

# piso.v

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## AUTHORS

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## DATES

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## INFORMATION

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### Brief

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PISO (parallel in serial out) The idea is to keep this core simple, and let the control logic be handled outside of this core.

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## piso

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```
module piso #(
  parameter
  BUS_WIDTH
  =
  1,
  parameter
  COUNT_AMOUNT
  =
  0,
  parameter
  DEFAULT_RESET_VAL
  =
  0,
```

```

parameter
DEFAULT_SHIFT_VAL
=
0
) ( input wire clk, input wire rstn, input wire ena, input wire rev, input v

```

parallel in serial out

## Parameters

<b>BUS_WIDTH</b>	width of the parallel data input in bytes.
<b>COUNT_AMOUNT</b>	If anything other than zero, the dcount and data output will use this value instead of the BUS_WIDTH size.
<b>DEFAULT_RESET_VAL</b>	Value that serial out will have after reset, default 0. Anything else will be 1.
<b>DEFAULT_SHIFT_VAL</b>	Value that will be shifted into the parallel output shift register. Default 0, anything else will be 1.

## Ports

<b>clk</b>	global clock for the core.
<b>rstn</b>	negative synchronus reset to clk.
<b>ena</b>	enable for core, use to change output rate. Enable serial shift output.
<b>rev</b>	reverse, 0 is MSb first out, 1 is LSb first out.
<b>load</b>	load parallel data into core. Reset for next data message to send. This can be done at any time.
<b>pdata</b>	parallel data input, registered at load only.
<b>sdata</b>	serialized data output.
<b>dcount</b>	Number of bits to shift out. When the count hits zero, the parallel data register is empty and last bit is output on sdata.