Report

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I. INTRODUCTION

One of the biggest challenges the researchers and industry practitioners are facing in wireless communication area is how to bridge the sharp gap between increasing demand of high speed communication of rich multimedia information with high level Quality of Service (QoS) and the limited radio frequency spectrum over a complex space-time varying environment. As the most promising technology for solving this problem, Multiple Input Multiple Output (MIMO) technology has been of immense research interest over the last several tens of years and become mature, which is incorporated into the emerging wireless broadband standard like 802.11ac [1] long-term evolution (LTE) [2]. The core idea of MIMO system is to use multiple antennas at both transmitting and receiving end, so that multiplexing gain (multiple parallel spatial data pipelines that can improve bandwidth efficiency) and diversity gain (better reliability of communication link) is obtained by employing spatial domain. Large MIMO (also called Massive MIMO) is an upgrade version of conventional MIMO system, it equips unprecedentedly hundreds of low power low price antennas at base station (BS), serving several tens of terminals simultaneously, It can achieve full potential of conventional MIMO system while providing additional power efficiency as well as system robustness [3] [4].

The price paid for large MIMO system is the increasing complexities for signal processing at both transmitting and receiving end. Uplink Detector is one of the key components in large MIMO system. With orders magnitude more antennas equipped at BS, benefit and challenge coexist in designing of detection algorithms for large MIMO uplink, on the one hand, large number of receive antennas provide potential of large diversity gain, on the other hand, complexity of the algorithm becomes extremely crucial to make system practical.

The optimal maximum likelihood detector (MLD) for MIMO system requires the complexity increase exponentially with number of transmitted antennas with a factor of the size of size of constellation, which is prohibitive in practical implementations. Sphere Decoder (SD) [5] is the most prominent algorithm that utilizes lattice structure of MIMO system. Its variant fixed complexity sphere decoder (FCSD) [6] make it possible to achieve near optimal performance with a fixed complexity under different signal to noise ratio (SNR). However, all the algorithms that based on lattice structure have the same shortage - their complexities increases exponentially with a factor of the size of symbol constellation. Therefore, they are prohibitive when it comes to a high order modulation scheme, for example in IEEE 802.11ac standard [1], the modulation scheme is 256QAM.

Suboptimal linear detectors (LD) like minimum mean square error (MMSE) and zero forcing (ZF) along with their sequential interference cancellation with optimized ordering (OSIC) counterparts [7] [8] [9], which have good performance for low loading factor in massive MIMO system (that is the number of receive antennas is much larger than the number of transmit antennas) [10]. In the last several years, a set of detection algorithms are proposed with complexities that is comparable with LD-OSIC and suboptimal performance can be achieved. The local search algorithm, such as likelihood ascend searching (LAS) [11] [12], an theoretical analysis of upper bound of bit error rate (BER) and lower bound of on asymptotic multiuser efficiency for the LAS detector was presented [13]. Layered Tabu search algorithm presented in [14] is superior to the LAS algorithms because it can move away to new searching area to avoid local minimal. Message passing detectors based on belief propagation (BF) and Gaussian Approximation (GA) [15] [16] [17] [18]. Markov Chain Monte Carlo (MCMC) algorithm [19] and Lattice Reduction (LR) aided detectors [20].

Firmly grounded in framework of statistical learning theory, Support Vector Machine (SVM) has become a powerful tool to solve real world supervised learning problems such as classification, regression and prediction. SVM method is a nonlinear generalization of Generalized Portrait algorithm developed by Vapnik in 1960s [21] [22], which can give good generalization performance to unseen data [23].

Research and industry interest of SVM boosted since 1990s, promoted by related works of Vapnik and co-workers at AT& T Bell laboratory [24] [25] [26] [27] [28] [29] Moreover, the kernel based methods [23] carries out nonlinear learning task by mapping input data sets into high dimensional feature space, then replacing inner product of feature mappings by computational inexpensive kernel functions discarding the actual structure of the feature space. This rational is supported mathematically by Reproducing Kernel Hilbert Space (RKHS). Based on the same regularized risk function principle, -Support Vector Regression (ϵ-SVR) was developed [26] [30].

Like SVM, ϵ-SVR solving original optimization problem by transforming it into Lagrange dual optimization problem, which can be solved by Quadratic Programming (QP), Sequential Minimal Optimization (SMO) algorithm was proposed as a fast algorithm to solve this QP problem by decompose the it into sub QP problems and solve them analytically [31], therefore, the computational intensive numerical method can be avoided. A more general method is decomposition solver, which refers to a set of algorithms that separate the optimization variables (Lagrange multipliers) into two sets W and N, W is the work set and N contains the remaining optimization variables. In each iteration, only the optimization variables in work set is optimized while keeping other variables fixed. SMO algorithm is an extreme case of decomposition solver. An important issue of decomposition solver is the choice of work set, one strategy is to choose Karush-Kuhn-Tucker (KKT) condition violators, and final converge can be guaranteed [32]. SMO algorithm restricts the size of work set to 2, because of linear constraint in dual problem that inducted by offset. In [33], a method to train SVM without offset was proposed, with the comparable performance to the SVM with offset. The authors work demonstrates that with the combination of two single optimization variable work set selection strategies which requires searching time $O(n)$ and update a work set size of two in each iteration, this method can achieve a iteration time as few as that searching over all pairs of optimization variables which requires $O(n^2)$ searching times.

Until now, although the mathematical foundation of kernel based methods is RKHS which is defined in complex domain, the most of practitioners are dealing with real data set. In communication and signal processing area, the channel gains, signals, waveforms etc. are all represented in complex form. Recently, a pure complex SVR & SVM based on complex kernel was proposed in [34], which can process the complex data set purely in complex domain. The simulation of channel realization and equalization in [34] demonstrate a better performance as well as reduced complexity comparing to simply split learning task into two real case by real kernel. Based on this work, we construct a prototype of a complexity-performance controllable detector for large MIMO based on dual channel complex SVR. The detector can work in two parallel real SVR pipeline which can be solved independently. Moreover, only real part of kernel matrix is needed in both channel. This means a large amount of computation can be reduced. Based on the discrete time MIMO channel model, In our regression model, this CSVR-detector is constructed without offset, Therefore, for each real SVR without offset, in principle, only one variable is needed to be updated in each iteration, In our prototype, we propose a sequential single optimization variable searching strategy that find two optimization variable sequentially, which can approximate the optimal double optimization variables searching strategy.

II. Brief Introduction to ϵ-Support Vector Regression

A. Regression Model

Suppose we are given training data set $((\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \cdots, (\mathbf{x}_l, y_l))$, l denotes the number of training samples, $\mathbf{x} \in \mathbb{R}^v$ denotes input data vector, v is the number of features in $\mathbf{x}$. y denotes output. The regression model (either linear or non-linear regression) is given by

$$y_i = \mathbf{w}^T \Phi(\mathbf{x}_i) + b \quad i \in 1 \cdots l \tag{1}$$

where $\mathbf{w}$ denotes regression coefficient vector, $\Phi(x)$ denotes the mapping of $\mathbf{x}$ to higher dimensional feature space. 1.

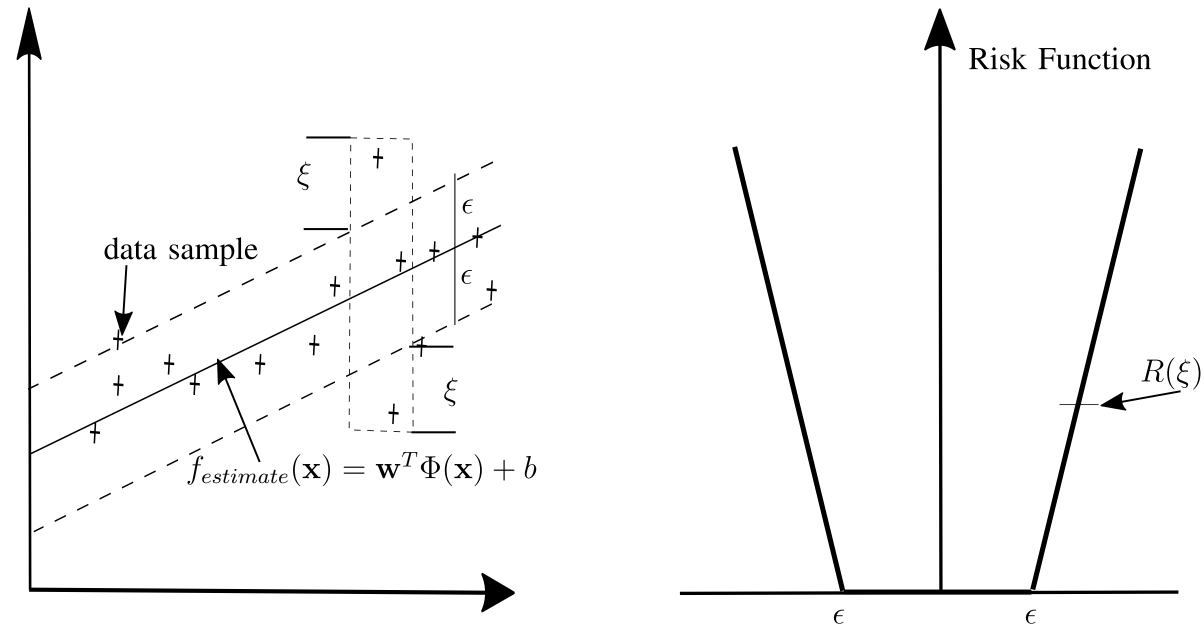

Fig. 1. ϵ-Support Vector Regression and Risk Functional

Here we give the primal optimization problem directly

$$\frac{1}{2}||\mathbf{w}||^2 + \sum_{j=1}^{l} C_i(R(\xi_i) + R(\hat{\xi}_i))$$

$$s.t. \begin{cases} y_i - \mathbf{w}^T\Phi(\mathbf{x}_i) - b & \leq \epsilon + \xi_i \\ \mathbf{w}^T\Phi(\mathbf{x}_i) + b - y_i & \leq \epsilon + \hat{\xi}_i \\ \epsilon, \xi, \hat{\xi} & \geq 0 \end{cases} \tag{2}$$

In 2, $\frac{1}{2}||\mathbf{w}||^2$ is the regularization term in order to ensure the flatness of regression model. ϵ

denotes the precision, if the error between estimation and real output is less than ϵ, As shown in Fig 1, only those data points outside the shadow part, which is called ϵ tube, contribute to cost function. ξ and $\hat{\xi}$ denote slack variables that cope with noise of input data set, $R(x)$ denotes risk function, the simplest risk function is $R(x) = x$, risk function is determined by the statistical distribution of noise [30], for example if the noise subject to Gaussian distribution, the optimal cost function is $R(x) = \frac{1}{2}x^2$. $C\sum_{i=1}^{l}(\xi_i + \hat{\xi}_i)$ denotes the penalty of noise, $C \in \mathbb{R}$ and $C \geq 0$ controls the trade off between regularization term and noise penalty term.

