Easy to Remember!

Linear Motion			Rotation	
position	x	\rightarrow	θ	angle
velocity	v	\rightarrow	ω	angular vel.
acceleration	a	\rightarrow	α	angular accel.
force	F	\rightarrow	τ	torque
momentum	p	\rightarrow	L	angular mom.
mass	m	\rightarrow	Ι	moment of In.
v = dx/dt		\rightarrow	$\omega = d\theta/dt$	
a = dv/dt		\rightarrow	$\alpha = d\omega/dt$	
$KE = {}_{(1/2)}mv^2$		\rightarrow	$^{(1/2)}I\omega^2$	
F = ma		>	$\tau = I\alpha$	
p = mv		\rightarrow	$L = I\omega$	
dp/dt = F		\rightarrow	$dL/dt=\tau$	