boxcom howto

Contents

1	USB board	3
	1.1 The front panel switch	3
	1.2 Board checkout	4
	1.2.1 Voltage rails	4
	1.2.2 Current monitor	4
	1.2.3 Serial loopback	
2	Butterfly board 2.1 Making connections	7 7
3	Firmware 3.1 Logger functions	
\mathbf{A}	phabetical command index	9
In	ternal command index	10

1 USB board

1.1 The front panel switch

Figure 1 shows how the front panel power switch should be wired.

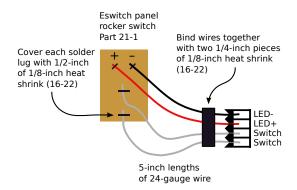


Figure 1: Panel switch wiring

1 USB board 1.2 Board checkout

1.2 Board checkout

1.2.1 Voltage rails

Use table 1 to keep track of voltage rails.

Net name	Test points	Acceptable	Actual
$V_{ m bus}$	TP100 vs. TP101	$4.5\mathrm{V} \rightarrow 5.5\mathrm{V}$	
$+3.3V_{\rm aux}$	TP400 vs. TP401	$3.14\mathrm{V} \rightarrow 3.45\mathrm{V}$	
$+3.3V_{\rm mon}$	TP500 vs. TP401	$3.14\mathrm{V} \rightarrow 3.45\mathrm{V}$	

Table 1: Voltage rail checkout table for the USB board.

1.2.2 Current monitor

The current monitor output at J500 will have a fixed DC output, since the voltage regulator following it always draws at least 1mA. As illustrated in figure 2, the slope set in hardware should give $\Delta V_{\rm out} = 1V$ for each additional 10mA of current draw from J501. Since the voltage output from J501 is controlled at 3.3V, a test load of $3.3k\Omega$ should increase the voltage at J500 by 100mV.

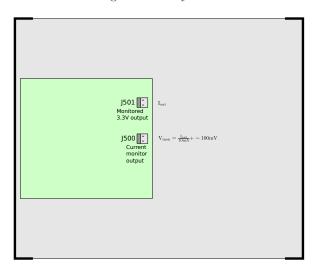


Figure 2: The output connectors used during the current monitor test.

Load applied to J501	Acceptable V _{out} at J500	Measured V _{out} at J500
Open	$90 \mathrm{mV} \rightarrow 110 \mathrm{mV}$	$V_{\rm out,o} =$
$3.3 \mathrm{k}\Omega$	$V_{\rm out,o} + 100 mV$	

Table 2: Passing voltage measurements for the current monitor test.

1 USB board 1.2 Board checkout

1.2.3 Serial loopback

The serial loopback test is a basic test of the USB/serial interface and the RS-232 transceiver. Make the breakout cable shown in figure 3, then make connections to the board as shown in figure 4.

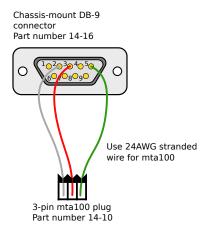


Figure 3: Wiring the DB9 breakout cable for the serial loopback test.

The serial loopback test script is:

boxcom/implement/data/scripts/tty_loopback.py

...and the test should pass at the speed listed in table 3.

Minimum passing baud	Measured passing baud
115200	

Table 3: Passing baud measurement for the serial loopback test. The usb board should be able to reliably pass the loopback test for data flowing in both directions at the minimum baud.

1 USB board 1.2 Board checkout

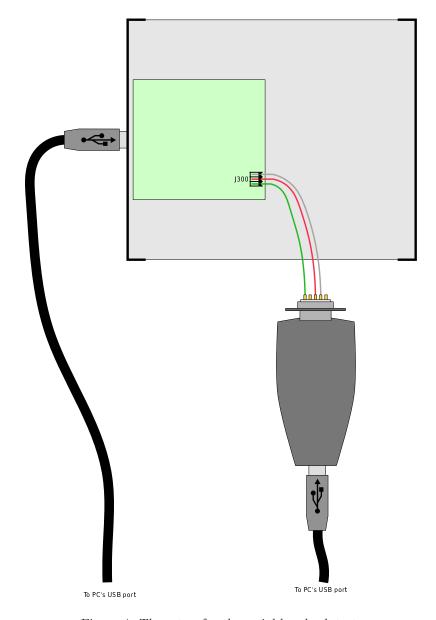


Figure 4: The setup for the serial loopback test.

2 Butterfly board

2.1 Making connections

Figure 5 shows the connections that should be made to the Butterfly board.

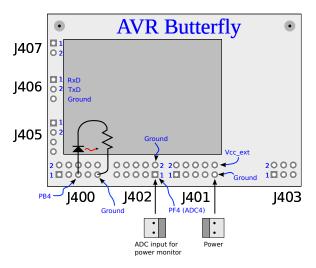


Figure 5: Connections to the AVR Butterfly

Figure 6 shows how the UART cable should be made.

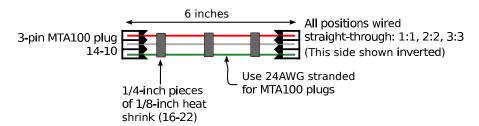


Figure 6: The UART cable connecting the Butterfly and USB boards.

3 Firmware

3.1 Logger functions

3.1.1 logger_msg_p

```
void logger_msg_p( char *logsys, logger_level_t loglevel, const char *logmsg, ... );
```

Send a message to the logger module from permanent memory

Parameters

• logsys

Pointer to a string matching one of the logger system strings.

• loglevel

One of the logger level identifiers:

```
log_level_ISR (lowest level)
log_level_INFO
log_level_WARNING
log_level_ERROR (highest level)
```

• logmsg

Pointer to a string stored in permanent (flash) memory. This might be a C format string.

• ... (additional arguments)

Depending on the format string, the function may expect a sequence of additional arguments, each containing a value to be used to replace a format specifier in the format string. There should be at least as many of these arguments as the number of values specified in the format specifiers. Additional arguments are ignored by the function.

Examples

Output (After receiving the hello command):

```
[I] (command) Command 'hello' recognized.
```

3 Firmware 3.1 Logger functions

Alphabetical command index

3 Firmware 3.1 Logger functions

Internal command index