# tb cocotb.v

## **AUTHORS**

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## **DATES**

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## **INFORMATION**

## **Brief**

Test bench wrapper for cocotb

#### **License MIT**

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## tb\_cocotb

```
module tb_cocotb #(
parameter
BAUD_CLOCK_SPEED =
2000000,
parameter
BAUD_RATE =
2000000,
parameter
PARITY_ENA =
0,
parameter
```

```
PARITY_TYPE
parameter
STOP_BITS
parameter
DATA_BITS
8,
parameter
RX_DELAY
Θ,
parameter
RX_BAUD_DELAY
parameter
TX_DELAY
Θ.
parameter
TX_BAUD_DELAY
) ( input aclk, input arstn, output parity_err, output frame_err, input [DAT
```

Test bench for axis uart.

#### **Parameters**

BAUD\_CLOCK\_SPEED This is the aclk frequency in Hz

parameter

**BAUD\_RATE** Serial Baud, this can be any value including non-standard.

parameter

PARITY\_ENA Enable Parity for the data in and out.

parameter

**PARITY\_TYPE** Set the parity type, 0 = even, 1 = odd, 2 = mark, 3 = space.

parameter

**STOP\_BITS** Number of stop bits, 0 to crazy non-standard amounts.

parameter

**DATA\_BITS** Number of data bits, 1 to crazy non-standard amounts.

parameter

**RX\_DELAY** Delay in rx data input.

parameter

parameter

RX\_BAUD\_DELAY Delay in rx baud enable. This will delay when we sample a bit (default is

midpoint when rx delay is 0).

**TX\_DELAY** Delay in tx data output. Delays the time to output of the data.

parameter

**TX\_BAUD\_DELAY** Delay in tx baud enable. This will delay the time the bit output starts.

parameter

#### **Ports**

aclk Clock for AXIS

arstn Negative reset for AXIS

parity\_err Indicates error with parity check (active high)

frame\_err Indicates error with frame (active high)

s\_axis\_tdata Input data for UART TX.

s\_axis\_tvalids\_axis\_treadyWhen set active high the input data is valids\_axis\_treadyWhen active high the device is ready for input data.

m\_axis\_tdata Output data from UART RX

m\_axis\_tvalid When active high the output data is valid

m\_axis\_tready When set active high the output device is ready for data.

uart\_clk Clock used for BAUD rate generation

uart\_rstn Negative reset for UART, for anything clocked on uart\_clk

tx transmit for UART (output to RX)
rx receive for UART (input from TX)
rts request to send is a loop with CTS
cts clear to send is a loop with RTS

## **INSTANTIATED MODULES**

## dut

```
axis_uart #(

BAUD_CLOCK_SPEED(BAUD_CLOCK_SPEED),

BAUD_RATE(BAUD_RATE),

PARITY_ENA(PARITY_ENA),

PARITY_TYPE(PARITY_TYPE),

STOP_BITS(STOP_BITS),

DATA_BITS(DATA_BITS),

RX_DELAY(RX_DELAY),

RX_BAUD_DELAY(RX_BAUD_DELAY),

TX_BAUD_DELAY(TX_BAUD_DELAY)

) dut ( .aclk(aclk), .arstn(arstn), .parity_err(parity_err), .frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(
```

Device under test, axis\_uart