

Popularity Adjusted Block Models are  
Generalized Random Dot Product Graphs  
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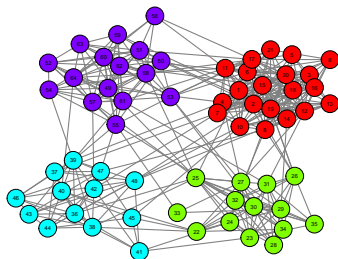


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# Community Detection for Networks



How can we cluster the nodes of a network?

Statistical inference (parametric approach):

1. Define a generative model for graph:  $G \mid z_1, \dots, z_n, \vec{\theta} \sim P(\vec{z}, \vec{\theta})$ .
2. Develop a method for obtaining estimators:  $f(G) = (\hat{\vec{z}}, \hat{\vec{\theta}})$ .
3. Describe asymptotic properties of estimators:  $(\hat{\vec{z}}, \hat{\vec{\theta}}) \rightarrow (\vec{z}, \vec{\theta})$ .

# Overview

1. Block Models and the Popularity Adjusted Block Model
2. Generalized Random Dot Product Graphs
3. Connecting the PABM to the GRDPG
4. Community Detection for the PABM

## Block Models

# Bernoulli Graphs

Let  $G = (V, E)$  be an undirected and unweighted graph with  $|V| = n$ .

$G$  is described by adjacency matrix  $A$  such

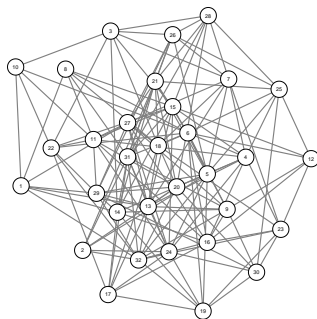
that  $A_{ij} = \begin{cases} 1 & \exists \text{ edge between } i \text{ and } j \\ 0 & \text{else} \end{cases}$

$A_{ji} = A_{ij}$  and  $A_{ii} = 0 \forall i, j \in [n]$ .

$A \sim \text{BernoulliGraph}(P)$  iff:

1.  $P \in [0, 1]^{n \times n}$  describes edge probabilities between pairs of vertices.
2.  $A_{ij} \stackrel{\text{ind}}{\sim} \text{Bernoulli}(P_{ij})$  for each  $i < j$ .

**Example 1:** If every entry  $P_{ij} = \theta$ , then  $A \sim \text{BernoulliGraph}(P)$  is an Erdos-Renyi graph. For this model,  $A_{ij} \stackrel{\text{iid}}{\sim} \text{Bernoulli}(\theta)$ .



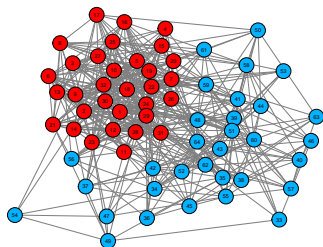
# Block Models

Suppose each vertex  $v_1, \dots, v_n$  has labels  $z_1, \dots, z_n \in \{1, \dots, K\}$ , and each  $P_{ij}$  depends on labels  $z_i$  and  $z_j$ .

Then  $A \sim \text{BernoulliGraph}(P)$  is a *block model*.

**Example 2:** Stochastic Block Model with two communities

- $z_1, \dots, z_n \in \{1, 2\}$
- $$P_{ij} = \begin{cases} p & z_i = z_j = 1 \\ q & z_i = z_j = 2 \\ r & z_i \neq z_j \end{cases}$$
- To make this an assortative SBM, set  $pq > r^2$ .
- In this example,  $p = 1/2$ ,  $q = 1/4$ , and  $r = 1/8$ .



