#_ important PyTorch Operations [+100]

Basics and Tensor Operations:

- torch.tensor(data): Creαte α PyTorch tensor from data.
- torch.zeros(size): Create a tensor filled with zeros.
- torch.ones(size): Create a tensor filled with ones.
- torch.rand(size): Create a tensor with random values uniformly distributed between 0 and 1.
- torch.randn(size): Create a tensor with random values from a normal distribution.
- torch.arange(start, end, step): Create a 1-D tensor of size (end start) / step.
- tensor.size(): Get the size of the tensor.
- tensor.view(size): Resize the tensor.
- tensor.reshape(size): Reshape the tensor.
- tensor.numpy(): Convert tensor to a NumPy array.
- torch.from_numpy(ndarray): Create α tensor from α NumPy αrray.
- tensor.to(device): Move tensor to α specified device (CPU or GPU).
- tensor.type(dtype): Cast the tensor to a specified type.

Math Operations:

- torch.add(x, y): Element-wise addition of tensors.
- torch.sub(x, y): Element-wise subtraction of tensors.
- torch.mul(x, y): Element-wise multiplication of tensors.
- torch.div(x, y): Element-wise division of tensors.
- torch.matmul(x, y): Matrix multiplication.
- torch.mm(x, y): Alias for torch.matmul for 2D tensors.
- torch.dot(x, y): Dot product of two tensors.
- torch.exp(tensor): Exponential of each element in the tensor.
- torch.log(tensor): Natural logarithm of each element in the tensor.
- torch.pow(tensor, exponent): Power of each element in the tensor.
- torch.sqrt(tensor): Square root of each element in the tensor.
- torch.abs(tensor): Absolute value of each element in the tensor.

- torch.sum(tensor): Sum of all elements in the tensor.
- torch.mean(tensor): Mean of all elements in the tensor.
- torch.max(tensor): Maximum value in the tensor.
- torch.min(tensor): Minimum value in the tensor.
- torch.std(tensor): Standard deviation of the tensor.

Indexing, Slicing, Joining:

- tensor[index]: Access elements using Python indexing.
- tensor[start: end: step]: Slice the tensor.
- torch.cat(tensors, dim): Concatenate tensors along a dimension.
- torch.stack(tensors, dim): Stack tensors αlong α new dimension.
- torch.chunk(tensor, chunks, dim): Split tensor into a specific number of chunks.
- torch.split(tensor, split_size, dim): Split tensor into sections.

Gradient and Computational Graph:

- tensor.requires_grad_(): Enable tracking of gradient for the tensor.
- tensor.backward(): Compute the gradient of the tensor.
- tensor.grad: Access the gradient of the tensor.
- with torch.no_grad(): Context manager to disable gradient computation.

Neural Network Building Blocks:

- torch.nn.Linear(in_features, out_features): Fully connected layer.
- torch.nn.Conv2d(in_channels, out_channels, kernel_size): 2D convolution layer.
- torch.nn.MaxPool2d(kernel_size, stride): 2D max pooling layer.
- torch.nn.ReLU(): ReLU activation function.
- torch.nn.Sigmoid(): Sigmoid activation function.
- torch.nn.Tanh(): Tanh activation function.
- torch.nn.BatchNorm2d(num_features): Bαtch normαlizαtion for 2D inputs.
- torch.nn.Dropout(p): Dropout layer.

Loss Functions:

- torch.nn.MSELoss(): Mean squared error loss.
- torch.nn.CrossEntropyLoss(): Cross-entropy loss for multi-class classification.
- torch.nn.BCELoss(): Binary cross-entropy loss.
- torch.nn.BCEWithLogitsLoss(): Binary cross-entropy loss with logits.
- torch.nn.NLLLoss(): Negative log-likelihood loss.

Optimizers:

- torch.optim.SGD(params, 1r): Stochastic Gradient Descent optimizer.
- torch.optim.Adam(params, lr): Adam optimizer.
- torch.optim.Adagrad(params, lr): Adagrad optimizer.
- torch.optim.RMSprop(params, 1r): RMSprop optimizer.

Data Handling:

- torch.utils.data.Dataset: Abstract class representing a dataset.
- torch.utils.data.DataLoader(dataset): Data loader for a dataset.
- torchvision.transforms: Common image transformations for pre-processing.
- torchvision.datasets: Datasets for common vision tasks.

