ECE551 - Homework 5

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1 Sampling and Interpolation for Band-Limited Vectors

(a) We have the Fourier vector

$$w_k[n] = e^{j\frac{2\pi kn}{M}}$$

and

$$2\cos x = e^{jx} + e^{-jx}$$

So

$$\begin{split} x_1[n] &= 1 + \cos\left(\frac{2\pi n}{M}\right) + \cos\left(\frac{8\pi n}{M}\right) \\ &= w_0[n] + \frac{1}{2}\left(e^{j\frac{2\pi n}{M}} + e^{-j\frac{2\pi n}{M}}\right) + \frac{1}{2}\left(e^{j\frac{8\pi n}{M}} + e^{-j\frac{8\pi n}{M}}\right) \\ &= w_0[n] + \frac{1}{2}\left(w_1[n] + w_{-1}[n] + w_4[n] + w_{-4}[n]\right) \end{split}$$

Its DFT is

$$\begin{split} X_1[k] &= \sum_{n=0}^{M-1} x_1[n] w_{-k}[n] \\ &= \frac{1}{2} \left(\sum_{n=0}^{M-1} 2w_{-k}[n] + w_{-k-1}[n] + w_{-k+1}[n] + w_{-k-4}[n] + w_{-k+4}[n] \right) \end{split}$$

We can see that

$$\sum_{n=0}^{M-1} w_k[n] = \sum_{n=0}^{M-1} \exp\left(j\frac{2\pi k}{M}\right)^n$$

$$= \frac{1 - \exp\left(j\frac{2\pi k}{M}\right)^M}{1 - \exp\left(j\frac{2\pi k}{M}\right)} \quad (\because \text{ geometric series})$$

$$= A$$

Whenever the numerator of A is 0 (k=0), its denominator is also 0. Therefore A has a peak at k. Hence, $X_1[k]$ has peaks at $k = 0, \pm 1, \pm 4$, so its bandwidth is [-4, 4].

Similarly,

$$x_{2}[n] = \cos\left(\frac{3\pi n}{M}\right) = \frac{1}{2} \left(e^{j\frac{3\pi n}{M}} + e^{-j\frac{3\pi n}{M}}\right)$$

$$\Rightarrow X_{2}[n] = \sum_{n=0}^{M-1} x_{2}[n]e^{-j\frac{2\pi k n}{M}}$$

$$= \frac{1}{2} \sum_{n=0}^{M-1} \left(e^{j\frac{2\pi n}{(3-2k)}} + e^{j\frac{2\pi n}{(-3-2k)}}\right)$$

$$= \frac{1}{2} \left(\frac{1 - \exp\left(j\frac{\pi n}{M}(3-2k)\right)^{M}}{1 - \exp\left(j\frac{\pi n}{M}(-3-2k)\right)^{M}}\right) \neq 0, \forall k \in \mathbb{Z}$$

Hence, $x_2[n]$ is full-band.

(b) We take

$$\Phi = \left[w_0, w_1, ..., w_{\frac{k_0+1}{2}-1}, w_{M-\frac{k_0+1}{2}+1}, ..., w_{M-1} \right]$$

Because x is band limited s.t. $X[k] = 0, \forall k \in \left[\frac{k_0+1}{2}, M - \frac{k_0+1}{2}\right]$, it means that we remove the part from $\frac{k_0+1}{2}$ to $M - \frac{k_0+1}{2}$ of the DFT.

2 Band Limited Space with Rational Sampling Rate Changes

- (a) Since we only care about the effect of g, we consider only until g[n] is apply (the first 5 steps).
 - Figure 1 shows the results for M=2, N=3, K=3. After upsampling by 2 (second row), we need the cut-off frequency of g to be $\frac{\pi}{3} \leq w_c \leq \frac{\pi}{3}$. By applying the low-pass filter g[-n] (third row), the gap between two copies is $\frac{5\pi}{3} \frac{\pi}{3} = \frac{4\pi}{3}$. After downsampling by 3 (forth row), the gap is reduced to 0, so upsampling it by 3 (fifth row) also gives the same gap. So the cut-off frequency has to be $w_c = \frac{\pi}{3}$.
- (b) Figure 2 shows the results for M=2, N=3, K=4. After upsampling by 2 (second row), we need the cut-off frequency of g to be $\frac{\pi}{4} \leq w_c \leq \frac{3\pi}{4}$. After apply downsampling by 3 (forth row), the gap is $\frac{\pi}{2}$. Therefore the gap is reduced by

