

# Experiments Around Training Data Selection Methods for Image Classification

Department of Statistics Data Analysis Qualifying Exam

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December 16, 2019

# Problem Statement and Objective

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- ▶ CNNs may fit poorly when there is insufficient data, and the data collection and labelling process can be expensive

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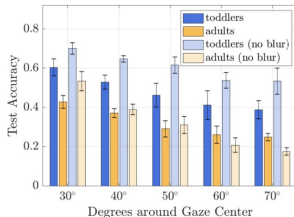
- ▶ Deep convolutional neural networks make use of the current wealth of curated image datasets and computational resources
- ▶ CNNs may fit poorly when there is insufficient data, and the data collection and labelling process can be expensive
- ▶ Goal: Determine a training set sampling method to select the best possible images under a fixed training set size

# Problem Statement and Objective

- ▶ Deep convolutional neural networks make use of the current wealth of curated image datasets and computational resources
- ▶ CNNs may fit poorly when there is insufficient data, and the data collection and labelling process can be expensive
- ▶ Goal: Determine a training set sampling method to select the best possible images under a fixed training set size
- ▶ Largely based on “Toddler-Inspired Visual Object Learning” by Bambach, Crandal, Smith, and Yu (2018)

# Background: “Toddler-Inspired Visual Object Learning”

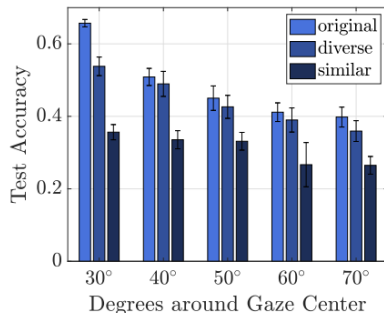
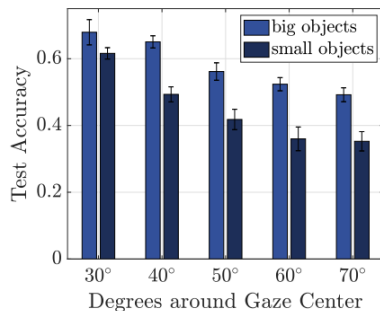
- ▶ Compared images taken by first-person cameras mounted on toddlers and parents
- ▶ Training VGG16 using toddler data resulted in higher test accuracy than training on parent data (same test set in both cases)



## Background: “Toddler-Inspired Visual Object Learning”

- ▶ Distilled the differences in the datasets into two components: object size (how much of the image does the object take up) and image “diversity” (hard to measure)
- ▶ Subsampled the images to obtain training subsets of:
  - ▶ big objects
  - ▶ small objects
  - ▶ diverse images
  - ▶ similar images
  - ▶ random subset
- ▶ Image similarity/distance based on an image embedding (GIST features)
- ▶ Found that when objects are larger or when images are more diverse, test accuracy improves

# Background: “Toddler-Inspired Visual Object Learning”





# Outline and Summary

## 1. Replication studies

# Outline and Summary

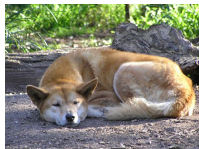
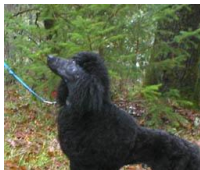
1. Replication studies
2. New methods for training data selection

# Outline and Summary

1. Replication studies
2. New methods for training data selection
3. Conclusions and future work

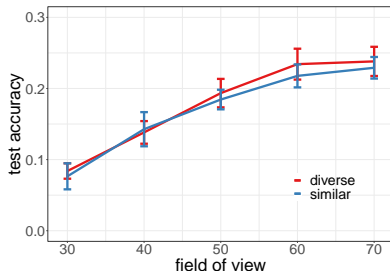
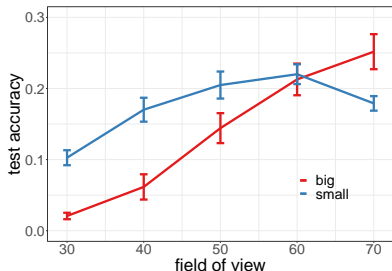
# Replication Study: Stanford Dogs dataset

