tb cocotb.v

AUTHORS

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DATES

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INFORMATION

Brief

Test bench wrapper for cocotb

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tb_cocotb

```
module tb_cocotb #(
parameter
CLOCK_SPEED
=
2000000,
parameter
BUS_WIDTH
=
4,
parameter
SELECT_WIDTH
=
1,
parameter
```

```
RATE
=
115200
) ( input aclk, input arstn, input [BUS_WIDTH*8-1:0] s_axis_tdata, input s_a
```

SPI core with axis input/output data. Read/Write is size of BUS_WIDTH bytes. Write activates core for read.

Parameters

CLOCK_SPEED This is the aclk frequency in Hz, this is the the frequency used for the bus and is

parameter divided by the rate.

BUS_WIDTH AXIS data width in bytes.

parameter

SELECT_WIDTH Bit width of the slave select.

parameter

RATE Select the data rate of the spi core.

parameter

Ports

aclk Clock for AXIS

arstn Negative reset for AXIS s_axis_tdata Input data for UART TX.

s_axis_tvalid When set active high the input data is valid

s_axis_tready When active high the device is ready for input data.

m_axis_tvalid When active high the output data is valid

m_axis_tready When set active high the output device is ready for data.sclk spi clock, should only drive output pins to devices.

 mosi
 transmit for master output

 miso
 receive for master input

 ssn_i
 slave select input

 ssn_o
 slave select output

 rate
 output rate of spi core.

parameter

cpol clock polarity of spi_clk
cpha clock phase of spi_clk

miso_dcount Current number of input bits available from parallel register.

mosi_dcount current number of output bits available to serial shift output.

INSTANTIATED MODULES

dut

```
axis_spi_master #(

CLOCK_SPEED(CLOCK_SPEED),

BUS_WIDTH(BUS_WIDTH),

SELECT_WIDTH(SELECT_WIDTH)
```

```
) dut ( .aclk(aclk), .arstn(arstn), .s_axis_tdata(s_axis_tdata), .s_axis_t
```

Device under test, $axis_spi_master$