# Block Models

## Erdos-Renyi Model (1959)

- $P_{ij} = \theta$  (not a block model)
- 1 parameter  $\theta$

## Stochastic Block Model (Lorrain and White, 1971)

- $P_{ij} = \theta_{z_i z_j}$
- $K(K + 1)/2$  parameters  $\theta_{kl}$

## Degree Corrected Block Model (Karrer and Newman, 2011)

- $P_{ij} = \theta_{z_i z_j} \omega_i \omega_j$
- $K(K + 1)/2 + n$  parameters  $\theta_{kl}, \omega_i$

## Popularity Adjusted Block Model (Sengupta and Chen, 2017)

- $P_{ij} = \lambda_{iz_j} \lambda_{jz_i}$
- $Kn$  parameters  $\lambda_{ik}$



# Popularity Adjusted Block Model

**Def** Popularity Adjusted Block Model (Sengupta and Chen, 2017):

Let each vertex  $i \in [n]$  have  $K$  popularity parameters  $\lambda_{i1}, \dots, \lambda_{iK} \in [0, 1]$ . Then  $A \sim \text{PABM}(P)$  if each  $P_{ij} = \lambda_{iz_j} \lambda_{jz_i}$ , e.g., if  $z_i = k$  and  $z_j = l$ ,  $P_{ij} = \lambda_{il} \lambda_{jk}$ .

**Lemma** (Noroozi, Rimal, and Pensky, 2020):

$A$  is sampled from a PABM if  $P$  can be described as:

1. Let each  $P^{(kl)}$  denote the  $n_k \times n_l$  matrix of edge probabilities between communities  $k$  and  $l$ .
2. Organize popularity parameters as vectors  $\lambda^{(kl)} \in \mathbb{R}^{n_k}$  such that  $\lambda_i^{(kl)} = \lambda_{k_i l}$  is the popularity parameter of the  $i^{\text{th}}$  vertex of community  $k$  towards community  $l$ .
3. Each block can be decomposed as  $P^{(kl)} = \lambda^{(kl)} (\lambda^{(lk)})^\top$ .

**Notation:**  $A \sim \text{PABM}(\{\lambda^{(kl)}\}_K)$ .

## Generalized Random Dot Product Graphs

# (Generalized) Random Dot Product Graph Model

Random Dot Product Graph  $A \sim \text{RDPG}(X)$   
(Young and Scheinerman, 2007)

- Latent vectors  $x_1, \dots, x_n \in \mathbb{R}^d$  such that  $x_i^\top x_j \in [0, 1]$
- $A \sim \text{BernoulliGraph}(XX^\top)$  where  $X = \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^\top$

Generalized Random Dot Product Graph  $A \sim \text{GRDPG}_{p,q}(X)$   
(Rubin-Delanchy, Cape, Tang, Priebe, 2020)

- Latent vectors  $x_1, \dots, x_n \in \mathbb{R}^{p+q}$  such that  $x_i^\top I_{p,q} x_j \in [0, 1]$   
and  $I_{p,q} = \text{blockdiag}(I_p, -I_q)$
- $A \sim \text{BernoulliGraph}(XI_{p,q}X^\top)$  where  $X = \begin{bmatrix} x_1 & \cdots & x_n \end{bmatrix}^\top$

If latent vectors  $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} F$ , then we write  
 $(A, X) \sim \text{RDPG}(F, n)$  or  $(A, X) \sim \text{GRDPG}_{p,q}(F, n)$ .

# (Generalized) Random Dot Product Graph Model

## Recovery/Estimation

Want to estimate  $X$  from  $A$ , or alternatively, interpoint distances, inner products, or angles.

## Adjacency Spectral Embedding

To embed in  $\mathbb{R}^d$ ,

1. Compute  $A \approx \hat{V} \hat{\Lambda} \hat{V}^\top$  where  $\hat{\Lambda} \in \mathbb{R}^{d \times d}$  and  $\hat{V} \in \mathbb{R}^{n \times d}$ .

For RDPG, use  $d$  greatest eigenvalues; for GRDPG, use  $p$  most positive and  $q$  most negative eigenvalues.

