# Connecting the Popularity Adjusted Block Model to the Generalized Random Dot Product Graph SDSS 2021 Lightning Presentation

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June 2021

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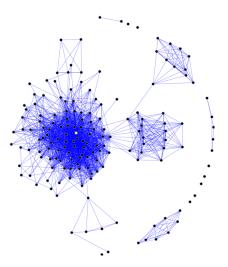
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#### Overview

- 1. Block Models and the Popularity Adjusted Block Model
- 2. Generalized Random Dot Product Graphs
- 3. Connecting the PABM to the GRDPG
- 4. Community Detection for the PABM

# **Block Models**

#### **Networks**



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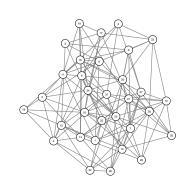
# Bernoulli Graphs

Let G=(V,E) be an undirected and unweighted graph with  $\lvert V \rvert = n.$ 

G is described by adjacency matrix A such that  $A_{ij} = \begin{cases} 1 & \exists \text{ edge between } i \text{ and } j \\ 0 & \text{else} \end{cases}$   $A_{ji} = A_{ij}$  and  $A_{ii} = 0 \ \forall i,j \in [n].$ 

 $A \sim BernoulliGraph(P)$  iff:

- 1.  $P \in [0,1]^{n \times n}$  describes edge probabilities between pairs of vertices.
- 2.  $A_{ij} \stackrel{ind}{\sim} Bernoulli(P_{ij})$  for each i < j.

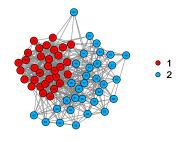


#### **Block Models**

Suppose each vertex  $v_1,...,v_n$  has hidden labels  $z_1,...,z_n \in [K]$ , and each  $P_{ij}$  depends on labels  $z_i$  and  $z_j$ . Then  $A \sim BernoulliGraph(P)$  is a block model.

Example: Stochastic Block Model (Lorrain and White, 1971) with two communities

- $ightharpoonup z_1, ..., z_n \in \{1, 2\}$
- $P_{ij} = \begin{cases} p & z_i = z_j = 1\\ q & z_i = z_j = 2\\ r & z_i \neq z_j \end{cases}$
- To make this an assortative SBM, set  $pq > r^2$ .
- In this example, p = 1/2, q = 1/4, and r = 1/8.



# Popularity Adjusted Block Model

Definition based on Noroozi, Rimal, and Pensky (2020); model first proposed by Sengupta and Chen (2017).

$$A \sim PABM(\{\lambda^{(kl)}\}_K)$$
 iff

- 1. w.l.o.g., organize P such that each block  $P^{(kl)} \in [0,1]^{n_k \times n_l}$  contains edge probabilities between communities k and l.
- 2. Organize parameters as vectors such that  $\lambda^{(kl)} \in \mathbb{R}^{n_k}$  are the popularity parameters of members of community k to community l.

 $\{\lambda^{(kl)}\}_K$  is the set of  $K^2$  popularity vectors.

- 3. Then we can write each block of P as  $P^{(kl)} = \lambda^{(kl)} (\lambda^{(lk)})^{\top}$ .
- 4. Sample  $A \sim BernoulliGraph(P)$ .

Example: K=2

$$P = \begin{bmatrix} P^{(11)} & P^{(12)} \\ P^{(21)} & P^{(22)} \end{bmatrix} = \begin{bmatrix} \lambda^{(11)} (\lambda^{(11)})^\top & \lambda^{(12)} (\lambda^{(21)})^\top \\ \lambda^{(21)} (\lambda^{(12)})^\top & \lambda^{(22)} (\lambda^{(22)})^\top \end{bmatrix}$$

## Community Detection in Block Models

#### Likelihood

$$L = \prod_{i < j} \prod_{k,l}^{K} \left( p_{k,l,i,j}^{A_{ij}} (1 - p_{k,l,i,j})^{1 - A_{ij}} \right)^{z_{ik} z_{jl}}$$

- $lackbox{ML}$  method for community detection:  $\hat{ec{z}} = rg \max_{ec{z}} L$
- NP-complete
  - Expectation-Maximization
  - Bayesian methods
  - Spectral methods

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# Generalized Random Dot Product Graphs

#### Generalized Random Dot Product Graph

Generalized Random Dot Product Graph  $A \sim GRDPG_{p,q}(X)$  (Rubin-Delanchy, Cape, Tang, Priebe, 2020)

- ▶ Latent vectors  $x_1,...,x_n \in \mathbb{R}^{p+q}$  such that  $x_i^{\top}I_{p,q}x_j \in [0,1]$  and  $I_{p,q} = blockdiag(I_p,-I_q)$
- $lacksquare A \sim BernoulliGraph(XI_{p,q}X^{\top}) \text{ where } X = \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^{\top}$

If latent vectors  $X_1,...,X_n \stackrel{iid}{\sim} F$ , then we write  $(A,X) \sim GRDPG_{p,q}(F,n)$ .