- ▶ ~20,000 images of 120 dog breeds
- ▶ 100 images per breed set aside for training
  - ▶ further subdivided into 50-50 big/small or diverse/similar
- ▶ 25 images per breed set aside for validation
- ▶ Remainder for testing



# Replication Study: Stanford Dogs dataset

- ▶ Some evidence that object size affects training
- ▶ No significant evidence that image diversity affects training



# Replication Study: CIFAR-10

## CIFAR-10

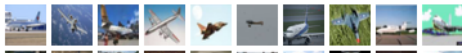
- ▶  $32 \times 32$  RGB images of 10 different object classes
- ▶ 5,000 training and 1,000 testing images per class
- ▶ No bounding box information
  - ▶ Diversity experiment only
  - ▶ No adjusting field of view

## Sampling method

1. Choose training size  $n$
2. Draw  $2n$  images using diverse, similar, or random sampling
3. Split the data in half for training and validation
4. Fit VGG16 and assess accuracy on the test set

# Replication Study: CIFAR-10

**airplane**



**automobile**



**bird**



**cat**



**deer**



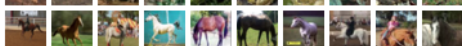
**dog**



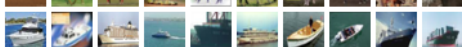
**frog**



**horse**



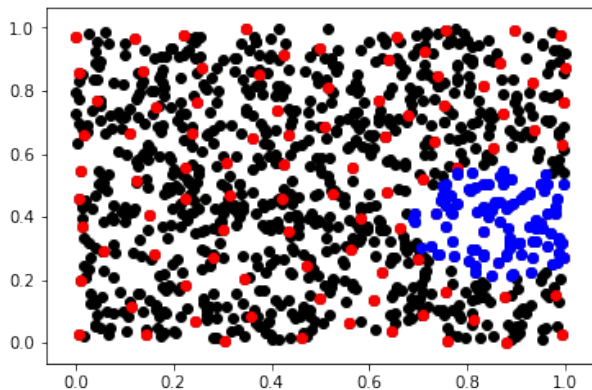
**ship**



**truck**

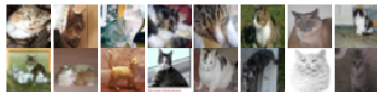
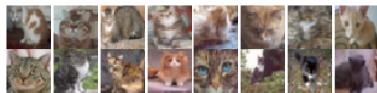
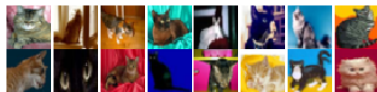


