

The Huber Loss

```
In [305]: using JuMP, Gurobi

data = zeros(15)

data[1] = 6.31
data[2] = 3.78
data[3] = 24
data[4] = 1.71
data[5] = 2.99
data[6] = 4.53
data[7] = 2.11
data[8] = 3.88
data[9] = 4.67
data[10] = 4.25
data[11] = 2.06
data[12] = 23
data[13] = 1.58
data[14] = 2.17
data[15] = .02

A = zeros(15,2)
B = zeros(13,2)
j = 1
for i = 1:15
    A[i,1] = i
    A[i,2] = 1
    if i != 3 && i != 12
        B[j,1] = i
        B[j,2] = 1
        j += 1
    end
end

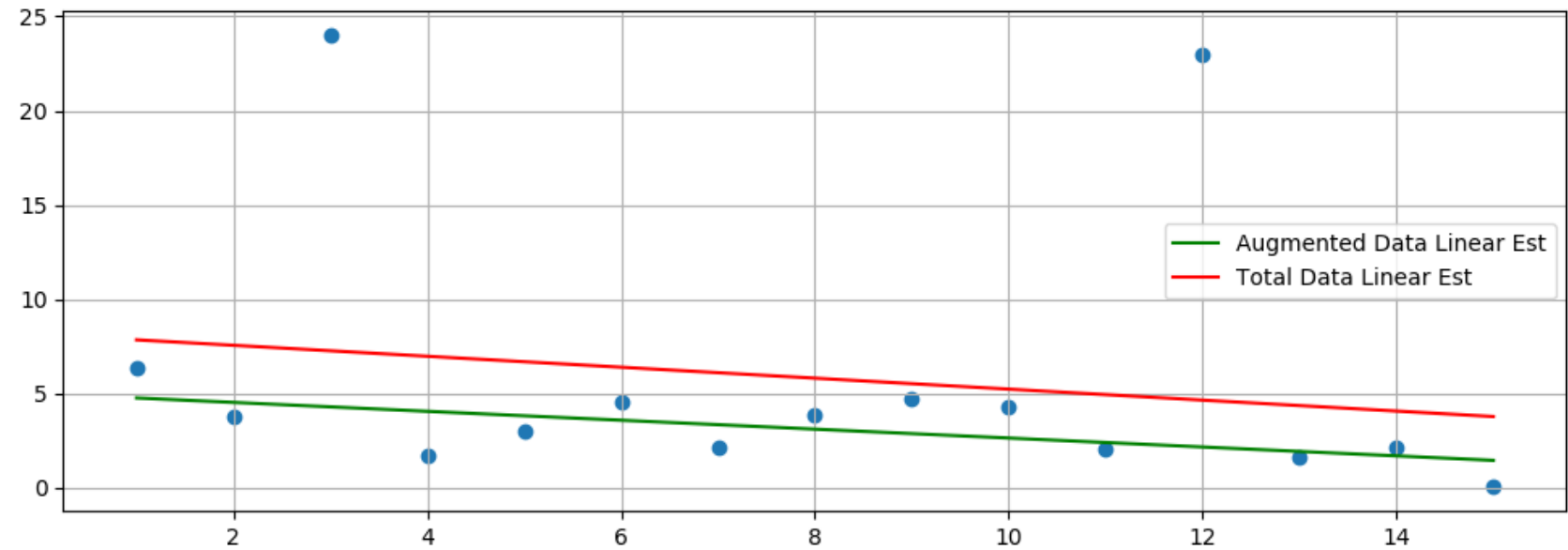
wopt = A\data;
west = A*wopt;

aug_data = zeros(13)

aug_data[1] = 6.31
aug_data[2] = 3.78
aug_data[3] = 1.71
aug_data[4] = 2.99
aug_data[5] = 4.53
aug_data[6] = 2.11
aug_data[7] = 3.88
aug_data[8] = 4.67
aug_data[9] = 4.25
aug_data[10] = 2.06
aug_data[11] = 1.58
aug_data[12] = 2.17
aug_data[13] = .02

aug_opt = B\aug_data
aug_est = B*aug_opt;
```

```
In [297]: using PyPlot
figure(figsize=(12,4))
t = linspace(1,15,100)
y1 = aug_opt[1]*t + aug_opt[2]
y2 = wopt[1]*t + wopt[2]
plot(t,y1,"g-")
plot(t,y2,"r-")
grid()
scatter(1:15,data)
legend(["Augmented Data Linear Est", "Total Data Linear Est"]);
```



