# UP\_APB3



April 2, 2025

Jay Convertino

# **Contents**

1	Usa	nge 2
	1.1	Introduction
	1.2	Dependencies
		1.2.1 fusesoc_info Depenecies 2
	1.3	In a Project
2	Arc	hitecture 5
	2.1	cocotb
3	Bui	lding 6
		fusesoc
	3.2	Source Files
		3.2.1 fusesoc_info File List 6
	3.3	Targets
		3.3.1 fusesoc_info Targets 6
	3.4	Directory Guide
4	Sim	nulation 8
	4.1	iverilog
	4.2	cocotb
5	Мо	dule Documentation 9
	5.1	up apb3
		tb_apb3-v
		tb_cocotb-py
		tb cocotb-v

# 1 Usage

#### 1.1 Introduction

This core converts the APB3 bus to the uP bus. This allows any core with a uP bus to be interfaced with a APB3 bus. These busses are very similar and is done with combinatoral logic only.

# 1.2 Dependencies

The following are the dependencies of the cores.

- fusesoc 2.X
- iverilog (simulation)
- cocotb (simulation)

## 1.2.1 fusesoc\_info Depenecies

- dep
  - AFRL:utility:helper:1.0.0

# 1.3 In a Project

This core is made to interface APB3 bus to uP based device cores. This is part of a family of converters based on Analog Devices uP specification. Using this allows usage of Analog Devices AXI Lite core, AFRL APB3, AFRL Wishbone Classic, and AFRL Wishbone Pipeline converters. Meaning any uP core can be easily customized to any bus quickly. These are made for relativly slow speed bus device interfaces. An example of a Verilog uP interface provided below.

```
begin
  r_up_rack <= 1'b0;
  r_up_wack <= 1'b0;
  r_up_rdata <= 0;
              <= 1'b0;
  r_rx_ren
  r overflow <= 1'b0;
  r control reg <= 0;
end else begin
  r up rack
             <= 1'b0;
  r_up_wack <= 1'b0;
              <= 1'b0;
  r tx wen
              <= 1'b0;
  r rx ren
  r up rdata <= r up rdata;
  //clear reset bits
  r control reg[RESET RX BIT] <= 1'b0;
  r_control_reg[RESET_TX_BIT] <= 1'b0;
  if(rx_full == 1'b1)
  begin
    r_overflow <= 1'b1;
  end
  //read request
  if(up rreq == 1'b1)
  begin
    r up rack \leq 1'b1;
    case(up raddr[3:0])
      RX FIFO_REG: begin
        r up rdata <= rx rdata & {{(BUS WIDTH*8-
           → DATA_BITS) {1'b0}}, {DATA_BITS {1'b1}}};
        r_rx_ren <= 1'b1;
     end
      STATUS REG: begin
        r_up_rdata <= \{\{(BUS_WIDTH*8-8)\{1'b0\}\},\
           → s_parity_err, s_frame_err, r_overflow,

→ r_irq_en , tx_full , tx_empty , rx_full ,
           → rx valid };
        r_overflow <= 1'b0;
      end
      default: begin
        r up rdata <= 0;
     end
```

```
endcase
    end
    //write request
    if (up_wreq == 1'b1)
    begin
      r_up_wack <= 1'b1;
      //only allow write once ack (Analog Devices does

→ the same)

      if(r up wack == 1'b1) begin
        case(up waddr[3:0])
          TX_FIFO_REG: begin
            r tx wdata <= up wdata;
                        <= 1'b1:
            r tx wen
          end
          CONTROL_REG: begin
            r_control_reg <= up_wdata;</pre>
          end
          default: begin
          end
        endcase
      end
    end
 end
end
//up control register processing and fifo reset
always @(posedge clk)
begin
  if(rstn == 1'b0)
  begin
    r rstn rx delay \leq \sim 0;
    r_rstn_tx_delay <= \sim 0;
    r_{irq}en \le 1'b0;
  end else begin
    r rstn_rx_delay <= {1'b1, r_rstn_rx_delay[
       → FIFO DEPTH-1:1]};
    r_rstn_tx_delay <= {1'b1, r_rstn_rx_delay[
       → FIFO_DEPTH-1:1]};
    if(r_control_reg[RESET_RX_BIT])
    begin
      r rstn rx delay <= {FIFO DEPTH{1'b0}};
    end
```

```
if(r_control_reg[RESET_TX_BIT])
begin
    r_rstn_tx_delay <= {FIFO_DEPTH{1'b0}};
end

if(r_control_reg[ENABLE_INTR_BIT] != r_irq_en)
begin
    r_irq_en <= r_control_reg[ENABLE_INTR_BIT];
end
end
end</pre>
```

# 2 Architecture

The only module is the up\_apb3 module. It is listed below.

 up\_apb3 Convert APB3 to the Analog Devices uP BUS. (see core for documentation).

#### 2.1 cocotb

To use the cocotb tests you must install the following python libraries.

```
$ pip install cocotb
$ pip install cocotbext-axi
```

Each module has a cocotb based simulation. These use the cocotb extensions made by Alex. The two extensions used are cocotbext-axi and cocotbext-uart. These provide outside verification of the implimentation. These tests consist of 3 different fusesoc targets.