B. Risk Functional

From the rationale of regularized risk function, let $f_{true}(\mathbf{x})$ denotes true regression function and $f_{estimate}(\mathbf{x})$, $c(\mathbf{x}, y, f_{estimate}(\mathbf{x}))$ denotes the risk function, the regression model can be written as $y = f_{true}(\mathbf{x}) + \xi$, ξ denotes additive noise. Assume the data samples are i.i.d. Based on Maximum Likelihood (ML) principle we want to

$$\begin{aligned} maximize \quad \prod_{i=1}^{l} P(y_i | f_{estimation}(\mathbf{x}_i)) \qquad &= maximize \quad \textstyle\prod_{i=1}^{l} P(\xi_i) \\ &= maximize \quad \textstyle\prod_{i=1}^{l} P(y_i - f(\mathbf{x}_i)), \end{aligned} \tag{3}$$

Take the logarithm of (79), we have

$$maximize \quad \sum_{i=1}^{l} log(P(y_i - f_{estimation}(\mathbf{x}_i))), \tag{4}$$

Therefore the ith risk function of $(\mathbf{x_i}, y_i)$ can be written as

$$c(\mathbf{x}_i, y_i, f_{estimation}(\mathbf{x}_i)) = -log(P(y_i - f_{estimation}(\mathbf{x}_i))). \tag{5}$$

Thus the equivalent formula of (12) can be written as

$$minimize \quad \sum_{i=1}^{l} c(\mathbf{x}_i, y_i, f_{estimation}(\mathbf{x}_i)), \tag{6}$$

In ϵ-SVR, Vapnik's ϵ-insensitive function, as shown in (7), is applied to (5).

$$|x|_\epsilon = \begin{cases} 0 & if \quad |x| < \epsilon \\ |x| - \epsilon & otherwise \end{cases} \tag{7}$$

Thus the cost function in ϵ-SVR can be written as

$$\tilde{c}(\mathbf{x}, y, f_{estimation}(\mathbf{x})) = \frac{1}{l}\sum_{i=1}^{l} m_i(-log(P(|y_i - f_{estimation}(\mathbf{x}_i)|_\epsilon))), \tag{8}$$

where $m_i \in \mathbb{R}$, $m_i > 0$ denotes the weight parameter, if $y_i > f_{estiamtion}(\mathbf{x})$, $m_i = m_{positive}$, else $m_i = m_{negative}$, Therefore the regularized risk function can written as

$$minimize \quad \lambda||\mathbf{w}||^2 + \tilde{c}(\mathbf{x}, y, f_{estimation}(\mathbf{x})), \tag{9}$$

where λ denotes the weight of regularization term, divide (9) by $\frac{1}{2\lambda}$, we have the optimization problem

$$minimize \quad \frac{1}{2}||\mathbf{w}||^2 + \sum_{i=1}^{l} C_i(-log(P(|y_i - f_{estimation}(\mathbf{x}_i)|_\epsilon))), \tag{10}$$

where $C_i = \frac{m_i}{2\lambda l}$, based on (10), by introducing slack variables, we can easily derive the equivalent optimization problem as same as (2):

$$
\begin{aligned}
&minimize \quad f(\mathbf{w}) = \frac{1}{2}||\mathbf{w}||^2 + \sum_{j=1}^{l} C_i(R(\xi_i) + R(\hat{\xi}_i)) \\
&s.t. \begin{cases} y_i - \mathbf{w}^T\Phi(\mathbf{x}_i) - b & \leq \epsilon + \xi_i \\ \mathbf{w}^T\Phi(\mathbf{x}_i) + b - y_i & \leq \epsilon + \hat{\xi}_i \\ \epsilon, \xi, \hat{\xi} & \geq 0 \end{cases}
\end{aligned} \tag{11}
$$

where $R(x) = -log(P(x))$, by this way, the discontinuity of ϵ-insensitive function is conquered.

C. Lagrange Duality

According to Lagrange Theorem, the optimization problem (11) can be transferred to dual form by combining original objective function with linear combination of equality and inequality constraints, the combination coefficient is called Lagrange multiplier. Thus we have Lagrange function.

$$
\begin{aligned}
\Theta(\mathbf{w}, b, \xi, \hat{\xi}, \alpha, \hat{\alpha}, \eta, \hat{\eta}) = &\frac{1}{2}||\mathbf{w}||^2 + \sum_{j=1}^{l} C_i(R(\xi_i) + R(\hat{\xi}_i)) - \sum_{i=1}^{l}(\eta_i\xi_i + \hat{\eta}_i\hat{\xi}_i) \\
&- \sum_{i=1}^{l} \alpha_i(\epsilon + \xi_i - y_i + \mathbf{w}^T\Phi(\mathbf{x}_i)) - \sum_{i=1}^{l} \hat{\alpha}_i(\epsilon + \hat{\xi}_i + y_i - \mathbf{w}^T\Phi(\mathbf{x}_i)) \\
&s.t. \begin{cases} \eta, \hat{\eta}, \alpha, \hat{\alpha} \geq 0 \\ \xi, \hat{\xi} \geq 0 \end{cases}
\end{aligned} \tag{12}
$$

where η,$\hat{\eta}$, α, $\hat{\alpha}$ are Lagrange multipliers.

The sufficient and necessary condition that $f(\mathbf{w}^*)$ is the global minimum of (11) is called

Karush-Kuhn-Tucker (KKT) conditions, which can be written as [35]

$$\frac{\partial \Theta}{\partial \mathbf{w}} = \mathbf{w} - \sum_{i=1}^{l} (\alpha_i - \hat{\alpha}_i) \Phi(\mathbf{x}_i) = 0 \tag{13}$$

$$\frac{\partial \Theta}{\partial \xi} = C_i R^{'}(\xi_i) - \eta_i - \alpha_i = 0 \tag{14}$$

$$\frac{\partial \Theta}{\partial \hat{\xi}} = C_i R^{'}(\hat{\xi}_i) - \hat{\eta}_i - \hat{\alpha}_i = 0 \tag{15}$$

$$\frac{\partial \Theta}{\partial b} = \sum_{i=1}^{l} (\alpha_i - \hat{\alpha}_i) = 0 \tag{16}$$

$$\begin{cases} \alpha, \hat{\alpha} \geq 0 \\ \alpha(y - \mathbf{w}^T \Phi(\mathbf{x}) - b - \epsilon - \xi) = 0 \\ \hat{\alpha}(\mathbf{w}^T \Phi(\mathbf{x}) + b - y - \epsilon - \hat{\xi}) = 0 \\ y - \mathbf{w}^T \Phi(\mathbf{x}) - b - \epsilon - \xi \leq 0 \\ \mathbf{w}^T \Phi(\mathbf{x}) + b - y - \epsilon - \hat{\xi} \leq 0 \end{cases} \tag{17}$$

The conditions in (17) is called KKT complimentary condition. Then substitute (14)-(17) to (12) and for sake of brevity, we make C_i uniform to all data samples, we have the dual form of objective function

$$\theta(\alpha,\hat{\alpha}) = \frac{1}{2}\sum_{i=1}^{l}\sum_{i=1}^{l}(\alpha_i-\hat{\alpha}_i)(\alpha_j-\hat{\alpha}_j)\Phi(\mathbf{x}_j)^T\Phi(\mathbf{x}_i) + C\sum_{i=1}^{l}[(R(\xi_i)-\xi_i R^{'}(\xi_i))$$

$$+(R(\hat{\xi}_i)-\hat{\xi}_i R^{'}(\hat{\xi}_i))] + \sum_{i=1}^{l}[(\alpha_i-\hat{\alpha}_i)y_i-(\alpha_i+\hat{\alpha}_i)\epsilon]$$

$$-\sum_{i=1}^{l}\sum_{i=1}^{l}(\alpha_i-\hat{\alpha}_i)(\alpha_j-\hat{\alpha}_j)\Phi(\mathbf{x}_j)^T\Phi(\mathbf{x}_i),$$

$$s.t. \begin{cases} \sum_{i=1}^{l}(\alpha_i-\hat{\alpha}_i)=0 \\ 0<\alpha<C\tilde{R}^{'}(\alpha) \\ 0<\hat{\alpha}<C\tilde{R}^{'}(\hat{\alpha}) \end{cases} \tag{18}$$

Obviously $\theta(\alpha,\hat{\alpha}) \le \Theta(\mathbf{w},\alpha,\hat{\alpha},\eta,\hat{\eta})$, notice by transforming $\Theta(\mathbf{w},\alpha,\hat{\alpha},\eta,\hat{\eta})$, (14)-(17) are satisfied, therefore, KKT complimentary condition (17) is the only requirement to find global optimal point of original optimization problem. Because

$$\Theta(\mathbf{w},\alpha,\hat{\alpha},\eta,\hat{\eta}) = f(\mathbf{w}) + \sum_i(\alpha_i g_i(\mathbf{w})+\hat{\alpha}_i\hat{g}_i(\mathbf{w})) + \sum_i(\eta_i l_i(\mathbf{w})+\hat{\eta}_i\hat{l}_i(\mathbf{w})), \tag{19}$$

where $g_i(\mathbf{w})$, $g_i(\hat{\mathbf{w}})$, $l_i(\mathbf{w})$, $\hat{l}_i(\mathbf{w})$ denote inequality constraints.

$$g_i(\mathbf{w}) = \mathbf{y}_i - \mathbf{w}^T\Phi(\mathbf{x}_i) - b - \epsilon - \xi_i \le 0 \tag{20}$$

$$\hat{g}_i(\mathbf{w}) = \mathbf{w}^T\Phi(\mathbf{x}_i) + b - \mathbf{y}_i - \epsilon - \hat{\xi}_i \le 0 \tag{21}$$

$$l_i(\mathbf{w}) = -\xi_i \le 0 \tag{22}$$

$$\hat{l}_i(\mathbf{w}) = -\hat{\xi}_i \le 0 \tag{23}$$

Hence $\Theta \leq f(\mathbf{w})$, we have $\theta \leq \Theta \leq f(\mathbf{w})$, therefore the upper bound of θ is determined by the original objective function $f(\mathbf{w})$. when $\theta = f(\mathbf{w})$, according to (19), the linear combination term of inequality constraints equal to zero, that is, KKT complimentary conditions in (17) satisfied. hence the global optimal point is found for both θ and $f(\mathbf{w})$ if and only if the equality holds. Therefore duality gap is defined as $G = f(\mathbf{w}) - \theta$, which can be used as an evaluation for the closeness of one solution to the global optimal.

