

Lecture September 17

Project 2

$$\left. \begin{aligned} \frac{d^2 u(x)}{dx^2} &= \lambda u(x) \\ u(0) &= u(1) = 0 \\ x &\in [0, 1] \end{aligned} \right\} \rightarrow$$

$$T u = \lambda u$$

$$T = \frac{1}{h^2} \begin{bmatrix} 2 & -1 & & & 0 \\ -1 & 2 & -1 & & \\ & -1 & \ddots & \ddots & \\ 0 & & \ddots & -1 & 2 \\ & & & -1 & 2 \end{bmatrix}$$

Jacobi's method

$$\boxed{S T S^T = D} = [\lambda_1, \lambda_2, \dots, \lambda_n]$$

$$S = \begin{bmatrix} 1 & & & 0 \\ & \ddots & & \\ 0 & & \cos \theta & \sin \theta \\ & & -\sin \theta & \cos \theta \end{bmatrix}$$

$$S S^T = S^T S = \underline{1}$$

$$S \cdot \left[\underset{\substack{\uparrow \\ S^T S}}{T} \cdot u = \lambda \cdot u \right]$$

$$S^T S^T \underbrace{S u}_{\substack{\uparrow \\ \text{eigenvector}}} = \lambda \underbrace{S u}$$

$$S_m S_{m-1} \dots S_1^T S_1^T \dots S_{m-1} S_m = D$$

Final eigenvector:

$$v = \boxed{S_m S_{m-1} \dots S_1} u$$

$$u = ?$$

complete orthogonal basis

u , defined for $i=1, \dots, n$

$$T \in \mathbb{R}^{n \times n}$$

$$u_i \in \mathbb{R}^n$$

Project 2a:

$$u_i^T u_j = \delta_{ij}$$

$$v_i^T v_j = u_i^T \underbrace{S^T S}_{\substack{\uparrow \\ 1}} u_j = \delta_{ij}$$

—

final basis also orthogonal,
Unit Test 1: check that

$v_i^T v_j = \delta_{ij}$ is satisfied,
with a complete orthogonal
basis u , we can express
a new orthogonal basis
 v

$$v_j = \sum_{i=1}^n \boxed{S_{ji}} u_i$$

They are given by the
Jacobi rotations

$$\boxed{S = S_m S_{m-1} \dots S_1}$$

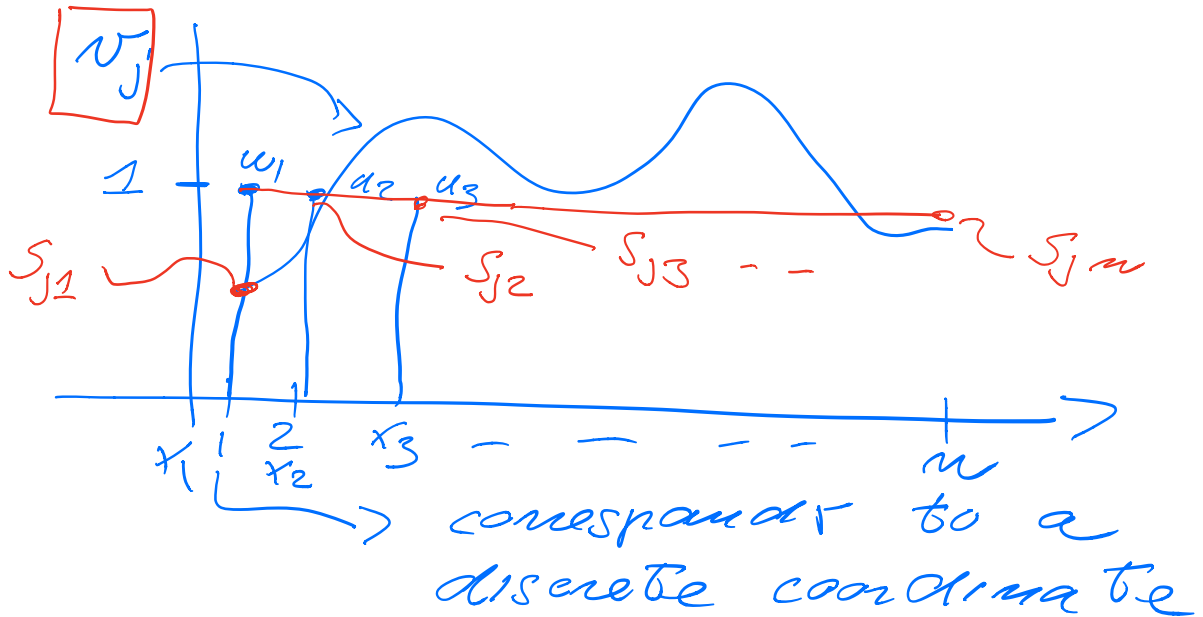
$$u = [u_1 \ u_2 \ \dots \ u_n]$$

$$u_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad u_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} \quad \dots$$

