

JOHNATHAN FERCHER DA ROSA

Tech Lead (Staff Software Engineer)

 johnfercher.com

 johnathan-fercher


 johnfercher



EXPERIENCE

Tech Lead

Mercado Libre

 2024/01 – Nowadays

 Remote

- I am working in FOS-In team developing features related to in-bound process.

Senior Software Engineer

Gympass

 2023/08 – 2023/12

 Remote

- I worked in the PACE team developing features related to check-in and booking.

Software Engineer II

Uber

 2022/05 – 2023/04

 Remote

- I worked in Ambient Safety team developing features related to safety.

Senior Analyst Developer

Mercado Libre

 2019/04 – 2022/04

 Remote

- I worked in the follow teams (TMS, FOS, XD-Orchestrator) developing features related to logistics.

Junior Analyst Developer

Braspag (Cielo)

 2017/08 – 2019/01

 Rio de Janeiro

- I worked in Risk team developing features related to antifraud.

Scientific Internship

National Laboratory of Scientific Computing (LNCC)

 2014/03 – 2015/02

 Petrópolis

- In the LNCC, I worked at Laboratory of Collaborative Environments and Applied Multimedia (ACiMA) with virtual reality.

Trainee of Research and Development

Allen Informática

 2013/03 – 2014/01

 Petrópolis

- I worked in P&D team developing features of many projects.

EDUCATION

M.Sc. in Robotics

Military Institute of Engineering

 2015/01 – 2017/01  Rio de Janeiro

Dissertation title: Construction of a Framework of Path Planning and Trajectory Control in Real Time of Multiple Robots

B.Tech. in Information and Communications Technology

FAETERJ

 2012/01 – 2015/01  Petrópolis

Monograph title: Construction of a robot soccer team to the category IEEE Very Small Size Soccer

LANGUAGES

Portuguese



English



Spanish



SKILLS

Golang

Object-Oriented Programming

C++

Design Patterns

Microservices

Domain-Driven Design

Observability

Software Architecture

SOLID

C#

Automated Testing

Messaging

REST

Docker

MySQL

ElasticSearch

Datadog

Document Database

Key-Value Database

Kibana

NewRelic

Git/Github

Linux & MacOS

Jira

Slack

HONORS & AWARDS



Runner-up Robocup 2D Soccer Simulation League

Latin American Robotics Competition



4th Place - IEEE Very Small Size Soccer

Latin American Robotics Competition

PROJECTS

Maroto

OpenSource (+1500 stars on Github)

- Maroto is an opensource go lang library that allows the generation of PDFs in an easy way. The main focus of maroto is to be simple, with that in mind, the library has a grid system based on Bootstrap and there are some components that aid the development of complex documents.

Blog

Medium

- My personal blog where I write about many subjects, in general: programming, robotics, academic, games and hack.

Presentations

Opened and Internal Events

- Campus Party, The Developer's Conference, DevFest - SUL (Google Developers Group Event), MELI Tech Day (Mercado Libre Internal Event), TechTalk (Braspag Internal Event), CCOMP Talk (UNIFESO Event) and Various Academic Events.

TaleSlab

OpenSource

- TaleSlab is an opensource project that generates maps (slabs) to the game TaleSpire. Was done a clean room reverse engineering in the game protocol to understand how to serialize and deserialize the data correctly, and was developed a map generation engine.

VSS-SDK

OpenSource

- The VSS-SDK is an opensource project that aid to build robot soccer teams. The SDK focus on IEEE Very Small Size Soccer category present on Latin-American Robotics Competition.

SIRLab

Laboratory

- The SIRLab is a laboratory from FAETERJ-Petrópolis which realizes research in robotics. The laboratory has projects of Rescue Simulation, Smart Home, Robot Soccer (IEEE Very Small Size Soccer) and Soccer Simulation (RoboCup 2D Soccer Simulation).

Volunteer

Staff

- Google Developers Group, Petrópolis.
- Brazilian Robotics Olympiad

PUBLICATIONS

Journal Articles

- Rosa, J., & Rosa, P. (2020). Multiple path planning of terrestrial robots in dynamic environments. *Military journal of science and technology*, 38, 27–36.

Conference Proceedings

- Rosa, J. F., & Ferreira Rosa, P. F. (2017). A general approach to the problem of path planning and trajectory control of multiple terrestrial robots in dynamic environments. In *2017 brazilian symposium on intelligent automation*, Porto Alegre, Brazil.
- Rosa, J. F., & Ferreira Rosa, P. F. (2016). Construction of a framework of path planning and trajectory control in real time of multiple robots. In *III workshop on msc dissertation and phd thesis in robotics*, Recife, Brazil.