In conclusion, the dual objective function can be written as

$$\begin{aligned}
&maximize \quad \theta = -\frac{1}{2}\sum_{i=1}^{l}\sum_{i=1}^{l}(\alpha_i - \hat{\alpha_i})(\alpha_j - \hat{\alpha_j})\Phi(\mathbf{x}_j)^T\Phi(\mathbf{x}_i) + \sum_{i=i}^{l}[(\alpha_i - \hat{\alpha_i})y_i - (\alpha_i + \hat{\alpha_i})\epsilon] \\
&+C\sum_{i=1}^{l}[\tilde{R}(\xi_i) + \tilde{R}(\hat{\xi_i})] \\
&= -\frac{1}{2}(\mathbf{a} - \hat{\mathbf{a}})^T\mathbf{K}(\mathbf{a} - \hat{\mathbf{a}}) + (\mathbf{y} - \epsilon)^T\mathbf{a} + (-\mathbf{y} - \epsilon)^T\hat{\mathbf{a}} + \mathbf{e}^T C(\tilde{R}(\xi) + \tilde{R}(\hat{\xi})),
\end{aligned} \tag{24}$$

where $\mathbf{a} = [\alpha_1, \alpha_2, \ldots, \alpha_l]^T$, $\hat{\mathbf{a}} = [\hat{\alpha}_1, \hat{\alpha}_2, \ldots, \hat{\alpha}_l]^T$, $\mathbf{y} = [y_1, y_2, \ldots y_l]^T$, $\mathbf{e} = [1, 1, \ldots, 1]^T \in \mathbb{R}^l$, $\mathbf{e}_i$ denotes the vector that only ith component is 1 while the rest are all 0, $\tilde{R}(\xi) = R(\xi) - \xi R'(\xi) \in \mathbb{R}^l$, $\mathbf{K}_{ij} = \Phi(\mathbf{x}_j)^T\Phi(\mathbf{x}_i)$ denotes data kernel matrix. We define the following $2l$ vectors $\mathbf{a}^{(*)} = [\begin{smallmatrix}\mathbf{a}\\ \hat{\mathbf{a}}\end{smallmatrix}]$, $\mathbf{v} \in \mathbb{R}^{2l}$,

$$\mathbf{v}_i = \begin{cases} 1 & i = 1, \ldots, l \\ -1 & i = l+1, \ldots, 2l \end{cases} \tag{25}$$

(24) can also be reformulate as

$$maximize \quad \Theta = -\frac{1}{2}(\mathbf{a}^*)^T \left[\begin{smallmatrix}\mathbf{K} & -\mathbf{K}\\ -\mathbf{K} & \mathbf{K}\end{smallmatrix}\right] \mathbf{a}^{(*)} + [(\mathbf{y} - \epsilon)^T, (-\mathbf{y} - \epsilon)^T]\mathbf{a}^{(*)} + \mathbf{e}^T C(\tilde{R}(\xi) + \tilde{R}(\hat{\xi})), \tag{26}$$

III. System Model

Consider a complex large MIMO uplink multiplexing system with N_t users, each user has one transmit antenna. The number of receive antennas at Base Station (BS) is N_r, $N_r \geq N_t$. Typically large MIMO systems have hundreds of antennas at BS serving several tens of terminals, as shown in Fig 2.

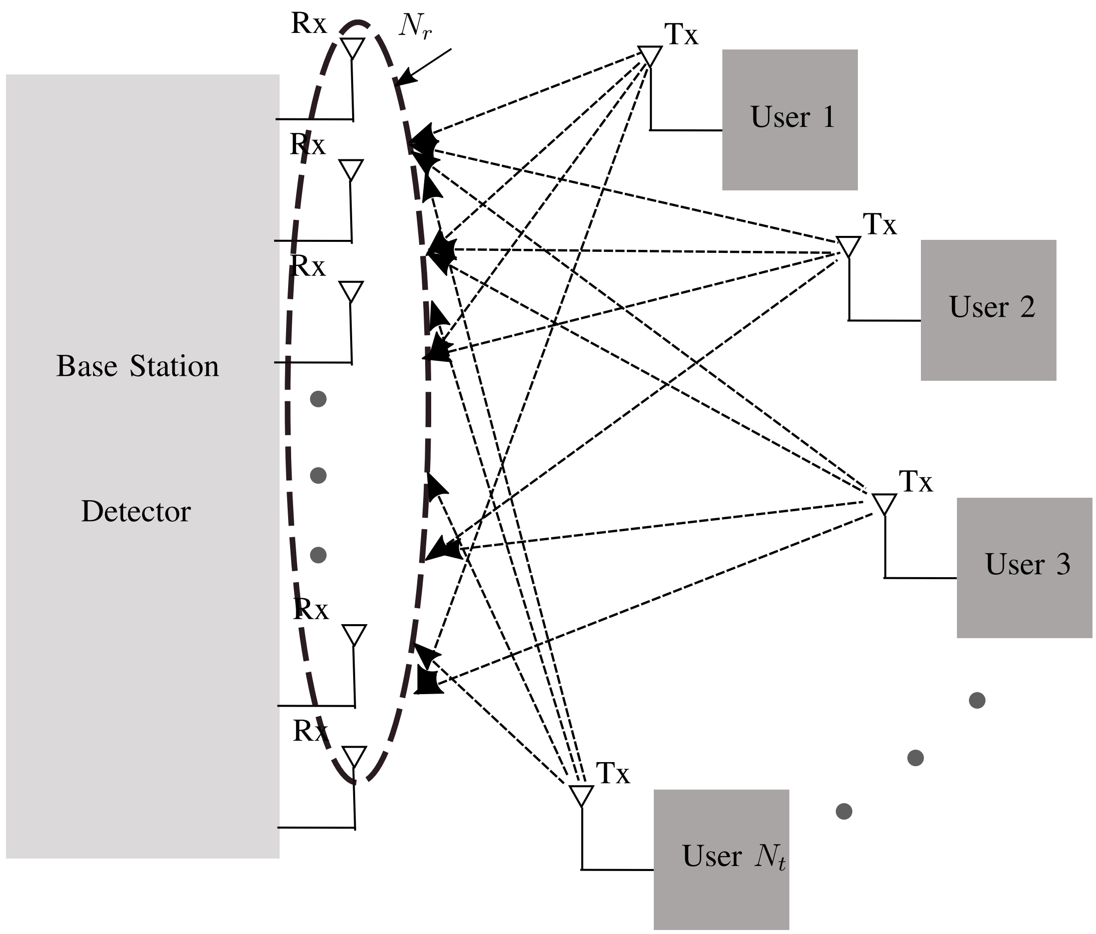

Fig. 2. Large MIMO uplink system

Uncoded bit sequences, which are modulated to complex symbols, are transmitted by users over a flat fading channel. The discrete time model is:

$$\mathbf{y} = \mathbf{H}\mathbf{s} + \mathbf{n}, \tag{27}$$

where $\mathbf{y} \in \mathbb{C}^{N_r \times 1}$ is the received symbol vector, $\mathbf{s} \in \mathbb{C}^{N_t}$ is the transmitted symbol vector, with components that are mutually independent and taken from a finite signal constellation alphabet $\mathbb{O}$ (e.g. 4-QAM, 16-QAM, 64-QAM) of size M. The transmitted symbol vectors $\mathbf{s} \in \mathbb{O}^{N_t}$, satisfy $\mathbb{E}[\mathbf{s}\mathbf{s}^H] = \mathbf{I}_{N_t} E_s$, where E_s denotes the symbol average energy, and $\mathbb{E}[\cdot]$ denotes the expectation operation. Furthermore $\mathbf{H} \in \mathbb{C}^{N_r \times N_t}$ denotes the Rayleigh fading channel propagation matrix with independent identically distributed (i.i.d) circularly symmetric complex Gaussian zero mean components with unit variance. Finally, $\mathbf{n} \in \mathbb{C}^{N_r}$ is the additive white Gaussian noise (AWGN) vector with zero mean components and $\mathbb{E}[\mathbf{n}\mathbf{n}^H] = \mathbf{I}_{N_r} N_0$, where N_0 denotes the noise power spectrum density, and hence $\frac{E_s}{N_0}$ is the signal to noise ratio (SNR).

Assume the receiver has perfect channel state information (CSI), meaning that $\mathbf{H}$ is known, as well as the SNR. The task of the MIMO decoder is to recover $\mathbf{s}$ based on $\mathbf{y}$ and $\mathbf{H}$.

IV. Dual Channel Complex Support Vector Regression for Large MIMO system

Based on discrete time model of large MIMO uplink system in (27), in our regression model, the training data sample at detector is $(\mathbf{h}_1, y_1)(\mathbf{h}_2, y_2), \ldots, (\mathbf{h}_{N_r}, y_{N_r})$, where $\mathbf{h}_i$ denotes ith row of channel propagation matrix $\mathbf{H}$, this yields a regression task without offset b:

$$y_i = f_{true}(\mathbf{h}_i) + n, \tag{28}$$

$$f_{true}(\mathbf{h}_i) = \mathbf{h}_i \mathbf{s}, \tag{29}$$

$$\tag{30}$$

where $f_{true}()$ denotes the underlying true function, n denotes additive noise. In this regression problem, receive symbol y is the output data, $\mathbf{h}$ is input data sample, transmitted symbol vector s is regression coefficients. Because the large MIMO system we consider here is complex, we employ complex support vector regression (CSVR) without offset term b. As shown in section II, in order to derive Lagrange duality optimization formula, partial derivatives of objective function with respect to $\mathbf{w}$ and ξ are needed to be calculated, in CSVR, that means take partial derivatives to risk functions which are defined in complex domain. Recently mathematical results of Wirtinger's calculus in Reproducing Kernel Hilbert Space (RKHS) is employed to solve this problem [36]. First we generalize our regression model by complex RKHS, Let $<,>_H$ denotes inner product operation in real RKHS. $<,>_{\mathbb{H}}$ denotes inner products operation in complex RKHS. Assume $\mathbf{x}$, $\mathbf{y}$, $\mathbf{z}$, j, $k \in \mathbb{C}$, complex Hilbert space has the following properties

Property 1. $<\mathbf{x}, \mathbf{y}>_{\mathbb{H}} = <\overline{\mathbf{y}, \mathbf{x}}>_{\mathbb{H}}$

Property 2. $<j\mathbf{x} + k\mathbf{y}, \mathbf{z}>_{\mathbb{H}} = j <\mathbf{x}, \mathbf{z}>_{\mathbb{H}} + k <\mathbf{y}, \mathbf{z}>_{\mathbb{H}}$

Property 3. $<\mathbf{z}, j\mathbf{x} + k\mathbf{y}> = \bar{j} <\mathbf{z}, \mathbf{x}>_{\mathbb{H}} + \bar{k} <\mathbf{z}, \mathbf{y}>_{\mathbb{H}}$

