# SuiteSparse:GraphBLAS: a parallel implementation of the GraphBLAS specification

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## SuiteSparse:GraphBLAS matrix data structure

- both CSC (compressed sparse column form) and CSR. Default is CSR.
- sparse (O(n + |A|) space): a dense vector of sparse vectors
- ullet or hypersparse (O(|A|)): a sparse vector of sparse vectors
- ZOMBIES!: an entry marked for deletion (negated row index so binary search still OK)
- pending tuples: an entry in an ordered list, waiting to inserted
- values: just about anything (each scalar of fixed size)
- no value given to the implicit entry

## Parallel algorithms (assume CSC)

- matrix-matrix and matrix-vector multiply. Three primary methods:
  - saxpy-style (Gustavson and hash)
  - hash method (Nagasaka, Matsuoka, Azad, Buluç (2018);
    extended here with a concurrent data structure via atomics)
  - dot, with mask: C(M) = AB'
  - dot, without mask but C dense (in-place)
- dot-style with mask: each M<sub>ij</sub>
- saxpy-style: 4 kinds of tasks, all can be used in a single
  C = AB. Tasks selected based on amount of work per column, and number of threads. Let f be the flop count.
- Parallel assignment: C(I,J)=A, with ZOMBIES! ... and pending tuples too.

## Parallel matrix multiply (assume CSC)

Four kinds of saxpy tasks, each with 3 variants: no mask, M, and  $\neg M$ .

- coarse Gustavson task: C(:,j1:j2) = A \* B (:,j1:j2) by one thread with O(n) workspace, owns columns j1:j2. Time is O(n+f).
- fine Gustavson task: multiple threads cooperate on a single column: C(:,j) = A \* B (:,j). Threads share a single O(n) workspace; using atomics. Time is O(n/p + f/p).
- coarse hash task: C(:,j1:j2) = A \* B (:,j1:j2), by one thread using O(h) workspace, h << n, where h = 4f. Time is O(f) assuming few collisions.
- fine hash task: multiple threads cooperate on a single column: C(:,j) = A \* B (:,j). Threads share O(h) workspace, h << n, where h = 4f. Time is O(f/p) assuming few collisions.

#### Fine Gustavson task: with no mask

To compute both pattern and values of C.

- concurrent data structure: two arrays of size n: X for numerical values, F for state (int8) for n concurrent finite-state machines. F is calloc'd so starts as zero.
- phase1: scatter the mask (no mask for this case however).
- phase2: scatter/sum values in X, using machine F. Using atomics. Time is O(f) assuming no spin-wait.
- phase3: count c(j) = nnz(C(:,j)) for each j. Time is O(n/p) with p threads for a single column j.
- phase4: Cp = cumsum(c) for column pointers, for all j Time is O(n/p) for entire matrix.
- phase5: gather from X to create values and pattern of C(:,j).

## Fine Gustavson task: no mask

OCK Initial State. Unlocked cci.j) not seen X(i) not c(i,j) seen, initialized X (i) initialized is unlocked

Fine Gustavson task: with mask M M(i,j)=1 (ii not seen ( X(i) initialized M(i,j)=1 M(i,j) = 0

Fine Gustauson task: with phase 2 ignore initial X(i) initialized M(i,j)=0

#### Fine hash tasks

- F has size 4f, 64-bit integers: F[k]=(h,f).
- f: lowest 2 bits: for 4-state finite-state machine
- h: upper 62 bits: h = row index i + 1 occupying the hash entry F[k]
- F[k]=(h,f) can be read/swapped/written in a single atomic operation
- The four states:
  - h=0, f=0: unlocked, unoccuppied.
  - h=i+1, f=1: unlocked, occuppied by row i. C(i,j) not seen, or ignored. X(k) not initialized.
  - h=i+1, f=2: unlocked, occuppied by row i. C(i,j) seen.
    X(k) initialized.
  - h=anything, f=3: locked, occuppied by something.
- simple hash function; linear probing if first entry occuppied.
- hash table size based on flop count f for that column j.