The green line has a better fit to the non-outlier data as we are not considering the outlier data. The red line lies above the green line for $x = 1:15$ because it considers the very large, outlier data.

```
In [298]: m = Model(solver=GurobiSolver())
@variable(m, z[1:15])
@variable(m, slope)
@variable(m, offset)

for i = 1:15
    @constraint(m, z[i] >= A[i,1]*slope + offset - data[i])
    @constraint(m, z[i] >= -(A[i,1]*slope + offset - data[i]))
end

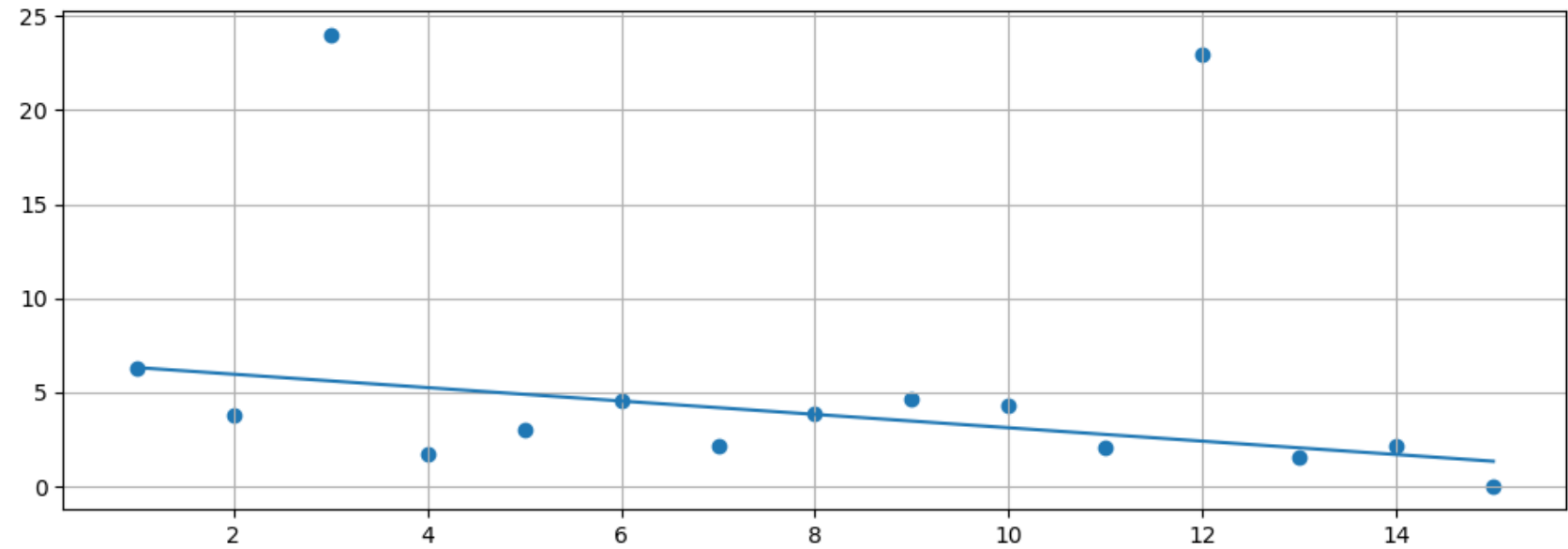
@objective(m, Min, sum(z[i] for i=1:15))
solve(m)
slope = getvalue(slope)
offset = getvalue(offset);
```

Optimize a model with 30 rows, 17 columns and 90 nonzeros
Coefficient statistics:
Matrix range [1e+00, 2e+01]
Objective range [1e+00, 1e+00]
Bounds range [0e+00, 0e+00]
RHS range [2e-02, 2e+01]
Presolve removed 15 rows and 0 columns
Presolve time: 0.00s
Presolved: 15 rows, 17 columns, 45 nonzeros

| Iteration | Objective | Primal Inf. | Dual Inf. | Time |
|-----------|-----------------------|--------------|--------------|------|
| 0 | handle free variables | | | 0s |
| 21 | 5.4030000e+01 | 0.000000e+00 | 0.000000e+00 | 0s |

Solved in 21 iterations and 0.00 seconds
Optimal objective 5.403000000e+01

```
In [299]: y3 = slope*t + offset
figure(figsize=(12,4))
plot(t,y3)
grid()
scatter(1:15,data);
```



The L_1 linear fit handles outlier data better than L_2 linear fits. This is because L_1 linear fitting takes a linear difference, whereas the L_2 linear fitting using the square of the difference. So large variances in L_2 makes a very large contribution to the norm, whereas large differences in L_1 is not as important.

