#### ECE551 - Homework 5

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# 1 Sampling and Interpolation for Band-Limited Vectors

(a) We have the Fourier vector

$$w_k[n] = e^{j\frac{2\pi kn}{M}}$$

and

$$2\cos x = e^{jx} + e^{-jx}$$

So

$$\begin{split} x_1[n] &= 1 + \cos\left(\frac{2\pi n}{M}\right) + \cos\left(\frac{8\pi n}{M}\right) \\ &= w_0[n] + \frac{1}{2}\left(e^{j\frac{2\pi n}{M}} + e^{-j\frac{2\pi n}{M}}\right) + \frac{1}{2}\left(e^{j\frac{8\pi n}{M}} + e^{-j\frac{8\pi n}{M}}\right) \\ &= w_0[n] + \frac{1}{2}\left(w_1[n] + w_{-1}[n] + w_4[n] + w_{-4}[n]\right) \end{split}$$

Its DFT is

$$\begin{split} X_1[k] &= \sum_{n=0}^{M-1} x_1[n] w_{-k}[n] \\ &= \frac{1}{2} \left( \sum_{n=0}^{M-1} 2w_{-k}[n] + w_{-k-1}[n] + w_{-k+1}[n] + w_{-k-4}[n] + w_{-k+4}[n] \right) \end{split}$$

We can see that

$$\sum_{n=0}^{M-1} w_k[n] = \sum_{n=0}^{M-1} \exp\left(j\frac{2\pi k}{M}\right)^n$$

$$= \frac{1 - \exp\left(j\frac{2\pi k}{M}\right)^M}{1 - \exp\left(j\frac{2\pi k}{M}\right)} \quad (\because \text{ geometric series})$$

$$= A$$

Whenever the numerator of A is 0 (k=0), its denominator is also 0. Therefore A has a peak at k. Hence,  $X_1[k]$  has peaks at  $k = 0, \pm 1, \pm 4$ , so its bandwidth is [-4, 4].

Similarly,

$$x_{2}[n] = \cos\left(\frac{3\pi n}{M}\right) = \frac{1}{2} \left(e^{j\frac{3\pi n}{M}} + e^{-j\frac{3\pi n}{M}}\right)$$

$$\Rightarrow X_{2}[n] = \sum_{n=0}^{M-1} x_{2}[n]e^{-j\frac{2\pi k n}{M}}$$

$$= \frac{1}{2} \sum_{n=0}^{M-1} \left(e^{j\frac{2\pi n}{(3-2k)}} + e^{j\frac{2\pi n}{(-3-2k)}}\right)$$

$$= \frac{1}{2} \left(\frac{1 - \exp\left(j\frac{\pi n}{M}(3-2k)\right)^{M}}{1 - \exp\left(j\frac{\pi n}{M}(-3-2k)\right)^{M}}\right) \neq 0, \forall k \in \mathbb{Z}$$

Hence,  $x_2[n]$  is full-band.

(b) We take

$$\Phi = \left[ w_0, w_1, ..., w_{\frac{k_0+1}{2}-1}, w_{M-\frac{k_0+1}{2}+1}, ..., w_{M-1} \right]$$

Because x is band limited s.t.  $X[k] = 0, \forall k \in \left[\frac{k_0+1}{2}, M - \frac{k_0+1}{2}\right]$ , it means that we remove the part from  $\frac{k_0+1}{2}$  to  $M - \frac{k_0+1}{2}$  of the DFT.

# 2 Band Limited Space with Rational Sampling Rate Changes

- (a) Since we only care about the effect of g, we consider only until g[n] is apply (the first 5 steps).
  - Figure 1 shows the results for M=2, N=3, K=3. After upsampling by 2 (second row), we need the cut-off frequency of g to be  $\frac{\pi}{3} \leq w_c \leq \frac{\pi}{3}$ . By applying the low-pass filter g[-n] (third row), the gap between two copies is  $\frac{5\pi}{3} \frac{\pi}{3} = \frac{4\pi}{3}$ . After downsampling by 3 (forth row), the gap is reduced to 0, so upsampling it by 3 (fifth row) also gives the same gap. So the cut-off frequency has to be  $w_c = \frac{\pi}{3}$ .
- (b) Figure 2 shows the results for M=2, N=3, K=4. After upsampling by 2 (second row), we need the cut-off frequency of g to be  $\frac{\pi}{4} \leq w_c \leq \frac{3\pi}{4}$ . After apply downsampling by 3 (forth row), the gap is  $\frac{\pi}{2}$ . Therefore the gap is reduced by

