(b)
$$\begin{pmatrix} 1 & -1 & 3 \\ 0 & 1 & 2 \\ 2 & -2 & 1 \end{pmatrix} \begin{pmatrix} 0 & 2 & 2 \\ 1 & 2 & 3 \\ -1 & 0 & 3 \end{pmatrix} = \begin{pmatrix} -1-3 & 2-2 & 2-3+9 \\ 1-2 & 2 & 3+6 \\ -2-1 & 4-4 & 4-6+3 \end{pmatrix}$$

$$= \begin{vmatrix} -4 & 0 & 8 \\ -1 & 2 & 9 \\ -3 & 0 & 1 \end{vmatrix}$$

$$\mathbb{R}^{4} = U_{1} + U_{2} + U_{3}$$

 $U_1 = Span \{ \hat{e}_i \}$ $U_2 = Span \{ \hat{e}_i \}$



fiso if and only if ruA = 3.

Use row reduction:

$$\begin{bmatrix} 0 & 2 & 2 \\ 1 & -2 & -1 \\ -1 & 2 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 0 & 2 & 2 \\ 1 & -2 & -1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \text{ru} A = Z$$

Afis not on 150.

We only need to express f(e) interms (B) To compute Report, B

$$f(\hat{e}_i) = \begin{pmatrix} 0 \\ -1 \end{pmatrix} = a\begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} + c\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + c\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \Rightarrow a = 0$$

$$a = 0$$

$$c = 0$$

$$a = 2$$

$$b = 1$$

$$c = 0$$

$$f(\vec{e}_1) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \alpha(0)$$

$$f(\vec{e}_2) = \begin{pmatrix} 2 \\ -2 \\ 2 \end{pmatrix} = \alpha(0) + b\begin{pmatrix} 1 \\ -1 \end{pmatrix} + c\begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow c = 2$$

$$c = 2 + b = 2 - 2 = 0$$

$$f(\bar{e}_3) = \begin{pmatrix} 2 \\ -1 \end{pmatrix} = \alpha \begin{pmatrix} 0 \\ 0 \end{pmatrix} + b \begin{pmatrix} 0 \\ -1 \end{pmatrix} + c \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$



din Imf & 2

and 4=dimkerf+dim Int => dimkerf>2 =>krf+80}

(d) false take
$$B=\operatorname{std}$$
 $B=(\tilde{e}_{z},\tilde{e}_{1},\tilde{e}_{3})$
then $\operatorname{Rep}_{B,\tilde{B}}$ id $=(0,0)$ $+$ T .

(e)
$$+ ALJL$$

(e) $+ ALJL$

(f) $TRUE$. Say $B = (\vec{v}_1 \vec{v}_2 \vec{v}_3)$ if $Rep_B = T$

then $f(\vec{v}_1) = \vec{v}_1$, $f(\vec{v}_2) = \vec{v}_2$ $f(\vec{v}_3) = \vec{v}_3$

Then
$$\tau(\vec{x})$$

$$\Rightarrow if \ \vec{v} \in \mathbb{R}^{3} \quad \vec{v} = \alpha \vec{v}_{1} + b \vec{v}_{2} + c \vec{v}_{3} \quad \leq 0$$

$$\zeta(\vec{v}) = \alpha \zeta(\vec{v}_{1}) + b f(\vec{v}_{2}) + c f(\vec{v}_{3}) = \zeta(\vec{v}_{3}) + b \vec{v}_{2} + c \vec{v}_{3} = \zeta(\vec{v}_{3})$$

$$= \alpha \vec{v}_{1} + b \vec{v}_{2} + c \vec{v}_{3} = \zeta(\vec{v}_{3})$$

$$\bigcirc$$
 $g: \mathbb{R}^3 \longrightarrow \mathbb{R}^3$ s.t. ...

notice it [0] [1] [1] is a substitute
$$\vec{u}_1 = g(\frac{1}{2})$$
 $\vec{u}_2 = g(\frac{1}{2})$ $\vec{u}_3 = g(\frac{1}{2})$ to define g_1 , it is enough to declare $\vec{u}_1 = g(\frac{1}{2})$

Set
$$\vec{u}_1 := \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$
 $\vec{u}_2 := \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$ $\vec{u}_3 := \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$