Model Training and Evaluation:

- model.train(): Set the model to training mode.
- model.eval(): Set the model to evaluation mode.
- torch.save(model.state_dict(), path): Save model state.
- model.load_state_dict(torch.load(path)): Load model state.

GPU **Operations**:

- torch.cuda.is_available(): Check if CUDA is available.
- tensor.cuda(): Move tensor to GPU.
- model.cuda(): Move model to GPU.

• torch.device("cuda:0"): Specify which GPU to use.

Autograd and Function:

- torch.autograd.Variable(tensor): Deprecated, use tensors with requires_grad.
- torch.autograd.grad(outputs, inputs): Compute gradients w.r.t inputs.
- torch.autograd.Function: Base class for custom autograd Functions.

Advanced Tensor Operations:

- torch.unbind(tensor, dim): Removes a tensor dimension.
- torch.squeeze(tensor): Remove all dimensions of size 1.
- torch.unsqueeze(tensor, dim): Add a dimension of size 1.
- torch.transpose(tensor, dim0, dim1): Transpose two dimensions of a tensor.
- torch.t(tensor): Transpose for 2D tensors.
- torch.einsum(equation, tensors): Perform Einstein summation.
- torch.norm(tensor, p): Compute the p-norm.
- torch.clamp(tensor, min, max): Clamp tensor values to a range.

Randomness and Probability:

- torch.manual_seed(seed): Manually set the random seed for reproducibility.
- torch.randperm(n): Random permutation of integers from 0 to n-1.
- torch.bernoulli(tensor): Draw binary random numbers from a Bernoulli distribution.

Tensor Serialization:

- torch.save(tensor, path): Save tensor to file.
- torch.load(path): Load tensor from file.

Functional Interface:

• torch.nn.functional.relu(tensor): Functional interface for ReLU.

- torch.nn.functional.conv2d(input, weight): Functional interface for 2D convolution.
- torch.nn.functional.max_pool2d(input, kernel_size): Functionαl interface for 2D max pooling.
- torch.nn.functional.cross_entropy(input, target): Functional interface for cross-entropy loss.

Custom Modules and Models:

- class MyModule(torch.nn.Module): Define a custom neural network module.
- \bullet def forward(self, x): Define the forward pass of a module.

Tensor Decompositions and Linear Algebra:

- torch.svd(tensor): Singular value decomposition.
- torch.eig(tensor): Compute the eigenvalues and eigenvectors.
- torch.inverse(tensor): Compute the inverse of a matrix.

Parallel and Distributed Computing:

- torch.nn.DataParallel(model): Data parallelism over multiple GPUs.
- torch.distributed.init_process_group(backend): Initialize the distributed backend for multi-process parallelism.

Tensor Inspection and Debugging:

- tensor.type(): Get the data type of the tensor.
- tensor.device: Get the device of the tensor.
- tensor.layout: Get the memory layout of the tensor.
- tensor.is_cuda: Check if the tensor is on CUDA.
- tensor.requires_grad: Check if the tensor requires gradient.
- torch.set_printoptions(precision): Set printing options for tensors.

Advanced GPU and CUDA Operations:

torch.cuda.memory_allocated(): Get the current GPU memory usage.

- torch.cuda.memory_cached(): Get the cached GPU memory.
- torch.cuda.empty_cache(): Release cached memory.
- torch.cuda.get_device_name(device): Get the name of the GPU device.

Quantization for Model Optimization:

- torch.quantization.quantize_dynamic(model, dtype): Apply dynamic quantization to a model.
- torch.quantization.quantize_static(model, calibration, dtype): Apply static quantization to a model.
- torch.quantization.QuantStub(): Quantization stub for quantizable modules.
- torch.quantization.DeQuantStub(): Dequantization stub for quantizable modules.
- torch.quantization.prepare(model): Prepare the model for quantization calibration.
- torch.quantization.convert(model): Convert the model to α quantized version.

Tensor Advanced Operations:

- torch.gather(input, dim, index): Gather values along an axis specified by dim.
- torch.scatter(input, dim, index, src): Write values from src into input at positions specified by index.
- torch.repeat_interleave(tensor, repeats, dim): Repeαt elements of α tensor along a dimension.
- torch.roll(tensor, shifts, dims): Roll the elements of α tensor along a given dimension.

Functional API for Complex Operations:

- torch.nn.functional.dropout(input, p, training): Apply dropout to the input.
- torch.nn.functional.interpolate(input, size, mode): Upsample or downsample a tensor.
- torch.nn.functional.pad(input, pad, mode, value): Pαd α tensor.