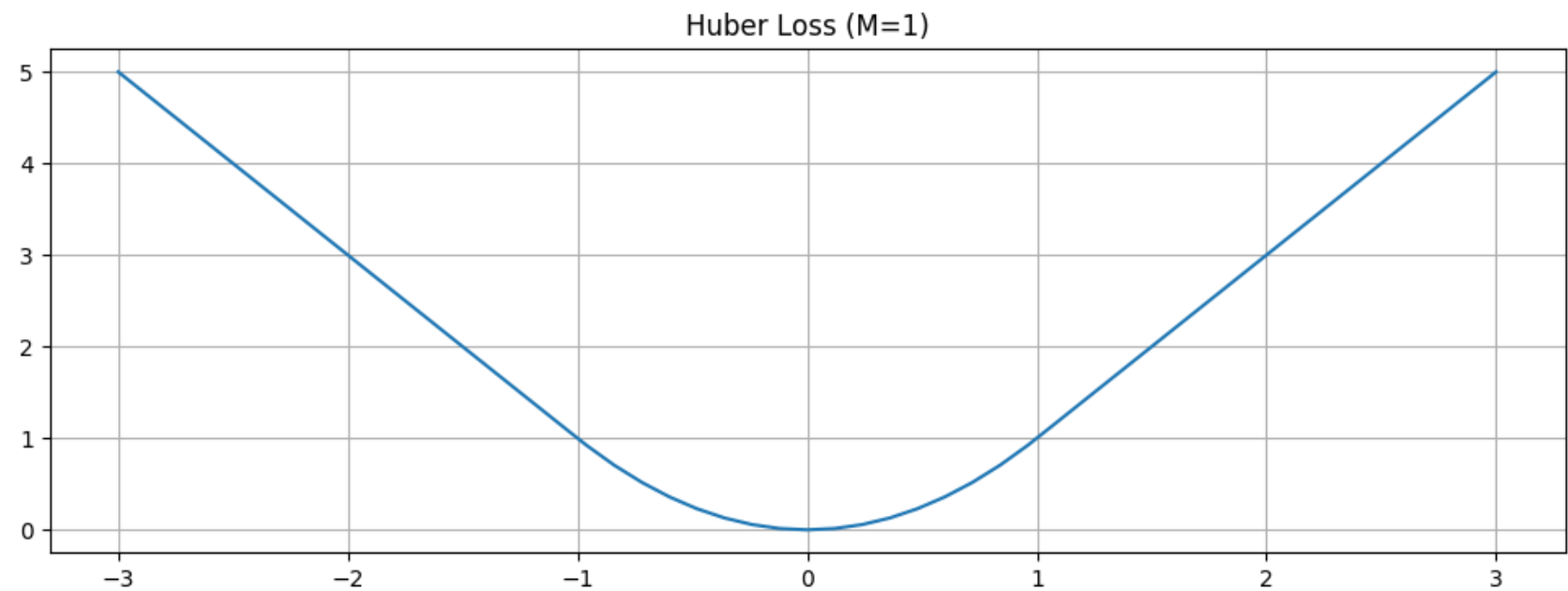
```
In [300]: M = 1
I = 50
out = zeros(I + 1,2);
```

```
In [301]: for i = 0:I
          x = -3 + i*6/I
          m = Model(solver=GurobiSolver())
          @variable(m, v >= 0)
          @variable(m, w <= M)
          @constraint(m, w + v >= x)
          @constraint(m, w + v >= -x)
          @objective(m, Min, w^2 + 2*M*v)
          solve(m);
          out[i+1,1] = x
          out[i+1,2] = getobjectivevalue(m)
        end
```

Optimize a model with 2 rows, 2 columns and 4 nonzeros
Model has 1 quadratic objective term
Coefficient statistics:
Matrix range [1e+00, 1e+00]
Objective range [2e+00, 2e+00]
QObjective range [2e+00, 2e+00]
Bounds range [1e+00, 1e+00]
RHS range [3e+00, 3e+00]
Presolve removed 2 rows and 2 columns
Presolve time: 0.00s
Presolve: All rows and columns removed