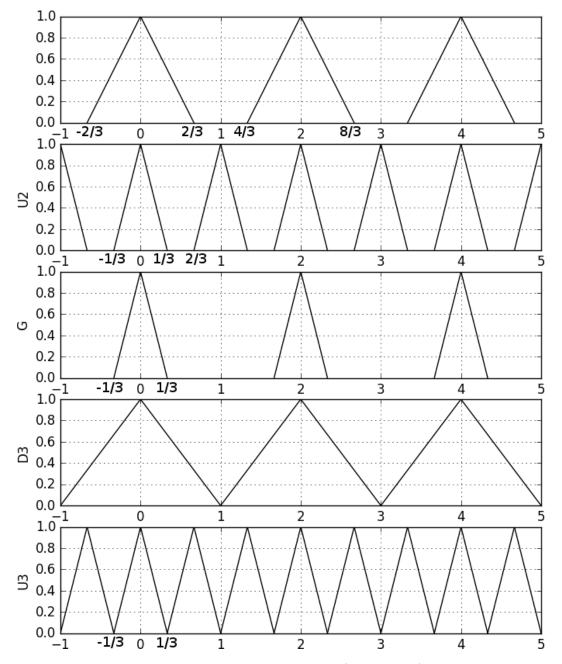


Figure 1: M = 2, N = 3, K = 3 (x scale is  $\pi$ )

a third after upsampling by 3 (fifth row). So the second condition for cut-off frequency is  $\frac{\pi}{4} \leq w_c \leq \frac{5\pi}{12}$ .

$$\frac{\pi}{4} \le w_c \le \frac{3\pi}{4}$$
 and  $\frac{\pi}{4} \le w_c \le \frac{5\pi}{12} \Rightarrow \frac{\pi}{4} \le w_c \le \frac{5\pi}{12}$ 

(c) If the signal in  $[-\frac{2\pi}{K},\frac{2\pi}{K}],$  the gap's width is

$$2\pi - \frac{2\pi}{K} - \frac{2\pi}{K} = 2\pi(1 - \frac{2}{K})$$

After upsampling by M, the range is  $\left[-\frac{2\pi}{KM}, \frac{2\pi}{KM}\right]$  and the gap is  $\frac{2\pi}{M}(1-\frac{2}{K})$ . Therefore the first condition of  $w_c$  is

$$\frac{2\pi}{KM} \le w_c \le \frac{2\pi}{KM} + \frac{2\pi}{M}(1 - \frac{2}{K}) \Leftrightarrow \frac{2\pi}{KM} \le w_c \le \frac{2\pi}{M}(1 - \frac{1}{K})$$

After downsampling by N, the  $\left[-\frac{2\pi N}{KM}, \frac{2\pi N}{KM}\right]$  and the gap is  $2\pi - \frac{2\pi N}{KM} - \frac{2\pi N}{KM} = 2\pi (1 - \frac{2}{KM})$ .

Therefore, after upsampling by N, the lower bound of the first copy (after at frequency of 0) is

$$\frac{1}{N} \cdot \frac{2\pi N}{KM} + \frac{1}{N} \cdot 2\pi (1 - \frac{2N}{KM}) = \frac{2\pi}{KM} + \frac{2\pi}{N} - \frac{4\pi}{KM} = \frac{2\pi}{N} - \frac{2\pi}{KM} = 2\pi (\frac{1}{N} - \frac{1}{KM})$$

So the second condition of  $w_c$  is

$$\frac{2\pi}{KM} \le w_c \le 2\pi (\frac{1}{N} - \frac{1}{KM})$$

Combining the first and second condition gives

$$\frac{2\pi}{KM} \le w_c \le 2\pi (\frac{1}{N} - \frac{1}{KM}) \qquad (\because M < N \text{ so the second condition is tighter})$$

