

# Computational Physics - Project 1

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# 1 Introduction to Project 1

In physics, we often have to deal with differential equations of second order, which can be generally written in the form

$$\frac{d^2 y}{dx^2} + k^2(x)y = f(x) \quad , \quad (1)$$

where we call  $f$  the inhomogeneous term and  $k^2(x)$  is a real function. A special case of these cases is Poisson's equation, which reads in the one-dimensional, spherical case

$$\frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d\Phi}{dr} \right) = -4\pi\rho(r) \quad . \quad (2)$$

Doing some substitutions, we can write this in the following, more general form:

$$-u''(x) = f(x) \quad (3)$$

In this project, we try to solve eq.(3) with the boundary conditions  $u(0) = u(1) = 0$ . Therefore, we have to discretize  $f$  and  $u$ . We approximate  $u(x)$  as  $v_i$ , using a grid of  $n$  gridpoints  $x_i = i \cdot h$ . Thus,  $h = 1/(n+1)$  is our steplength. We will also write  $f_i = f(x_i) = f(hi)$ .

Approximating the second derivative of  $u$ , we get

$$-\frac{v_{i+1} + v_{i-1} - 2v_i}{h^2} = f_i \quad (4)$$

Our goal is to solve this equation (4). Therefore, we will rewrite it as a set of linear equations in matrix form.

## 1.1 Rewriting the equation in matrix-form

Eq (4) can be written as a set of linear equations in matrix form. Therefore, we have to do the following steps:

$$\begin{aligned} -\frac{v_{i+1} + v_{i-1} - 2v_i}{h^2} &= f_i \\ -(v_{i+1} + v_{i-1} - 2v_i) &= h^2 \cdot f_i \end{aligned} \quad (5)$$

(6)

Assuming we have an  $n \times n$ -matrix  $\mathbf{A}$  of the following form

$$\mathbf{A} = \begin{pmatrix} 2 & -1 & 0 & \dots & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & \dots \\ 0 & -1 & 2 & -1 & 0 & \dots \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & \dots & \dots & -1 & 2 & -1 \\ 0 & \dots & \dots & 0 & -1 & 2 \end{pmatrix} \quad , \quad (7)$$

then we can rewrite this matrix in index notation as

$$a_{ij} = \begin{cases} 2 & \text{if } i = j \\ -1 & \text{if } |i - j| = 1 \\ 0 & \text{else} \end{cases} \quad . \quad (8)$$

Using this, we can also rewrite the multiplication  $\mathbf{w} = \mathbf{A} \cdot \mathbf{v}$  with an  $n$ -dimensional vector  $\mathbf{v}$  in the following way:

$$w_i \stackrel{\text{def}}{=} \sum_{j=1}^n a_{ij} \cdot v_j \stackrel{(8)}{=} -v_{i-1} + 2v_i - v_{i+1} \quad (9)$$

By using this result and substituting  $h^2 \cdot f_i \rightarrow \bar{b}$  in eq (5), we get to the following equation:

$$\mathbf{A}\mathbf{v} = \bar{\mathbf{b}} \quad (10)$$

with matrix  $\mathbf{A}$  as given above. This is a set of linear equations that we are going to solve with our program. In this example, we will assume that  $f(x)$  is given by  $f(x) = 100e^{-10x}$ . Thus, the analytical solution of eq (3) is given by  $u(x) = 1 - (1 - e^{-10})x - e^{-10x}$ . We will later compare our numerical results to this solution.