Title: Learning Automata of Black Box Software and Hardware with Side Chan-

nel Analysis

**Author:** Johnathan DiMatteo

Supervisor: Sebastian Fischmeister

## Motivation

How do we verify software systems are properly designed and secure? One way is to create a model of the software to compare to the specifications. There are numerous ways to infer models by analyzing code or performing tests (such as black box fuzzing). Black box fuzzing sends random or malformed input to a system to get the system to crash or respond in a way that does not conform to specifications. The goal is to ensure a completed system does not have unintended behaviour, which could ultimately lead to vulnerabilities. But model learning, also known as automata learning, is about algorithms that are able to learn a complete representation of software systems automatically. Similar to how humans learn, the algorithms provide inputs and observe outputs to determine the global states of the system. They use past behaviour of the system to select the next input to send. Over time, they can identify valid transitions and which states the system should be in to build an accurate representation (such as a state diagram or other) of the software system. With this representation, vulnerabilities should be easy to spot. Some examples of case studies where vulnerabilities were identified using model learning are: Transport Layer Security (TLS) protocols [3], Windows 8 TCP Client [4], and credit card readers [2]. As more and more companies are adopting and using IoT devices, this has become an extremely important research topic to ensure software and hardware systems conform to specifications and work as intended.

The goal of this paper is to enforce security and safety in devices through *Model Learning*. Our proposed method is to use *Side Channel Analysis* to make learning more "black box".

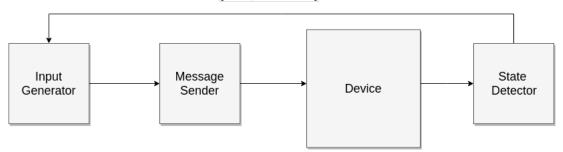
## Background

State diagrams are a way to model a system concerning a finite number of states, inputs and outputs. Inputs are external stimuli that interact with the system. Outputs are a system's response to an input. A state determines the behavior of a system. For example, a coffee machine can have three states, "Off", "Standby", and "Ready". The coffee maker will only pour coffee after the press of Button B in the "Ready" state, will be turned off in the "Off" state, and will wait for the user to load a coffee pod in the "Standby" state. A state is bound to a set of rules and functions (i.e. it is impossible to pour coffee in the "Off" state). State diagrams are common in software validation. We will be focusing on a specific type of state diagram model known as a Mealy Machine.

# 1 Assumptions

The first step to discover hidden functionality is to obtain the input and output alphabet of the protocol. We can do this through reverse engineering the message format of the black box, otherwise known as protocol fuzzing (cite). We will assume the input alphabet is known (and the hidden functionality?).

#### {state, confidence}



Any input not belonging to the known input is considering to be hidden.

## **Problem Statement**

Given the input alphabet of a black box system, reverse engineer the FSM representing the system to find undocumented functionality.

- 1. **Input Generator**: Given the current predicted state (**output? ask Sebastian**) and history of previous states (**outputs?**) and queries, determine the next query that is most likely to induce a state change in the system under observation.
- 2. **State Detector**: Given a response from the system under observation and history of previous responses, estimate the current state (**output? ask Sebastian**).
- 3. **Message Sender**: Given a query, translate the query into a valid message accepted by the system.

## References

- [1] George Argyros, Ioannis Stais, Suman Jana, Angelos D Keromytis, and Aggelos Kiayias. Sfadiff: Automated evasion attacks and fingerprinting using black-box differential automata learning. In *Proceedings of the 2016 ACM SIGSAC Conference on Computer and Communications Security*, pages 1690–1701. ACM, 2016.
- [2] Georg Chalupar, Stefan Peherstorfer, Erik Poll, and Joeri De Ruiter. Automated reverse engineering using lego $\mathbb{R}$ . WOOT, 14:1–10, 2014.
- [3] Joeri de Ruiter and Erik Poll. Protocol state fuzzing of TLS implementations. In 24th USENIX Security Symposium (USENIX Security 15), pages 193–206, Washington, D.C., 2015. USENIX Association.
- [4] Paul Fiterău-Broștean, Ramon Janssen, and Frits Vaandrager. Combining model learning and model checking to analyze tcp implementations. In *International Conference on Computer Aided Verification*, pages 454–471. Springer, 2016.
- [5] M. Tappler, B. K. Aichernig, and R. Bloem. Model-based testing iot communication via active automata learning. In 2017 IEEE International Conference on Software Testing, Verification and Validation (ICST), volume 00, pages 276–287, March 2017.
- [6] Frits Vaandrager. Model learning. Communications of the ACM, 60(2):86–95, January 2017.