

1)

$$\text{Show } K = \frac{-1}{2\sqrt{EG}} \left\{ \left(\frac{E_v}{\sqrt{EG}} \right)_v + \left(\frac{G_u}{\sqrt{EG}} \right)_u \right\}$$

when $F=0$

$$K = \frac{\begin{vmatrix} -\frac{1}{2}E_v + 0 & -\frac{1}{2}G_{uv} & \frac{1}{2}E_u & 0 - \frac{1}{2}E_v \\ -\frac{1}{2}G_u & E & 0 & \\ \frac{1}{2}G_v & 0 & G & \end{vmatrix} - \begin{vmatrix} 0 & \frac{1}{2}E_v & \frac{1}{2}G_u \\ \frac{1}{2}E_v & E & 0 \\ \frac{1}{2}G_u & 0 & G \end{vmatrix}}{(EG-0)^2}$$

$$\frac{(-\frac{1}{2}E_v - \frac{1}{2}G_{uv})EG - (\frac{1}{2}E_u)(-\frac{1}{2}G_u G) + \frac{1}{2}E_v \frac{1}{2}G_v E - (-\frac{1}{2}E_v \frac{1}{2}E_v G + \frac{1}{2}G_u(-\frac{1}{2}G_u E))}{(EG)^2}$$

$$= \frac{-\frac{1}{2}E_v EG - \frac{1}{2}G_{uv} EG + \frac{1}{4}E_u G_u G + \frac{1}{4}E_v G_v E + \frac{1}{4}E_v E_v G + \frac{1}{4}G_u G_u E}{(EG)^2}$$

$$K = -\frac{1}{2\sqrt{EG}} \left(\left(\frac{E_v}{\sqrt{EG}} \right)_v + \left(\frac{G_u}{\sqrt{EG}} \right)_u \right)$$

$$\frac{\partial}{\partial v} \left(E_v (EG)^{-1/2} \right) = \frac{E_{vv}}{\sqrt{EG}} - \frac{1}{2} \frac{E_v E_v G}{(EG)^{3/2}} - \frac{1}{2} \frac{E_v G_v E}{(EG)^{3/2}}$$

$$\frac{\partial}{\partial u} \left(\frac{G_u}{\sqrt{EG}} \right) = \frac{\partial}{\partial u} G_u (EG)^{-1/2} = \frac{G_{uu}}{\sqrt{EG}} - \frac{1}{2} \frac{G_u E_u G}{(EG)^{3/2}} - \frac{1}{2} \frac{G_u G_u E}{(EG)^{3/2}}$$

$$K = -\frac{1}{2} \frac{E_{vv}}{EG} + \frac{1}{4} \frac{E_v E_v G}{(EG)^2} + \frac{1}{4} \frac{E_v G_v E}{(EG)^2} - \frac{1}{2} \frac{G_{uu}}{(EG)^2} + \frac{1}{4} \frac{G_u E_u G}{(EG)^2} + \frac{1}{4} \frac{G_u G_u E}{(EG)^2}$$

$$= \frac{-\frac{1}{2}E_{vv} EG + \frac{1}{4}E_v E_v G + \frac{1}{4}E_v G_v E - \frac{1}{2}G_{uu} EG + \frac{1}{4}G_u E_u G + \frac{1}{4}G_u G_u E}{(EG)^2}$$

2. $\sigma(u,v) = (u \cos(v), u \sin(v), \ln(u))$ - Catenoid
 $\bar{\sigma}(u,v) = (u \cos(v), u \sin(v), v)$ - Helicoid

$\sigma_u = (\cos(v), \sin(v), \frac{1}{u})$ $\sigma_v = (-u \sin(v), u \cos(v), 0)$

$E = 1 + \frac{1}{u^2}$, $F = 0$, $G = u^2$

$\bar{\sigma}_u = (\cos(v), \sin(v), 0)$ $\bar{\sigma}_v = (-u \sin(v), u \cos(v), 1)$

$\bar{E} = 1$ $\bar{F} = 0$ $\bar{G} = u^2 + 1$

from $K = -\frac{1}{2\sqrt{EG}} \left[\left(\frac{E_v}{\sqrt{EG}} \right)_v + \left(\frac{G_u}{\sqrt{EG}} \right)_u \right]$

$E_v = 0$ $G_u = 2u$ $EG = u^2 + 1$

$\rightarrow K = -\frac{1}{2\sqrt{u^2+1}} \left(\frac{2u}{\sqrt{u^2+1}} \right)_u$

$\bar{E}_v = 0$ $\bar{G}_u = 2u$ $\bar{EG} = u^2 + 1$

$\bar{K} = -\frac{1}{2\sqrt{u^2+1}} \left(\frac{2u}{\sqrt{u^2+1}} \right)_v$

thus the curvatures are the same

Now show $\bar{\sigma} \circ \sigma^{-1}$ is not an isometry.

first, to be an isometry $f = \bar{\sigma} \circ \sigma^{-1}$ must be a diffeomorphism. We know that the helicoid and catenoid are ~~globally~~ locally isometric which means they have the same first fundamental form. The global isometry must fail, because $\bar{\sigma} \circ \sigma^{-1}$ is not a diffeomorphism.

