# Section 10: Large sample theory

#### ARE 210

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The section notes are available on the section Github at github.com/johnloeser/are 210 in the "section 10" folder.

## 1 Definitions

- Assume we observe iid  $W = \{W_i\}_{i=1}^n$ , with  $W_i \sim P$ , interested in  $\theta(P)$ 
  - $\hat{\theta}_n$  is a **consistent** estimator of  $\theta$  if  $\hat{\theta}_n \stackrel{p}{\to} \theta$
  - $-\hat{\theta}_n$  is **asymptotically normal** if  $\sqrt{n}(\hat{\theta}_n \theta) \stackrel{d}{\to} N(0, V)$  for some V
  - If  $V_n \stackrel{p}{\to} V$  as defined above, we say it's a **consistent variance estimator**
- Math tricks
  - ULLN (defined below) used repeatedly for convergence of functions, when we want to apply LLN but don't satisfy requirements
  - **MVT**:  $h: \mathbf{R}^p \to \mathbf{R}^q$  continuously differentiable, then  $h(b) = h(\theta) + \frac{\partial h(\tilde{b})}{\partial b}(b \theta)$ , where  $\tilde{b} = \alpha b + (1 \alpha)\theta$  for  $\alpha \in (0, 1)$
  - Note that I'll confusingly use W to either denote the data or a random variable with distribution P
- Extremum estimation:  $\hat{\theta}_n = \arg \max_{b \in \Theta} Q_n(W, b)$ 
  - Consistency 1: Assume (i)  $\Theta$  is compact, (ii)  $Q_n$  is continuous in  $b \in \Theta$ , (iii)  $Q_n$  is measurable in W, (iv)  $\exists Q_0(b)$  such that 1)  $Q_0(b)$  is uniquely maximized at  $\theta \in \Theta$ , and 2)  $\sup_{b \in \Theta} |Q_n(b, W) Q_0(b)| \stackrel{p}{\to} 0$ . Then  $\hat{\theta}_n \stackrel{p}{\to} \theta$ .
  - Consistency 2: Substitute (i) for  $\theta \in \text{int}(\Theta)$  and  $\Theta$  is convex, and (ii) for  $Q_n(b, W)$  is concave in b
  - **Asymptotic normality**: Suppose (i)  $\hat{\theta}_n \stackrel{p}{\to} \theta$ , (ii)  $\theta \in \text{int}(\Theta)$ , (iii)  $Q_n(b, W)$  twice continuously differentiable with respect to  $b \in \mathcal{N}_{\theta}$ , where  $\mathcal{N}_{\theta}$  denotes a neighborhood of  $\theta$ , (iv)  $\sqrt{n} \frac{\partial}{\partial b} Q_n(b, W) \stackrel{d}{\to} N(0, \Sigma(\theta))$ , (v)  $\sup_{c \in \mathcal{N}_{\theta}} \left| \frac{\partial^2 Q_n(c, W)}{\partial b \partial b^{\mathrm{T}}} H(c) \right| \stackrel{p}{\to} 0$ , where  $H(c) = \frac{\partial^2 Q_0(c)}{\partial b \partial b^{\mathrm{T}}}$ . Then  $\sqrt{n}(\hat{\theta} \theta) \stackrel{d}{\to} N(0, V)$ , where  $V = H(\theta)^{-1} \Sigma(\theta) H(\theta)^{-1}$
- M-estimation:  $\hat{\theta}_n = \arg\max_{b \in \Theta} \frac{1}{n} \sum_{i=1}^n q(W_i, b)$ 
  - **ULLN, Consistency 1**: (Used for proof of consistency) Suppose (i)  $\Theta$  is compact, (ii) q(W, b) is continuous in b, (iii) q(W, b) is measurable in W, (iv)  $\mathbf{E}[\sup_{b\in\Theta}|q(W, b)|]<\infty$ . Then  $\sup_{b\in\Theta}\left|\frac{1}{n}\sum_{i=1}^{n}q(W_i, b)-\mathbf{E}[q(W, b)]\right|\stackrel{p}{\to}0$ .