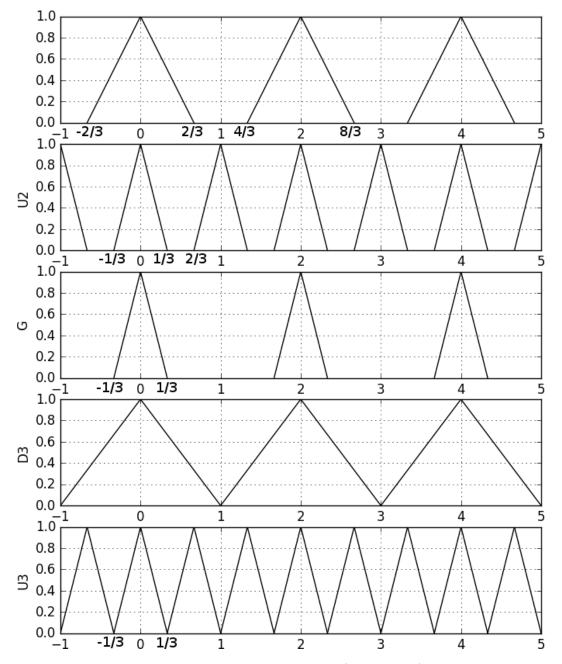


Figure 1: M = 2, N = 3, K = 3 (x scale is π)

a third after upsampling by 3 (fifth row). So the second condition for cut-off frequency is $\frac{\pi}{4} \leq w_c \leq \frac{5\pi}{12}$.

$$\frac{\pi}{4} \le w_c \le \frac{3\pi}{4}$$
 and $\frac{\pi}{4} \le w_c \le \frac{5\pi}{12} \Rightarrow \frac{\pi}{4} \le w_c \le \frac{5\pi}{12}$

(c) If the signal in $\left[-\frac{2\pi}{K}, \frac{2\pi}{K}\right]$, the gap's width is

$$2\pi - \frac{2\pi}{K} - \frac{2\pi}{K} = 2\pi(1 - \frac{2}{K})$$

After upsampling by M, the range is $\left[-\frac{2\pi}{KM}, \frac{2\pi}{KM}\right]$ and the gap is $\frac{2\pi}{M}(1-\frac{2}{K})$. Therefore the first condition of w_c is

$$\frac{2\pi}{KM} \le w_c \le \frac{2\pi}{KM} + \frac{2\pi}{M}(1 - \frac{2}{K}) \Leftrightarrow \frac{2\pi}{KM} \le w_c \le \frac{2\pi}{M}(1 - \frac{1}{K})$$

After downsampling by N, the $\left[-\frac{2\pi N}{KM}, \frac{2\pi N}{KM}\right]$ and the gap is $2\pi - \frac{2\pi N}{KM} - \frac{2\pi N}{KM} = 2\pi (1 - \frac{2}{KM})$. So the second condition of w_c is

$$\frac{2\pi N}{KM} \le w_c \le \frac{2\pi N}{KM} + 2\pi (1 - \frac{2}{KM}) \Leftrightarrow \frac{2\pi N}{KM} \le w_c \le 2\pi (\frac{1}{N} - \frac{1}{KM})$$

Combining the first and second condition gives

$$\frac{2\pi}{KM} \le w_c \le 2\pi (\frac{1}{N} - \frac{1}{KM}) \qquad (\because M < N \text{ so the second condition is tighter})$$

3 Multirate Systems

(a) Let u[n] be the output after downsampling and v[n] be the output after convolving with g.

$$\begin{split} U(z) &= \frac{1}{2} \sum_{k=0}^{1} X \left(e^{-j\frac{2\pi k}{2}} z^{1/2} \right) \\ &= \frac{1}{2} \left(X(z^{1/2} + X(e^{-j\pi} z^{1/2})) \right) \\ V(z) &= G(z) U(z) \\ Y(z) &= V(z^3) \\ &= G(z^3) U(z^3) \\ &= \frac{1}{2} \left(X(z^{3/2} + X(e^{-j\pi} z^{3/2})) \right) \end{split}$$