## (Generalized) Random Dot Product Graph Model

#### Recovery/Estimation

Want to estimate X given A.

#### Adjacency Spectral Embedding

To embed in  $\mathbb{R}^{p+q}$ ,

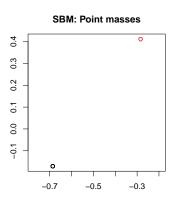
- 1. Compute  $A \approx \hat{V} \hat{\Lambda} \hat{V}^{\top}$  where  $\hat{\Lambda} \in \mathbb{R}^{(p+q) \times (p+q)}$  and  $\hat{V} \in \mathbb{R}^{n \times (p+q)}$  by using p most positive and q most negative eigenvalues.
- 2. Let  $\hat{X} = \hat{V} |\hat{\Lambda}|^{1/2}$ .

Rubin-Delanchy et al., 2020:

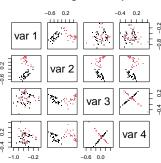
$$\max_{i} \|\hat{X}_i - Q_n X_i\| \stackrel{a.s.}{\to} 0$$

$$Q_n \in \mathbb{O}(p,q)$$

## Connecting Block Models to the GRDPG



#### PABM: Orthogonal subspaces



# Connecting the PABM to the GRDPG

## Connecting the PABM to the GRDPG (K = 2)

**Theorem** (KTT):  $A \sim PABM(\{\lambda^{(kl)}\}_2)$  is equivalent to  $A \sim GRDPG_{3,1}(XU)$  for block diagonal X constructed from  $\{\lambda^{(kl)}\}_2$  and predetermined  $U \in \mathbb{O}(4)$ .

Proof: Decompose  ${\cal P}$  as follows

$$X = \begin{bmatrix} \lambda^{(11)} & \lambda^{(12)} & 0 & 0\\ 0 & 0 & \lambda^{(21)} & \lambda^{(22)} \end{bmatrix}$$

$$U = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & 0 & 1/\sqrt{2} & -1/\sqrt{2} \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$P = (XU)I_{3,1}(XU)^{\top} = \begin{bmatrix} \lambda^{(11)}(\lambda^{(11)})^{\top} & \lambda^{(12)}(\lambda^{(21)})^{\top} \\ \lambda^{(21)}(\lambda^{(12)})^{\top} & \lambda^{(22)}(\lambda^{(22)})^{\top} \end{bmatrix}$$

## Connecting the PABM to the GRDPG $(K \ge 2)$

**Theorem** (KTT):  $A \sim PABM(\{\lambda^{(kl)}\}_K)$  is equivalent to  $A \sim GRDPG_{p,q}(XU)$  such that

- p = K(K+1)/2
- q = K(K-1)/2
- $lackbox{ }U$  is orthogonal and predetermined for each K
- ▶ X is block diagonal and composed of  $\{\lambda^{(kl)}\}_K$   $\implies$  if  $x_i^{\top}$  and  $x_j^{\top}$  are two rows of XU corresponding to different communities, then  $x_i^{\top}x_j=0$ .

**Remark** (non-uniqueness of the latent configuration):  $A \sim GRDPG_{p,q}(XU) \implies A \sim GRDPG_{p,q}(XUQ)$   $\forall Q \in \mathbb{O}(p,q)$ 

**Corollary**: X is block diagonal by community and U is orthogonal  $\implies$  each community corresponds to a subspace in  $\mathbb{R}^{K^2}$ .

Subspace property holds even with linear transformation  $Q\in \mathbb{O}(p,q).$ 

# Community Detection for the PABM

# Sparse Subspace Clustering

Sparse Subspace Clustering (Elhamifar and Vidal, 2009): Let the rows of  $X \in \mathbb{R}^{n \times d}$  are vectors that lie on or near a small number of low-dimensional subspaces. SSC constructs a graph from X as follows:

- 1. For each  $i \in [n]$ , solve the optimization problem  $c_i = \arg\min_c \|c\|_1$  subject to  $x_i = Xc$  and  $c^{(i)} = 0$ .
- 2. Construct a similarity graph using  $B = |C| + |C^{\top}|$  as its affinity matrix, where  $C = \begin{bmatrix} c_1 & \cdots & c_n \end{bmatrix}$ .