Lemma 1. $\mathbf{h}_i \mathbf{s} \in <\mathbf{h}_i, \mathbf{s}^*>_{\mathbb{H}}$

Proof. Assume $\mathbf{a}$, $\mathbf{b} \in \mathbb{R}^v$, it can be easily proved

$$\mathbf{a}^T\mathbf{b} \in < \mathbf{a}, \mathbf{b} >_H, \tag{31}$$

From Property 1 and Property 3, it is obvious

$$< \mathbf{g}, \mathbf{h} >_{\mathbb{H}} = < \mathbf{g}^r, \mathbf{h}^r >_H + < \mathbf{g}^i, \mathbf{h}^i >_H + i(< \mathbf{g}^i, \mathbf{h}^r >_H - < \mathbf{g}^r, \mathbf{h}^i >_H) \tag{32}$$

where $\mathbf{g}$,$\mathbf{h} \in \mathbb{C}^v$, and $\mathbf{g} = \mathbf{g}^r + i\mathbf{g}^i$, $\mathbf{h} = \mathbf{h}^r + i\mathbf{h}^i$. Therefore,

$$\begin{aligned} < \mathbf{h}, \mathbf{s}^* >_{\mathbb{H}} &= < \mathbf{h}^r, (\mathbf{s}^*)^r >_H + < \mathbf{h}^i, (\mathbf{s}^*)^i >_H + i(< \mathbf{h}^i, (\mathbf{s}^*)^r >_H - < \mathbf{h}^r, (\mathbf{s}^*)^i >_H) \\ &= < \mathbf{h}^r, \mathbf{s}^r >_H - < \mathbf{h}^i, \mathbf{s}^i >_H + i(< \mathbf{h}^i, \mathbf{s}^r >_H + < \mathbf{h}^r, \mathbf{s}^i >_H), \end{aligned} \tag{33}$$

$$\mathbf{h}\mathbf{s} = \mathbf{h}^r\mathbf{s}^r - \mathbf{h}^i\mathbf{s}^i + i(\mathbf{h}^i\mathbf{s}^r + \mathbf{h}^r\mathbf{s}^i), \tag{34}$$

Because of (31), (33) and (34), $\mathbf{h}_i\mathbf{s} \in < \mathbf{h}_i, \mathbf{s}^* >_{\mathbb{H}}$. □

represent $\mathbf{s}^*$ by $\mathbf{w}$, The general regularized risk function of large MIMO detection in complex

RKHS can be formulated:

$$\begin{aligned} minimize \quad & \frac{1}{2}||w||^2_{\mathbb{H}} + C\sum_{k=1}^{N_r}[(R(\xi_k^r) + R(\hat{\xi}_k^r) + R(\xi_k^i) + R(\hat{\xi}_k^i))] \\ & s.t. \begin{cases} Re(y_k - <\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}}) \leq \epsilon + \xi_k^r \\ Re(<\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}} - y_k) \leq \epsilon + \hat{\xi}_k^r \\ Im(y_k - <\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}}) \leq \epsilon + \xi_k^i \\ Im(<\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}} - y_k) \leq \epsilon + \hat{\xi}_k^i \\ \xi^r, \hat{\xi}^r, \xi^i, \hat{\xi}^i \geq 0 \end{cases} \end{aligned} \tag{35}$$

where $Re()$ and $Im()$ denote real part and imaginary part of a complex variable, restrictions are set to real and imaginary part of regression function separately. Let $\mathbf{K} = \mathbf{H}\mathbf{H}^H$ denotes the kernel function, $\mathbf{K} = \mathbf{K}^r + i\mathbf{K}^i$, $\mathbf{K}^r$ and $\mathbf{K}^i$ denote matrix of corresponding real part and imaginary part. Similar to the Lagrange duality rational in section II-C, Lagrange function is formulated for (35)

$$\begin{aligned} \theta = & \frac{1}{2}||w||^2_{\mathbb{H}} + C\sum_{k=1}^{N_r}[(R(\xi_k^r) + R(\hat{\xi}_k^r) + R(\xi_k^i) + R(\hat{\xi}_k^i))] - \sum_{k=1}^{N_r}(\eta_i\xi_k^r + \hat{\eta}_k\hat{\xi}_k^r + \tau_k\xi_k^i + \hat{\tau}_k\hat{\xi}_k^i) \\ & - \sum_{k=1}^{N_r}\alpha_k(\epsilon + \xi_k^r - Re(y_k) + Re(<\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}})) - \sum_{k=1}^{N_r}\hat{\alpha}_k(\epsilon + \hat{\xi}_k^r + Re(y_k) - Re(<\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}})) \\ & - \sum_{k=1}^{N_r}\beta_k(\epsilon + \xi_k^i - Im(y_k) + Im(<\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}})) - \sum_{k=1}^{N_r}\hat{\beta}_k(\epsilon + \hat{\xi}_k^i + Im(y_k) - Im(<\mathbf{h}_k, \mathbf{w}>_{\mathbb{H}})) \\ & s.t. \begin{cases} \eta, \hat{\eta}, \tau, \hat{\tau}\alpha, \hat{\alpha}, \beta, \hat{\beta} \geq 0 \\ \xi^r, \hat{\xi}^r, \xi^i, \hat{\xi}^i \geq 0 \end{cases} \end{aligned} \tag{36}$$

with Wirtinger's calculus applied to RKHS described in [36], The partial derivatives of θ respect to $\mathbf{w}$, which is define at complex domain, as well as the real variables ξ^r, $\hat{\xi}^r$, ξ^i and $\hat{\xi}^i$ can be deduced

$$\begin{cases} \frac{\partial\Theta}{\partial\mathbf{w}^*} = \frac{1}{2}\mathbf{w} - \frac{1}{2}\sum_{k=1}^{N_r}\alpha_k\mathbf{h}_k + \frac{1}{2}\sum_{k=1}^{N_r}\hat{\alpha}_k\mathbf{h}_k + \frac{i}{2}(\sum_{k=1}^{N_r}\beta_k\mathbf{h}_k - \sum_{k=1}^{N_r}\hat{\beta}_k\mathbf{h}_k) = 0 \\ \Rightarrow \mathbf{w} = \sum_{k=1}^{N_r}(\alpha_k - \hat{\alpha}_k)\mathbf{h}_k - i\sum_{k=1}^{N_r}(\beta_k - \hat{\beta}_k)\mathbf{h}_k \\ \frac{\partial\Theta}{\partial\xi_k^r} = CR'(\xi_k^r) - \eta_k - \alpha_k = 0 \Rightarrow \eta_k = CR'(\xi_k^r) - \alpha_k \\ \frac{\partial\Theta}{\partial\hat{\xi}_k^r} = CR'(\hat{\xi}_k^r) - \hat{\eta}_k - \hat{\alpha}_k = 0 \Rightarrow \hat{\eta}_k = CR'(\hat{\xi}_k^r) - \hat{\alpha}_k \\ \frac{\partial\Theta}{\partial\xi_k^i} = CR'(\xi_k^i) - \tau_k - \beta_k = 0 \Rightarrow \tau_k = CR'(\xi_k^i) - \beta_k \\ \frac{\partial\Theta}{\partial\hat{\xi}_k^i} = CR'(\hat{\xi}_k^i) - \hat{\eta}_k - \hat{\beta}_k = 0 \Rightarrow \hat{\eta}_k = CR'(\hat{\xi}_k^i) - \hat{\beta}_k \end{cases} \tag{37}$$

Based on (37), we have

$$\begin{aligned} &< \mathbf{h}_i, \mathbf{w} >_{\mathbb{H}} = \sum_{j=1}^{N_r}(\alpha_j - \hat{\alpha}_j) < \mathbf{h}_i, \mathbf{h}_j >_{\mathbb{H}} + i\sum_{j=1}^{N_r}(\beta_j - \hat{\beta}_j) < \mathbf{h}_i, \mathbf{h}_j >_{\mathbb{H}} \\ &= \sum_{j=1}^{N_r}(\alpha_j - \hat{\alpha}_j)\mathbf{h}_i\mathbf{h}_j^H + i\sum_{j=1}^{N_r}(\beta_j - \hat{\beta}_j)\mathbf{h}_i\mathbf{h}_j^H \\ &= \sum_{j=1}^{N_r}(\alpha_j - \hat{\alpha}_j)\mathbf{K}_{ij}^r - \sum_{j=1}^{N_r}(\beta_j - \hat{\beta}_j)\mathbf{K}_{ij}^i + i(\sum_{j=1}^{N_r}(\alpha_j - \hat{\alpha}_j)\mathbf{K}_{ij}^i + \sum_{j=1}^{N_r}(\beta_j - \hat{\beta}_j)\mathbf{K}_{ij}^r), \end{aligned} \tag{38}$$

$$\begin{aligned} ||\mathbf{w}||_{\mathbb{H}}^2 &= \sum_{i,j=1}^{N_r}(\alpha_i - \hat{\alpha}_i)(\alpha_i - \hat{\alpha}_i)\mathbf{h}_i\mathbf{h}_j^H + \sum_{i,j=1}^{N_r}(\beta_i - \hat{\beta}_i)(\beta_i - \hat{\beta}_i)\mathbf{h}_i\mathbf{h}_j^H \\ &+ i(\sum_{i,j=1}^{N_r}(\alpha_i - \hat{\alpha}_i)(\beta_j - \hat{\beta}_j)\mathbf{h}_i\mathbf{h}_j^H - \sum_{i,j=1}^{N_r}(\alpha_i - \hat{\alpha}_i)(\beta_j - \hat{\beta}_j)\mathbf{h}_j\mathbf{h}_i^H) \end{aligned} \tag{39}$$

Because $\mathbf{K}$ is Hermitian, thus $\mathbf{K}_{ij} = \mathbf{K}_{ji}^*$, if we have r_i and $r_j \in \mathbb{R}$,

$$\sum_{i,j}^{l} r_i r_j \mathbf{K}_{ij}^i = -\sum_{i,j}^{l} r_i r_j \mathbf{K}_{ji}^i = -\sum_{i,j}^{l} r_i r_j \mathbf{K}_{ij}^i, \tag{40}$$

Therefore

$$\sum_{i,j}^{l} r_i r_j \mathbf{K}_{ij}^i = 0, \tag{41}$$

Based on (41), (39) can be changed to

$$||\mathbf{w}||_{\mathbb{H}}^2 = \sum_{i,j=1}^{N_r} (\alpha_i - \hat{\alpha}_i)(\alpha_i - \hat{\alpha}_i)\mathbf{K}_{ij}^r + \sum_{i,j=1}^{N_r} (\beta_i - \hat{\beta}_i)(\beta_i - \hat{\beta}_i)\mathbf{K}_{ij}^r - 2\sum_{i,j=1}^{N_r} (\alpha_i - \hat{\alpha}_i)(\beta_j - \hat{\beta}_j)\mathbf{K}_{ij}^i. \tag{42}$$