Barrier solved model in 0 iterations and 0.00 seconds
Optimal objective 5.000000000e+00
Optimize a model with 2 rows, 2 columns and 4 nonzeros
Model has 1 quadratic objective term
Coefficient statistics:
Matrix range [1e+00, 1e+00]
Objective range [2e+00, 2e+00]
QObjective range [2e+00, 2e+00]

```
In [302]: figure(figsize=(12,4))
          plot(out[:,1],out[:,2])
          title("Huber Loss (M=1)")
          grid()
```



```
In [303]: m = Model(solver=GurobiSolver())
@variable(m, x)
@variable(m, b)
@variable(m, w[1:15] <= M)
@variable(m, v[1:15] >= 0)
for i = 1:15
    @constraint(m, w[i] + v[i] >= i*x + b - data[i])
    @constraint(m, w[i] + v[i] >= -(i*x + b - data[i]))
end
@objective(m, Min, sum((w[i])^2 + 2*M*v[i] for i = 1:15))
solve(m)
```

Optimize a model with 30 rows, 32 columns and 120 nonzeros
Model has 15 quadratic objective terms
Coefficient statistics:
Matrix range [1e+00, 2e+01]
Objective range [2e+00, 2e+00]
QObjective range [2e+00, 2e+00]
Bounds range [1e+00, 1e+00]
RHS range [2e-02, 2e+01]
Presolve time: 0.00s
Presolved: 30 rows, 32 columns, 120 nonzeros
Presolved model has 15 quadratic objective terms
Ordering time: 0.00s

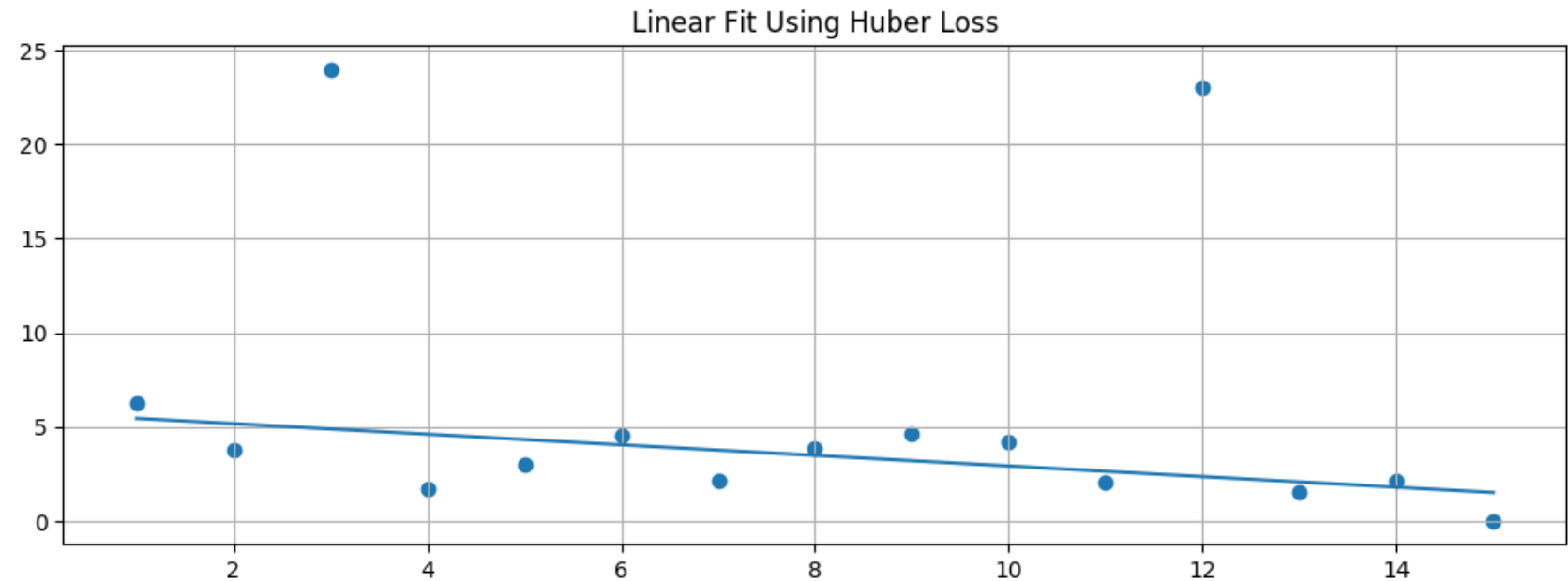
Barrier statistics:
Dense cols : 2
Free vars : 2
AA' NZ : 7.500e+01
Factor NZ : 1.080e+02
Factor Ops : 3.800e+02 (less than 1 second per iteration)
Threads : 1