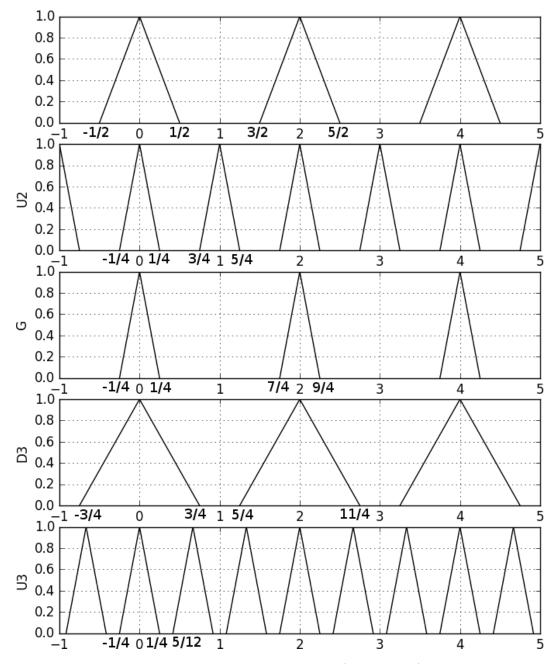


Figure 2: M = 2, N = 3, K = 4 (x scale is  $\pi$ )

#### 3 Multirate Systems

(a) Let u[n] be the output after downsampling and v[n] be the output after convolving with g.

$$\begin{split} U(z) &= \frac{1}{2} \sum_{k=0}^{1} X \left( e^{-j\frac{2\pi k}{2}} z^{1/2} \right) \\ &= \frac{1}{2} \left( X (z^{1/2} + X (e^{-j\pi} z^{1/2})) \right) \\ V(z) &= G(z) U(z) \\ Y(z) &= V(z^3) \\ &= G(z^3) U(z^3) \\ &= \frac{1}{2} \left( X (z^{3/2} + X (e^{-j\pi} z^{3/2})) \right) \end{split}$$

(b) x[n] = q(nT) is the same as downsampling by T, so u[z] is obtained by downsampling q(t) by 2T. Therefore

$$U(\omega) = \frac{1}{2T} \sum_{k=0}^{2T-1} Q\left(\frac{\omega - 2\pi k}{2T}\right)$$

$$V(\omega) = G(\omega)U(\omega)$$

$$Y(\omega) = V(3\omega)$$

$$= G(3\omega)U(3\omega)$$

$$= \frac{G(3\omega)}{2T} \sum_{k=0}^{2T-1} Q\left(\frac{3\omega - 2\pi k}{2T}\right)$$

Since  $q \in BL[-\frac{\pi}{T}, \frac{\pi}{T}]$  and the sampling rate  $\frac{1}{T}$ , we have the setting in Figure 3 To avoid aliasing, we need  $\frac{\pi}{T} < \frac{1}{2T} \Leftrightarrow \frac{2\pi-1}{T} < 0$ , which cannot satisfy. Therefore, q cannot avoid aliasing after sampling.

## 4 Pseudo-Inverse of Interpolation Filter: Single Channel Case

By orthogonality principle

$$x - \hat{x} \perp V = \operatorname{span}\{\sigma^{kN}g\}_{k \in \mathbb{Z}} \Leftrightarrow \left\langle x - \hat{x}, \sigma^{kN}g \right\rangle = 0$$

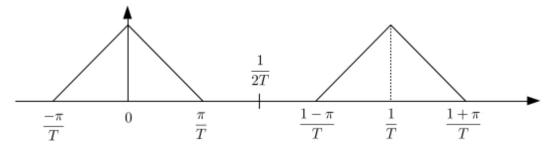


Figure 3: Sampling  $q \in BL[-\frac{\pi}{T}, \frac{\pi}{T}]$  with sampling rate of  $\frac{1}{T}$ 

Recall that convolution can be written as inner product, i.e.  $(u*v)[n] = \langle u, \sigma^n \tilde{v} \rangle$ . Therefore

$$\Leftrightarrow \left\langle x - \hat{x}, \sigma^{kN} g \right\rangle = ((x - \hat{x}) * \tilde{g})[kN] = 0$$

