axis uart.v

AUTHORS

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DATES

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INFORMATION

Brief

Core for interfacing with simple UART communications. Output is always the size of DATA_BITS.

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axis uart

```
module axis_uart #(
parameter
BAUD_CLOCK_SPEED
=
2000000,
parameter
BAUD_RATE
=
2000000,
parameter
PARITY_ENA
```

```
=
Θ,
parameter
PARITY_TYPE
parameter
STOP_BITS
parameter
DATA_BITS
parameter
RX_DELAY
parameter
RX_BAUD_DELAY
parameter
\mathsf{TX}\_\mathsf{DELAY}
Θ,
parameter
TX_BAUD_DELAY
) ( input aclk, input arstn, output parity_err, output frame_err, input [DAT
```

AXIS UART, simple UART with AXI Streaming interface.

Parameters

 $\textbf{BAUD_CLOCK_SPEED} \qquad \text{This is the aclk frequency in Hz}$

parameter

BAUD_RATE Serial Baud, this can be any value including non-standard.

parameter

PARITY_ENA Enable Parity for the data in and out.

parameter

PARITY_TYPE Set the parity type, 0 = even, 1 = odd, 2 = mark, 3 = space.

parameter

STOP_BITS Number of stop bits, 0 to crazy non-standard amounts.

parameter

DATA_BITS Number of data bits, 1 to crazy non-standard amounts.

parameter

RX_DELAY Delay in rx data input.

paramete

RX_BAUD_DELAY Delay in rx baud enable. This will delay when we sample a bit

parameter (default is midpoint when rx delay is 0).

TX_DELAY Delay in tx data output. Delays the time to output of the data.

parameter

TX_BAUD_DELAY Delay in tx baud enable. This will delay the time the bit output

parameter starts.

Ports

aclk Clock for AXIS

arstn Negative reset for AXIS

frame_err Indicates error with frame (active high)

s_axis_tdata Input data for UART TX.

s_axis_tvalid When set active high the input data is valid

s_axis_tready When active high the device is ready for input data.

m_axis_tdata Output data from UART RX

m axis tvalid When active high the output data is valid

m_axis_tready When set active high the output device is ready for data.

uart_clk Clock used for BAUD rate generation

tx transmit for UART (output to RX)

rx receive for UART (input from TX)

rts request to send is a loop with CTS

cts clear to send is a loop with RTS

INSTANTIATED MODULES

uart baud gen tx

Generates TX BAUD rate for UART modules using modulo divide method.

uart_baud_gen_rx

Generates RX BAUD rate for UART modules using modulo divide method.

uart_tx

```
axis_uart_tx #(

PARITY_ENA(PARITY_ENA),

PARITY_TYPE(PARITY_TYPE),

STOP_BITS(STOP_BITS),

DATA_BITS(DATA_BITS),

DELAY(TX_DELAY)
) uart_tx ( .aclk(aclk), .arstn(arstn), .s_axis_tdata(s_axis_tdata), .s_axis
```

Produces transmit data for tx UART from AXIS.

uart_rx

```
axis_uart_rx #(

PARITY_ENA(PARITY_ENA),

PARITY_TYPE(PARITY_TYPE),

STOP_BITS(STOP_BITS),

DATA_BITS(DATA_BITS),

DELAY(RX_DELAY)
) uart_rx ( .aclk(aclk), .arstn(arstn), .parity_err(parity_err), .frame_err(
```

Consumes receive data for rx UART to AXIS.