tb cocotb.v

AUTHORS

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DATES

2025/01/21

INFORMATION

Brief

Test bench wrapper for cocotb

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tb_cocotb

```
module tb_cocotb #(
parameter
CLOCK_SPEED
=
2000000,
parameter
BAUD_RATE
=
2000000,
parameter
PARITY_TYPE
=
0,
parameter
```

```
STOP_BITS

=
1,
parameter
DATA_BITS
=
8,
parameter
RX_BAUD_DELAY
=
0,
parameter
TX_BAUD_DELAY
=
0)
( input aclk, input arstn, output parity_err, output frame_err, input [ 7]
```

Test bench for axis uart.

Parameters

BAUD_CLOCK_SPEED This is the aclk frequency in Hz

BAUD_RATE Serial Baud, this can be any value including non-standard.

parameter

PARITY_ENA Enable Parity for the data in and out.

PARITY_TYPE Set the parity type, 0 = even, 1 = odd, 2 = mark, 3 = space.

parameter

STOP_BITS Number of stop bits, 0 to crazy non-standard amounts.

parameter

DATA_BITS Number of data bits, 1 to crazy non-standard amounts.

parameter

RX_DELAY Delay in rx data input.

RX_BAUD_DELAY Delay in rx baud enable. This will delay when we sample a bit (default is

parameter midpoint when rx delay is 0).

TX_DELAY Delay in tx data output. Delays the time to output of the data.

TX_BAUD_DELAY Delay in tx baud enable. This will delay the time the bit output starts.

parameter

BUS_WIDTH AXIS data bus width in bytes.

Ports

aclk Clock for AXIS

arstn Negative reset for AXIS

parity_err Indicates error with parity check (active high)
frame_err Indicates error with frame (active high)

s_axis_tvalid When set active high the input data is valid

s_axis_tready When active high the device is ready for input data.

m_axis_tvalid When active high the output data is valid

m_axis_tready When set active high the output device is ready for data.

uart_clk Clock used for BAUD rate generation

uart_rstn Negative reset for UART, for anything clocked on uart_clk

tx transmit for UART (output to RX)

rx receive for UART (input from TX)

rts request to send is a loop with CTS

cts clear to send is a loop with RTS

INSTANTIATED MODULES

dut

```
fast_axis_uart #(
    CLOCK_SPEED(CLOCK_SPEED),
    BAUD_RATE(BAUD_RATE),
    PARITY_TYPE(PARITY_TYPE),
    STOP_BITS(STOP_BITS),
    DATA_BITS(DATA_BITS),
    RX_BAUD_DELAY(RX_BAUD_DELAY),
    TX_BAUD_DELAY(TX_BAUD_DELAY)
) dut ( .aclk(aclk), .arstn(arstn), .parity_err(parity_err), .frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_err(frame_
```

Device under test, fast_axis_uart