Exercise 3.101 that f isometry iff f preserves first fund form.

and $F_1 \neq \bar{F}_1$ (it $\frac{1}{u^2}$ did not $\neq 2u$ due to (u^2+1))

3) Show \nexists surface s.t. $E=G=1$, $F=0$
and $e=1$, $g=-1$, $f=0$.

Proposition

$$f=0 \quad e=1 \Rightarrow \underline{\underline{(IN)}}$$

$$f_u=0 \quad e_v=0 \quad 0 = \Gamma'_{12} + \Gamma''_{11}$$

$$K = \frac{eg - f^2}{EG - F^2}$$

~~KK~~

Corollary 5.55

$$K = - \frac{(\sqrt{G})_{uu}}{\sqrt{G}}$$

$$\hookrightarrow = \frac{-1}{1} = -1$$

$$K = 0$$

so contradiction X

(4) Compute Christoffel symbols for an open set of the plane.

$$\sigma(u, v) = (u, v, 0)$$

a) $\sigma_u = (1, 0, 0) \quad \sigma_v = (0, 1, 0)$

$$\sigma_{uu} = (0, 0, 0) \quad \sigma_{vv} = (0, 0, 0)$$

$$\sigma_{uv} = 0\sigma_u + 0\sigma_v + 0N = \sigma_{vu}$$

thus $\Gamma_{ijk}^k = 0$

Gauss (IV) $\rightarrow EK = 0 \Rightarrow K = 0$ ^{since $E=1$}

b) ~~$\sigma(r, \theta) = (r \cos \theta, r \sin \theta, 0)$~~
 ~~$\sigma_r = (\cos \theta, \sin \theta, 0)$~~ ~~$\sigma_\theta = (-r \sin \theta, r \cos \theta, 0)$~~
 ~~$\sigma_{rr} = (0, 0, 0)$~~
 ~~$\sigma_{r\theta} =$~~

$\sigma_r = (\cos \theta, \sin \theta, 0) \quad \sigma_\theta = (-r \sin \theta, r \cos \theta, 0)$
 $E = 1 \quad F = 0 \quad G = r^2$

$$Q = 2EG - 2F^2 = 2r^2$$

1a) $\Gamma_{11}^1 = 0 - 0 + 0 = 0$

1b) $\Gamma_{12}^1 = 0$

1c) $\Gamma_{22}^1 = \frac{-2r^3}{2r^2} = -r$

d) $0 = \Gamma_{11}^2$

e) $\Gamma_{12}^2 = \frac{1}{r}$

f) $\Gamma_{22}^2 = 0$

4) continued

$$p'_{22} = -r \quad p'_{12} = \frac{1}{r}$$

$$(iv) \quad EK = \cancel{(p'_{11})^2_v} - \cancel{(p'_{12})^2_u} + \cancel{p'_{11} p'_{12}} + \cancel{p'_{12} p'_{22}} - \cancel{p'_{12} p'_{11}} - \cancel{(p'_{12})^2} \\ - (-\frac{1}{r^2}) \quad + \quad - \frac{1}{r^2}$$

$$E \neq 0 \Rightarrow \boxed{K = 0}$$

5)

a) sphere

b) cylinder

c) $z = x^2 - y^2$

justify why not pairwise locally isometric.

$$\sigma_s(\phi, \theta) = (\cos \theta \cos \phi, \cos \theta \sin \phi, \sin \theta)$$

$$\sigma_c(u, v) = (u \cos v, u \sin v, u)$$

$$\sigma(u, v) = (u, v, u^2 - v^2)$$

~~$$\sigma_\phi^s = (-\cos \theta \sin \phi, \cos \theta \cos \phi, 0)$$~~

~~$$\sigma_\theta^s = (-\sin \theta \cos \phi, -\sin \theta \sin \phi, \cos \theta)$$~~

~~$$E_s = \cos^2 \theta, \quad F^s = 0, \quad G^s = 1$$~~

~~$$K = \frac{-1}{2 \cos^2 \theta}$$~~

unit sphere $K = 1$

cylinder $K = 0 \approx$ plane

$$\text{recall} \quad K_{\text{graph}} = \frac{\phi_{xx} \phi_{yy} - \phi_{xy}^2}{(1 + \phi_x^2 + \phi_y^2)^2} = \frac{4 - 16}{(1 + 4x^2 + 4y^2)^2}$$

thus by contrapositive of Theorema Egregium