Apply (37), (38), (41) and (42) to (36), the final form of Lagrange duality can be obtained

$$\begin{gathered}
maximize \quad \theta = -\frac{1}{2}[\sum_{i,j}^{N_r} (\alpha_i - \hat{\alpha}_i)(\alpha_j - \hat{\alpha}_j)\mathbf{K}_{ij}^r + \sum_{i,j}^{N_r} (\beta_i - \hat{\beta}_i)(\beta_j - \hat{\beta}_j)\mathbf{K}_{ij}^r] \\
-\sum_{i}^{N_r} (\alpha_i + \hat{\alpha}_i + \beta + \hat{\beta}_i)\epsilon + [\sum_{i=1}^{N_r} (\alpha_i - \hat{\alpha}_i)Re(y_i) + \sum_{i=1}^{N_r} (\beta_i - \hat{\beta}_i)Im(y_i)] \\
+C\sum_{i}^{N_r} (\tilde{R}(\xi_i^r) + \tilde{R}(\hat{\xi}_i^r) + \tilde{R}(\xi_i^i) + \tilde{R}(\hat{\xi}_i^i)) \\
\begin{cases}
0 \le \alpha(\hat{\alpha}) \le C\tilde{R}(\xi^r)(\tilde{R}(\hat{\xi}^r)) \\
0 \le \beta(\hat{\beta}) \le C\tilde{R}(\xi^i)(\tilde{R}(\hat{\xi}^i)) \\
\xi^r(\hat{\xi}^r) \ge 0 \\
\xi^i(\hat{\xi}^i) \ge 0
\end{cases}
\end{gathered} \tag{43}$$

which can be divided into 2 independent regression task,

$$maximize \quad \Theta^r = -\frac{1}{2}\sum_{i,j}^{N_r}(\alpha_i - \hat{\alpha}_i)(\alpha_j - \hat{\alpha}_j)\mathbf{K}_{ij}^r - \sum_{i=1}^{N_r}(\alpha_i + \hat{\alpha}_i)\epsilon + \sum_{i=1}^{N_r}(\alpha_i - \hat{\alpha}_i)Re(y_i) + C\sum_{i=1}^{N_r}(\tilde{R}(\xi_i^r)$$

$$+\tilde{R}(\hat{\xi}_i^r))$$

$$\begin{cases} 0 \leq \alpha(\hat{\alpha}) \leq C\tilde{R}(\xi^r)(\tilde{R}(\hat{\xi}^r)) \\ \xi^r(\hat{\xi}^r) \geq 0 \end{cases} \tag{44}$$

$$maximize \quad \Theta^i = -\frac{1}{2}\sum_{i,j}^{N_r}(\beta_i - \hat{\beta}_i)(\beta_j - \hat{\beta}_j)\mathbf{K}_{ij}^r - \sum_{i=1}^{N_r}(\beta_i + \hat{\beta}_i)\epsilon + \sum_{i=1}^{N_r}(\beta_i - \hat{\beta}_i)Im(y_i) + C\sum_{i=1}^{N_r}(\tilde{R}(\xi_i^i)$$

$$+\tilde{R}(\hat{\xi}_i^i))$$

$$\begin{cases} 0 \leq \beta(\hat{\beta}) \leq C\tilde{R}(\xi^i)(\tilde{R}(\hat{\xi}^i)) \\ \xi^i(\hat{\xi}^i) \geq 0 \end{cases} \tag{45}$$

The alternate form can be written as

$$maximize \quad \Theta^r = -\frac{1}{2}(\alpha - \hat{\alpha})^T\mathbf{K}^r(\alpha - \hat{\alpha}) + Re(\mathbf{y})^T(\alpha - \hat{\alpha}) - \epsilon(\mathbf{e}^T(\alpha + \hat{\alpha})) + C(\mathbf{e}^T(\tilde{R}(\xi^r) + \tilde{R}(\hat{\xi}^r)))$$

$$\begin{cases} 0 \leq \alpha(\hat{\alpha}) \leq C\tilde{R}(\xi^r)(\tilde{R}(\hat{\xi}^r)) \\ \xi^r(\hat{\xi}^r) \geq 0 \end{cases} \tag{46}$$

$$maximize \quad \Theta^i = -\frac{1}{2}(\beta - \hat{\beta})^T\mathbf{K}^r(\beta - \hat{\beta}) + Im(\mathbf{y})^T(\beta - \hat{\beta}) - \epsilon(\mathbf{e}^T(\beta + \hat{\beta})) + C(\mathbf{e}^T(\tilde{R}(\xi^i) + \tilde{R}(\hat{\xi}^i)))$$

$$\begin{cases} 0 \leq \beta(\hat{\beta}) \leq C\tilde{R}(\xi^i)(\tilde{R}(\hat{\xi}^i)) \\ \xi^i(\hat{\xi}^i) \geq 0 \end{cases} \tag{47}$$

where $(\alpha - \hat{\alpha})$, $(\beta - \hat{\beta})$,$Re(\mathbf{y})$, $Im(\mathbf{y})$ denote vectors, $\mathbf{e} = [1, 1, \ldots, 1]^T \in \mathbb{R}^{N_r}$, $\mathbf{K}^r$ denotes the matrix consist of real part of kernel components. Observe that solving (46) and (47) are equivalent to solving two independent real Support vector regression task (dual channel), only the real part of kernel matrix is required for each channel. In section VI, we will further show that from the statistic analyst of channel orthogonality (which is also named channel hardening phenomenon), the imaginary part of kernel matrix can also be omitted in stopping criteria. Therefore, in large MIMO uplink system, our CSVR-MIMO detector can save half of the cost in kernel matrix computation.

V. Work Set Selection and Solver

(43) can be viewed as quadratic optimization problem, The traditional optimization algorithms such as Newton, Quasi Newton can not be directly applied to this problem, because the sparseness of kernel matrix $\mathbf{K}$ can not be guaranteed, so that a prohibitive storage may be required when dealing with large data set.

Decomposition method is a set of efficient algorithms that can help to conquer this difficulty. Decomposition method works iteratively, the basic idea of decomposition method is to choose a subset of variable pairs S (named work set) to optimize in each iteration step while keep the rest variable pairs N fixed. Sequential Minimal Optimization (SMO) is an extreme case of decomposition method, the work set size is 2, an analytic quadratic programming (QP) step instead of numerical QP step can be taken in each iteration.

Because (44) and (45) are symmetric, in this section we discuss real part only. By dividing the variables into work set S and fixed set N, we have $(\alpha, \hat{\alpha}) = ((\alpha_N, \hat{\alpha}_N)\mathbf{e}_N + (\alpha_S + \hat{\alpha}_S)\mathbf{e}_S)$, where $\mathbf{e}_K$ denotes the modified vector of $\mathbf{e}$ with the components in set K zeroed, for sake of brevity we replace $\alpha_K \mathbf{e}_K$ by α_K. Thus (46) can be changed to:

$$maximize \quad \Theta^r = -\frac{1}{2}[(\alpha-\hat{\alpha})_S^T \mathbf{K}_{SS}^r (\alpha-\hat{\alpha})_S + 2(\alpha-\hat{\alpha})_N^T \mathbf{K}_{NS}^r (\alpha-\hat{\alpha})_S] + Re(\mathbf{y})_S^T (\alpha-\hat{\alpha})_S -$$
$$\epsilon(\mathbf{e}^T(\alpha+\hat{\alpha})_S) - \frac{1}{2}(\alpha-\hat{\alpha})_N^T \mathbf{K}_{NN}^r (\alpha-\hat{\alpha})_N + Re(\mathbf{y})_N^T (\alpha-\hat{\alpha})_N - \epsilon(\mathbf{e}^T(\alpha+\hat{\alpha})_N)$$
$$+C(\mathbf{e}^T(\tilde{R}(\xi^r) + \tilde{R}(\hat{\xi}^r))), \tag{48}$$

Where $\mathbf{K}^r = \begin{bmatrix} \mathbf{K}_{SS}^r & \mathbf{K}_{SN}^r \\ \mathbf{K}_{NS}^r & \mathbf{K}_{NN}^r \end{bmatrix}$ is a permutation of $\mathbf{K}^r$, $\mathbf{K}_{SN}^r = \mathbf{K}_{NS}^r$ and $\alpha_S \in \mathbb{R}^{N_r}$ denotes the vector with the components that do not belong to S zeroed. In each iteration, in (48), α_N is fixed and only the sub problem that correlated to α_S is solved i.e

$$maximize \quad \Theta_S^r = -\frac{1}{2}[(\alpha-\hat{\alpha})_S^T \mathbf{K}_{SS}^r (\alpha-\hat{\alpha})_S] + [Re(\mathbf{y})_S^T - (\alpha-\hat{\alpha})_N^T \mathbf{K}_{NS}^r](\alpha-\hat{\alpha})_S - \epsilon < \mathbf{e}_S^T, (\alpha+\hat{\alpha})_S >, \tag{49}$$

In decomposition method, a proper work set selection strategy is required so that speed and performance requirement can be guaranteed. One approach is to choose dual variable pairs that violate KKT conditions, so that after each iteration, the objective function can be increased according to Osuna's theorem [32], Heuristic methods are used in in order to accelerate process, in work set selection process, the algorithm first searches among the non-bound variables (that is $0 < \alpha < C\tilde{R}(\xi)$), which are more likely to violate KKT condition, then searching the whole dual variable set, the second dual variable that can maximize optimization step of the first coordinate is chosen, approximate step size is used as evaluator for sake of reducing computational cost. Lin propose another work set selection strategy based on an alternative form of KKT condition.

Another class of approaches is to choose the dual variables whose update can provide the maximum improvements to objective function. That is

$$maximize \quad \bigtriangledown \Theta_S = \Theta_S((\alpha_S + \delta_S \mathbf{e}_S), (\hat{\alpha}_s + \hat{\delta}_S \mathbf{e}_S)) - \Theta_S(\alpha_S, \hat{\alpha}_S), \tag{50}$$

where $\delta_S = \alpha_S^{new} - \alpha_S$, the gain in (50) can be written as

$$\bigtriangledown\Theta_S^r = -\frac{1}{2}[(\delta-\hat{\delta})_S^T \mathbf{K}_{SS}^r (\delta-\hat{\delta})_S + 2(\alpha-\hat{\alpha})_S^T \mathbf{K}_{SS}^r (\delta-\hat{\delta})_S] + [Re(\mathbf{y})_S^T - (\alpha-\hat{\alpha})_N^T \mathbf{K}_{NS}^r](\delta-\hat{\delta})_S$$
$$-\epsilon \mathbf{e}_S^T(\delta+\hat{\delta})_S = -\frac{1}{2}(\delta-\hat{\delta})_S^T \mathbf{K}_{SS}^r (\delta-\hat{\delta})_S + [Re(\mathbf{y})_S^T - (\alpha-\hat{\alpha})^T \mathbf{K}_S^r](\delta-\hat{\delta})_S - \epsilon \mathbf{e}_S^T(\delta+\hat{\delta})_S \tag{51}$$

In (51), we use

$$(\alpha-\hat{\alpha})_S^T \mathbf{K}_{SS}^r + (\alpha-\hat{\alpha})_N^T \mathbf{K}_{NS}^r = [(\alpha-\hat{\alpha})_S^T, (\alpha-\hat{\alpha})_N^T] \begin{bmatrix} \mathbf{K}_{SS}^r \\ \mathbf{K}_{NS}^r \end{bmatrix} = (\alpha-\hat{\alpha})^T \mathbf{K}_S^r, \tag{52}$$

where $\mathbf{K}_S^r \in \mathbb{R}^{N_r \times S}$ denotes the matrix constructed by all the columns that belong to work set S. Then we define intermediate variable vector $\Phi \in \mathbb{C}^{N_r}$, $\Phi^r = Re(\mathbf{y}) - \mathbf{K}^r(\alpha - \hat{\alpha})$ and $\Phi^i = Im(\mathbf{y}) - \mathbf{K}^r(\beta - \hat{\beta})$ Thus (51) can be rewritten as

$$\bigtriangledown\Theta_S^r = -\frac{1}{2}(\delta-\hat{\delta})_S^T \mathbf{K}_{SS}^r (\delta-\hat{\delta})_S + (\Phi_S^r)^T(\delta-\hat{\delta})_S - \epsilon \mathbf{e}_S^T(\delta+\hat{\delta})_S \tag{53}$$

The offset term is omitted in Large MIMO system, therefore different from SMO type algorithms, there is no linear equation constraint as shown in (18), it is possible to update only one variable pair in each iteration. However, recent work shows more efficient work set selection strategy based on maximum gain selection approaches, that choose two pair of dual variables can reduce computational cost while maintaining the comparable performance with that with offset [**?**]. Here we propose sequential 1-D work set selection strategy, which can approximate the performance of optimal 2-D work set selection, while only $O(n)$ searching times required for the former one instead of $O(n^2)$ searching times.