2. For RDPG, let  $\hat{X} = \hat{V} \hat{\Lambda}^{1/2}$ ; for GRDPG, let  $\hat{X} = \hat{V} |\hat{\Lambda}|^{1/2}$ .

RDPG:  $\max_i \|\hat{X}_i - W_n X_i\| \xrightarrow{a.s.} 0$  (Athreya et al., 2018)

GRDPG:  $\max_i \|\hat{X}_i - Q_n X_i\| \xrightarrow{a.s.} 0$  (Rubin-Delanchy et al., 2020)

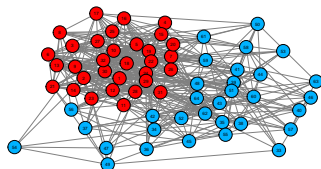
## Connecting the PABM to the GRDPG

# Connecting Block Models to the (G)RDPG Model

All Bernoulli Graphs are RDPG (if  $P$  is positive semidefinite) or GRDPG (in general).

**Example 2** (cont'd): Assortative SBM ( $pq > r^2$ ) with  $K = 2$

$$P_{ij} = \begin{cases} p & z_i = z_j = 1 \\ q & z_i = z_j = 2 \\ r & z_i \neq z_j \end{cases}$$



$$P = \begin{bmatrix} P^{(11)} & P^{(12)} \\ P^{(21)} & P^{(22)} \end{bmatrix} = XX^\top$$

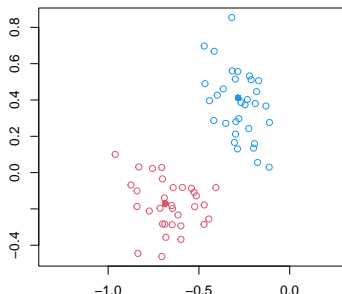
$$X = \begin{bmatrix} \sqrt{p} & 0 \\ \vdots & \vdots \\ \sqrt{p} & 0 \\ \sqrt{r^2/p} & \sqrt{q - r^2/p} \\ \vdots & \vdots \\ \sqrt{r^2/p} & \sqrt{q - r^2/p} \end{bmatrix}$$

# Connecting Block Models to the (G)RDPG Model

**Example 2** (cont'd): If we want to perform community detection,

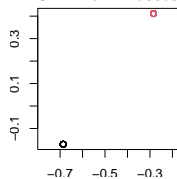
1. Note that  $A$  is a RDPG because  $P = XX^\top$ .
2. Compute the ASE  $A \approx \hat{X}\hat{X}^\top$  with  $\hat{X} = \hat{V}\hat{\Lambda}^{1/2}$ .
3. Apply clustering algorithm (e.g.,  $K$ -means) to  $\hat{X}$ , noting that as  $n \rightarrow \infty$ , the ASE approaches point masses.

ASE of the adjacency matrix drawn from SBM

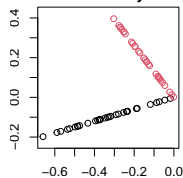


# Connecting Block Models to the (G)RDPG Model

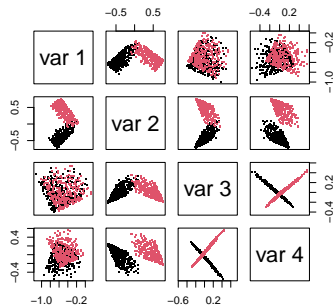
**SBM: Point masses**



**DCBM: Rays**



**PABM: Orthogonal subspaces**





# Connecting the PABM to the GRDPG

**Theorem (KTT):**  $A \sim \text{PABM}(\{\lambda^{(kl)}\}_K)$  is equivalent to  $A \sim \text{GRDPG}_{p,q}(XU)$  with

- $p = K(K+1)/2$ ,  $q = K(K-1)/2$
- $U \in \mathbb{O}(K^2)$
- $X \in \mathbb{R}^{n \times K^2}$  is block diagonal and composed of  $\{\lambda^{(kl)}\}_K$  with each block corresponding to a community.

$$X = \begin{bmatrix} \Lambda^{(1)} & \dots & 0 \\ 0 & \ddots & 0 \\ 0 & \dots & \Lambda^{(K)} \end{bmatrix} \in \mathbb{R}^{n \times K^2}$$

$$\Lambda^{(k)} = \begin{bmatrix} \lambda^{(k1)} & \dots & \lambda^{(kK)} \end{bmatrix} \in \mathbb{R}^{n_k \times K}$$

