

Programming Assignment 2

```
In [ ]: # Import what you need
```

Question 1

Study the Python notebook on image manipulation. Load an image from your working folder as a tensor of order 3. Perform the following on the images by simply manipulating this tensor. **You are not allowed to use any specialized libraries or any specialized functions, only basic Python and Numpy routines.**

- (A) Crop the image to 60% of its size symmetrically from the center.
Display the resulting image.

```
In [35]: # Your code here
import numpy as np
import matplotlib.pyplot as plt
import matplotlib.image as mpimg

##THIS FUNC IS TAKEN FROM IMAGE MANIPULATION MODULE
def display_image(arr_image,color_map=None,dim=(10,20)):
    plt.figure(figsize=dim)
    plt.axis('off')
    plt.imshow(arr_image, cmap=color_map)
    plt.show()

pix = mpimg.imread('Lycoris.jpeg')

print("Tensor: ", pix.shape, "\n")
display_image(pix)

height, width, color = pix.shape
centerY = height/2
centerX = width/2

##new image's height
heightN = int(height * 0.6)
widthN = int(width * 0.6)
print(heightN,widthN)

##calculate the gaps on top and bottom
topGap = int((height - heightN) / 2)
sideGap = int((width - widthN) / 2)

## not allowed to use this cropping method;
#pixN = pix[ topGap: topGap+heightN , sideGap: sideGap+widthN, :]

pixL = np.zeros((heightN, widthN, color), dtype=np.uint8)
```

```
for i in range(heightN):
    for j in range(widthN):
        pixN[i,j] = pix[i+topGap,j+sideGap]

print("Tensor: ", pixN.shape, "\n")
display_image(pixN)
```

Tensor: (2890, 2890, 3)



1734 1734

Tensor: (1734, 1734, 3)



(B) Display the image upon flipping it horizontally. Left becomes right and right becomes left.

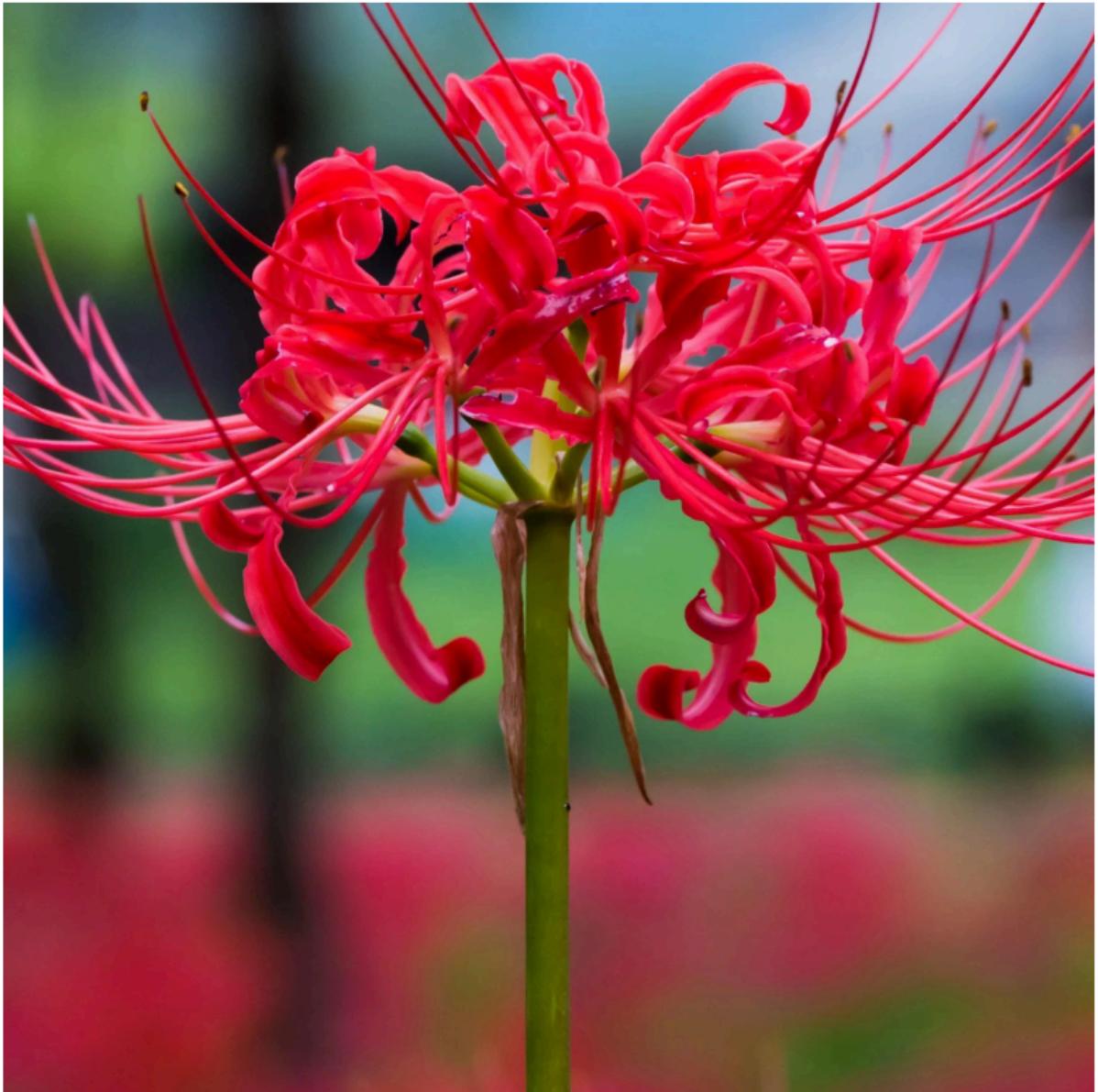
```
In [65]: # Your code here

pixL = np.zeros((heightN, widthN, color), dtype=np.uint8)

for i in range(heightN):
    for j in range(widthN):
        #reverse the second loop and write from right ot left in to the new
        pixL[i,j] = pix[i+topGap,sideGap+widthN-j]

print("Tensor: ", pixL.shape, "\n")
display_image(pixL)
```

