# tb cocotb.v

## **AUTHORS**

## **JAY CONVERTINO**

#### **DATES**

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# **INFORMATION**

## **Brief**

Test bench wrapper for cocotb

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## tb\_cocotb

```
module tb_cocotb #(
parameter
CLOCK_SPEED
=
2000000,
parameter
BUS_WIDTH
=
4,
parameter
SELECT_WIDTH
=
1,
parameter
```

```
RATE
=
115200
) ( input aclk, input arstn, input [BUS_WIDTH*8-1:0] s_axis_tdata, input s_a
```

SPI core with axis input/output data. Read/Write is size of BUS\_WIDTH bytes. Write activates core for read.

#### **Parameters**

CLOCK\_SPEED This is the aclk frequency in Hz, this is the the frequency used for the bus and is

parameter divided by the rate.

BUS\_WIDTH AXIS data width in bytes.

parameter

**SELECT\_WIDTH** Bit width of the slave select.

parameter

**RATE** Select the data rate of the spi core.

parameter

#### **Ports**

aclk Clock for AXIS

arstn Negative reset for AXIS s\_axis\_tdata Input data for UART TX.

s\_axis\_tvalid When set active high the input data is valid

**s\_axis\_tready** When active high the device is ready for input data.

m\_axis\_tdata Output data from UART RX

m\_axis\_tvalid When active high the output data is valid

m\_axis\_treadywhen set active high the output device is ready for data.sclkspi clock, should only drive output pins to devices.

 mosi
 transmit for master output

 miso
 receive for master input

 ssn\_i
 slave select input

 ssn\_o
 slave select output

 rate
 output rate of spi core.

parameter

cpol clock polarity of spi\_clk
cpha clock phase of spi\_clk

## **INSTANTIATED MODULES**

## dut

```
axis_spi #(
CLOCK_SPEED(CLOCK_SPEED),
BUS_WIDTH(BUS_WIDTH),
SELECT_WIDTH(SELECT_WIDTH)
) dut ( .aclk(aclk), .arstn(arstn), .s_axis_tdata(s_axis_tdata), .s_axis_tv
```

Device under test, axis\_spi