

## Lecture 23

### Q: What is the flux factor at the LHC ?

Flux Factor also called  $L$  “instantaneous luminosity” or just “luminosity”

$$L = n_A n_B A |v_A - v_B| = \frac{N_A N_B |v_A - v_B|}{\underbrace{Vol}_{\text{Vol. of bunch} = A_B \times l}}$$

Now  $\sigma$  is fixed, so to maximize number of events collected, need to maximize  $L$

- $N_A = N_B = N = 10^{11}$  (fixed)
- $|v_A - v_B| = 2c$  can get much higher!
- $Vol \sim A_B \cdot l$

At the LHC, acceleration is done with radio-frequency EM feild that fixes  $l$  (Protons ride in the troughs of this feild) The wavelength of this feild sets  $l \sim \frac{c}{2 \times 400 \text{ MHz}} \sim \frac{3}{4} m$  The one handle we have is  $A_B$ , focusing magnets (quadruples) act like a lens near the collision points to squeeze the beam. So far focusing magnets have achieved squeezing down to the radii of  $10 \mu m$ ! Width of a human hair.

$$A_B \sim 10^{-10} m^2$$

$\Rightarrow$

$$L = 2c \frac{N^2}{l A} \sim 10^{-36} cm^{-2} s^{-1}$$

## Talk a bit about Accelerators

Particles moving in a circle are accelerating.

Accelerating charged particles radiate. (synchrotron radiation)

Turns out, power lost to synchrotron radiation given by:

$$P \sim 0.3 \left( \frac{1 \text{ km}}{R} \right)^2 \left( \frac{E}{m} \right)^4 \frac{\text{eV}}{\text{s}}$$

For LHC:

$$- \frac{E}{m} \sim 7000$$

$$- R_{LHC} \sim \frac{27 \text{ km}}{2\pi}$$

$$P \sim 10^5 \frac{\text{GeV}}{\text{s}}$$

This is a major drawback of a circular collider.

To keep particles in circle need thousands of superconducting bending magnets.

$$|\vec{B}| = \frac{|\vec{p}|}{eR_{\text{curv}}} \sim 3 \frac{E(\text{TeV})}{R(\text{km})} \text{ Tesla}$$

$\Rightarrow$

$$E(\text{TeV}) \sim \frac{1}{3} B(T) R(\text{km})$$

Most restrictive constraint on increasing the energy at the LHC.

Modern superconducting magnets have max strength of  $\sim 20$  T.

With current technologies need larger ring to go to significantly higher energy.

Efforts now underway for  $\sim 100$  TeV collider (100 km in Geneva)

China also planning something similar.

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## Bunches

Lets try to build some intuition around the bunches.

Say earlier that they have the diminsions of a long strand of human hair.

- $l \sim 0.40 \text{ m}$
- $A_B \sim (10^{-3} \text{ m})^2$
- $\text{vol}_{\text{bunch}} \sim 10^{-6} \text{ m}^3$
- $\text{vol}_{\text{protons}} \sim 10^{11} r_p^3 \sim 10^{-34} \text{ m}^3$
- $\frac{\text{vol}_{\text{proton}}}{\text{vol}_{\text{bunch}}} \sim 10^{-28}$

Proton beams are mostly empty

$\Rightarrow$  Hard to get them to collide.

Focusing Magnets squeeze beam size

$$A_B \sim (10^{-5} \text{ m})^2 \Rightarrow v_{\text{bunch}} \sim 10^{-10} \text{ m}^3$$

Decrease in  $\text{Vol}_{\text{bunch}}$  by  $10^4$  critical for physics program at LHC.

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## Detectors

Once bunches are accelerated they are made to collide (Every 25ns at LHC)

When protons collide and exchange large amount of momentum, create shower of partilces from collision point.

$$\underbrace{|p_1 p_2\rangle_I}_{t=-\infty} \rightarrow \underbrace{|\{p_f^i \dots p_f^n\}\rangle}_{t=+\infty}$$

Dynamics of the collision is imprinted on the final state particles.

eg:

