

# Thesis Skeleton

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June 12, 2019

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# 1 Introduction

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## 1.2 Motor Proteins

## 1.3 Dynein

### 1.3.1 Directed Motion

### 1.3.2 Drunken Walking

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# 2 The Model

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## 2.3 Equations of Motion

### 2.3.1 The one bound state

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# 5 Conclusions

## 5.1 Summary

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