John Chrosniak

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EDUCATION

University of Virginia, School of Engineering & Applied Science — **Charlottesville, VA**
Master of Science, Computer Science – GPA: 3.96/40 — *December 2023*
Certificate, Cyber-Physical Systems
Head Teaching Assistant, Machine Learning

University of Virginia, School of Engineering & Applied Science — **Charlottesville, VA**
Bachelor of Science, Computer Engineering & Computer Science – GPA: 3.91/4.0 — *May 2022*
Minor, Engineering Business

WORK EXPERIENCE

Leidos — **McLean, VA**
Connected Autonomous Vehicle Software Engineer — *March 2024 - Present*
- Developing open-source software for connected autonomous semi-trucks to improve the safety and efficiency of port operations
- Contracting for the US DOT Federal Highway Administration (FHWA) on the Cooperative Automation Research Mobility Applications (CARMA) project

Code19 Racing — **Remote**
Autonomous Racecar Engineer (Part-Time) — *September 2024 - Present*
- Deriving a dynamical model of a full-scale autonomous racecar through state information using a combination of physics and AI
- Improving vehicle localization through sensor fusion to maintain accurate state estimation when traveling upwards of 100 mph

LEADERSHIP EXPERIENCE

Cavalier Autonomous Racing Team — **Charlottesville, VA**
Perception Team Lead — *March 2021 - Present*
- Orchestrated the design, development, and deployment of the object detection, tracking, and trajectory prediction stack for precise state estimation of a full-scale autonomous racecar competing in the Indy Autonomous Challenge
- Trained and deployed a LiDAR object detection neural network using PyTorch and TensorRT to detect opponent vehicles

University of Virginia Solar Car Team — **Charlottesville, VA**
Embedded System Team Lead — *May 2020 – July 2022*
- Spearheaded PCB and RTOS design for a distributed embedded architecture that interfaces the motor, battery pack, and other components of a full-scale, solar-powered racecar via CANbus
- Helped lead the team to compete in its first race in over 20 years

RESEARCH EXPERIENCE

Combining AI & Physics for Vehicle Dynamics Modeling – [Code], [RA-L Paper] — *Fall 2023*
- Pioneered a physics-informed neural network capable of estimating time-variant coefficients for a vehicle dynamics model using observations of the vehicle's motion for safe and precise control
- Introduced a constraining mechanism to ensure estimated coefficients always lie within their physically meaningful range
- Tools: [Python, PyTorch, ROS2, Comet ML]

RACECAR Autonomous Racing Dataset – [Code], [IROS Paper], [ROSCon Presentation] — *Spring 2023*
- Developed a multi-threaded library to convert ROS2 bag files to the nuScenes dataset format for community release
- Facilitated collaboration from six international universities to release the first autonomous racing dataset
- Tools: [C++, ROS2, ROSBag API, OpenCV, PCL, Docker]

Trajectory Prediction of Formula Racing Cars – [Code], [ICRA Workshop Paper] — *Spring 2021*
- Trained an LSTM neural network to predict the future trajectory of Formula race cars using historical motion observations
- Designed a filtering algorithm to simulate visual occlusion for a virtual camera in the Deep Racing simulator
- Tools: [Python, PyTorch, UDP, Shapely]

PROJECTS

AIPD: Enforcing Traffic Violations with Autonomous Vehicles – [Code] — *Spring 2022*
- Created a proof of concept demonstration of how autonomous vehicles could effectively enforce traffic laws without the need for traffic stops using the nuScenes dataset
- Tools: [Python, ROS, ROSBag API, OpenCV, Qt]

Anti-Theft Package Delivery System – [Firmware], [Hardware], [Web App] — *Fall 2021*
- Designed the embedded software and hardware for a prototype package delivery system that allows users to generate single-use passcodes and view video footage from deliveries on a web application
- Tools: [Raspberry Pi, C++, Python, AWS S3, OpenCV, Flask, KiCad]

Semantic Segmentation of Agricultural Fields – [Code] — *Fall 2020*
- Deployed a semantic segmentation computer vision model to identify agricultural regions at risk of polluting the Chesapeake Bay watershed using satellite image data
- Tools: [Python, Tensorflow, Keras, GeoPandas, Rasterio]

SKILLS SUMMARY

- **Languages:** Python, C/C++, MATLAB, Java, Assembly (x86/ARM), CUDA
- **Tools:** PyTorch, TensorFlow, Keras, PCL, OpenCV, TensorRT, AWS, Docker, Travis-CI, Git, MySQL
- **Frameworks:** ROS, ROS2, Django, Flask, MbedOS
- **Platforms:** Linux, STM32, MSP432, Arduino, Raspberry Pi, Jetson