- Energy Conservation
- Momentum Conservation
- Charge Conservation

- etc

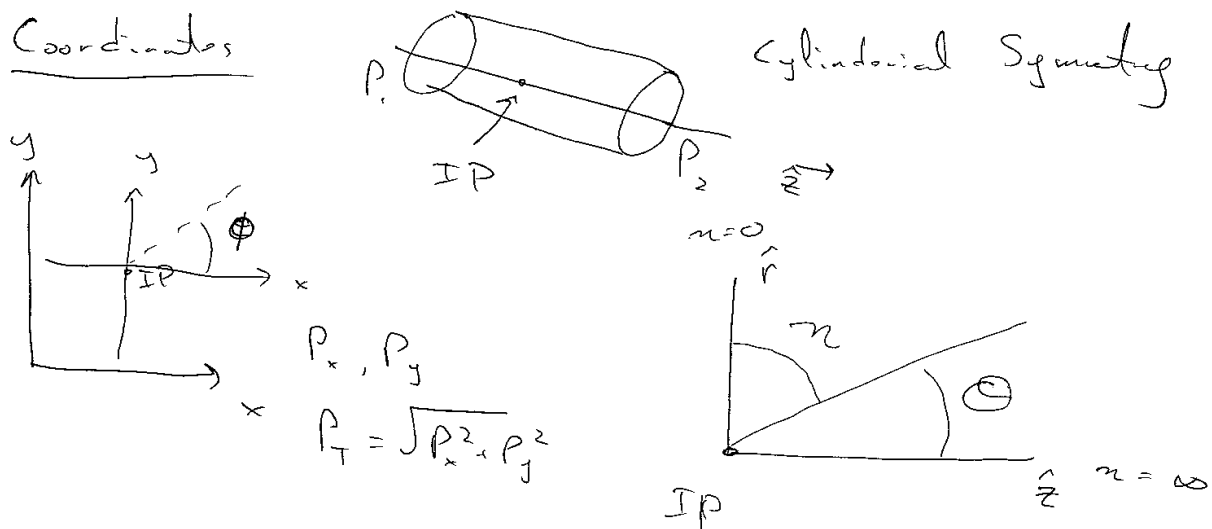
We want to measure as many particles and properties as possible.

|                   |  |
|-------------------|--|
| “Easy” to measure | $E$ and $\vec{p}$ ( $\Rightarrow m = \sqrt{E^2 - p^2}$ ) |
|                   | charge of leptons and hadrons                            |

|                   |                           |
|-------------------|---------------------------|
| “Hard” to measure | Angular $\vec{p}$ or Spin |
|                   | Charge of quarks          |

Detectors not built to be sensitive to spins.

### Coordinates



“pseudo-rapidity” (Explore this in HW)

$$\eta = -\ln \tan \frac{\theta}{2}$$

“rapidity”

$$y = \frac{1}{2} \ln \frac{E + p_z}{E - p_z}$$

$\eta = y$  for massless particles.

We know  $p_T^L = 0$ , we don't know  $p_z^L$ , so we are often interested in variables (like  $p_T$ ) that are independent of Boosts along  $z$ .

Massless particle:  $p^\mu = p_T(\cosh \eta, \cos \phi, \sin \phi, \sinh \eta)$

Massive particle:  $p^\mu = (m_T \cosh y, p_T \cos \phi, p_T \sin \phi, m_T \sinh y)$

where  $m_T = \sqrt{p_T^2 + m^2}$  is called the “transverse mass”, invariant to boosts along z

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In order to be detected, a particle must undergo an interaction with detector material. (Again this is an enormous subject, we will only scratch surface)

Typically talk about how particles lose energy to the detectors.

Three key mechanisms:

- Ionisation Energy loss
  - Radiation Energy loss
  - Nuclear Interactions
- ) Ionisation and Radiation energy loss are long range interactions from the EM force
- ) Nuclear Interactions are from the strong or weak force, both short range
- ) Ionisation Energy Loss is interaction with electrons in atoms.
- ) Radiation Energy Loss and Nuclear Interactions Energy Loss is interaction with atomic nucleus.