The final eigenvector v_j
for eigenvalue λ_j will

be a linear combination of all u_i , defined by the S_{ij}

We want the v_j to be a function we can plot



With orthogonal transformations, eigenvalues are unchanged, but the eigenvectors change via $[S u]$

$$v_j = \begin{bmatrix} x & x & x & x \\ x & x & x & x \\ x & x & x & x \end{bmatrix} u_i$$

Modifying $\frac{d^2 u(x)}{dx^2} = -F u(x)$

to a different problem but with almost the same code.
 Schrödinger's eq for one particle in 3-dim:

$$\left(-\frac{\hbar^2}{2m} \nabla^2 + \boxed{V(\vec{r})} \right) \psi(\vec{r}) = E \psi(\vec{r})$$

$$\vec{r} = x\vec{e}_x + y\vec{e}_y + z\vec{e}_z$$

Cartesian \rightarrow spherical coordinates
 3 decoupled differential eqs
 one for $\phi \in [0, 2\pi]$

$$- \quad - \quad \theta \in [0, \pi]$$

$$- \quad - \quad r \in [0, \infty)$$

$$x, y, z \in (-\infty, +\infty)$$

$$\psi(\vec{r}) = \boxed{Y_{ml}(\theta, \phi)} R(r)$$

We have

$l=0$

$$- \frac{\hbar^2}{2m} \left(\frac{1}{r^2} \frac{d}{dr} r^2 \frac{d}{dr} + \frac{l(l+1)}{r^2} \right) R(r)$$

$$+ V(r) R(r) = E R(r)$$

\downarrow gives 2nd derivative +

Problem $\frac{R(0) = \text{const} = ?}{R(\infty) = 0}$

Solve instead
 $u(r) = r R(r)$

$$\frac{1}{r^2} \frac{d}{dr} r^2 \frac{d}{dr} \left(\frac{u(r)}{r} \right)$$

$$\Rightarrow -\frac{\hbar^2}{2m} \left[\frac{d^2 u(r)}{dr^2} \right] + [V(r)] u(r) = [E u(r)]$$

$$R(0) = \text{const} \Rightarrow u(0) = 0$$

$$u(0) = 0 \quad \text{and} \quad u(\infty) = 0$$

Original:

$$\left[\frac{d^2 u(x)}{dx^2} \right] = -E u(x)$$

$$V(r) = \frac{1}{2} m \omega^2 r^2$$

$$-\frac{\hbar^2}{2m} \frac{d^2 u}{dr^2} + \frac{1}{2} m \omega^2 r^2 u(r) = E u(r)$$

Scale the equations:

Dim-less variable $\rho = \alpha \cdot r$
dimension
inverse
length

$$-\frac{\hbar^2 \alpha^2}{2m} \frac{d^2 u}{d\rho^2} +$$

$$\frac{1}{2} m \omega^2 \frac{\rho^2}{\alpha^2} u(\rho) = E u(\rho)$$

multiply with $\frac{2m}{\hbar^2 \alpha^2}$

$$-\frac{d^2 u}{d\rho^2} + \boxed{\frac{m^2 \omega^2}{\hbar^2 \alpha^4}} \rho^2 u = \lambda u$$

$$\lambda = \frac{E \cdot 2m}{\hbar^2 \alpha^2}$$

$$\frac{m^2 \omega^2}{\hbar^2 \alpha^4} = 1 \Rightarrow$$

$$\alpha^2 = \sqrt{\frac{m^2 \omega^2}{\hbar^2}} \Rightarrow$$

$$\alpha = \sqrt{\frac{m \cdot \omega}{\hbar}}$$

$$\sqrt{\frac{mc^2 \hbar \omega}{\hbar^2 c^2}}$$

(energy \times length)²

$\sim \frac{1}{\text{length}}$

$\alpha = \text{natural length scale,}$

$$-\frac{\alpha^2 u}{\alpha g^2} + g^2 u = \lambda u$$

Discretized version

$$T u = \lambda u$$

$$T = \begin{bmatrix} \frac{2}{h^2} + g_1^2 & -\frac{1}{h^2} & 0 & 0 \\ -\frac{1}{h^2} & \frac{2}{h^2} + g_2^2 & -\frac{1}{h^2} & 0 \\ 0 & -\frac{1}{h^2} & \ddots & \ddots \\ 0 & 0 & -\frac{1}{h^2} & \frac{2}{h^2} + g_n^2 \end{bmatrix}$$