
```
function zPrime = f4a(x, z)
    zPrime = zeros(1, 4);
    zPrime(1) = z(2);
    zPrime(2) = z(1)^3 - z(1)*z(2);
    zPrime(3) = z(4);
    zPrime(4) = (3*z(1)^2 - z(2))*z(3) - z(1)*z(4);
    zPrime = transpose(zPrime);
end
```

Not enough input arguments.

Error in f4a (line 3)
 zPrime(1) = z(2);

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