| Iter | Objective | | Residual | | Compl | Time |
|------|----------------|-----------------|----------|----------|----------|------|
| | Primal | Dual | Primal | Dual | | |
| 0 | 3.09994877e+05 | -2.99850223e+04 | 0.00e+00 | 1.00e+03 | 1.00e+06 | 0s |
| 1 | 1.41170553e+06 | -1.10717831e+06 | 0.00e+00 | 3.69e+00 | 4.55e+04 | 0s |
| 2 | 2.11112505e+05 | -1.60845142e+05 | 0.00e+00 | 3.69e-06 | 6.20e+03 | 0s |
| 3 | 2.58533189e+04 | -2.29553984e+04 | 0.00e+00 | 3.71e-12 | 8.13e+02 | 0s |
| 4 | 4.89577697e+03 | -3.34776285e+03 | 0.00e+00 | 1.24e-14 | 1.37e+02 | 0s |
| 5 | 7.46863396e+02 | -4.54750634e+02 | 0.00e+00 | 7.11e-15 | 2.00e+01 | 0s |
| 6 | 1.97368833e+02 | 4.98426352e-01 | 0.00e+00 | 1.13e-14 | 3.28e+00 | 0s |
| 7 | 1.12980111e+02 | 7.85726950e+01 | 0.00e+00 | 6.44e-15 | 5.73e-01 | 0s |
| 8 | 9.72702625e+01 | 9.27694671e+01 | 0.00e+00 | 7.11e-15 | 7.50e-02 | 0s |
| 9 | 9.59533887e+01 | 9.50239427e+01 | 0.00e+00 | 7.11e-15 | 1.55e-02 | 0s |
| 10 | 9.55271477e+01 | 9.54662891e+01 | 0.00e+00 | 3.55e-15 | 1.01e-03 | 0s |
| 11 | 9.55036500e+01 | 9.54956672e+01 | 0.00e+00 | 8.44e-15 | 1.33e-04 | 0s |
| 12 | 9.55002892e+01 | 9.54991709e+01 | 0.00e+00 | 3.55e-15 | 1.86e-05 | 0s |
| 13 | 9.54998155e+01 | 9.54996573e+01 | 0.00e+00 | 1.09e-14 | 2.64e-06 | 0s |
| 14 | 9.54997485e+01 | 9.54997261e+01 | 0.00e+00 | 8.66e-15 | 3.73e-07 | 0s |
| 15 | 9.54997390e+01 | 9.54997358e+01 | 0.00e+00 | 3.55e-15 | 5.27e-08 | 0s |
| 16 | 9.54997377e+01 | 9.54997372e+01 | 0.00e+00 | 4.44e-16 | 7.45e-09 | 0s |

Barrier solved model in 16 iterations and 0.00 seconds
Optimal objective 9.54997377e+01

Out[303]: :Optimal

```
In [304]: y3 = getvalue(x)*t + getvalue(b)
figure(figsize=(12,4))
plot(t,y3)
grid()
title("Linear Fit Using Huber Loss")
scatter(1:15,data);
```



Hyperbolic Program

Part a

We start with the expression: $t(a^T x + b) \geq 1$, where $t \geq 0$ and $x \in \mathbb{R}^n$. We use the equivalence from the homework, which is:

$w^T w \leq xy$, where $x, y \geq 0 \iff \left\| \begin{bmatrix} 2w \\ x - y \end{bmatrix} \right\| \leq x + y$ We do this by letting $w = 1$, $x = (a^T x + b)$, and $y = t$.