## Diverse vs. Similar Samples from a Point Cloud

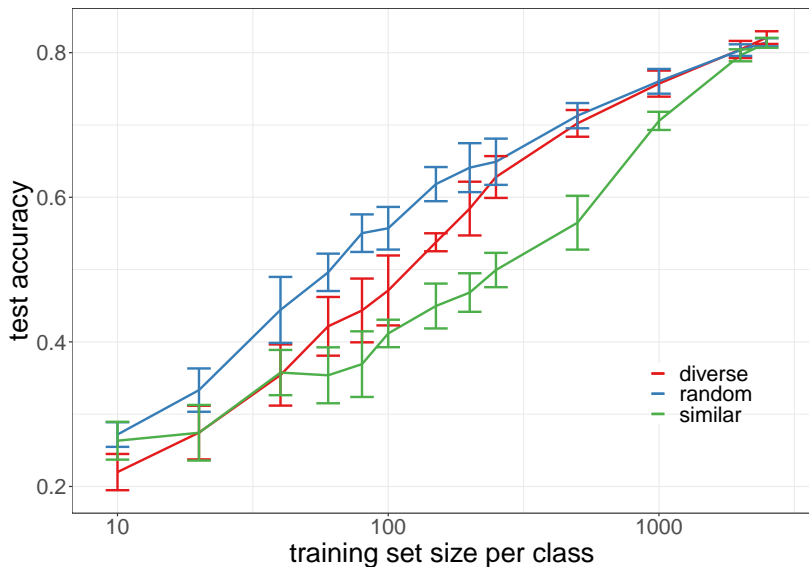




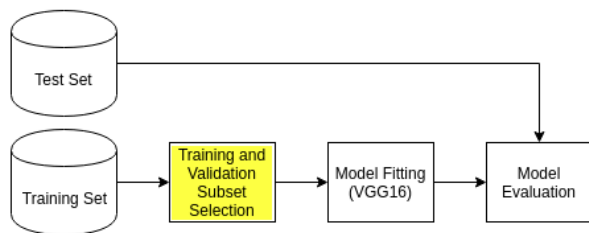
# Diverse vs. Similar vs. Random Samples of CIFAR-10 Cats



# Replication Study: CIFAR-10



# New Approaches to Training Set Selection



# Wilson Editing

- ▶ Originally developed for  $k$ -nearest neighbors
- ▶ Algorithm
  1. Start with a sample  $X_1, \dots, X_n \in \mathbb{R}^p$  and corresponding discrete labels  $Y_1, \dots, Y_n \in \{1, \dots, q\}$
  2. For  $i = 1, \dots, n$ , determine  $\hat{Y}_i$  using leave-one-out cross-validated  $k$ -nearest neighbors classification
  3. Discard  $i \in \{1, \dots, n\}$  where  $Y_i \neq \hat{Y}_i$  to construct a reduced, “edited” training set
  4. Use the edited training set to fit a new  $k$ -nearest neighbors model
- ▶ Outperforms “unedited”  $k$ -nearest neighbors (comparing risk on a held-out test set)

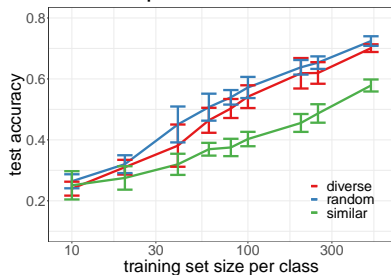
## ► Algorithm

1. Use Wilson editing (using the GIST embedding) to reduce the training set
2. For a training size  $n$ , draw a diverse sample from the edited training set
3. Fit VGG16 on the diverse, edited training subset
4. Assess model performance on the test set

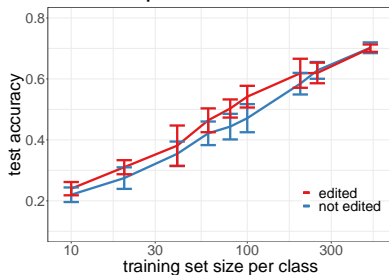
## ► Idea: Draw a diverse sample while excluding “outliers”

# Wilson Editing

Editing done prior to drawing diverse samples



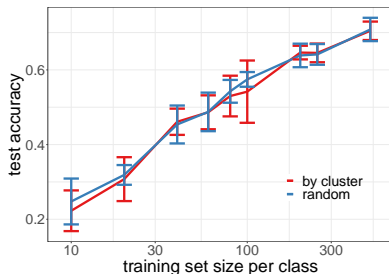
Effect of editing prior to drawing diverse samples



# Clustering

## Algorithm

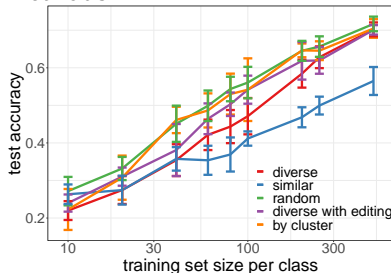
1. Use  $k$ -means clustering (using the GIST embedding) to split each class into “subclasses”
2. For a training size  $n$ , draw a cluster/subclass-stratified sample
3. Fit VGG16 on the stratified training subset
4. Assess model performance on the test set



# Summary and Conclusions

- ▶ Diverse sampling outperforms similar sampling but fails to improve upon uniform random sampling
- ▶ Removing outlier images prior to drawing a diverse sample seems to improve model performance
- ▶ Cluster-stratified sampling resulted in equivalent model performance as uniform random sampling
- ▶ Future work
  - ▶ More sophisticated clustering methods
  - ▶ Active learning based approaches

Comparison of sampling methods





## Additional Slides



# GIST Embedding



# Transfer Learning