

In this note we explore the space of cluster adjacent functions on A_3 . We would particularly like to understand how much of this space is spanned by $f_{A_2}^{++}$ and $f_{A_2}^{+-}$ evaluated on the 6 A_2 subalgebras of A_3 , and if there is a natural cluster algebraic way to express $\mathcal{E}_6^{(2)}$.

Cluster definitions

Our generic A_3 seed will be $x_1 \rightarrow x_2 \rightarrow x_3$. Then we will define our \mathcal{X} -coordinates as

$$\begin{aligned}
 x_{1,1} &= 1/x_1 & x_{1,2} &= x_3 & v_1 &= \frac{(1+x_2)(1+x_1+x_1x_2+x_1x_2x_3)}{x_2x_3} \\
 x_{2,1} &= \frac{1+x_1+x_1x_2}{x_1x_2x_3} & x_{2,2} &= \frac{1+x_1+x_1x_2}{x_2} & v_2 &= x_2(1+x_3) \\
 x_{3,1} &= \frac{1+x_2+x_2x_3}{x_3} & x_{3,2} &= x_1(1+x_2+x_2x_3) & v_3 &= \frac{1+x_1}{x_1x_2} \\
 e_1 &= \frac{1+x_1+x_1x_2+x_1x_2x_3}{(1+x_1)x_3} & e_2 &= \frac{x_2x_3}{1+x_2} & e_3 &= \frac{1+x_1}{x_1x_2(1+x_3)} \\
 e_4 &= x_1(1+x_2) & e_5 &= \frac{x_2(1+x_3)}{1+x_1+x_1x_2+x_1x_2x_3} & e_6 &= 1/x_2.
 \end{aligned} \tag{1}$$

Note that these definitions are different from 1401.6446 (the map is: starting with the expressions in 1401.6446, take $x_i \rightarrow 1/x_i$, and then an overall inversion (i.e. $v_i \rightarrow 1/v_i$, etc)). This is the result of having a different convention for converting \mathcal{A} to \mathcal{X} -coordinates, and is a minor but annoying change to make.

In $\text{Gr}(4,6)$ language, we take

$$x_1 = \frac{\langle 1236 \rangle \langle 2345 \rangle}{\langle 1234 \rangle \langle 2356 \rangle}, \quad x_2 = \frac{\langle 1235 \rangle \langle 3456 \rangle}{\langle 1356 \rangle \langle 2345 \rangle}, \quad x_3 = \frac{\langle 1456 \rangle \langle 2356 \rangle}{\langle 1256 \rangle \langle 3456 \rangle}, \tag{2}$$

and then the \mathcal{X} -coordinates are

$$\begin{aligned}
 x_{1,1} &= \frac{\langle 1234 \rangle \langle 2356 \rangle}{\langle 1236 \rangle \langle 2345 \rangle} & x_{1,2} &= \frac{\langle 1456 \rangle \langle 2356 \rangle}{\langle 1256 \rangle \langle 3456 \rangle} & v_1 &= \frac{\langle 1246 \rangle \langle 1345 \rangle}{\langle 1234 \rangle \langle 1456 \rangle} \\
 x_{2,1} &= \frac{\langle 1256 \rangle \langle 1346 \rangle}{\langle 1236 \rangle \langle 1456 \rangle} & x_{2,2} &= \frac{\langle 1346 \rangle \langle 2345 \rangle}{\langle 1234 \rangle \langle 3456 \rangle} & v_2 &= \frac{\langle 1235 \rangle \langle 2456 \rangle}{\langle 1256 \rangle \langle 2345 \rangle} \\
 x_{3,1} &= \frac{\langle 1245 \rangle \langle 3456 \rangle}{\langle 1456 \rangle \langle 2345 \rangle} & x_{3,2} &= \frac{\langle 1236 \rangle \langle 1245 \rangle}{\langle 1234 \rangle \langle 1256 \rangle} & v_3 &= \frac{\langle 1356 \rangle \langle 2346 \rangle}{\langle 1236 \rangle \langle 3456 \rangle} \\
 e_1 &= \frac{\langle 1246 \rangle \langle 3456 \rangle}{\langle 1456 \rangle \langle 2346 \rangle} & e_2 &= \frac{\langle 1235 \rangle \langle 1456 \rangle}{\langle 1256 \rangle \langle 1345 \rangle} & e_3 &= \frac{\langle 1256 \rangle \langle 2346 \rangle}{\langle 1236 \rangle \langle 2456 \rangle} \\
 e_4 &= \frac{\langle 1236 \rangle \langle 1345 \rangle}{\langle 1234 \rangle \langle 1356 \rangle} & e_5 &= \frac{\langle 1234 \rangle \langle 2456 \rangle}{\langle 1246 \rangle \langle 2345 \rangle} & e_6 &= \frac{\langle 1356 \rangle \langle 2345 \rangle}{\langle 1235 \rangle \langle 3456 \rangle}.
 \end{aligned} \tag{3}$$

These are now the same as 1401.6446.