So now we can write our original expression as $t(a^T x + b) \geq 1 \iff \left\| \begin{bmatrix} 2 \\ a^T x + b - t \end{bmatrix} \right\| \leq a^T x + b + t$

Then we can note that $\begin{bmatrix} 2 \\ a^T x + b - t \end{bmatrix} = \begin{bmatrix} 0 & 0 & \dots & 0 \\ a_1 & a_2 & \dots & a_n \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} 2 \\ b - t \end{bmatrix}$

So by letting $A = \begin{bmatrix} 0 & 0 & \dots & 0 \\ a_1 & a_2 & \dots & a_n \end{bmatrix}$, $b = \begin{bmatrix} 2 \\ b - t \end{bmatrix}$, $c = a$, and $d = b + t$ we see the final desired form of:

$$\|Ax + b\| \leq c^T x + d$$

Part b

First let $s_i = (a_i^T x + b_i)^{-1}$. For each s_i , we introduce a slack variable t_i such that $t_i \geq 1/(a_i^T x + b_i)$ This necessary condition can be written as: $t_i(a_i^T x + b_i) \geq 1$, which we recognize from part a.

So our objective function can be written as: $\sum_{i=1}^p t_i$ subject to the given constraints and the additional constraints: $t_i(a_i^T x + b_i) \geq 1 \forall i = 1, \dots, p$.

The original constraints are transformed with little effort: $\|(-1) \begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}^T \vec{x} + (-d_i)\| \leq 0 \quad \forall i = 1, \dots, q$

The additional constraints are added by following the logic behind part a, as follows:

$$\left\| \begin{bmatrix} 0 & \dots & 0 \\ a_{i,1} & \dots & a_{i,n} \end{bmatrix} + \begin{bmatrix} 2 \\ b_i - t_i \end{bmatrix} \right\| \leq a_i^T x + b_i + t_i \quad \forall i = 1, \dots, p$$

Note that by imposing the additional constraint of $t_i \geq 0 \forall i = 1, \dots, p$ we have, along with the additional constraints added above, that $a_i^T x + b_i > 0 \forall i = 1, \dots, p$. This is because t_i 's are positive and $t_i(a_i^T x + b_i) \geq 1$, which implies that $(a_i^T x + b_i)$ must also be positive.

So finally we can write out the SOCP as:

$$\begin{aligned} \min : & \sum_{i=1}^p t_i \quad \text{subject to} \\ & \|(-1) \begin{bmatrix} c_1 & c_2 & \dots & c_n \end{bmatrix}^T \vec{x} + (-d_i)\| \leq 0 \quad \forall i = 1, \dots, q \\ & \left\| \begin{bmatrix} 0 & \dots & 0 \\ a_{i,1} & \dots & a_{i,n} \end{bmatrix} + \begin{bmatrix} 2 \\ b_i - t_i \end{bmatrix} \right\| \leq a_i^T x + b_i + t_i \\ & -t_i \leq 0 \quad \forall i = 1, \dots, p \end{aligned}$$

Heat Pipe Design

Using the information from the problem, we construct the following geometric program:

$$\begin{aligned} \max : & \alpha_4 T r^2 \quad \text{subject to} \\ & T \leq T_{max}, \quad -T \leq T_{min} \\ & r \leq r_{max}, \quad -r \leq r_{min} \\ & w \leq w_{max}, \quad -w \leq w_{min} \\ & w \leq 0.1 r \end{aligned}$$

Then we use the following variable substitutions:

$$\begin{aligned} x &:= \log T \\ y &:= \log r \\ z &:= \log w \end{aligned}$$

and rewrite our program as:

$$\begin{aligned} \max : & x + 2y + \log \alpha_4 \quad \text{subject to} \\ & y + \log (e^{\log \alpha_1 - z + x} + \alpha_2 + e^{\log \alpha_3 + z}) \leq \log C_{max} \\ & \log T_{min} \leq x \leq \log T_{max} \\ & \log r_{min} \leq y \leq \log r_{max} \\ & \log w_{min} \leq z \leq \log w_{max} \end{aligned}$$

$z - y \leq \log 0.1$

This is a convex optimization problem.

```
In [308]: using Mosek

m = Model(solver=MosekSolver())

C_max = 500

@variable(m, X[1:3])

@constraint(m, X[3] - X[2] <= log(0.1))
@NLconstraint(m, X[2] + log(exp(X[1]-X[3]) + 1 + exp(X[3])) <= log(C_max))
@objective(m, Max, X[1] + 2X[2])
solve(m)
```

Problem

| | |
|-------------------|--|
| Name | : |
| Objective sense | : max |
| Type | : GECO (general convex optimization problem) |
| Constraints | : 2 |
| Cones | : 0 |
| Scalar variables | : 3 |
| Matrix variables | : 0 |
| Integer variables | : 0 |

