Lecture 29

Continuing with Electroweak Unification...

So we have ... Local gauge invariance of SU(2)

$$\phi(x) \to e^{ig\vec{\alpha}(x)\cdot\sigma}\phi(x)$$

implying that

$$\phi(x) = \begin{pmatrix} v_e \\ e \end{pmatrix}$$

two compoent spinor: "weak iso spin"

Requires the addition of 3 gauge feilds via

$$\partial_{\mu} \to D_{\mu} = \partial_{\mu} + ig\vec{W}_{\mu} \cdot \vec{\sigma}$$

$$\vec{W}_{\mu} = \{W_{\mu}^1, W_{\mu}^2, W_{\mu}^3\}$$

Before adding the gauge invariance.

$$\mathcal{L} = i\bar{\phi}\gamma_{\mu}\partial^{\mu}\phi = i\nu_{e}\gamma_{\mu}\partial^{\mu}\nu_{e} + ie\gamma_{\mu}\partial^{\mu}e$$

where e and v_e are 4-component solutions to the Dirac Equation.

With the gauge invariance.

$$\mathcal{L} \to \mathcal{L}' = i\bar{\phi}\gamma_{\mu}D^{\mu}\phi + (\text{kinetic term for Ws} \sim F_{\mu\nu}F^{\mu\nu})$$
$$= i\bar{\phi}\gamma_{\mu}\left(\partial_{\mu} + ig(W_{1}^{\mu}\sigma_{1} + W_{2}^{\mu}\sigma_{2} + W_{3}^{\mu}\sigma_{3})\right)\phi + \dots$$

Now define

$$\sigma_{\pm} = \frac{1}{2}(\sigma_1 \pm i\sigma_2) = \begin{cases} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \\ \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \end{cases}$$

So,

$$\vec{W} \cdot \vec{\sigma} = W_1^{\mu} \sigma_1 + W_2^{\mu} \sigma_2 + W_3^{\mu} \sigma_3$$
$$= W_+^{\mu} \sigma_+ + W_-^{\mu} \sigma_- + W_3^{\mu} \sigma_3$$

define $W^{\pm}_{\mu}=(W^1_{\mu}\mp iW^2_{\mu})$

So,

$$\mathcal{L} \supset = i\bar{\phi}\gamma_{\mu} \left(\partial_{\mu} + ig \left(W^{\mu}_{+} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + W^{\mu}_{-} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + W^{\mu}_{3} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right) \right) \phi$$