- sim\_cocotb\_full Standard simulation of TX/RX passing data to and from cocotbexts.
- sim cocotb rx Simulation of data receive using cocotbext.
- **sim\_cocotb\_tx** Simulation of data transmit using cocotbext.

Then you must use the cocotb sim target. The targets above can be run with various bus and fifo parameters.

This core only uses combinatoral methods to convert a few signals between the uP bus the APB3.

Please see 5 for more information.

# 3 Building

The APB3 core is written in Verilog 2001. They should synthesize in any modern FPGA software. The core comes as a fusesoc packaged core and can be included in any other core. Be sure to make sure you have meet the dependencies listed in the previous section.

# 3.1 fusesoc

Fusesoc is a system for building FPGA software without relying on the internal project management of the tool. Avoiding vendor lock in to Vivado or Quartus. These cores, when included in a project, can be easily integrated and targets created based upon the end developer needs. The core by itself is not a part of a system and should be integrated into a fusesoc based system. Simulations are setup to use fusesoc and are a part of its targets.

# 3.2 Source Files

# 3.2.1 fusesoc\_info File List

- src
  - src/up\_apb3.v
- tb
  - tb/tb apb3.v
- tb\_cocotb
  - 'tb/tb cocotb.py': 'file type': 'user', 'copyto': '.'
  - 'tb/tb cocotb.v': 'file type': 'verilogSource'

# 3.3 Targets

#### 3.3.1 fusesoc info Targets

default

Info: Default for IP intergration.

• sim

Info: Base simulation using icarus as default.

· sim cocotb

Info: Cocotb unit tests

# 3.4 Directory Guide

Below highlights important folders from the root of the directory.

- 1. **docs** Contains all documentation related to this project.
  - **manual** Contains user manual and github page that are generated from the latex sources.
  - specs Contains specifications for the bus.
- 2. **src** Contains source files for the core
- 3. **tb** Contains test bench files for iverilog and cocotb
  - cocotb testbench files

# 4 Simulation

There are a few different simulations that can be run for this core.

# 4.1 iverilog

iverilog is used for simple test benches for quick verification, visually, of the core.

# 4.2 cocotb

To use the cocotb tests you must install the following python libraries.

```
$ pip install cocotb
$ pip install cocotbext-up
$ pip install cocotbext-apb
```

Each module has a cocotb based simulation. These use the cocotb extensions APB and uP. To install these locally use the following.cocotb

```
$ pip install —break-system-packages -e .
```

• **sim\_cocotb** Standard simulation APB3 to uP conversion using cocotbexts.

Then you must use the cocotb sim target. The targets above can be run with various parameters.

```
sim_cocotb AFRL:bus:up_apb3
sim_cocotb AFRL:bus:up_apb3
```

# **5 Module Documentation**

- up\_apb3 APB3 to uP converter
- **tb\_apb3-v** Verilog test bench
- **tb\_cocotb-py** Cocotb python test routines
- **tb\_cocotb-v** Cocotb verilog test bench

The next sections document the module in detail.

# up\_apb3.v

#### **AUTHORS**

#### JAY CONVERTINO

#### **DATES**

# 2024/03/19

# **INFORMATION**

#### **Brief**

APB3 slave to uP interface

#### License MIT

Copyright 2024 Jay Convertino

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions:

The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software.

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

# up\_apb3

```
module up_apb3 #(
parameter
ADDRESS_WIDTH
= 16,
parameter
BUS_WIDTH
= 4
) ( input clk, input rstn, input [ADDRESS_WIDTH-1:0] s_apb_paddr, input [0:0]
```

APB3 slave to uP interface

#### **Parameters**

ADDRESS\_WIDTH Width of the APB3 address port in bits.

aramete

**BUS\_WIDTH** Width of the APB3 bus data port in bytes.

paramet

#### **Ports**

clk Clock rstn negative reset

s\_apb\_paddr APB3 address bus, up to 32 bits wide.s\_apb\_psel APB3 select per slave (1 for this core).

**s\_apb\_penable** APB3 enable device for multiple transfers after first.

s\_apb\_preadys\_apb\_pwriteAPB3 ready is a output from the slave to indicate its able to process the request.APB3 Direction signal, active high is a write access. Active low is a read access.

s\_apb\_pwdatas\_apb\_prdataAPB3 write data port.APB3 read data port.

s\_apb\_pslverror APB3 error indicates transfer failure, not implimented.

uP bus read request up\_rreq uP bus read ack up\_rack uP bus read address up\_raddr up\_rdata uP bus read data up\_wreq uP bus write request uP bus write ack up\_wack uP bus write address up\_waddr up\_wdata uP bus write data

# **VARIABLES**

# valid

```
assign valid = s_apb_psel & s_apb_penable & rstn
```

This will add an extra clock cycle. since enable happens after select. both are needed to use the device.

# s\_apb\_pslverror

```
assign s_apb_pslverror = 1'b0
```

APB3 error is always 0, no error.