Optimizer started.
Interior-point optimizer started.
Presolve started.
Linear dependency checker started.
Linear dependency checker terminated.
Eliminator started.
Freed constraints in eliminator : 0
Eliminator terminated.
Eliminator - tries : 1 time : 0.00
Lin. dep. - tries : 1 time : 0.00
Lin. dep. - number : 0
Presolve terminated. Time: 0.00
Matrix reordering started.
Local matrix reordering started.
Local matrix reordering terminated.
Matrix reordering terminated.

| | |
|-------------------------------------|-------------------------------|
| Optimizer - threads | : 2 |
| Optimizer - solved problem | : the primal |
| Optimizer - Constraints | : 2 |
| Optimizer - Cones | : 0 |
| Optimizer - Scalar variables | : 5 conic : 0 |
| Optimizer - Semi-definite variables | : 0 scalarized : 0 |
| Factor - setup time | : 0.00 dense det. time : 0.00 |
| Factor - ML order time | : 0.00 GP order time : 0.00 |
| Factor - nonzeros before factor | : 15 after factor : 17 |
| Factor - dense dim. | : 0 flops : 2.70e+01 |

| ITE | PFEAS | DFEAS | GFEAS | PRSTATUS | POBJ | DOBJ | MU | TIME |
|-----|---------|---------|---------|-----------|-----------------|-----------------|---------|------|
| 0 | 5.3e+00 | 2.5e+00 | 3.8e+00 | 0.00e+00 | 0.000000000e+00 | 2.813410717e+00 | 1.0e+00 | 0.00 |
| 1 | 1.2e+00 | 6.0e-01 | 9.5e-01 | -4.85e-01 | 3.771113669e+00 | 4.496832620e+00 | 2.5e-01 | 0.00 |
| 2 | 2.4e-01 | 3.0e-01 | 2.7e-01 | 2.22e-01 | 9.266063993e+00 | 9.639624658e+00 | 6.7e-02 | 0.00 |
| 3 | 1.2e-02 | 1.4e-02 | 4.0e-02 | 7.97e-01 | 1.074281033e+01 | 1.080359853e+01 | 7.3e-03 | 0.00 |
| 4 | 2.9e-03 | 1.2e-03 | 5.0e-03 | 1.00e+00 | 1.082709581e+01 | 1.082734469e+01 | 1.4e-03 | 0.00 |
| 5 | 2.5e-04 | 1.7e-04 | 1.4e-04 | 9.85e-01 | 1.084432319e+01 | 1.084350063e+01 | 1.0e-04 | 0.00 |
| 6 | 3.3e-06 | 2.5e-06 | 7.3e-07 | 9.96e-01 | 1.084554724e+01 | 1.084553303e+01 | 1.3e-06 | 0.00 |
| 7 | 1.7e-08 | 1.3e-08 | 3.6e-09 | 1.00e+00 | 1.084556109e+01 | 1.084556102e+01 | 6.5e-09 | 0.00 |

Interior-point optimizer terminated. Time: 0.00.

Optimizer terminated. Time: 0.01

Interior-point solution summary

| | | | | | |
|-----------------|----------------------------|------------|-------|------------|------------|
| Problem status | : PRIMAL_AND_DUAL_FEASIBLE | | | | |
| Solution status | : OPTIMAL | | | | |
| Primal. obj: | 1.0845561091e+01 | nrm: 4e+00 | Viol. | con: 6e-08 | var: 0e+00 |
| Dual. obj: | 1.0845561018e+01 | nrm: 2e+00 | Viol. | con: 0e+00 | var: 4e-08 |

Basic solution summary

| | | | | | |
|-----------------|-----------------|------------|-------|------------|------------|
| Problem status | : UNKNOWN | | | | |
| Solution status | : UNKNOWN | | | | |
| Primal. obj: | 0.000000000e+00 | nrm: 0e+00 | Viol. | con: 5e+00 | var: 0e+00 |
| Dual. obj: | 0.000000000e+00 | nrm: 0e+00 | Viol. | con: 0e+00 | var: 2e+00 |

Out[308]: :Optimal

```
In [309]: println("The optimal heat transfer is: ", exp(getobjectivevalue(m)))
```

The optimal heat transfer is: 51305.90289873848