# piso.v

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### **DATES**

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## **INFORMATION**

#### **Brief**

PISO (parallel in serial out) The idea is to keep this core simple, and let the control logic be handled outside of this core.

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## piso

```
module piso #(
parameter
BUS_WIDTH
=
1
) ( input clk, input rstn, input ena, input load, input [BUS_WIDTH*8-1:0] processing to the second content of the second content of
```

parllel in serial out

#### **Parametes**

**BUS\_WIDTH** width of the parallel data input in bytes.

#### **Ports**

clk global clock for the core.

rstn negative syncronus reset to clk.

ena enable for core, use to change output rate. Enable serial shift output.

load load parallel data into core. Reset for next data message to send. This can be done at any

time.

pdata parallel data input, registered at load only.

sdata serialized data output.

dcount Number of bits to shift out. When the count hits zero, the parallel data register is empty and

last bit is output on sdata.