If X obeys the Subspace Detection Property, then it produces a similarity graph B such that  $B_{ij}=0 \ \forall z_i\neq z_j$ .

## Sparse Subspace Clustering for Community Detection

Noroozi et al. observed that the rank of P is  $K^2$  and the columns of P belonging to each community has rank K to justify SSC for the PABM.

$$c_i = \arg\min_c \|c\|_1$$
 subject to  $A_{\cdot,i} = Ac$  and  $c^{(i)} = 0$ 

GRDPG-based approach: Apply SSC to the ASE of  ${\it A}.$ 

$$c_i = \arg\min_c \|c\|_1$$
 subject to  $\hat{x}_i = \hat{X}c$  and  $c^{(i)} = 0$  
$$A \approx \hat{X}I_{p,q}\hat{X}^{ op}$$

# Sparse Subspace Clustering

#### Theorem (KTT):

#### Let

- ▶  $P_n$  describe the edge probability matrix of the PABM with n vertices, and  $A_n \sim BernoulliGraph(P_n)$ .
- $ightharpoonup \hat{V}_n$  be the matrix of eigenvectors of  $A_n$  corresponding to the K(K+1)/2 most positive and K(K-1)/2 most negative eigenvalues.

#### Then

▶  $\exists N < \infty$  such that when n > N,  $\sqrt{n}\hat{V}_n$  obeys the Subspace Detection Property with probability 1.

# Orthogonal Spectral Clustering

**Theorem** (KTT): If  $P = V\Lambda V^{\top}$  is the spectral decomposition of P for the PABM and V has rows  $v_i^{\top}$ , then  $v_i^{\top}v_j = 0 \ \forall z_i \neq z_j$ .

**Theorem** (KTT): If  $A \approx \hat{V} \hat{\Lambda} \hat{V}^{\top}$  is the spectral decomposition of A for the PABM using the K(K+1)/2 most positive and K(K-1)/2 most negative eigenvalues, and we denote  $\hat{v}_i^{\top}$  as the rows of  $\hat{V}$ , then

$$\max_{i,j:z_i \neq z_j} \hat{v}_i^{\top} \hat{v}_j = O_P \left( \frac{(\log n)^c}{\sqrt{n\rho_n}} \right)$$

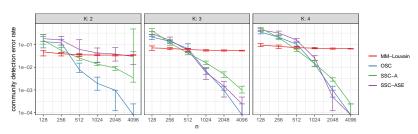
#### Orthogonal Spectral Clustering (KTT):

- 1. Let V be the eigenvectors of A corresponding to the K(K+1)/2 most positive and K(K-1)/2 most negative eigenvalues.
- 2. Compute  $B = |nVV^{\top}|$  applying  $|\cdot|$  entry-wise.
- 3. Construct graph  $\hat{G}$  using B as its similarity matrix.
- 4. Partition  $\hat{G}$  into K disconnected subgraphs.

# Simulation Study

#### Simulation setup:

- 1.  $Z_1, ..., Z_n \stackrel{iid}{\sim} Categorical(1/K, ..., 1/K)$
- 2.  $\lambda_{ik} \stackrel{iid}{\sim} Beta(a_{ik}, b_{ik})$   $a_{ik} = \begin{cases} 2 & z_i = k \\ 1 & z_i \neq k \end{cases}, b_{ik} = \begin{cases} 1 & z_i = k \\ 2 & z_i \neq k \end{cases}$
- 3.  $P_{ij} = \lambda_{iz_j} \lambda_{jz_i}$
- 4.  $A \sim BernoulliGraph(P)$



#### Conclusion

- 1. The PABM is a recently developed flexible block model that can be used to describe many graphs with community structure.
- 2. Likelihood maximization is NP-complete for block models, so we need to take a different approach to community detection.
- 3. The GRDPG, which describes all block models, motivates a spectral approach to statistical inference on graphs.
- 4. Under the GRDPG framework, the PABM is induced by a latent configuration in  $\mathbb{R}^{K^2}$  consisting of K K-dimensional subspaces that are all orthogonal to each other.
- 5. The latent configuration of the PABM under the GRDPG framework leads to two methods for community detection, both of which have nice theoretical asymptotic properties.

#### Thank you

Code and draft of the paper available at https://github.com/johneverettkoo/pabm-grdpg

R package coming soon at https://github.com/johneverettkoo/pabm