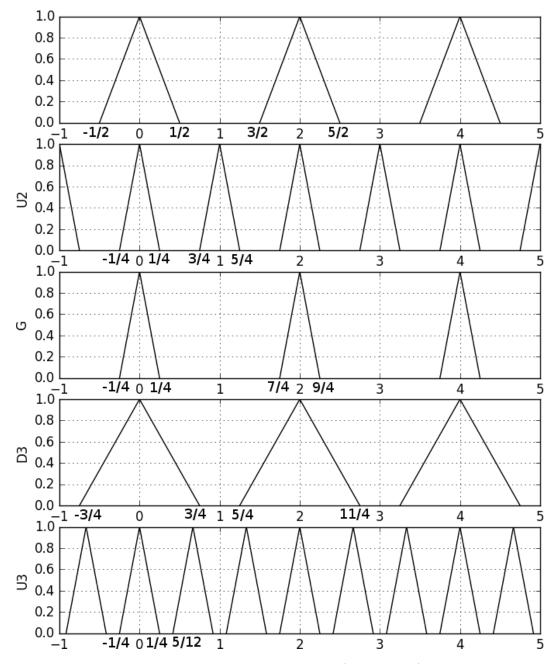


Figure 2: M = 2, N = 3, K = 4 (x scale is π)

(b) x[n] = q(nT) is the same as downsampling by T, so u[z] is obtained by downsampling q(t) by 2T. Therefore

$$\begin{split} U(\omega) &= \frac{1}{2T} \sum_{k=0}^{2T-1} X \left(\frac{\omega - 2\pi k}{2} \right) \\ V(\omega) &= G(\omega) U(\omega) \\ Y(\omega) &= V(3\omega) \\ &= G(3\omega) U(3\omega) \\ &= \frac{G(3\omega)}{2T} \sum_{k=0}^{2T-1} X \left(\frac{3\omega - 2\pi k}{2} \right) \end{split}$$

Since $q \in BL[-\frac{\pi}{T}, \frac{\pi}{T}]$ and the sampling rate $\frac{1}{T}$, we have the setting in Figure 3 To avoid aliasing, we need $\frac{\pi}{T} < \frac{1}{2T} \Leftrightarrow \frac{2\pi - 1}{T} < 0$, which cannot satisfy.

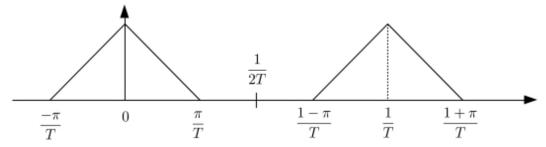


Figure 3: Sampling $q \in BL[-\frac{\pi}{T}, \frac{\pi}{T}]$ with sampling rate of $\frac{1}{T}$

Therefore, q cannot avoid aliasing after sampling.

4 Pseudo-Inverse of Interpolation Filter: Single Channel Case

By orthogonality principle

$$x - \hat{x} \perp V = \operatorname{span}\{\sigma^{kN}g\}_{k \in \mathbb{Z}} \Leftrightarrow \left\langle x - \hat{x}, \sigma^{kN}g \right\rangle = 0$$

Recall that convolution can be written as inner product, i.e. $(u * v)[n] = \langle u, \sigma^n \tilde{v} \rangle$. Therefore

$$\Leftrightarrow \left\langle x - \hat{x}, \sigma^{kN} g \right\rangle = ((x - \hat{x}) * \tilde{g})[kN] = 0$$

Let $s = (x - \hat{x}) * \tilde{g}$, its z-transform is

$$S(z) = (X(z) - \hat{X}(x))G(z^{-1}) = 0$$

where X(z), $\hat{X}(z)$, and $G(z^{-1})$ are the z-transform of x[n], $\hat{x}[n]$, and $\tilde{g}[n]$. We have the polyphase decomposition as

$$X(z) = \pi(z)X_p(z^N)$$

$$G(z) = G_p(z^N)^{\top}\pi(z)^{\top}$$

$$\hat{X}(z) = \pi(z)\hat{X}_p(z^N) = \pi(z)G_p(z^N)\tilde{H}_p(z^N)X_p(z^N)$$

(because $z^N=\omega$ and $\hat{X}_p(\omega)=G_p(\omega)\tilde{H}_p(\omega)X_p(\omega)$). Substituting them to S(z) gives:

$$S(z) = \left[\pi(z) X_p(z^N) - \pi(z) G_p(z^N) \tilde{H}_p(z^N) X_p(z^N) \right] G_p(z^{-N})^\top \pi(z^{-1})^\top$$