# Connecting the PABM to the GRDPG

$$X = \begin{bmatrix} \Lambda^{(1)} & \dots & 0 \\ 0 & \ddots & 0 \\ 0 & \dots & \Lambda^{(K)} \end{bmatrix} \quad U \in \mathbb{O}(K^2)$$

$$A \sim \text{PABM}(\{\lambda^{(kl)}\}_K) \iff A \sim \text{GRDPG}_{p,q}(XU)$$

**Remark 1** (orthogonality of subspaces): If  $y_i^\top$  and  $y_j^\top$  are two rows of  $XU$  corresponding to different communities, then  $y_i^\top y_j = 0$ .

**Remark 2** (non-uniqueness of the latent configuration):  
If  $A \sim \text{GRDPG}_{p,q}(Y)$ , then  $A \sim \text{GRDPG}_{p,q}(YQ)$  for any  $Q$  in the indefinite orthogonal group with signature  $p, q$ .

**Remark 3:** Communities correspond to subspaces even with linear transformation  $Q \in \mathbb{O}(p, q)$ , but this may break the orthogonality property.

## Community Detection for the PABM

# Orthogonal Spectral Clustering

**Theorem (KTT):** If  $P = V\Lambda V^\top$  and  $B = nVV^\top$ , then  $B_{ij} = 0$  if  $z_i \neq z_j$ .

**Algorithm:** Orthogonal Spectral Clustering:

1. Let  $V$  be the eigenvectors of  $A$  corresponding to the  $K(K+1)/2$  most positive and  $K(K-1)/2$  most negative eigenvalues.
2. Compute  $B = |nVV^\top|$  applying  $|\cdot|$  entry-wise.
3. Construct graph  $G$  using  $B$  as its similarity matrix.
4. Partition  $G$  into  $K$  disconnected subgraphs.

**Theorem (KTT):** Let  $\hat{B}_n$  with entries  $\hat{B}_n^{(ij)}$  be the affinity matrix from OSC. Then  $\forall$  pairs  $(i, j)$  belonging to different communities and sparsity factor satisfying  $n\rho_n = \omega((\log n)^{4c})$ ,

$$\max_{i,j} \hat{B}_n^{(ij)} = O_P\left(\frac{(\log n)^c}{\sqrt{n\rho_n}}\right)$$

# Sparse Subspace Clustering

**Corollary:** The ASE of  $A \sim \text{PABM}(\{\lambda^{(kl)}\}_K)$  lies near a collection of  $K$ -dimensional subspaces in  $K^2$  dimensions.

**Algorithm:** Sparse Subspace Clustering (Elhamifar & Vidal, 2009):

1. Solve  $n$  optimization problems  $c_i = \arg \min_c \|c\|_1$  subject to  $x_i = X^\top c$  and  $c^{(i)} = 0$ .

This is typically performed via LASSO:

$$c_i = \arg \min \frac{1}{2} \|x_i - X_{-i}^\top c\|_2^2 + \lambda \|c\|_1$$

2. Compile solutions  $C = \begin{bmatrix} c_1 & \cdots & c_n \end{bmatrix}$ .
3. Construct affinity matrix  $B = |C| + |C^\top|$ .

# Sparse Subspace Clustering

## Theorem (KTT):

Let

- $P_n$  describe the edge probability matrix of the PABM with  $n$  vertices, and  $A_n \sim \text{BernoulliGraph}(P_n)$ ;
- $\hat{V}_n$  be the matrix of eigenvectors of  $A_n$  corresponding to the  $K(K+1)/2$  most positive and  $K(K-1)/2$  most negative eigenvalues.

Then

- For some  $\lambda > 0$  and  $N < \infty$ ,  $\sqrt{n}\hat{V}_n$  obeys the Subspace Detection Property with probability 1 when  $n > N$ .

Remarks:

- For large  $n$ , we can identify  $\lambda$  for SDP (Wang and Xu, 2016).
- SDP does not guarantee community detection.

# Simulation Results

