tb cocotb.v

AUTHORS

JAY CONVERTINO

DATES

2025/06/24

INFORMATION

Brief

Test bench wrapper for cocotb

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tb cocotb

```
module tb_cocotb #(
parameter
CLOCK_SPEED
=
2000000,
parameter
RX_BAUD_DELAY
=
0,
parameter
TX_BAUD_DELAY
=
0
) ( input wire aclk, input wire arstn, output wire parity_err, output wire
```

Parameters

CLOCK_SPEED This is the aclk frequency in Hz

parameter

RX_BAUD_DELAY Delay in rx baud enable. This will delay when we sample a bit (default is midpoint

when rx delay is 0).

TX_BAUD_DELAY Delay in tx baud enable. This will delay the time the bit output starts.

parameter

Ports

aclk Clock for AXIS

arstn Negative reset for AXIS

frame_err Indicates the diff line went to no diff before data catpure finished.

Bits explained below:

```
- S = SYNC ONLY (4)

- 1 = Send only a sync pulse specified by TYY

- 0 = Send normal sync + data.

- D = DELAY ENABLED (3)

- 1 = Make sure there is a delay of 4us

- 0 = Send out immediatly

- TYY = TYPE OF DATA (2:0)

- 000 = NA

- 001 = REG (NOT IMPLIMENTED)

- 010 = DATA

- 100 = CMD/STATUS
```

s_axis_tvalid - When set active high the input data is valid s_axis_tready - When active high the device is ready for input data. m_axis_tdata - Output data from UART RX m_axis_tuser - Information about the AXIS data {S,D,TYY} (4:0)

Bits explained below:

```
- S = SYNC ONLY (4)

- 1 = Only received a sync pulse specified by TYY

- 0 = Normal sync + data received.

- D = DELAY BEFORE DATA (3)

- 1 = Delay of 4us or more before data

- 0 = No delay between data

- TYY = TYPE OF DATA (2:0)

- 000 NA

- 001 REG (NOT IMPLIMENTED)

- 010 DATA

- 100 CMD/STATUS
```

m_axis_tready - When active high the output data is valid m_axis_tready - When set active high the output device is ready for data. tx_active - Active high indicates transmit is in progress. tx_diff - transmit for 1553 (output to RX) rx_diff - receive for 1553 (input from TX)

INSTANTIATED MODULES

dut

```
axis_1553 #(

CLOCK_SPEED(CLOCK_SPEED),

RX_BAUD_DELAY(RX_BAUD_DELAY),

TX_BAUD_DELAY(TX_BAUD_DELAY)
) dut ( .aclk(aclk), .arstn(arstn), .parity_err(parity_err), .frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(fra
```

Device under test, axis_1553