *in vivo* studies where the LV walls are of interest.  
341 This is advantageous as it simplifies the overall acquisition and reconstruction  
342 process.

343 Finally, although the application of non-anatomical priors yielded accept-  
344 able quantification results on the available animal cohort (i.e. hearts without  
345 lesions and with sufficiently thick LV walls), the application of anatomical  
346 information for cardiac PET imaging is not to be fully excluded, particularly  
347 when non-transmural lesions are present in the considered datasets [7] and  
348 in general when the thinnest structures are of interest.

## 349 5. Conclusions

350 We have demonstrated the necessity of prior information during the iter-  
351 ative reconstruction of *ex vivo* cardiac datasets, to be performed in combina-  
352 tion with the modelling of the scanner’s resolution. The use of side anatom-  
353 ical information was not essential for our animal datasets, and a well-tuned

354 non-anatomical prior was sufficient for the recovery of the LV activity.

355 The analysis of the simulated data demonstrates that the Bowsher prior  
356 could have potential use in the recovery, delineation and analysis of the PET  
357 datasets, particularly if the thickness of the considered structures is expected  
358 to drop below the 4 mm.

## 359 **6. New knowledge gained**

360 This work addresses the previously unanswered question regarding the  
361 usefulness of anatomical and non-anatomical priors for the quantification of  
362 cardiac PET images. It provides guidelines for the reconstruction of cardiac  
363 emission datasets, partially confirming the results of previous literature on  
364 brain PVC, partially adding new insights into the usefulness of the prior  
365 information in the reconstruction of different cardiac structures. The study  
366 design using *ex vivo* cardiac datasets acquired on both a pre-clinical and a  
367 clinical scanner is innovative and original.

## 368 **7. Competing interests**

369 The authors declare that they have no competing interests.

## 370 **8. Author's contributions**

371 AT was responsible for the study design, the simulation setup, the recon-  
372 structions and the data collection and analysis, and drafted the manuscript.  
373 JN and KV assisted with the study design, the analysis of data and the  
374 careful revision of the manuscript. JUV, PC, JD and OG participated in  
375 the study design and critically revised the manuscript. All authors read and  
376 approved the final manuscript.

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