- Consistency 2: Assume (i)  $\theta \in \text{int}(\Theta)$  and  $\Theta$  is convex, (ii) q(W, b) is concave in b, (iii) q(W, b) is measurable in W, (iv) 1)  $\mathbf{E}[q(W, b)]$  is uniquely maximized at  $\theta$  and 2)  $\mathbf{E}[|q(W, b)|] < \infty \ \forall \ b \in \Theta$ . Then  $\hat{\theta}_n \stackrel{p}{\to} \theta$ .
- **Asymptotic normality**: Follow results for extremum estimation. Letting  $S(W,b) = \frac{\partial q(W,b)}{\partial b}$  and  $H(W,b) = \frac{\partial S(W,b)^T}{\partial b}$ ,  $\Sigma(\theta) = V[S(W,\theta)]$  and  $H(\theta) = \mathbf{E}[H(W,\theta)]$ .
  - \* **NLLS**: Let  $q((Y,Z),b) = -\frac{1}{2}(Y \Psi(Z,b))^2$ , and let  $\epsilon = Y \Psi(Z,\theta)$ . Then  $\Sigma(\theta) = \mathbf{E}[\epsilon^2 \frac{\partial \Psi}{\partial b} \frac{\partial \Psi}{\partial b}^T]$  and  $H(\theta) = -\mathbf{E}[\frac{\partial \Psi}{\partial b} \frac{\partial \Psi}{\partial b}^T]$ . We call  $\mathbf{E}[\epsilon^2 | Z] = \sigma^2$  conditional homoskedasticity.
- MLE:  $\hat{\theta}_n = \arg\max_{b \in \Theta} \frac{1}{n} \sum_{i=1}^n \log p(W_i, b)$ 
  - **Identification**: Sufficient that  $\theta$  uniquely maximizes the log likelihood
  - Consistency: See conditions for M-estimation or GMM (using moment condition  $\mathbf{E}_{\theta} \left[ \frac{\partial \log p(W_i, \theta)}{\partial b} \right] = 0$ )
  - **Asymptotic normality**: Follow results for M-estimation. Letting  $I(\theta)$  be the Fisher Information Matrix (variance of the score),  $\Sigma(\theta) = I(\theta)$  and  $H(\theta) = I(\theta)$ , so  $\sqrt{n}(\hat{\theta} \theta) \stackrel{d}{\to} N(0, I(\theta)^{-1})$ 
    - \* Ronald Fisher thought  $\Rightarrow$  MLE is asymptotically efficient and achieves the Cramer-Rao lower bound, so you'll be forgiven for thinking this also
- **GMM**:  $\hat{\theta}_n = \arg\max_{b \in \Theta} -\frac{1}{2} \left[ \frac{1}{n} \sum_{i=1}^n m(W_i, b) \right]^T S_n(W) \left[ \frac{1}{n} \sum_{i=1}^n m(W_i, b) \right]$ 
  - **Identification**: Let  $Q_0(b) = -\frac{1}{2}\mathbf{E}[m(W,b)]^{\mathrm{T}}S\mathbf{E}[m(W,b)]$ . Suppose  $\mathbf{E}[m(W,b)] = 0 \Leftrightarrow b = \theta$ . Then if S is strictly positive definite,  $\theta = \arg\max_b Q_0(b)$ .
  - Consistency 1: Suppose (i)  $\Theta$  is a compact subset of  $\mathbf{R}^d$ , (ii) m(W,b) is continuous in b, (iii) m(W,b) is measurable in W, and (iv)  $S_n(W) \stackrel{p}{\to} S$ , where S is symmetric positive definite. Suppose further (1) assumptions made above for identification, and (2)  $\mathbf{E}[\sup_{b\in\Theta}|m(W,b)|] < \infty$ . Then  $\hat{\theta}_n \stackrel{p}{\to} \theta$ .
  - Consistency 2: Replace (i), (ii), and (2) with  $Q_n(b)$  is concave and  $\mathbf{E}[m(W,b)]$  exists and is finite
  - Asymptotic normality: Let  $m_n(b) = \sum_{i=1}^n m(W_i, b)$ ,  $M_n(b) = \frac{\partial m_n(b)}{\partial b}$ , and  $M(b) = \mathbf{E}[\frac{\partial m(W,b)}{\partial b}]$ . Then assuming 1)  $M_n(\hat{\theta}_n)W_nM_n(\tilde{b}_n)'$  is invertible, for  $\tilde{b}_n = \alpha\hat{\theta}_n + (1-\alpha)\theta$  for  $\alpha \in [0,1]$ , 2)  $M_n(\hat{\theta}_n) \stackrel{p}{\to} M(\theta)$ , and 3) assumptions made above for consistency,  $\sqrt{n}(\hat{\theta}_n \theta) \stackrel{d}{\to} N(0, V)$  where  $V = (M(\theta)SM(\theta)^{\mathrm{T}})^{-1}M(\theta)SV[m(W,\theta)]SM(\theta)^{\mathrm{T}}(M(\theta)SM(\theta)^{\mathrm{T}})^{-1}$

### 2 Some useful bits

- 1. This is the fun part! Get excited!
- 2. Each find-the-estimator problem will generally follow three steps 1) show consistency, 2) show asymptotic normality, and 3) show you've got a consistent estimator of the variance. Typically we'll work with M-estimators, MLE, or GMM estimators, so you'll be able to recognize the class of estimator and appeal to existing results for each step. You'll often need to apply the MVT and a ULLN to show the variance estimator is consistent.

## 3 Practice questions

- 1) Derive the Fisher Information matrix of a  $N(\mu, \sigma^2)$  random variable. Construct an unbiased 95% confidence interval for  $\widehat{\mu}_{MLE}$  using  $\widehat{\sigma}_{MLE}$ . What is its asymptotic variance? How can we interpret it asymptotically?
- 2) (Problem 1, PS5) Consider the parametric model  $\{p(x, \theta) : \theta > 0\}$  where

$$p(x,\theta) = \theta x^{\theta-1}$$
  $x \in (0,1)$ 

- a. Suppose we observe an i.i.d. sample from this density. Find the Maximum Likelihood estimator of  $\theta$  and calculate the Fisher Information.
  - b. Show whether the the MLE is consistent for  $\theta$ .
  - c. Derive the limiting distribution of the MLE.
  - d. Find a Method of Moments estimator for  $\theta$  and discuss its consistency.
- e. Does there exist a UMVUE for  $\theta$ ? If so, does it attain the Cramer-Rao lower bound?
- 3) Prove the asymptotic normality of the GMM estimator.