

# Engineering Notebook

John  
Mueller

9/10/21

## 1st meeting

- Akbar is our product owner
- We git hub + make backlog
- first goal is to set-up airsim on PC (both lab + personal)
- Work on product vision

9/13/21

- Repository made
  - Going to start installation tonight on my PC
- A ran into problems, airsim keeps crashing my PC.  
Will have to see if I installed it wrong

9/16/21

- Meeting with professor Cheng
- did some research on airsim crashing  
PCs, might be that my drivers are outdated  
will try updating drivers tonight

9/19/21

- Helped with SDS and SRS, specifically worked on the SDD's Design constraints, future contingencies, and helped Dillon and Elijah with System Architecture

o Also from past meeting with Abbas

goals for in + future

- Create One UAV
- Create multiple UAV
- Have them play "pong"
- Use them to calculate volume

• Still having problems installing Airsim...

9/28/21

- still having major problems installing airsim, host crashes my computer, running out of options
- started looking over the repository professor Alkabas gave us (last year's team), so far not much to note just looking at 500 and 505.

9/28/21

- Looked at other teams code and took note of any notable code snippets, handed notes to team
- Most of notes was about how to spawn drones, seems like other team really focused on the Gulf for their project and nothing else...
- Helped Naimah with slides for presentation tomorrow.

9/30/21

Presentation Day!

Went well!

10/2/21

- Dillon is scrum master has pushed us to reorganize our meeting structure.
- Tried to reinstall airosim from scratch, still crashed

10/7/21

- met with team, reorganized meeting times

- watched presentations today, took notes on others to help improve our presentation

- scheduled PO meeting with Akbar, will have to be there

10/11/21

- Had meeting with team at capstone room
- Talked with Dillon asking what work I can do specifically, gave me tasks to do with Naimah

10/18/21

- Worked with Naimah to update to update the test plan, finished the traceability matrix
- pushed my version of test plan with updated traceability matrix and some grammatical fixes

10/20/21

- Had meeting with team in capstone room
- Tasked with reviewing SRS sections 4.1 - 4.3 and SRS section 5

10/25/21

• pushed new version of SRS with updated  
4.1 - 4.3 and 5

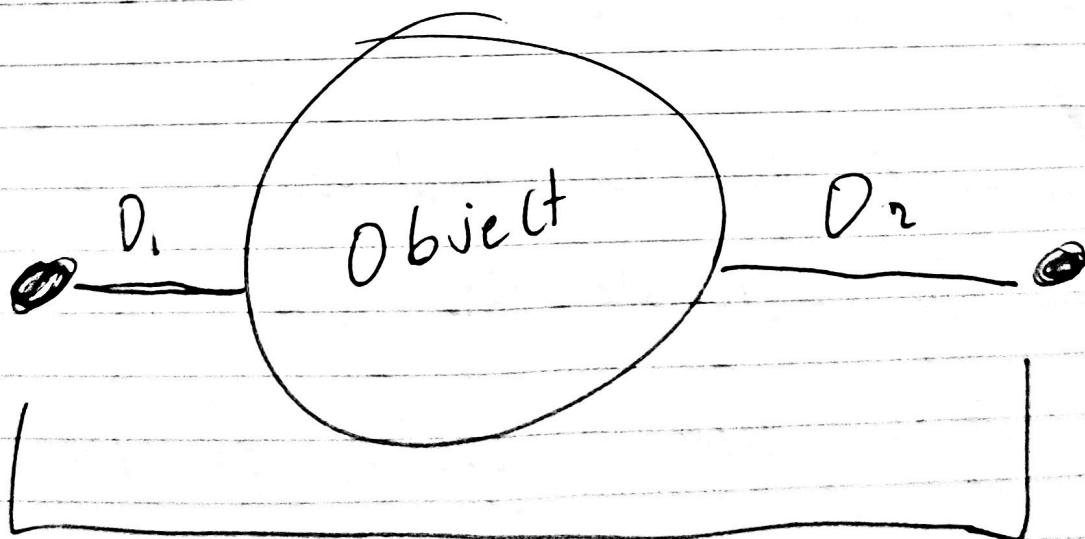
- Helped Narmah with powerpoint presentation

10/28/21

- Presentation today, went well

17/1/21

- Working on implementing a method  
to length of slice of object



total distance =  $T$

$$T - D_1 - D_2 = \text{Object Length}$$

11/3/21

- Researched into coding with python and notable arsim api's
- Found implementation of Distance sensor for drone

11/5/21

- After talking with Dillon, realized that I need to find not length but magnitude of slice of object.
- Researched formulas - that would be able to calculate this, found that distance formula would be the best

$$\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

11/9/21

- Started coding implementation of get slice
- first problem arose - do not know how to grab individual x, y, z coordinates of drones - need more research

11/17/21

- found way to grab individual drone x, y, z coordinates

simGetVehiclePose

- Going to finish first code implementation

11/24/21

- problem arose with `simGetVehicleForces`;  
Only used for cars
- Must use `getMultiRotorState`

11/29/21

- Implemented new `getMultiRotorState` as well as implementing distance sensors to `settings.json` file
- pushing first version of the `getSlice()` method.

12 / 1 / 21

- Added if-else statement to 'getSlice()' to ensure that distance sensors actually work when needed
- Also calibrated sensors correctly to scan objects

12 / 3 / 21

- Started reviewing test plan, fixing notes from grader
- Also began testing getSlice() method with drone\_swarm