A. Single Direction Solver

Recall KKT complementary condition

$$\begin{cases} (C\tilde{R}(\xi^r) - \alpha)\xi^r = 0 \\ (C\tilde{R}(\hat{\xi}^r) - \hat{\alpha})\hat{\xi}^r = 0 \\ \alpha(Re(y) - < \mathbf{h}, \mathbf{w} >_{\mathbb{H}} - \epsilon - \xi^r) = 0 \\ \hat{\alpha}(< \mathbf{h}, \mathbf{w} >_{\mathbb{H}} - Re(y) - \epsilon - \hat{\xi}^r) = 0 \end{cases} \tag{54}$$

it can be easily observed that $\alpha\hat{\alpha} = 0$, because $0 \leq \alpha(\hat{\alpha}) \leq C\tilde{R}(\xi^r)(C\tilde{R}(\hat{\xi}^r))$, ξ^r and $\hat{\xi}^r$ satisfy $\xi^r\hat{\xi}^r = 0$. Hence we can substitute $\lambda = \alpha - \hat{\alpha}$ and $|\lambda| = \alpha + \hat{\alpha}$, therefore the update unit is single optimization variable λ, rather than pair α and $\hat{\alpha}$. We will first introduce 1-D work set selection strategy in which one optimization variable that maximizes the gain of objective function is updated in one iteration. Reformulate by λ and $\sigma = \lambda^{new} - \lambda$ sub optimization objective function(49) and its gain (53)

$$maximize \quad \theta^r_S = -\frac{1}{2}[\lambda_S^T \mathbf{K}^r_{SS} \lambda_S] + [Re(\mathbf{y})^T_S - \lambda_N^T \mathbf{K}^r_{NS}]\lambda_S - \epsilon < \mathbf{e}^T_S, |\lambda_S| >, \tag{55}$$

$$\triangledown\theta^r_S = -\frac{1}{2}\sigma_S^T \mathbf{K}^r_{SS}\sigma_S + (\Phi^r_S)^T \sigma_S - \epsilon < \mathbf{e}^T_S, |\lambda^{new}_S| - |\lambda_S| >, \tag{56}$$

For 1-D solver, the sub optimization objective function can be written as

$$maximize \quad \theta_1^r = -\frac{1}{2}(\lambda_1^{new})^2\mathbf{K}_{11}^r + [Re(y_1) - \sum_{j=2}^{N_r}\mathbf{K}_{1j}^r\lambda_j]\lambda_1^{new} - \epsilon(|\lambda_1^{new}|), \tag{57}$$

take the partial derivative of θ_1^r respect to λ_1^{new}, where we define $\Phi_i^r = Re(y_i) - \sum_{j=1}^{N_r}\lambda_j^r\mathbf{K}_{ij}^r$, similarly, as to dual variable λ^i , we define $\Phi_i^i = Im(y_i) - \sum_{j=1}^{N_r}\lambda_j^i\mathbf{K}_{ij}^r$. Here for sake of brevity, we use λ. Hence we have

$$\begin{aligned}
&\frac{\partial\theta_1^r}{\partial\lambda_1^{new}} = -\lambda_1^{new}\mathbf{K}_{11}^r + Re(y_1) - \sum_{j=2}^{N_r}\lambda_j^{new}\mathbf{K}_{1j}^r - \epsilon(sgn(\lambda_1^{new})) = \\
&-\lambda_1^{new}\mathbf{K}_{11}^r + \Phi_1^r + \lambda_1\mathbf{K}_{11}^r - \epsilon(sgn(\lambda_1^{new})) \\
&\Rightarrow \lambda_1^{new} = \lambda_1 + \frac{\Phi_1^r - \epsilon(sgn(\lambda_1^{new}))}{\mathbf{K}_{11}^r},
\end{aligned} \tag{58}$$

The update of α_1 or $\hat{\alpha}_1$ is completed by clipping

$$\lambda_1^{new \quad clipped} = [\lambda_1^{new}]_{-CR'(\xi)}^{CR'(\xi)} \tag{59}$$

where $[]_a^b$ denotes clipping function

$$[x]_a^b = \begin{cases} a \quad if \quad x \leq a \\ x \quad if \quad a < x < b \\ b \quad if \quad x \geq b \end{cases} \tag{60}$$

Define $\sigma = \lambda^{new \quad clipped} - \lambda$, based on (56), The gain of objective function respect to ith optimization variable is

$$
\begin{aligned}
&\bigtriangledown\theta_i^r = \theta^r(\lambda_1+\sigma_1) - \theta^r(\lambda_1)\\
&= -\frac{1}{2}\sigma_i^2\mathbf{K}_{ii}^r + \Phi_i^r\sigma_i - \epsilon(|\lambda_i^{new \quad cipped}| - |\lambda_i|)\\
&= \sigma_i[-\frac{1}{2}\sigma_i\mathbf{K}_{ii}^r + \Phi_i^r] - \epsilon(|\lambda_i^{new \quad clipped}| - |\lambda_i|),
\end{aligned} \tag{61}
$$

In 1-D searching procedure, the optimization variable which has the maximum gain of sub optimization objective function is updated as 1 in (57), that is

$$
1 = arg_{(i=1,\ldots,N_r)} \max \bigtriangledown\Theta_i^r, \tag{62}
$$

B. Double Direction Solver

Although omission of offset in the CSVR-MIMO detector makes 1-D solver possible, however recent work in machine learning field shows training SVM without offset by 2-D solver with special work set selection strategies has more rapid training speed while the comparable performance is retained. The 2-D solver uses the same principle as 1-D solver, the work set size is 2, that is $\lambda_S = \lambda_1\mathbf{e}_1 + \lambda_2\mathbf{e}_2$. Based on (56), the sub objective function can be written as

$$
\begin{aligned}
&maximize \quad \theta_{1,2}^r = -\frac{1}{2}[(\lambda_1^{new})^2\mathbf{K}_{11}^r + (\lambda_2^{new})^2\mathbf{K}_{22}^r + 2\lambda_1^{new}\lambda_2^{new}\mathbf{K}_{12}^r] -\\
&\lambda_1^{new}\sum_{j\neq 1,2}^{N_r}\lambda_j\mathbf{K}_{1j}^r - \lambda_2^{new}\sum_{j\neq 1,2}^{N_r}\lambda_j\mathbf{K}_{2j}^r + Re(y_1)\lambda_1^{new} + Re(y_2)\lambda_2^2\\
&-\epsilon(|\lambda_1^{new}| + |\lambda_2^{new}|),
\end{aligned} \tag{63}
$$

Based on (63), the partial derivatives of $\theta_{1,2}^r$ with respect to λ_1^{new} and λ_2^{new} are

$$\frac{\partial\theta_{1,2}^r}{\partial\lambda_1^{new}} = -\lambda_1^{new}\mathbf{K}_{11}^r - \lambda_2^{new}\mathbf{K}_{12}^r - \sum_{j\neq 1,2}^{N_r}\lambda_j\mathbf{K}_{1j}^r + Re(y_1) - \epsilon sgn(\lambda_1^{new}) =$$
$$-\lambda_1^{new}\mathbf{K}_{11}^r - \lambda_2^{new}\mathbf{K}_{12}^r + \Phi_1^r + \lambda_1\mathbf{K}_{11}^r + \lambda_2\mathbf{K}_{12}^r - \epsilon sgn(\lambda_1^{new}) = 0 \quad (64)$$
$$\frac{\partial\theta_{1,2}^r}{\partial\lambda_2^{new}} = -\lambda_2^{new}\mathbf{K}_{22}^r - \lambda_1^{new}\mathbf{K}_{12}^r - \sum_{j\neq 1,2}^{N_r}\lambda_j\mathbf{K}_{2j}^r + Re(y_2) - \epsilon sgn(\lambda_2^{new}) =$$
$$-\lambda_2^{new}\mathbf{K}_{22}^r - \lambda_1^{new}\mathbf{K}_{12}^r + \Phi_2^r + \lambda_1\mathbf{K}_{12}^r + \lambda_2\mathbf{K}_{22}^r - \epsilon sgn(\lambda_2^{new}) = 0 \quad (65)$$

where $\frac{\partial|x|}{\partial x} = sgn(x)$ denotes the sign of x. Based on (64) and (65) we have

$$(\lambda_1^{new} - \lambda_1)\mathbf{K}_{11}^r = \Phi_1^r - \epsilon sgn(\lambda_1^{new}) - (\lambda_2^{new} - \lambda_2)\mathbf{K}_{12}^r \quad (66)$$

$$(\lambda_2^{new} - \lambda_2)\mathbf{K}_{22}^r = \Phi_2^r - \epsilon sgn(\lambda_2^{new}) - (\lambda_1^{new} - \lambda_1)\mathbf{K}_{12}^r \quad (67)$$

hence based on (66) and (67), the update formula of λ_1^{new} and λ_2^{new} are

$$\lambda_1^{new} = \lambda_1 + \frac{\Phi_1^r\mathbf{K}_{22}^r - \Phi_2^r\mathbf{K}_{12}^r - \epsilon[sgn(\lambda_1^{new})\mathbf{K}_{22}^r - sgn(\lambda_2^{new})\mathbf{K}_{12}^r]}{\mathbf{K}_{11}^r\mathbf{K}_{22}^r - (\mathbf{K}_{12}^r)^2} \quad (68)$$

$$\lambda_2^{new} = \lambda_2 + \frac{\Phi_2^r\mathbf{K}_{11}^r - \Phi_1^r\mathbf{K}_{12}^r - \epsilon[sgn(\lambda_2^{new})\mathbf{K}_{11}^r - sgn(\lambda_1^{new})\mathbf{K}_{12}^r]}{\mathbf{K}_{11}^r\mathbf{K}_{22}^r - (\mathbf{K}_{12}^r)^2} \quad (69)$$

Then the updated optimization variables are clipped by constraint

$$\lambda^{new \quad clipped} = [\lambda^{new}]_{-CR'(\xi)}^{CR'(\xi)}, \quad (70)$$

It is obviously the dual variables in 2-D solver have the same update rule as that of 1-D solver. Based on (53), assume the ith and jth dual variable pair are chosen, the gain of 2-D solver objective function can be written as

$$\bigtriangledown\theta_{ij}^{r} = -\frac{1}{2}[\sigma_i^2\mathbf{K}_{ii}^{r} + \sigma_j^2\mathbf{K}_{jj}^{r} + 2\sigma_i\sigma_j\mathbf{K}_{ij}^{r}] + \Phi_i^{r}\sigma_i + \Phi_j^{r}\sigma_j$$
$$-\epsilon(|\lambda_i^{new \quad clipped}| - |\lambda_i| + |\lambda_j^{new \quad clipped}| - |\lambda_j|), \tag{71}$$

recall the gain of objective function of 1-D solver in (61), we obtain

$$\bigtriangledown\theta_{ij}^{r} = \bigtriangledown\theta_i^{r} + \bigtriangledown\theta_j^{r} - \sigma_i\sigma_j\mathbf{K}_{ij}^{r}, \tag{72}$$

where $\bigtriangledown\Theta_i^r$, $\bigtriangledown\Theta_j^r$ denote gains of 1-D solver with ith and jth dual variable pairs are chosen.