Tensor: (1734, 1734, 3)



(C) Display the image after flipping it vertically. Top becomes bottom and bottom becomes top.

```
In [69]: # Your code here

pixT = np.zeros((heightN, widthN, color), dtype=np.uint8)

for i in range(heightN):
    for j in range(widthN):
        #reverse the second loop and erite from right ot left in to the new
        pixT[i,j] = pix[topGap+heightN-i,sideGap+j]

print("Tensor: ", pixT.shape, "\n")
display_image(pixT)
```

Tensor: (1734, 1734, 3)



(D) Rotate the image by 90° counter clock-wise. Display the resulting image.

```
In [73]: # Your code here

pix90 = np.zeros((widthN, heightN, color), dtype=np.uint8)

for i in range(heightN):
    for j in range(widthN):
        #reverse the second loop and erite from right ot left in to the new
        pix90[j,i] = pix[topGap+i,sideGap+j]

print("Tensor: ", pix90.shape, "\n")
display_image(pix90)
```

Tensor: (1734, 1734, 3)



Question 2

Use the code provided in the Python notebook on linear systems and answer the following.

- (A) **Modify** the code in the function for Gaussian elimination so that it also [allows row exchanges in general](#). Solve the following system by using your code.

$$\begin{bmatrix} 0 & 1 & 2 \\ 5 & -2 & 6 \\ 3 & 1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 9 \\ 2 \end{bmatrix}$$

```
In [75]: # Gauss-Jordan Elimination (without row-swapping)
def findRREF(A):
    """
    Input: a general rectangular matrix
    Output: the row reduced echelon form of the matrix A
    by using Gauss-Jordan elimination
    """

    augA = np.copy(A)
    m,n=augA.shape
    print("Augmented matrix: \n",augA)
    for k in range(m):
        # Check that the matrix is not rank deficient
        if np.abs(augA[k,k]) < 10**(-15):
            for i in range(k+1, m):

                ## use > 10**(-15) to check if the [i,k] is 0, if so swap the
                if np.abs(augA[i, k]) > 10**(-15):
                    augA[[k, i]] = augA[[i, k]]
                    print('Swapped rows',i,'and',k)
                    break

                #####
            else:
                exit("The given matrix is singular or requires row swapping"
# Convert the pivot element to 1
                augA[k,:] = augA[k,:]/augA[k,k]

                for i in range(m):
                    if i==k:
                        continue
                    z = -augA[i,k]
                    # Change the entire rows (k+1)st onward
                    augA[i,:] = augA[i,:]+z*augA[k,:]
                    print("Pass {}:\n".format(k+1))
                    print(augA)
    return augA

np.set_printoptions(precision=4)
A = np.array([[0,1,2,3],
              [5,-2,6,9],
              [3,1,-2,2]],dtype=float)
augA_modified = findRREF(A)
# The last column is the solution
soln = augA_modified[:,3:]
print("\n The Solution is \n",soln)
```

```
Augmented matrix:  
[[ 0.  1.  2.  3.]  
 [ 5. -2.  6.  9.]  
 [ 3.  1. -2.  2.]]  
Swapped rows 1 and 0  
Pass 1:
```

```
[[ 1. -0.4  1.2  1.8]  
 [ 0.   1.   2.   3. ]  
 [ 0.   2.2 -5.6 -3.4]]
```

```
Pass 2:
```

```
[[ 1.   0.   2.   3.]  
 [ 0.   1.   2.   3.]  
 [ 0.   0.  -10. -10.]]
```

```
Pass 3:
```

```
[[ 1.   0.   0.   1.]  
 [ 0.   1.   0.   1.]  
 [-0. -0.   1.   1.]]
```