= $G_p(z^{-N})^\top \pi(z^{-1})^\top \pi(z) \left[X_p(z^N) - G_p(z^N) \tilde{H}_p(z^N) X_p(z^N) \right]$

We know that $\pi(z^{-1})^{\top}\pi(z) = I - A(z)$, where A(z) contains non-zero phases, thus will vanish $G_p(z^{-N})^{\top}A(z)\left[X_p(z^N) - G_p(z^N)\tilde{H}_p(z^N)X_p(z^N)\right]$. Therefore

$$\begin{split} S(z) &= G_p(z^{-N})^\top \left[X_p(z^N) - G_p(z^N) \tilde{H}_p(z^N) X_p(z^N) \right] \\ &= G_p(z^{-N})^\top X_p(z^N) - G_p(z^{-N})^\top G_p(z^N) \tilde{H}_p(z^N) X_p(z^N) \\ &= \left[G_p(z^{-N})^\top - G_p(z^{-N})^\top G_p(z^N) \tilde{H}_p(z^N) \right] X_p(z^N) = 0, \forall X_p(z^N) \\ &\Rightarrow G_p(z^{-N})^\top - G_p(z^{-N})^\top G_p(z^N) \tilde{H}_p(z^N) = 0 \end{split}$$

Since $\omega = z^n$

$$G_p(\omega^{-1})^{\top} - G_p(\omega^{-1})^{\top} G_p(\omega) \tilde{H}_p(\omega) = 0$$

$$\Leftrightarrow G_p(\omega^{-1})^{\top} G_p(\omega) \tilde{H}_p(\omega) = G_p(\omega^{-1})^{\top}$$

$$\Leftrightarrow \tilde{H}_p(\omega) = \left(G_p(\omega^{-1})^{\top} G_p(\omega) \right)^{-1} G_p(\omega^{-1})^{\top}$$

5 Ideal-Matched Sampling and Interpolation with Nonorthogonal Filters

(a)
$$N=2\Rightarrow \omega=z^N=z^2$$
 z-transform of $g[n]$ is
$$G(z)=1+\frac{1}{2}(z^{-1}+z)$$

Since N=2, we need components z^0 and z^{-1}

$$\Rightarrow G(z) = 1 + z^{-1} \left(\frac{1}{2} + \frac{1}{2} z^2 \right)$$

For type-I polyphase decomposition

$$G_p(\omega) = \begin{bmatrix} G_0(\omega) \\ G_1(\omega) \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} + \frac{1}{2}\omega \end{bmatrix} \Rightarrow G_p(\omega^{-1})^{\top} = \begin{bmatrix} 1, & \frac{1}{2} + \frac{1}{2}\omega^{-1} \end{bmatrix}$$

From problem 4, we have

$$\tilde{H}_p(\omega) = \left(G_p(\omega^{-1})^\top G_p(\omega)\right)^{-1} G_p(\omega^{-1})^\top$$

$$G_p(\omega^{-1})^{\top} G_p(\omega) = \left[1, \quad \frac{1}{2} + \frac{1}{2}\omega^{-1} \right] \left[\frac{1}{\frac{1}{2} + \frac{1}{2}\omega} \right]$$
$$= 1 + \frac{1}{4}(1 + \omega^{-1})(1 + \omega)$$
$$= \frac{6 + \omega + \omega^{-1}}{4}$$

$$\Rightarrow \tilde{H}_p(\omega) = \left(\frac{6+\omega+\omega^{-1}}{4}\right)^{-1} \left[1, \frac{1}{2} + \frac{1}{2}\omega^{-1}\right]$$

We have

$$\begin{split} H(z) &= \tilde{H}_p(z^2)\pi(z^{-1})^\top \qquad \text{(type-II, with } z^2 = \omega) \\ &= \frac{4}{6+\omega+\omega^{-1}} \left[1, \quad \frac{1}{2} + \frac{1}{2}\omega^{-1} \right] \left[\frac{1}{z} \right] \\ &= \frac{4(1+\frac{z}{2}+\frac{z^{-1}}{2})}{6+z^2+z^{-2}} \\ &= \frac{2(2+z+z^{-1})}{6+z^2+z^{-2}} \end{split}$$

