

view_frames Result

Recorded at time: 250.415

odom

Broadcaster: /gazebo
Average rate: 10.204 Hz
Most recent transform: 250.357 (0.058 sec old)
Buffer length: 4.900 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 250.414 (0.001 sec old)
Buffer length: 4.900 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 250.414 (0.001 sec old)
Buffer length: 4.900 sec

right_wheel