## Two Basic Types of Detectors

### Trackers

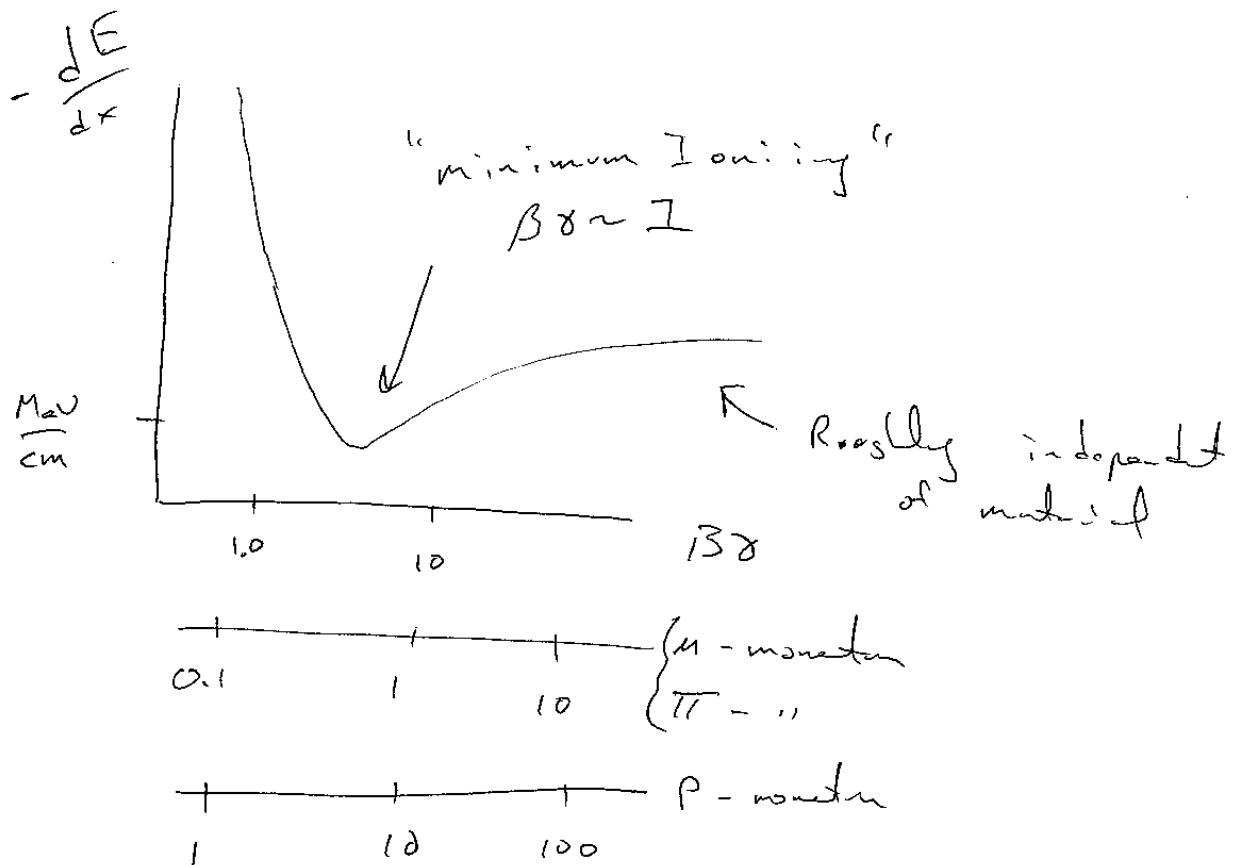
- Sensitive to ionization loss
- Non destructive  $\vec{p}_{in} \sim \vec{p}_{out}$
- Small fraction of energy deposited indicates particle position

### Calorimeters

- Extract potential energy from Radiation or Nuclear Interactions
- Destructive  $p_{out} = 0$
- Use ionization loss to measure energy of radiation / nuclear interactions

## Ionization

Fast moving particle that interacts electromagnetically with an electron in an atom.  
Particle kicks out electrons, loses energy.



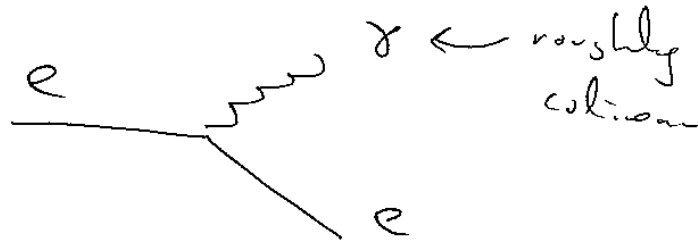
Ionization dominates as long as particles are not too relativistic:  $\beta\gamma \lesssim 1000$

Above this a new effect takes over ...

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## Radiation Loss

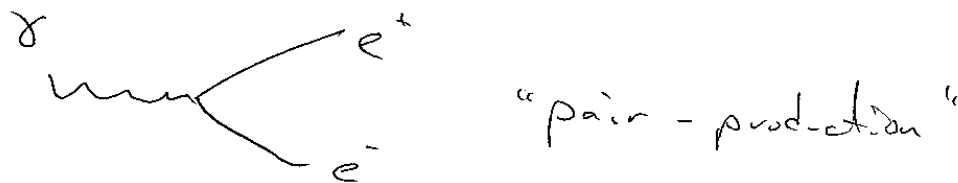
At very high energy.



The photon carries a large fraction of the initial energy.

“Bremsstrahlung” Radiation (German for breaking)

Same effect works for photons



Involve interactions with nuclei to conserve four-momentum.

