CS 111: Homework 2: Due by 11:59 pm Sunday, January 29, 2023

Submit your paper as one PDF file, and tell GradeScope which page(s) each problem is on. If you worked with a partner, you must each turn in your own homework paper, and report the name and perm number of your partner. No groups of more than two allowed.

1. Consider the permutation matrix

$$P = \left(\begin{array}{cccc} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{array}\right).$$

- 1.1. Find a 4-permutation v = [something] such that A[v,:] == P @ A holds for every 4-by-4 matrix A. Test your answer by running a few lines of Python, and include the code and output from your testing in your LaTeX writeup.
- 1.2. For the same P, find a 4-permutation w = [something] such that A[:,w] == A @ P holds for every 4-by-4 matrix A. Turn in your testing for your answer.
- 2. The routine Lsolve() is in the file cs111/LU.py. It is called as y = Lsolve(L, b), where L must be unit lower triangular, that is, a square, lower triangular matrix whose diagonal is all ones. Modify Lsolve() to take an optional third keyword argument unit_diag that defaults to True. If unit_diag is False, your modified routine should not require (or assert) that the diagonal is all ones, but instead it should do the necessary arithmetic to get the right answer to Ly = b for any nonsingular lower triangular matrix L. Test your answer, both by itself and with LUsolve(), and include a screenshot of your testing along with your code as part of your LaTeX writeup.
- 3. Write Usolve(), analogous to Lsolve() in the file cs111/LU.py, to solve an upper triangular system Ux = y. You should again include an optional argument unit_diag, as in problem (2), but this time its default should be False. Test your answer, both by itself and with LUsolve(), and include a screenshot of your testing along with your code as part of your LaTeX writeup. Hint: Loops can be run backward in Python, say from n-1 down to 0, by writing

4. Suppose that A is a nonsymmetric invertible matrix, b is a vector, and that you have called

L, U,
$$p = cs111.LUfactor(A)$$
.

Now suppose you want to solve the system $A^Tx = b$ (not Ax = b) for x. Show how to do this using only calls to Lsolve() and Usolve() (as modified in problems (2) and (3)).

You may not call LUsolve() or any of numpy's built-in solvers (like npla.solve()), and you may not call LUfactor() again. You are allowed to transpose any matrices you wish; recall that M.T means the transposed matrix M^T in numpy. Test your method in numpy on a randomly generated 6-by-6 matrix and show the code and output in Jupyter.