Let  $s = (x - \hat{x}) * \tilde{g}$ , its z-transform is

$$S(z) = (X(z) - \hat{X}(x))G(z^{-1}) = 0$$

where X(z),  $\hat{X}(z)$ , and  $G(z^{-1})$  are the z-transform of x[n],  $\hat{x}[n]$ , and  $\tilde{g}[n]$ . We have the polyphase decomposition as

$$X(z) = \pi(z)X_p(z^N)$$

$$G(z) = G_p(z^N)^{\top}\pi(z)^{\top}$$

$$\hat{X}(z) = \pi(z)\hat{X}_p(z^N) = \pi(z)G_p(z^N)\hat{H}_p(z^N)X_p(z^N)$$

(because  $z^N=\omega$  and  $\hat{X}_p(\omega)=G_p(\omega)\tilde{H}_p(\omega)X_p(\omega)$ ). Substituting them to S(z) gives:

$$S(z) = \left[ \pi(z) X_p(z^N) - \pi(z) G_p(z^N) \tilde{H}_p(z^N) X_p(z^N) \right] G_p(z^{-N})^\top \pi(z^{-1})^\top$$
  
=  $G_p(z^{-N})^\top \pi(z^{-1})^\top \pi(z) \left[ X_p(z^N) - G_p(z^N) \tilde{H}_p(z^N) X_p(z^N) \right]$ 

We know that  $\pi(z^{-1})^{\top}\pi(z) = I - A(z)$ , where A(z) contains non-zero phases, thus will vanish  $G_p(z^{-N})^{\top}A(z)\left[X_p(z^N) - G_p(z^N)\tilde{H}_p(z^N)X_p(z^N)\right]$ . Therefore

$$S(z) = G_{p}(z^{-N})^{\top} \left[ X_{p}(z^{N}) - G_{p}(z^{N}) \tilde{H}_{p}(z^{N}) X_{p}(z^{N}) \right]$$

$$= G_{p}(z^{-N})^{\top} X_{p}(z^{N}) - G_{p}(z^{-N})^{\top} G_{p}(z^{N}) \tilde{H}_{p}(z^{N}) X_{p}(z^{N})$$

$$= \left[ G_{p}(z^{-N})^{\top} - G_{p}(z^{-N})^{\top} G_{p}(z^{N}) \tilde{H}_{p}(z^{N}) \right] X_{p}(z^{N}) = 0, \forall X_{p}(z^{N})$$

$$\Rightarrow G_{p}(z^{-N})^{\top} - G_{p}(z^{-N})^{\top} G_{p}(z^{N}) \tilde{H}_{p}(z^{N}) = 0$$

Since  $\omega = z^n$ 

$$G_p(\omega^{-1})^{\top} - G_p(\omega^{-1})^{\top} G_p(\omega) \tilde{H}_p(\omega) = 0$$
  

$$\Leftrightarrow G_p(\omega^{-1})^{\top} G_p(\omega) \tilde{H}_p(\omega) = G_p(\omega^{-1})^{\top}$$
  

$$\Leftrightarrow \tilde{H}_p(\omega) = \left( G_p(\omega^{-1})^{\top} G_p(\omega) \right)^{-1} G_p(\omega^{-1})^{\top}$$

## 5 Ideal-Matched Sampling and Interpolation with Nonorthogonal Filters

(a) 
$$N = 2 \Rightarrow \omega = z^N = z^2$$

z-transform of g[n] is

$$G(z) = 1 + \frac{1}{2}(z^{-1} + z)$$

Since N=2, we need components  $z^0$  and  $z^{-1}$ 

$$\Rightarrow G(z) = 1 + z^{-1} \left( \frac{1}{2} + \frac{1}{2} z^2 \right)$$

For type-I polyphase decomposition

$$G_p(\omega) = \begin{bmatrix} G_0(\omega) \\ G_1(\omega) \end{bmatrix} = \begin{bmatrix} 1 \\ \frac{1}{2} + \frac{1}{2}\omega \end{bmatrix} \Rightarrow G_p(\omega^{-1})^{\top} = \begin{bmatrix} 1, & \frac{1}{2} + \frac{1}{2}\omega^{-1} \end{bmatrix}$$

From problem 4, we have

$$\tilde{H}_p(\omega) = \left(G_p(\omega^{-1})^\top G_p(\omega)\right)^{-1} G_p(\omega^{-1})^\top$$

$$G_p(\omega^{-1})^{\top} G_p(\omega) = \left[ 1, \quad \frac{1}{2} + \frac{1}{2}\omega^{-1} \right] \left[ \frac{1}{\frac{1}{2} + \frac{1}{2}\omega} \right]$$
$$= 1 + \frac{1}{4}(1 + \omega^{-1})(1 + \omega)$$
$$= \frac{6 + \omega + \omega^{-1}}{4}$$

$$\Rightarrow \tilde{H}_p(\omega) = \left(\frac{6+\omega+\omega^{-1}}{4}\right)^{-1} \left[1, \frac{1}{2} + \frac{1}{2}\omega^{-1}\right]$$