# up\_waddr

```
assign up_waddr = s_apb_paddr[ADDRESS_WIDTH-1:shift]
```

up\_waddr and s\_apb\_addr are a direct mapping.

# up\_waddr

up\_raddr and s\_apb\_addr are a direct mapping.

# up\_wdata

```
assign up_wdata = s_apb_pwdata
```

up\_wdata and s\_apb\_pwdata are a direct mapping.

# s\_apb\_prdata

```
assign s_apb_prdata = up_rdata
```

s\_apb\_prdata and up\_rdata are a direct mapping.

# up\_wreq

```
assign up_wreq = valid & s_apb_pwrite & r_cycle
```

uP write request is a combination of the APB3 valid and APB3 write select (active high is write).

# up\_rreq

```
assign up_rreq = valid & ~s_apb_pwrite & r_cycle
```

uP read request is a combination of the APB3 valid and APB3 write select (active low is read).

# s\_apb\_pready

```
assign s_apb_pready = (
up_wack |
up_rack
) & rstn
```

Ready is being treated like a awk

# tb\_apb3.v AUTHORS JAY CONVERTINO DATES 2021/06/23 INFORMATION Brief Test bench for abp3 slave

#### License MIT

Copyright 2021 Jay Convertino

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions:

The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

# tb\_apb3

```
module tb_apb3 ()
```

Test bench for apb3 slave. simple write and then read.

# **INSTANTIATED MODULES**

# up\_apb3

up\_apb3 #(

```
ADDRESS_WIDTH(16),

BUS_WIDTH(4)
) dut ( .clk(tb_data_clk), .rstn(tb_rstn), .s_apb_paddr(r_apb_paddr), .s_apb
```

Device under test, apb3 to uP

tb_cocotb.py
AUTHORS
JAY CONVERTINO
DATES
2025/03/04
INFORMATION
Brief
Cocotb test bench
License MIT
Copyright 2025 Jay Convertino
Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without imitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions:
The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software.
THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.
FUNCTIONS
random_bool
<pre>def random_bool()</pre>
Return a infinte cycle of random bools Returns: List

start\_clock

```
def start_clock(
dut
)
```

Start the simulation clock generator.

#### **Parameters**

dut Device under test passed from cocotb test function

# reset\_dut

```
async def reset_dut(
dut
)
```

Cocotb coroutine for resets, used with await to make sure system is reset.

# increment test

Coroutine that is identified as a test routine. Write data, on one clock edge, read on the next.

#### **Parameters**

dut Device under test passed from cocotb.

# increment test stream

Coroutine that is identified as a test routine. Write data, in a stream to registers, then read back stream.

# **Parameters**

dut Device under test passed from cocotb.

# in\_reset

```
@cocotb.test()
async def in_reset(
dut
)
```

Coroutine that is identified as a test routine. This routine tests if device stays in unready state when in reset.

#### **Parameters**

dut Device under test passed from cocotb.

# no\_clock

```
@cocotb.test()
async def no_clock(
dut
)
```

Coroutine that is identified as a test routine. This routine tests if no ready when clock is lost and device is left in reset.

# **Parameters**

**dut** Device under test passed from cocotb.

# tb coctb.v

# **AUTHORS**

#### JAY CONVERTINO

#### **DATES**

# 2025/03/26

# **INFORMATION**

#### **Brief**

Test bench wrapper for cocotb

#### License MIT

Copyright 2025 Jay Convertino

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions:

The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.BUS\_WIDTH

# tb\_cocotb

```
module tb_cocotb #(
parameter
ADDRESS_WIDTH
= 16,
parameter
BUS_WIDTH
= 2
4
) ( input clk, input rstn, input [ADDRESS_WIDTH-1:0] s_apb_paddr, input [0:0]
```

APB3 slave to uP interface DUT

#### **Parameters**

ADDRESS\_WIDTH Width of the APB3 address port in bits.

aramete

**BUS\_WIDTH** Width of the APB3 bus data port in bytes.

aramet

#### **Ports**

clk Clock rstn negative reset

s\_apb\_paddr APB3 address bus, up to 32 bits wide.s\_apb\_psel APB3 select per slave (1 for this core).

**s\_apb\_penable** APB3 enable device for multiple transfers after first.

s\_apb\_preadys\_apb\_pwriteAPB3 ready is a output from the slave to indicate its able to process the request.APB3 Direction signal, active high is a write access. Active low is a read access.

s\_apb\_pwdatas\_apb\_prdataAPB3 write data port.APB3 read data port.

s\_apb\_pslverror APB3 error indicates transfer failure, not implimented.

uP bus read request up\_rreq uP bus read ack up\_rack uP bus read address up\_raddr up\_rdata uP bus read data up\_wreq uP bus write request uP bus write ack up\_wack uP bus write address up\_waddr up\_wdata uP bus write data

# **INSTANTIATED MODULES**

# dut

```
up_apb3 #(

ADDRESS_WIDTH(ADDRESS_WIDTH),

BUS_WIDTH(BUS_WIDTH)
) dut ( .clk(clk), .rstn(rstn), .s_apb_paddr(s_apb_paddr), .s_apb_psel(s_apb_
```

Device under test, up\_apb3