C. Approximation to Optimal Double Direction Solver based on Single Direction Solver

From (72), it is obviously that the gain of 2-D solver is a summation of the gain of 2 independent 1-D solver and a correlation term $\sigma_i\sigma_j\mathbf{K}_{ij}^{r}$.

Obviously optimal 2-D coordinate combination (i, j) can be determined by comparing the gains of all the possibilities exhaustively, which requires $O(n^2)$ times of searching. Based on (72), we can approximate optimal 2-D solution by 1-D search approach, we will prove in large MIMO scenario, when N_t is sufficient large, with channel hardening become effective, this approximation is very efficient. Here we propose two kinds of 1-D approximate searching strategy:

1. 1-D searching without damping:

do one time 1-D searching and calculate all the 1-D gain based on (61), then choose the coordinate with first and second largest 1-D gain as the candidates, then update the two candidates by 2-D solver as shown in (68) and (69)

2. 1-D searching with damping:

do two times 1-D searchings, in the first round find optimization variable i that can maximize 1-D gain, then in the second round, find jth optimization variable with the value of ith coordinate updated.

From (72), it can be easily interpreted the efficient of 1-D approximation approach is majorly determined by the approximation ratio $\frac{\sigma_i \sigma_j \mathbf{K}^r_{ij}}{\triangledown\theta^r_i + \triangledown\theta^r_j}$, hence we provide theoretical analyse from the view of channel hardening phenomenon. Prior the theoretical analyse, we first investigate some mathematical properties of channel hardening (to be completed).

For 1-D solver the gradient of (58) with respect to λ can be written as

$$\lambda_1^{new} = \lambda_1 + \frac{\Phi_1 - sgn(\lambda_1^{new})\epsilon}{\mathbf{K}^r_{11}}, \tag{73}$$

In the update process the $sgn(\lambda^{new})$ is unknown at current step, therefore, we need to consider both the case $sgn(\lambda^{new}) = -1$ or 1 and choose the one with the larger objective function gain $\triangledown\theta^r_S$.

VI. Stopping Criteria

As we have explained in section II-C, the upper bound of Lagrangian dual objective function is determined by primal objective function, further more the optimal of primal and dual objective function is found if and only if the equality holds, that is

$$\theta(\lambda^r, \lambda^i) = f(\mathbf{w}, \xi) \tag{74}$$

$$\frac{1}{2}||\mathbf{w}||_{\mathbb{H}}^2 + C\sum_{i=1}^{N_r}[R(\xi_i^r) + R(\hat{\xi}_i^r) + R(\xi_i^i) + R(\hat{\xi}_i^i)], \tag{75}$$

(43) can be rewritten as follow by substituting $\lambda^r = \alpha - \hat{\alpha}$, $|\lambda^r| = \alpha + \hat{\alpha}$ and $\lambda^i = \beta - \hat{\beta}$, $|\lambda^i| = \beta + \hat{\beta}$

$$\theta(\lambda^r, \lambda^i) = -\frac{1}{2} < (\lambda^r)^T, \mathbf{K}^r\lambda^r > -\frac{1}{2} < (\lambda^i)^T, \mathbf{K}^r\lambda^i > + < Re(\mathbf{y})^T, \lambda^r > + < Im(\mathbf{y})^T, \lambda^i >$$
$$-\epsilon < \mathbf{e}^T, (|\lambda^r| + |\lambda^i|) > +C\sum_{i=1}^{N_r}[\tilde{R}(\xi_i^r) + \tilde{R}(\hat{\xi}_i^r) + \tilde{R}(\xi_i^i) + \tilde{R}(\hat{\xi}_i^i)], \tag{76}$$

Similarly, (39) can be formulated as

$$||\mathbf{W}||_{\mathbb{H}}^2 =< (\lambda^r)^T, \mathbf{K}^r\lambda^r > + < (\lambda^i)^T, \mathbf{K}^r\lambda^i > -2 < \lambda^r, \mathbf{K}^i\lambda^i >, \tag{77}$$

hence, duality gap can be formulated as

$$G(\lambda^r, \lambda^i) = f(\mathbf{w}, \xi) - \theta(\lambda^r, \lambda^i) =< (\lambda^r)^T, \mathbf{K}^r\lambda^r > + < (\lambda^i)^T, \mathbf{K}^r\lambda^i > - < Re(\mathbf{y})^T, \lambda^r > - < Im(\mathbf{y})^T, \lambda^i >$$
$$-\epsilon < \mathbf{e}^T, (|\lambda^r| + |\lambda^i|) > +C\sum_{i=1}^{N_r}[\xi_i^r R'(\xi_i^r) + \hat{\xi}_i^r R'(\hat{\xi}_i^r) + \xi_i^i R'(\xi_i^i) + \hat{\xi}_i^i R'(\hat{\xi}_i^i)] - 2 < \lambda^r, \mathbf{K}^i\lambda^i > . \tag{78}$$

As we explained in section II-B, the choice of risk function is determined by distribution of noise, as to Gaussian noise, the risk function is

$$R(\xi) = \frac{1}{2}\xi^2, \tag{79}$$

hence

$$\tilde{R}(\xi) = R(\xi) - \xi R'(\xi) = -\frac{1}{2}\xi^2, \tag{80}$$

In ϵ-SVR, the objective to employ slack variables ξ is to deal with the outliers that outside ϵ tube to compensate the influence from noise. Therefore

$$\xi_i^r = Re(\mathbf{y}_i) - Re(<\mathbf{h}_i, \mathbf{w}>_{\mathbb{H}}) - \epsilon \tag{81}$$

$$\hat{\xi}_i^r = Re(<\mathbf{h}_i, \mathbf{w}>_{\mathbb{H}}) - Re(\mathbf{y}_i) - \epsilon \tag{82}$$

Because $\xi^r \hat{\xi}^r = 0$ (estimation can only exceed ϵ tube in one direction), therefore there is only one of ξ and $\hat{\xi}$ need to be considered, thus

$$\xi_i^r(\hat{\xi}_i^r) = \max(0, |Re(\mathbf{y}_i) - Re(<\mathbf{h}_i, \mathbf{w}>_{\mathbb{H}})| - \epsilon) \tag{83}$$

$$\xi_i^i(\hat{\xi}_i^i) = \max(0, |Im(\mathbf{y}_i) - Im(<\mathbf{h}_i, \mathbf{w}>_{\mathbb{H}})| - \epsilon) \tag{84}$$

$$\xi\hat{\xi} = 0, \tag{85}$$

Therefore the risk function can be rewritten as

$$R(\xi_i^r) + R(\hat{\xi}_i^r) = \frac{1}{2}(|Re(\mathbf{y}_i) - Re(<\mathbf{h}_i, \mathbf{w}>_{\mathbb{H}})|)_\epsilon^2 \tag{86}$$

$$R(\xi_i^i) + R(\hat{\xi}_i^i) = \frac{1}{2}(|Im(\mathbf{y}_i) - Im(<\mathbf{h}_i, \mathbf{w}>_{\mathbb{H}})|)_\epsilon^2 \tag{87}$$

where $()_\epsilon$ denotes ϵ insensitive function as we mention in section II-B. Based on (38), we have

$$Re(\mathbf{y}_i) - Re(<\mathbf{h}_i, \mathbf{W}>_{\mathbb{H}}) = Re(\mathbf{y}_i) - \sum_{j=1}^{N_r} \lambda_j^r \mathbf{K}_{ij}^r + \sum_{j=1}^{N_r} \lambda_j^i \mathbf{K}_{ij}^i \tag{88}$$

$$Im(\mathbf{y}_i) - Im(<\mathbf{h}_i, \mathbf{W}>_{\mathbb{H}}) = Im(\mathbf{y}_i) - \sum_{j=1}^{N_r} \lambda_j^i \mathbf{K}_{ij}^r - \sum_{j=1}^{N_r} \lambda_j^r \mathbf{K}_{ij}^i \tag{89}$$

we define two intermediate variables Φ and Ψ

$$\Phi^r = Re(\mathbf{y}) - \mathbf{K}^r\lambda^r; \Phi^i = Im(\mathbf{y}) - \mathbf{K}^r\lambda^i \tag{90}$$

$$\Psi^r = \mathbf{K}^i\lambda^i; \Psi^i = -\mathbf{K}^i\lambda^r \tag{91}$$

Therefore based on (87)-(**??**), duality gap in (78) can be rewritten as

$$G(\lambda^r, \lambda^i) =< (\lambda^r)^T, \mathbf{K}^r\lambda^r > + < (\lambda^i)^T, \mathbf{K}^r\lambda^i > - < Re(\mathbf{y})^T, \lambda^r > - < Im(\mathbf{y})^T, \lambda^i >$$
$$+\epsilon < \mathbf{e}^T, (|\lambda^r| + |\lambda^i|) > +C\sum_{i=1}^{N_r}[(|\Phi_i^r + \Psi_i^r|)_\epsilon^2 + (|\Phi_i^i + \Psi_i^i|)_\epsilon^2] - 2 < \lambda^r, \mathbf{K}^i\lambda^i > . \tag{92}$$

Based on objective function in (76), (92) can be rewritten as

$$G = (\lambda_r, \lambda_i) =< Re(\mathbf{y})^T, \lambda^r > + < Im(\mathbf{y})^T, \lambda^i > -\epsilon < \mathbf{e}^T, (|\lambda^r| + |\lambda^i|) > -2\theta(\lambda_i, \lambda_j)$$
$$-2 < \lambda^r, \mathbf{K}^i\lambda^i > . \tag{93}$$

The duality gap between primal problem and dual problem is used to evaluate how close a solution is to global minimum. In our scenario, duality gap is employed as stopping criteria. Therefore to make stopping criteria more effective to monitor if algorithm convergent, we monitor the ratio by a value of tolerance (usually this tolerance is set to 10^{-3}).

$$\frac{G}{G + \theta} \tag{94}$$

A. Update Φ, Ψ and G

Here we give the pseudo code to update Φ, Ψ and G.