We have

$$\begin{split} H(z) &= \tilde{H}_p(z^2)\pi(z^{-1})^{\top} \qquad \text{(type-II, with } z^2 = \omega) \\ &= \frac{4}{6+\omega+\omega^{-1}} \left[ 1, \quad \frac{1}{2} + \frac{1}{2}\omega^{-1} \right] \begin{bmatrix} 1\\z \end{bmatrix} \\ &= \frac{4(1+\frac{z}{2}+\frac{z^{-1}}{2})}{6+z^2+z^{-2}} \\ &= \frac{2(2+z+z^{-1})}{6+z^2+z^{-2}} \end{split}$$

For the numerator

$$2(2+z+z^{-1}) = 2z^{-1}(2z+z^{2}+1)$$
$$= 2z^{-1}(z+1)(z+1)$$
$$= 2(z^{-1}+1)(z+1)$$

For the denominator

$$6 + z^{2} + z^{-2} = z^{-2}(6z^{2} + z^{4} + 1)$$

$$= z^{-2}(z^{2} + 3 + 2\sqrt{2})(z^{2} + 3 - 2\sqrt{2})$$

$$= (1 + (3 + 2\sqrt{2})z^{-2})(z^{2} + 3 - 2\sqrt{2})$$

$$= (1 + (3 + 2\sqrt{2})z^{-2})\left(z^{2} + \frac{1}{3 + 2\sqrt{2}}\right)$$

$$= (3 + 2\sqrt{2})\left(z^{-2} + \frac{1}{3 + 2\sqrt{2}}\right)\left(z^{2} + \frac{1}{3 + 2\sqrt{2}}\right)$$

$$= \mathcal{C}^{-1}(z^{-2} + \mathcal{C})(z^{2} + \mathcal{C}), \quad \text{where } \mathcal{C} = \frac{1}{3 + 2\sqrt{2}}$$

Therefore

$$H(Z) = \frac{2(z^{-1} + 1)(z + 1)}{\mathcal{C}^{-1}(z^{-2} + \mathcal{C})(z^{2} + \mathcal{C})}$$

$$= 2\mathcal{C}\frac{z^{-1} + 1}{z^{-2} + \mathcal{C}}\frac{z^{1} + 1}{z^{2} + \mathcal{C}}$$

$$= P(z^{-1})P(z), \quad \text{where } P(z) = \sqrt{2\mathcal{C}}\frac{z + 1}{z^{2} + \mathcal{C}}, \mathcal{C} = \frac{1}{3 + 2\sqrt{2}}$$

h[n] is the inverse z-transform of H(z).

(b) 
$$\tilde{H}_p(\omega)G_p(\omega) = 1 \Leftrightarrow \tilde{H}_p(\omega) \begin{bmatrix} 1\\ \frac{1}{2} + \frac{1}{2}\omega \end{bmatrix} = 1$$

Therefore, the shortest  $\tilde{H}_p(\omega)$  is  $\begin{bmatrix} 0 & 1 \end{bmatrix}$ 

$$H(z) = \tilde{H}_p(z^2)\pi(z^{-1})^{\top} = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ z \end{bmatrix} = 1$$

Hence,  $h = \delta$ 

#### 6 Python Exercise: DTFT Approximation using DFT

Figure 4-8 show the output with N=4096, M=200. The runtime for dtft\_approx is 0.1s and eq\_dtft\_approx is 0.0005s. Figure 9-13 show the output with N=4096, M=5000. The runtime for dtft\_approx is 2.7s and eq\_dtft\_approx is still 0.0005s. dtft\_approx's runtime significantly increases with M=5000; however, M does not affect eq\_dtft\_approx because it is implemented using fft. Figure 14-18 show the output with N=400, M=200. The runtime of eq\_dtft\_approx is around 0.0001s and dtft\_approx's is around 0.02s.

