EECS 203A HW6 John Liu 25961868

1. Suppose that g(x,y) is a degraded version of an ideal image f(x,y) with

$$g(x,y) = h(x,y) * f(x,y)$$

where h(x, y) is an ideal bandreject filter with parameters D_0 and W.

ideal bandreject filter

- a) Can we recover f(x,y) from g(x,y) using inverse filtering? Explain your answer.
- b) Can we recover f(x,y) from g(x,y) using Wiener filtering? Explain your answer.
- c) Given an input image f(x, y) that gives a corresponding degraded image g(x, y), describe the set of input images that will give the same filtered image g(x, y).

H(u,v) = { 0 if
$$D_0 - \frac{\omega}{2} \le D(u,v) \le D_0 + \frac{\omega}{2}$$

A) if $D(u,v) > D_0 + \frac{\omega}{2}$
Also due to IBRF, when $D_0 - \frac{\omega}{2} \le D(u,v) \le D_0 + \frac{\omega}{2}$. H(u,v)=0

Also dhe to IBRT, when $0.75 \le D(u,v) \le D_0 + \frac{1}{2}$. His inverse filtering b) -: N(x,y) = 0

- .: N(x,y)=0.: Sh(y,v)=0.: Wiener filter becomes threse filter
- ... Some as a). cannot recover f(x, y) from g(x, y) using Wiener filtering
- c) If H(u,v) F(u,v) the same as G(u,v) then get the same g(x,y) which means when $D(u,v) < D_0 \frac{w}{2}$ or $D(u,v) > D_0 + \frac{w}{2}$. i.e. H(u,v) = 1, the input image will give the same filtered image g(x,y)

2. Suppose that g(x,y) is a noisy version of an ideal image f(x,y)

$$g(x,y) = f(x,y) + n(x,y)$$

where the DFT magnitudes have the properties |N(u,v)| = 1 and |F(u,v)| decreases as $u^2 + v^2$ increases. Consider the filters H_1 and H_2 defined in the frequency domain by

$$H_1(u,v) = \frac{1}{1 + 0.01(u^2 + v^2)}$$
 and $H_2(u,v) = \sqrt{H_1(u,v)}$

The filters specified by $H_1(u, v)$ and $H_2(u, v)$ are applied to the image g(x, y).

a) Does $H_1(u, v)$ or $H_2(u, v)$ reduce more noise in g(x, y)? Explain your answer.

b) Does
$$H_1(u, v)$$
 or $H_2(u, v)$ blur the image $g(x, y)$ more? Explain your answer.

a) W2+V2 20

$$|H_1(u,v)| \leq |H_2(u,v)|$$

. H. (u, v) reduces more hoise

H₂(u,v) blurs the image
$$g(x,y)$$
 more.

3. Suppose that a rectangular area in image $f(x,y)$ with vertices $(x,y) = \{(7,3), (7,11), (12,11), (12,3)\}$

appears distorted in image
$$f'(x', y')$$
 with corresponding vertices $(x', y') = \{(6, 5), (6, 13), (12, 11), (12, 3)\}$
Determine the functions $x'(x, y)$ and $y'(x, y)$ using a bilinear model for the distortion.

Determine the functions
$$x'(x,y)$$
 and $y'(x,y)$ using a bilinear model for the distortion.

$$f'(x,y) = f(x,y) + f'(x,y) = f'(x,y) + f'(x,y) + f'(x,y) = f'(x,y) + f'(x,y) + f'(x,y) = f'(x,y) + f'(x,y) + f'(x,y) + f'(x,y) = f'(x,y) + f'(x,y) + f'(x,y) + f'(x,y) + f'(x,y) = f'(x,y) + f'(x,y)$$

$$f'(6.5) = f(7.3)$$
 $f'(6.13) = f(7.11)$. $f(12.11) = f(12.11)$ $f(12.3) = f(12.3)$

 $\Rightarrow \begin{cases} 0 = 1.2 \\ b = 0 \\ C = 0 \end{cases}$

$$f'(x'(x,y),y'(x,y)) = f(x,y)$$

$$(x(x,y), y(x,y)) = f(x,y)$$

$$x'(7.3) = 6$$
, $y'(7.3) = 5$
 $x'(7.11) = 6$, $y'(7.11) = 13$

$$x'(12.11)=12$$
, $y'(12.11)=11$
 $x'(12.3)=12$, $y'(12.3)=3$

$$X'(12.3) = 12$$
, $Y'(12.3) = 3$
 $X'(X,Y) = aX + by + Cxy + d$

$$\begin{cases} 6 = 7a + 3b + 21c + d \\ 6 = 7a + 11b + 77c + d \end{cases}$$

$$\begin{cases} 6 = 70 + 3b + 21c + d \\ 6 = 7a + 11b + 77c + d \\ 12 = 12a + 11b + 132c + d \\ 12 = 12a + 3b + 36c + d \end{cases}$$

$$|12 = 12a + 3b + 36c + d$$

 $y'(x,y) = ex + fy + gxy + h$
 $(5 = 7e + 3f + 21g + h)$

ith vertices
$$(x, y) = \{(7, 3), (7, 11), (12, 11), (13, 12), (14, 12), (15, 12), (15, 12), (16, 13), (16, 13), (17, 11), (17, 12), (18, 12), (19,$$

odel for the distortion.

(1) =
$$f(12.11)$$
 $f(12.3)$ = $f(12.3)$

$$y'(x,y) = ex+fy+gxy+h$$

 $5 = 7e+3f+21g+h$
 $13 = 7e+11f+77g+h$ \Rightarrow $f = 0$ \Rightarrow $y'(x,y) = -0.4x+xy+4.8$
 $3 = 12e+3f+36g+h$ $h = 4.8$

Computer Problem: Define the continuous-space Gaussian function by $G(x,y) = Ae^{-(x^2+y^2)/(2\sigma^2)}$. Generate a 31×31 digital filter q(i,j) over $i = -15, \dots, 0, \dots, 15$ and $j = -15, \dots, 0, \dots, 15$ by sampling G(x,y) so that g(0,0) = A and $g(7,0) = Ae^{-0.5}$. Normalize g(i,j) by finding A so that the sum of the g(i,j) mask values equals one. Degrade the triangle image by convolution with g(i,j). Use the inverse filtering method to restore the image. Submit your code, the g(i,j)mask coefficients, the degraded image, and the restored image. You may use Matlab or other available software to compute DFTs. g(0.0) = A $g(7.0) = Ae^{-0.5} \implies 6 = 7$ code: 'EFCS202A_HW6.m"

g(i): 'mask.csv"

olegraded image: 'triangle_degraded.jpg"

restored image: 'triangle_restored.jpg"