Based on the definition of Φ and Ψ in (90) and (92), we have the following procedure to update Φ and Ψ in real channel and imaginary channel, assume the optimization coordinate updated in each channel are 1 and 2.

---

procedure 1. UPDATE Φ^r AND Ψ^i IN REAL CHANNEL
    for $i = 1 : N_r$ **do**
        $\Phi_i^r = \Phi_i^r - \sigma_1^r \mathbf{K}_{i1}^r - \sigma_2^r \mathbf{K}_{i2}^r$
        $\Psi_i^i = \Psi_i^i - \sigma_1^r \mathbf{K}_{i1}^i - \sigma_2^r \mathbf{K}_{i2}^i$
    end for
end procedure

---

procedure 2. UPDATE Φ^i AND Ψ^r IN IMAGINARY CHANNEL
    for $i = 1 : N_r$ **do**
        $\Phi_i^i = \Phi_i^i - \sigma_1^i \mathbf{K}_{i1}^r - \sigma_2^i \mathbf{K}_{i2}^r$
        $\Psi_i^r = \Psi_i^r + \sigma_1^i \mathbf{K}_{i1}^i + \sigma_2^i \mathbf{K}_{i2}^i$
    end for
end procedure

Then the risk function term in (92) is updated as following

---

procedure 3. UPDATE RISK FUNCTION IN REAL CHANNEL(χ^r)
    $\chi^r = 0$ ▷ initial risk term
    for $i = 1 : N_r$ **do**
        if $|\Phi_i^r + \Psi_i^r| > \epsilon$ **then**
            $\chi^r += (|\Phi_i^r + \Psi_i^r| - \epsilon)^2$
        end if
    end for
end procedure

The pseudo code to update duality gap G based on (92) is shown as follow (assume the coordinate updated in real channel is i and j, in imaginary channel is m and f.

Here we give the pseudo code for sequential 1-D searching 2-D solver

procedure 4. UPDATE RISK FUNCTION IN IMAGINARY CHANNEL(χ^i)
  $\chi^i = 0$ ▷ initial risk term
  for $i = 1 : N_r$ **do**
    if $|\Phi_i^i + \Psi_i^i| > \epsilon$ **then**
      $\chi^i += (|\Phi_i^i + \Psi_i^i| - \epsilon)^2$
    end if
  end for
end procedure

procedure 5. UPDATE G(ratio of G)
  $G+ = Re(\mathbf{y}_1)\sigma_i^r + Re(\mathbf{y}_2)\sigma_j^r$
  $G+ = Im(\mathbf{y}_1)\sigma_m^i + Re(\mathbf{y}_2)\sigma_f^i$
  $G- = \epsilon(|\lambda_i^r + \sigma_i^r| - |\lambda_i^r| + |\lambda_j^r + \sigma_j^r| - |\lambda_j^r|)$
  $G- = \epsilon(|\lambda_m^i + \sigma_m^i| - |\lambda_m^i| + |\lambda_f^i + \sigma_f^i| - |\lambda_f^i|)$
  $G- = 2(\bigtriangledown\theta(\sigma_i^r, \sigma_j^r, \sigma_m^i, \sigma_f^i))$
  $G- =$
end procedure

VII. HYPERPARAMETER SETTING

VIII. COMPUTER SIMULATIONS

Computer simulation is launched to test the detection and run time performance of proposed dual channel complex support vector detection algorithm. For sake of brevity, the real case is tested first, all the experiments are made by C, compiled by gcc version 4.8.3 on 64 bit Fedora (release 19) Linux system. The experiment platform is a desktop computer with I5-4th generation CPU with quad processing cores, 3.2 GHz clock rate, 8 GB RAM.

For sake of brevity, we consider a real uncoded spatial multiplex large MIMO system to simulate one channel of the proposed dual channel complex support vector detection algorithm. with N_r received antennas and N_t transmitted antennas. The propagation channel matrix is constructed by channel gain components that are identically independent distributed (i.i.d) Gaussian random variables with zero mean and unit variance. transmitted symbols are mutually

Algorithm 1 Dual Channel Complex Support Vector Detection Algorithm

procedure CSVD($\mathbf{y}$,$\mathbf{H}$)

Step 1. Initialization

for $i = 1 : N_r$ **do** ▷ initialize λ^r, λ^i, Φ^r, Φ^i, Ψ^r, Ψ^i and duality gap G

$\lambda_i^r = 0, \lambda_i^i = 0$

$\Phi_i^r = Re(y_i), \Phi_i^i = Im(y_i)$

$\Psi_i^r = 0, \Psi_i^i = 0$

end for

Step 2. if $G > tol$, go to step 3, else go to Step 6

Step 3.

Sequentia 1-D searching 2-D solver with or without damping ▷ find two optimization variables to be updated

Step 4.

Procedure 1 update G, Φ and Ψ

Step 5.

$\tilde{x} = (\lambda^r + i\lambda^i)\mathbf{H}$ ▷ reconstruct $\mathbf{x}$

$\mathbf{x} = \mathbb{Q}(\tilde{x})$ ▷ $\mathbb{Q}(\cdot)$ denotes quantization operation based on symbol constellation

go back to Step 2

Step 6. **Return** $\mathbf{x}$

end procedure

---

procedure 2. SEQUENTIAL 2-D SOLVER WITHOUT DAMPING($1st$, $2nd$)

for $i = 1 : N_r$ **do**

update $\lambda_i^r(\lambda_i^i)$ by single direction solver

calculate $\bigtriangledown\theta_i^r(\bigtriangledown\theta_i^i)$ ▷ calculate the gain of sub objective function

end for

choose the dual variable with first and the second largest gain of sub objective function, denoted as 1st and 2nd

update $\Phi^r(\Phi^i)$ and $\Psi^r(\Psi^i)$ with respect to 1st and 2nd

Return 1st, 2nd

end procedure

---

independent modulated by M PAM with normalized average energy $\frac{1}{N_t}$, transmitted over flat fading channel, the sample of noise is AWGN with zero mean and variance $\frac{1}{10^{SNR/10}}$, where SNR denotes the signal to noise ratio. We make experiment to low loading factor system 100×40 and full loading factor 100×100, Fig 3 shows the symbol error rate (SER) performance.

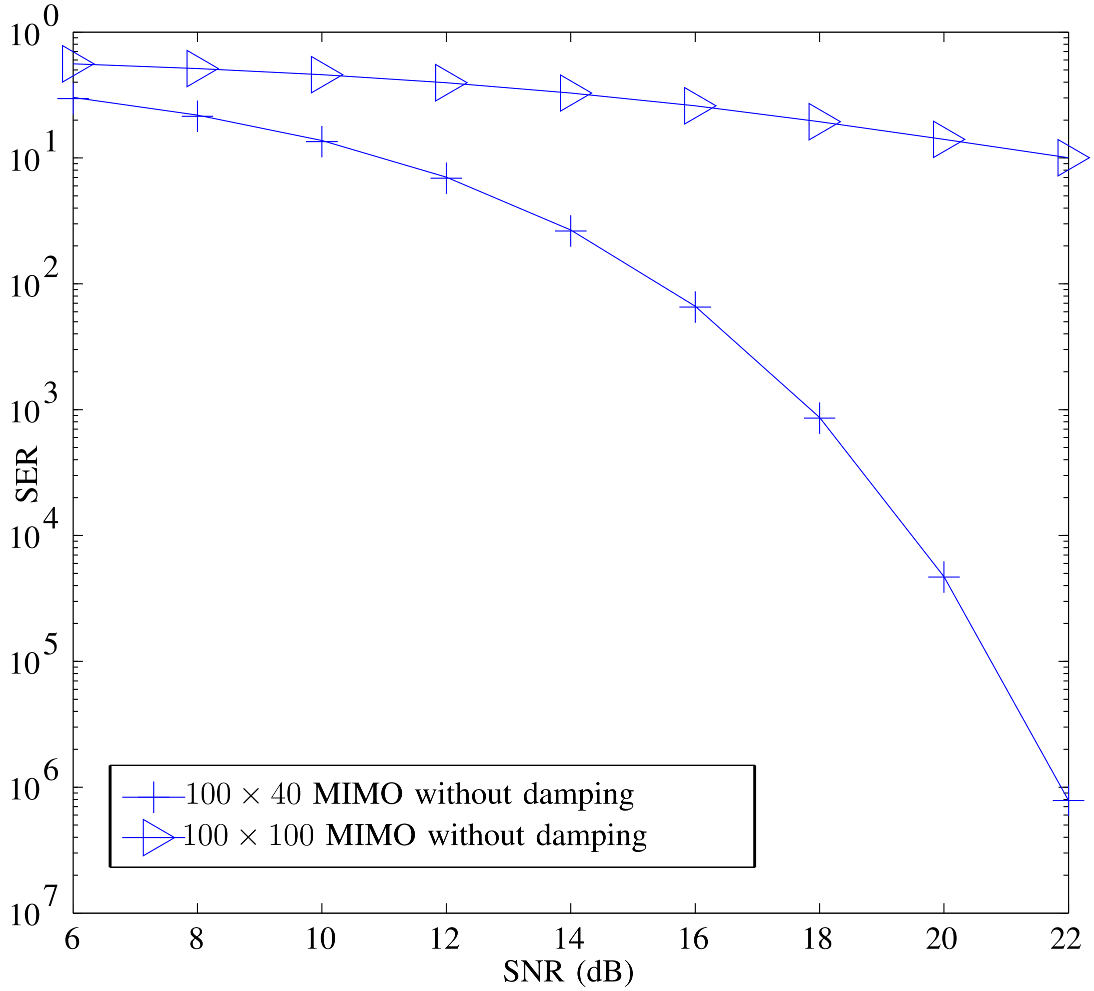

Fig. 3. SER performance of 100×100 and 100×40 MIMO system

procedure 3. SEQUENTIAL 2-D SOLVER WITH DAMPING($1s_1t$,$1st_2$)

  for $i = 1 : N_r$ **do** ▷ First round searching

    update $\lambda_i^r(\lambda_i^i)$ by single direction solver

    calculate $\bigtriangledown\theta_i^r(\bigtriangledown\theta_i^i)$ ▷ calculate the gain of objective function

  end for

  choose the dual variable with the largest gain of objective function as $1st_1$

  update $\Phi^r(\Phi^i)$ and $\Psi^r(\Psi^i)$ with respect to $1st_1$

  for $i = 1 : N_r$ **do** ▷ Second round searching

    update $\lambda_i^r(\lambda_i^i)$ by single direction solver

    calculate $\bigtriangledown\theta_i^r(\bigtriangledown\theta_i^i)$ ▷ calculate the gain of objective function

  end for

  choose the dual variable with the largest gain of objective function as $1st_2$

  update $\Phi^r(\Phi^i)$ and $\Psi^r(\Psi^i)$ with respect to $1st_2$

  Return $1st_1$ and $1st_2$

end procedure

IX. COMPLEXITY ANALYSIS

X. CONCLUSION

The conclusion goes here.

Appendix one text goes here.

APPENDIX A

Appendix two text goes here.

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