Overall, the results of  $\mathtt{dtft\_approx}$  is similar to  $\mathtt{eq\_dtft\_approx}$  but with significantly longer runtime. Increasing M or N makes the results finer and decreasing N or M makes the them rougher. Changing M only affects the frequency responses while changing N affect the original signals directly.

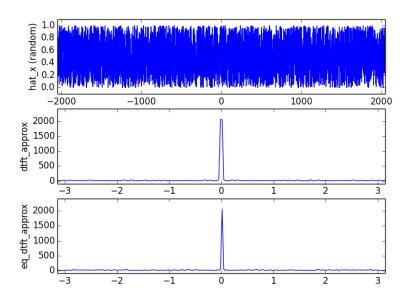


Figure 4: Random signal with N=4096, M=200

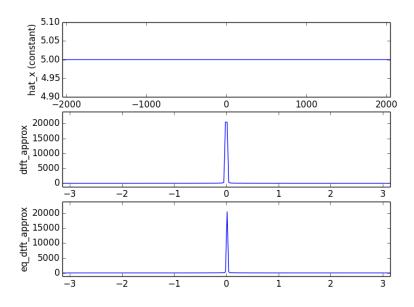


Figure 5: Constant signal with N=4096, M=200

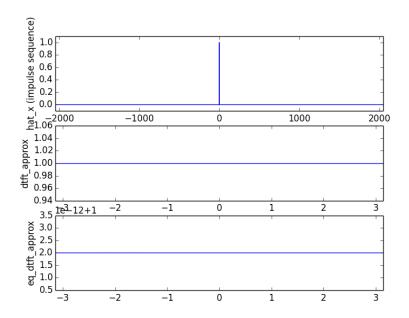


Figure 6: Impulse signal  $(x[n] = \delta[n])$  with N = 4096, M = 200

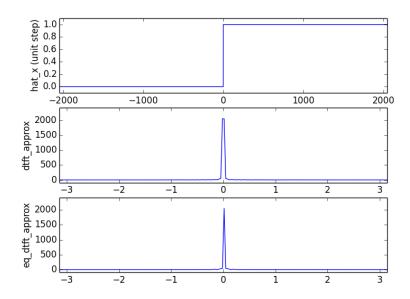


Figure 7: Unit step signal (x[n] = u[n]) with N = 4096, M = 200

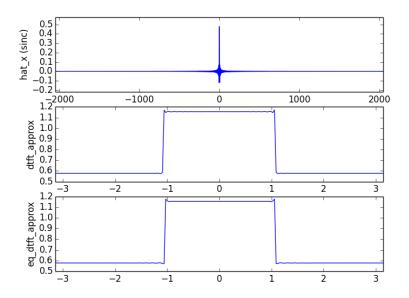


Figure 8:  $x[n] = \sqrt{3} \frac{\sin(\frac{\pi n}{3})}{\pi n}$  with N=4096, M=200