Symmetries

A_3 has a six-fold cyclic symmetry, which we denote by σ :

$$\sigma : x_1 \mapsto \frac{x_2}{1 + x_1 + x_1 x_2}, \quad x_2 \mapsto \frac{(1 + x_1) x_3}{1 + x_1 + x_1 x_2 + x_1 x_2 x_3}, \quad x_3 \mapsto \frac{1 + x_1 + x_1 x_2}{x_1 x_2 x_3}, \quad (4)$$

and which permutes the \mathcal{X} -coordinates by

$$\sigma : x_{i,j} \mapsto x_{i+1,j+1}, \quad v_i \mapsto v_{i+1}, \quad e_i \mapsto e_{i+1} \quad (5)$$

(where all of the indices are understood to be mod $\{2,3,6\}$ where it makes sense). In $\text{Gr}(4,6)$ language, σ is the standard $i \mapsto i + 1$ cyclic symmetry.

A_3 also has a two-fold flip symmetry, which we denote by τ :

$$\tau : x_1 \mapsto \frac{1}{x_3}, \quad x_2 \mapsto \frac{1}{x_2}, \quad x_3 \mapsto \frac{1}{x_1}, \quad (6)$$

and which permutes the \mathcal{X} -coordinates by

$$\begin{aligned} \tau : x_{1,j} &\leftrightarrow x_{1,j+1}, & x_{2,j} &\leftrightarrow x_{3,j+1}, & v_2 &\leftrightarrow v_3, \\ e_1 &\leftrightarrow 1/e_5, & e_2 &\leftrightarrow 1/e_4, & e_3 &\leftrightarrow 1/e_3, & e_6 &\leftrightarrow 1/e_6. \end{aligned} \quad (7)$$

The $\text{Gr}(4,6)$ flip is traditionally written as $i \rightarrow 7 - i$, which in the A_3 language is equivalent to $\tau\sigma^{-1}$.

Strictly speaking, τ is an automorphism only on the space of \mathcal{X} -coordinates, not on the full cluster algebra. To elevate τ to an automorphism on the full cluster algebra: take a cluster with coordinates $\{\mathcal{X}_1, \mathcal{X}_2, \mathcal{X}_3\}$, map them to $\{1/\tau(\mathcal{X}_1), 1/\tau(\mathcal{X}_2), 1/\tau(\mathcal{X}_3)\}$ and then swap the direction of all of the arrows in the cluster (i.e. take $b_{ij} \rightarrow -b_{ij}$). The result will now again be a cluster in A_3 . This is easiest to see in the seed cluster, which is invariant under τ :

$$\{x_1 \rightarrow x_2 \rightarrow x_3\} \mapsto \{1/\tau(x_1) \leftarrow 1/\tau(x_2) \leftarrow 1/\tau(x_3)\} = \{x_3 \leftarrow x_2 \leftarrow x_1\}. \quad (8)$$

The reason for this weirdness is that cluster automorphisms are only defined at the level of \mathcal{A} -coordinates. But since we want to deal with actual functions/Bloch-group elements, it makes more sense to list the “automorphisms” w.r.t. \mathcal{X} -coordinates and accept that there is this slight funny business.

Integrable Symbol

Imposing integrability on a generic symbol of weight 4 with arguments drawn from (1) leaves us with 1351 free parameters.

\mathcal{A} -adjacency vs. \mathcal{X} -adjacency

The two criteria we consider are:

- cluster \mathcal{A} -adjacency (only $\{\langle i \ i + 2 \rangle, \langle i \ i + 3 \rangle\}$ +frozen can appear),
- cluster \mathcal{X} -adjacency (only $\{\mathcal{X}_i, \mathcal{X}_{i+1}\}$ can appear).

Cluster \mathcal{A} -adjacency fixes 919 parameters, leaving us with 432. I haven't checked cluster \mathcal{X} -adjacency yet.

Imposing cluster-y coproduct

As was the case for A_2 , cluster \mathcal{A} -adjacency at symbol level already imposes a cluster-y coproduct at the level of $B_2 \wedge B_2$. Imposing this for $B_3 \otimes \mathbb{C}^*$ fixes 60 parameters, leaving us with 372.

Imposing symmetries

We now impose that the function respect the automorphisms of A_3 , as discussed above. We will now tabulate how many free parameters remain for each of the 4 possible sign choices:

$$f_{A_3}: \begin{array}{cccc} \sigma^+ \tau^+ & \sigma^+ \tau^- & \sigma^- \tau^+ & \sigma^- \tau^- \\ \hline 42 & 25 & 21 & 36 \end{array}$$

Local Coproduct

Only $f_{A_3}^{+-}$ and $f_{A_3}^{--}$ have non-zero $B_2 \wedge B_2$, and they have 6 and 2 free parameters in this space, respectively. Requiring that these take a local form fixes all of these parameters, killing off the $B_2 \wedge B_2$ for $f_{A_3}^{+-}$ and leaving us with the “traditional” f_{A_3} for $\{--\}$, which has $B_2 \wedge B_2 = \sum_i \{x_{i,1}\}_2 \wedge \{x_{i,2}\}_2$.