These processes occur infrequently, but are very significant events when they occur.  
(Contrasted to Ionization Energy Loss which is ~ continuous and minor)

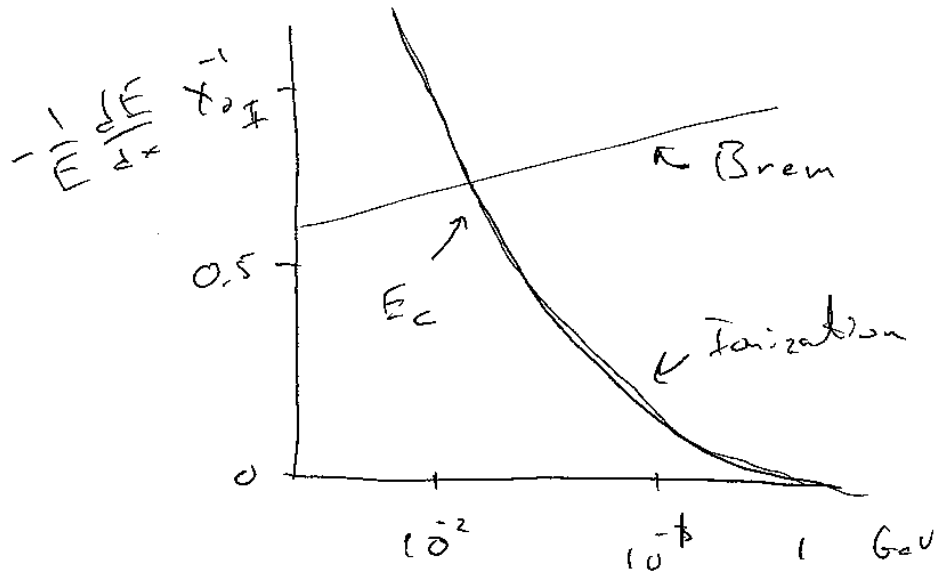
So here makes sense to talk about the probability for energy loss, not the average along path.

We will skip the details,

Bottom line:

$$\frac{dE}{dx} \sim -\frac{E}{x_0}$$

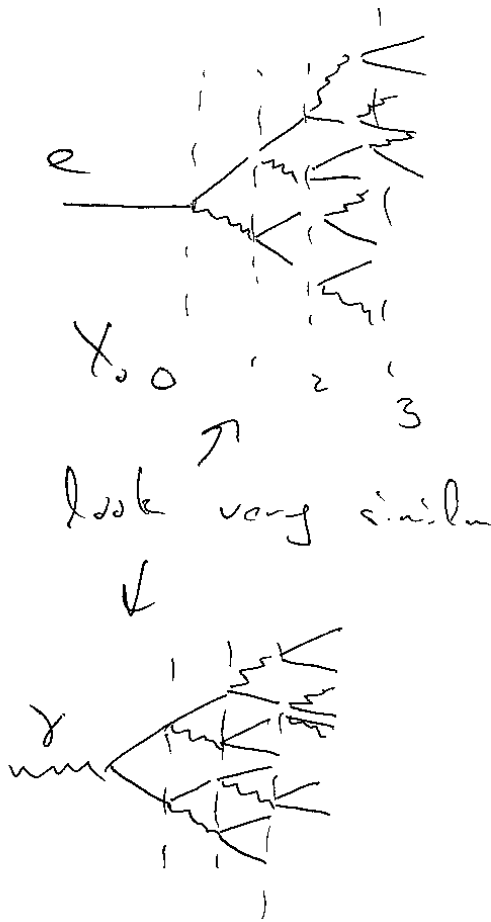
$x_0$  - length scale ("radiation length") distance over which electron loses  $e^{-1}$  of its energy. O(cm)



Similar story for photons.

$E_c$  - critical energy O( $10^{-2} - 10^{-1}$  GeV)





### “Electromagnetic Shower”

- ) For each  $e$  (or  $\gamma$ ) with  $E > E_c$  travels  $\sim 1x_0$  then gives up 1/2 energy to  $\gamma$  (or  $ee$ ).
- )  $e$ 's,  $\gamma$ 's with energy  $< E_c$  get absorbed via ionization

If initial energy  $E_0 \gg E_c$  then after  $t$ -radiation lengths there will be  $2^t$  particles. Approximately equal  $e$ 's and  $\gamma$ 's each with energy  $E(t) \sim \frac{E_0}{2^t}$ .

Shower will stop growing when

$$E(t) \simeq E_c \equiv E(t_{max})$$

$t_{max}$  is point in shower with max particles

$$t_{max} = \frac{\ln \frac{E_0}{E_c}}{\ln 2}$$

$\Rightarrow$  shower depth grows as  $\ln$

$N_{max}$  given by  $E_0/E_c$