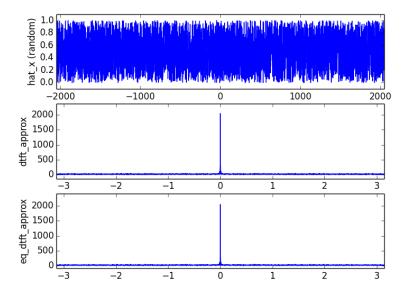


Figure 9: Random signal with N=4096, M=5000

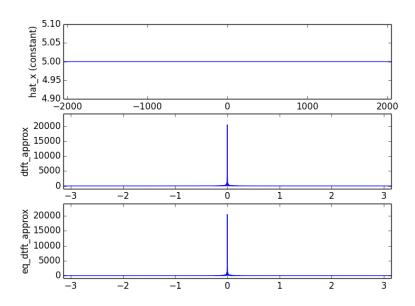


Figure 10: Constant signal with N = 4096, M = 5000

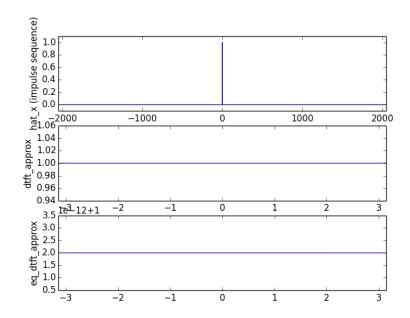


Figure 11: Impulse signal  $(x[n] = \delta[n])$  with N = 4096, M = 5000

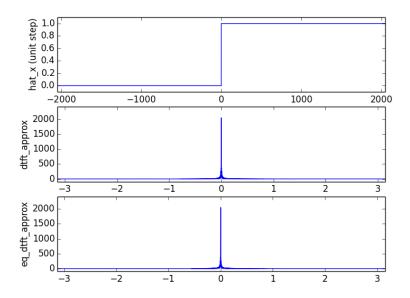


Figure 12: Unit step signal (x[n] = u[n]) with N = 4096, M = 5000

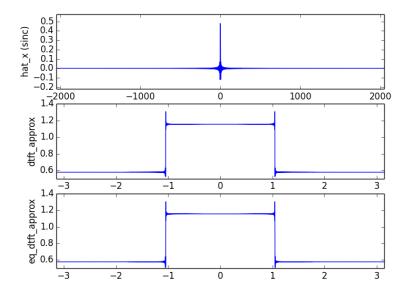


Figure 13:  $x[n] = \sqrt{3} \frac{\sin(\frac{\pi n}{3})}{\pi n}$  with N = 4096, M = 5000

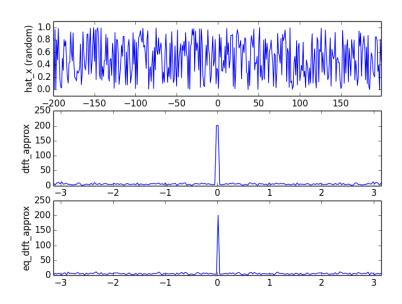


Figure 14: Random signal with N=400, M=200

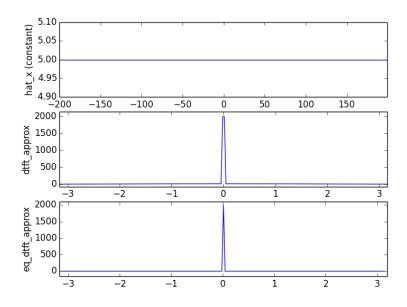


Figure 15: Constant signal with N=400, M=200

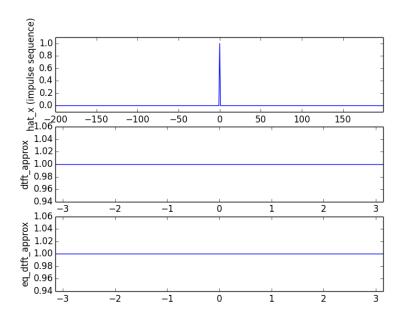


Figure 16: Impulse signal  $(x[n] = \delta[n])$  with N = 400, M = 200

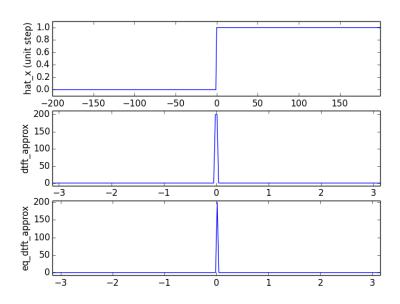


Figure 17: Unit step signal (x[n] = u[n]) with N = 400, M = 200

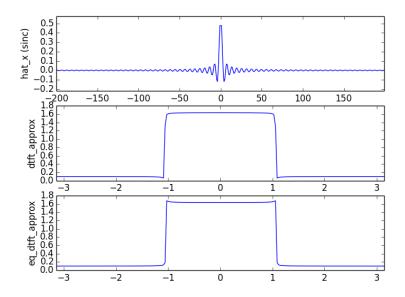


Figure 18:  $x[n] = \sqrt{3} \frac{\sin(\frac{\pi n}{3})}{\pi n}$  with N = 400, M = 200

# 7 Python Exercise: Image Scaling with Separable Filters

Figure 19 shows the results of the four pre-filters. Since the visual difference is subtle, their corresponding MSEs are included. Method (a) and (c) are actually the same since  $h=\delta$  so their MSEs are the same (MSE = 209.9389). The pattern (around leg and scarf area) of method (b) is overly smoothed while the alias effect of (a) and (c) is clearly visible; therefore its MSE is much higher (MSE = 147068.8310). Method (d) is uses the optimal filter so it has the lowest MSE (MSE = 178.7584).



Figure 19: Original image and four pre-filters (a-d) with corresponding  $\overline{\text{MSE}}$