The Solution is

```
[[1.]  
[1.]  
[1.]]
```

(B) **Use or modify** the provided code to write a function for finding the inverse of any square matrix. Use this to find the inverse of the following. Show the output.

```
In [98]: # Your code here  
def invByRREF(A):  
    m,n=A.shape  
    if m!=n:  
        exit("To find inverse, please provide a square matrix only.")  
    # Appropriate augmented matrix. One line  
    augA = np.copy(A)  
    modified_augA = findRREF(augA)  
    # Take appropriate slice of modified_augA for inverse  
    print('RRREF form:\n',modified_augA)  
    invA = np.zeros((m,n))  
    for i in range(m):  
        for j in range(n):  
            invA[j,i] = modified_augA[i,j]  
  
    return invA  
  
A = np.array([[1,1,4],  
             [3,2,4],  
             [1,1,6]],dtype=float)  
inv = invByRREF(A)  
print('Inverted matrix: \n',inv)
```

Augmented matrix:

```
[[1. 1. 4.]  
[3. 2. 4.]  
[1. 1. 6.]]
```

Pass 1:

```
[[ 1. 1. 4.]  
[ 0. -1. -8.]  
[ 0. 0. 2.]]
```

Pass 2:

```
[[ 1. 0. -4.]  
[-0. 1. 8.]  
[ 0. 0. 2.]]
```

Pass 3:

```
[[ 1. 0. 0.]  
[-0. 1. 0.]  
[ 0. 0. 1.]]
```

RRREF form:

```
[[ 1. 0. 0.]  
[-0. 1. 0.]  
[ 0. 0. 1.]]
```

Inverted matrix:

```
[[ 1. -0. 0.]  
[ 0. 1. 0.]  
[ 0. 0. 1.]]
```

(C) **Modify** the code to write a function for finding the determinant of a general square matrix. Show the output for a matrix of random integer entries (6×6). Use the built-in function np.linalg.det() to find the determinant of the same matrix for comparison.

In [142...]

```
# Your code here  
def find_det(A):  
    m,n = A.shape  
    mA = np.copy(A)  
    det = 0  
    if m!=n:  
        exit("To find determinant, please provide a square matrix only.")  
  
    ##base case for recursion to stop  
    if m == 2:  
        return (mA[0,0]*  
                mA[1,1]-  
                mA[0,1]*  
                mA[1,0])  
    else:  
        for i in range(m):  
            ## (-1)**i is for changing sign  
            det = det + (-1)**i * mA[0,i] * find_det(subMatrix(i,mA))  
return det
```

```
#next sub matrix ignoring the kth column, i didnt want to use np.delete
def subMatrix(k,A):
    m,n = A.shape
    mA = np.copy(A)
    subM = np.zeros((m-1,n-1))

    for i in range(1, m):
        cInx= 0; #column index for subM
        for j in range(n):
            if(k==j):
                continue
            subM[i-1,cInx] = mA[i,j]
            cInx +=1
    return subM

A = np.random.rand(6,6)

print(find_det(A))
print(np.linalg.det(A))
```

```
-0.05599039080043465
-0.05599039080043467
```

```
In [132]: for i in range(5):
    print(i)
```

```
0
1
2
3
4
```

```
In [ ]:
```

This notebook was converted to PDF with convert.ploomber.io