For the numerator

$$2(2+z+z^{-1}) = 2z^{-1}(2z+z^2+1)$$
$$= 2z^{-1}(z+1)(z+1)$$
$$= 2(z^{-1}+1)(z+1)$$

For the denominator

$$\begin{aligned} 6+z^2+z^{-2} &= z^{-2}(6z^2+z^4+1) \\ &= z^{-2}(z^2+3+2\sqrt{2})(z^2+3-2\sqrt{2}) \\ &= (1+(3+2\sqrt{2})z^{-2})(z^2+3-2\sqrt{2}) \\ &= (1+(3+2\sqrt{2})z^{-2})\left(z^2+\frac{1}{3+2\sqrt{2}}\right) \\ &= (3+2\sqrt{2})\left(z^{-2}+\frac{1}{3+2\sqrt{2}}\right)\left(z^2+\frac{1}{3+2\sqrt{2}}\right) \\ &= \mathcal{C}^{-1}(z^{-2}+\mathcal{C})(z^2+\mathcal{C}), \qquad \text{where } \mathcal{C} = \frac{1}{3+2\sqrt{2}} \end{aligned}$$

Therefore

$$\begin{split} H(Z) &= \frac{2(z^{-1}+1)(z+1)}{\mathcal{C}^{-1}(z^{-2}+\mathcal{C})(z^2+\mathcal{C})} \\ &= 2\mathcal{C}\frac{z^{-1}+1}{z^{-2}+\mathcal{C}}\frac{z^1+1}{z^2+\mathcal{C}} \\ &= P(z^{-1})P(z), \qquad \text{where } P(z) = \sqrt{2\mathcal{C}}\frac{z+1}{z^2+\mathcal{C}}, \mathcal{C} = \frac{1}{3+2\sqrt{2}} \end{split}$$

h[n] is the inverse z-transform of H(z).

(b)
$$\tilde{H}_p(\omega)G_p(\omega) = 1 \Leftrightarrow \tilde{H}_p(\omega) \begin{bmatrix} 1 \\ \frac{1}{2} + \frac{1}{2}\omega \end{bmatrix} = 1$$

Therefore, the shortest $\tilde{H}_p(\omega)$ is $\begin{bmatrix} 0 & 1 \end{bmatrix}$

$$H(z) = \tilde{H}_p(z^2)\pi(z^{-1})^{\top} = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ z \end{bmatrix} = 1$$

Hence, $h = \delta$

6 Python Exercise: DTFT Approximation using DFT

Figure 4-8 show the output with M=200. The runtime for dtft_approx is 0.1s and eq_dtft_approx is 0.0005s. Figure 9-13 show the output with M=5000. The runtime for dtft_approx is 2.7s and eq_dtft_approx is still 0.0005s. dtft_approx's runtime significantly increases with M=5000; however, M does not affect eq_dtft_approx because it is implemented using fft.