• torch.nn.functional.normalize(input, p, dim): Normalize a tensor.

Debugging and Profiling:

- torch.autograd.set_detect_anomaly(True): Enable anomaly detection for debugging.
- torch.autograd.profiler.profile(): Context manager for profiling the performance of PyTorch operations.

PyTorch Extensions and Utilities:

- torch.utils.checkpoint.checkpoint(function, *args): Enable checkpointing for memory-efficient gradients.
- torch.utils.data.random_split(dataset, lengths): Randomly split a dataset into non-overlapping new datasets of given lengths.
- torch.utils.tensorboard.SummaryWriter(log_dir): Log PyTorch models and metrics into TensorBoard.

Advanced Model Building:

- torch.nn.utils.rnn.pack_padded_sequence(input, lengths, batch_first): Pack α tensor containing padded sequences for RNN processing.
- torch.nn.utils.rnn.pad_packed_sequence(sequence, batch_first): Pad packed batch of variable length sequences.
- torch.nn.utils.prune.l1_unstructured(module, name, amount): Apply
 L1 unstructured pruning to α module.

Custom Autograd Functions:

- class MyFunction(torch.autograd.Function): Define α custom αutograd function.
- @staticmethod def forward(ctx, input): Forward pass for custom autograd function.
- @staticmethod def backward(ctx, grad_output): Backward pass for custom autograd function.

Interoperability with NumPy:

- torch.from_numpy(numpy_array): Create a tensor from a NumPy array.
- tensor.detach().numpy(): Convert a tensor to a NumPy array.

Distributed Training:

- torch.distributed.init_process_group(backend, world_size, rank): Initialize distributed process group for parallel training.
- torch.nn.parallel.DistributedDataParallel(model): Wrap model for distributed training.

TensorBoard Integration:

- from torch.utils.tensorboard import SummaryWriter: Import TensorBoard SummaryWriter for logging.
- writer.add_scalar('tag', value, step): Loq α scalar variable.
- writer.add_histogram('tag', values, step): Log values as a histogram.
- writer.add_image('tag', img_tensor, step): Loq an image.
- writer.add_graph(model, input_to_model): Log model graph.

Advanced CUDA Operations:

- torch.cuda.stream(stream): Context manager to select a stream.
- torch.cuda.amp.autocast(): Automatic mixed precision context manager.
- torch.cuda.amp.GradScaler(): Gradient scaler for mixed precision training.

Custom Datasets and Data Loaders:

- class CustomDataset(torch.utils.data.Dataset): Define α custom dataset.
- def __len__(self): Return the size of the dataset.
- def __getitem__(self, idx): Retrieve an item by index.

Serialization and Saving Models:

torch.save(object, path): Serialize a PyTorch object to disk.

- torch.load(path): Deserialize a PyTorch object from disk.
- model.state_dict(): Get model's state dictionary.
- model.load_state_dict(state_dict): Load a state dictionary into the model.

Working with Hooks:

- model.register_forward_hook(hook): Register a forward hook on the model.
- model.register_backward_hook(hook): Register a backward hook on the model.

Model Fine-Tuning and Transfer Learning:

- torchvision.models.resnet18(pretrained=True): Load a pre-trained ResNet-18 model.
- for param in model.parameters(): param.requires_grad = False: Freeze parameters for transfer learning.

PyTorch for Mobile:

- torch.jit.script(model): Convert model to TorchScript for mobile deployment.
- torch.jit.save(scripted_model, path): Save a scripted model for mobile use.

Dynamic Computational Graphs:

- torch.autograd.Variable(tensor, requires_grad): Wrapper around tensors for autograd.
- variable.grad_fn: Access grad function of the variable.

Specialized Layers and Functions:

- torch.nn.Embedding(num_embeddings, embedding_dim): A simple lookup table that stores embeddings of a fixed dictionary and size.
- torch.nn.MultiheadAttention(embed_dim, num_heads): Multi-head attention mechanism.

• torch.nn.utils.weight_norm(module, name): Apply weight normalization to a module.

Memory Management and Optimization:

• torch.cuda.memory_summary(device=None, abbreviated=False): Print α summary of CUDA memory allocation and usage.

Dynamic Quantization:

• torch.quantization.quantize_dynamic(model, {torch.nn.LSTM, torch.nn.Linear}, dtype=torch.qint8): Dynamically quantize LSTM and Linear layers for efficiency.