CS CAPSTONE PROGRESS REPORT

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AI GAMING

PREPARED FOR

NVIDIA

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Abstract

In this document we describe the what we have done so far with our project to create a deep learning program that can learn to play the game Galaga, and will be used as a training tool. We breifly describe the pupose of the project, the progress we made, and the problems we faced throughout the initial phase of development. We also set forward some goals and plans for the rest of the term and how we will be moving forward on this project.

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1 PROJECT PURPOSE

The main goal of our project is to create a neural net that can learn to play the game Galaga. The neural network must run on NVIDIA's Jetson developer kit. This project will be used by trainers and students in the field of deep learning. NVIDIA's Deep Learning Institute will take the work that we do and use it to create a learning course. It must be possible to recreate this project, or it will not make a good learning tool. As such, our documentation must be detailed enough to give readers a clear understanding of how we made the system.

2 CURRENT PROGRESS

Throughout the first term we have laid out all the ground work for out project. We've created documentation for our project requirements, our decisions for the technology that we want to use, and how we will be using that technology in our project. These documents have been given to our client who has signed and returned them to ensure that everything will run smoothly for the future of the project.

Over winter break we began implementation. The project at present has the following components: a neural network still in the stages of training to properly identify in game objects, a set of python scripts implementing port communication

protocol to allow the neural network to converse with the system hosting the game, and a hardware setup with camera to allow the Jetson to see what's happening on the other computer. Though there are many bugs to iron out, the system can communicate and commands can be given to the game from the neural network. Moving forward the main goals are increasing the speed of command, the accuracy of gameplay, and ironing out bugs.

3 PROBLEMS AND SOLUTIONS

We ran into several problems throughout the first term. One problem we had was our busy schedules. It was difficult to find times to meet up and work on projects. We had to schedule our weekly TA meeting on Fridays which wasn't ideal. Our TA is planning on scheduling all his meetings on Monday which might help for Winter term. We're also handling this problem by improving our lines of communication with each other. By staying in touch regularly and planning ahead, we have mitigated a lot of the scheduling issues that have plagued this term.

Another problem we had was getting our documents signed. Our client was very busy throughout the term and it took a while to to get responses from him. All of our assignments were either turned in late or without a signature. He said that his schedule should soon be clearing up and he won't have to travel as much so it shouldn't be as bad next term. Just in case our client remains difficult to contact we planned to ask him about more methods of contact as well as maybe finding other people at the company who can weigh in when he's unavilable.

Another problem arose in this project due to the vagueness of the initial project. Initially, we had no solid idea what our project was going to be, other than that it had to involve a neural network. Issues contacting our client compounded this issue as we needed information about what kinds of projects would be considered suitble for the task at hand. Eventually we were able to establish solid enough contact to determine our actual task.

The final issue first term arose from the difficulty of actually understanding neural networks. Learning about neural networks required much more research than we initially assumed, and the field is incredibly complex. In order to better understand what was going on, we had to try and cram tons of research into a very small period. This met with middling success and we still weren't fully confident in our design. We did, however, have a solution in mind. We reached out to our client and made contact with an engineer at NVIDIA. We also took advantage of the increased free time during winter break to more thoroughly study our subject and prepare the initial system.

The second term started off with a long winter break, during which major breakthroughs and problems were discovered. Perhaps the biggest thing to come out of winter break was a new understanding what exactly we had to do to get our neural network functioning. By the end of the break we had a much more solid plan for what we were going to accomplish. However, our initial approach to the network required some custom implementation that we weren't sure how to do yet. We didn't know how to get the neural net telling the game how to play. To solve this, we spoke with our client and he connected us with an engineer at NVIDIA who had more experience with neural networks. With his help, we came to the decision of implementing a single decision layer into the neural net that would take the output of the image processing layers and produce an output in the form of a game command.

The next big problem we needed to approach was the setup we need to use to get the setup correct for playing the game. Because we need to have the Jetson run the neural network, we've been gathering parts to allow us to put Galaga on a PC seperate from the jetson for playing. We've purchased a camera to watch the screen of the other PC and send that back as input. At the moment reflectivity is hampering this process, so we are working on getting a screen with as little reflectiveness as possible. Another major part of this setup was getting a program setup that could relay the commands from the neural net to the game. To solve this, we set up a basic communication server setup through python, which waits for commands and then simulates the keypresses ordered through a Windows api.

The major issue that hangs over our heads heading into the end of the term is the speed the neural network. On a normal PC, our system actually runs really well, but the Jetson is considerably slower. With average processing speed between 3 and 9 fps (frames per second) when implemented on the Jetson, our network is simply too slow to play a 60 fps game right now. We're testing ways around this limitation, but have come to a satisfactory conclusion as of yet.

4 RETROSPECTIVE

Positives	Deltas	Actions
Decided on Galaga as main	Need to improve system setup	Research more in depth how
project		deep learning systems are
		constructed
Found a way to work together	Need to carefully evaluate	Seek help from professors who
despite scheduling problems	design of system to ensure	research neural networks and
	robustness	ask our client if anyone at
		NVIDIA can give us some setup
		advice
Finished all necessary	Need to improve clarity and	Rewrite portions of
documentation	quality of documentation	documentation as our design
		improves to make sure our
		project's goals and design are
		clear
Figured out a preliminary	Need to complete setup of the	Begin working on neural
design with several tools we can	network to begin training	network setup, particularly
use to make it work		engaging phase 1, teaching the
		network how to recognize in
		game objects
Researched more and figured	Need to fully finish the design	Will continue to update
out how to work our project		documentation as we figure
		more out about the specific
		challenges of the project
Completed the alpha build of	Need to work out the kinks of	Test the system intently and
the project setup	our setup and continue training	improve functionality

5 WEEK BY WEEK SUMMARY

- 5.1 Spring Week 1
- 5.2 Spring Week 2
- 5.3 Spring Week 3
- 5.4 Spring Week 4
- 5.5 Spring Week 5
- 5.6 Spring Week 6
- 6 CODE
- 6.1 Python Script Plays the Game
- 6.2 Nodejs Server
- 7 PROJECT PHOTOS
- 7.1 Training Plot
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- 7.3 Final Project Setup