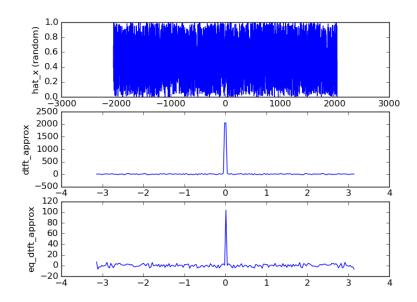


Figure 4: Random signal with M=200

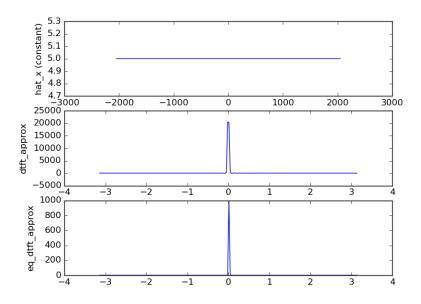


Figure 5: Constant signal with M=200

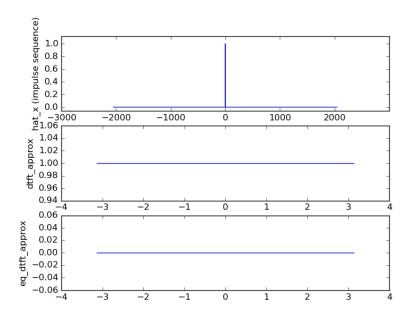


Figure 6: Impulse signal $(x[n] = \delta[n])$ with M = 200

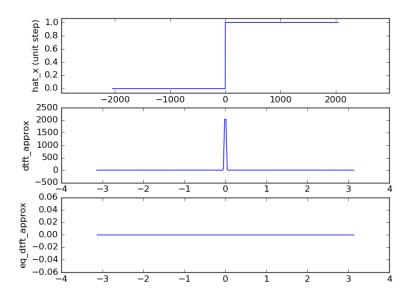


Figure 7: Unit step signal (x[n] = u[n]) with M = 200

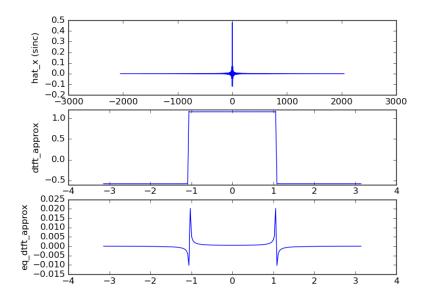


Figure 8: $x[n] = \sqrt{3} \frac{\sin(\frac{\pi n}{3})}{\pi n}$ with M = 200

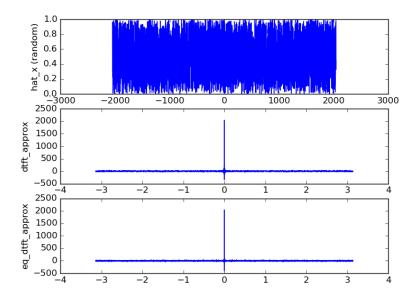


Figure 9: Random signal with M = 5000

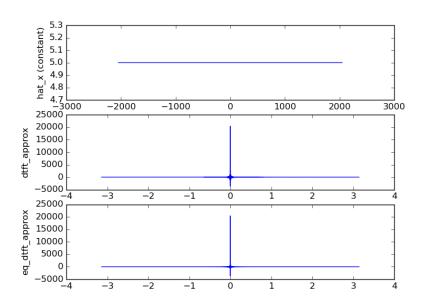


Figure 10: Constant signal with M = 5000

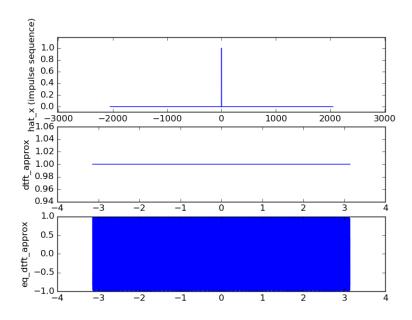


Figure 11: Impulse signal $(x[n]=\delta[n])$ with M=5000

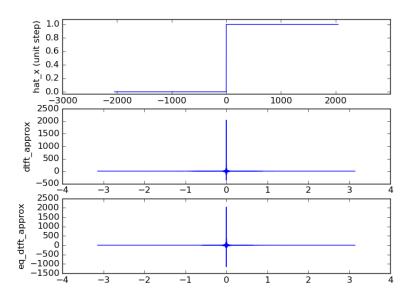


Figure 12: Unit step signal (x[n] = u[n]) with M = 5000

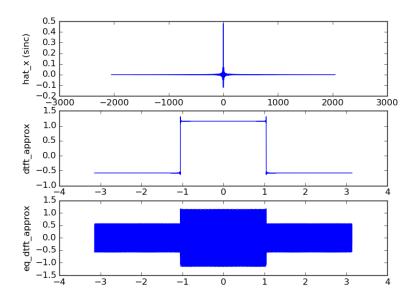


Figure 13: $x[n] = \sqrt{3} \frac{\sin(\frac{\pi n}{3})}{\pi n}$ with M = 5000

7 Python Exercise: Image Scaling with Separable Filters

Figure 14 shows the results of the four pre-filters. Since the visual difference is subtle, their corresponding MSEs are included. Method (a) and (c) are actually the same since $h = \delta$ so their MSEs are the same. The pattern (around leg and scarf area) of method (b) is overly smoothed.



Figure 14: Original image and four pre-filters (a-d) with corresponding MSE