|  |
| --- |
| tMotor leftMotor = motorD; tMotor rightMotor = motorA;  task main(){  int power;  power = 30;   while (true){  if(getColorReflected(S1)<=8){  setMotorSpeed(leftMotor, power);  setMotorSpeed(rightMotor, -7);  }  if(getColorReflected(S1)>13 && getColorReflected(S1)<19){  setMotorSpeed(leftMotor,(power-12));  setMotorSpeed(rightMotor,6);  }  if(getColorReflected(S1)>18 && getColorReflected(S1)<24){  setMotorSpeed(leftMotor,(power-18));  setMotorSpeed(rightMotor,12);  }  if(getColorReflected(S1)>23 && getColorReflected(S1)<28){  setMotorSpeed(leftMotor,0);  setMotorSpeed(rightMotor,18);  }  if(getColorReflected(S1)>=28){  setMotorSpeed(leftMotor,-7);  setMotorSpeed(rightMotor,power);  }  } } |