## Parallel matrix-matrix performance

C=A\*A for matrix ND/nd3k (n = 9000, with 3.3 million entries): All results on 20-core Intel Xeon. MATLAB R2018a.

#### time in seconds:

method	single	double	single	double
			complex	complex
MATLAB	-	3.76	-	7.90
GrB:1	3.12	3.35	4.63	4.92
GrB:20	0.22	0.24	0.33	0.31
GrB:40	0.18	0.21	0.27	0.29

#### speedup:

vs GrB:1	17.3	16.0	17.1	17.0
vs MATLAB	20.9	18.0	29.3	27.3

## Parallel matrix - sparse vector performance

C=A\*x for Freescale2 (n = 3 million, 14.3 million entries). x is 50% nonzero:

#### time in seconds:

method	single	double	single	double
			complex	complex
MATLAB	-	0.228	-	0.288
GrB:1	0.090	0.096	0.121	0.174
GrB:20	0.010	0.014	0.015	0.024
GrB:40	0.011	0.014	0.015	0.029

#### speedup:

vs GrB:1	8.2	6.9	8.1	6.0
vs MATLAB	20.7	16.3	19.2	9.9

### Parallel C(I,J)=A

- 128 variants:  $C(i,j)\langle M \rangle = C(i,j) \odot A$ 
  - M present, or not
  - mask complemented, or not
  - mask structural, or not
  - REPLACE option enabled, or not
  - accumlator ⊙ present, or not
  - A: scalar or matrix
  - S matrix constructed: see below
- implemented with 30 main kernels, including 7 special cases:
  - C=x with scalar x
  - C=A
  - C+=x when C is dense
  - C+=A when C is dense
  - C<M>=x, when C is dense
  - C<A>=A, when C is dense
  - C<M,struct>=A, when A is dense and C is empty

## Parallel C(I,J)=A, simple case

Basic case: no mask, no accumulator, no replace option, mask not complemented, I and J arbitray lists of indices, C and A sparse, ...

- 1st pass: structural extraction to compute S
  - extract S=C(I,J) where S(i,j) is the not value of C(I[i],J[j]), but its position in the data structure for C.
  - S and A have the same size.
  - S(i,j) tells where A(i,j) goes. Let p=S(i,j)
- 2nd pass: do updates, make zombies, count pending tuples
  - S(i,j) and A(i,j) both present. update: C(p) = A(i,j).
    A ZOMBIE might come back to life!
  - S(i,j) not present; A(i,j) present. A(i,j) becomes a pending tuple, waiting to be inserted. Lazy.
  - S(i,j) present; A(i,j) not present. Entry at C(p) must be deleted ... becomes a ZOMBIE!
- cumulative sum of pending tuples found per thread
- 3rd pass: each thread puts its pending tuples in common list

## Parallel C=A(I,J) performance

A is square, n=100 million, 1 billion entries.

C = A(I,J), where I=randperm(n,n/10), also J.

Note: GrB algorithm not presented in this talk. Results here to compare with next slide on C(I, J)=A.

	threads	time	speedup	speedup
		(sec)	vs MATLAB	vs GrB:1
MATLAB	1	8.87	1	1.07
GrB	1	9.48	0.94	1
GrB	5	2.70	3.28	3.51
GrB	10	1.90	4.66	4.98
GrB	20	1.48	5.98	6.39
GrB	40	1.35	6.56	7.01

## Parallel C(I,J)=A performance

Same A, I, and J as last slide. A(I,J) = 2\*A(I,J) (no change to pattern).

	threads	time	speedup	speedup
		(sec)	vs MATLAB	vs GrB:1
MATLAB	1	$\infty$	-	0
GrB	1	32.02	$\infty$	1
GrB	5	8.88	$\infty$	3.60
GrB	10	5.91	$\infty$	5.42
GrB	20	4.78	$\infty$	6.69
GrB	40	4.43	$\infty$	7.32

GrB: about 3x the time for C=A(I,J) but this expression starts with that; remainder is A(I,J)=2\*C.

MATLAB: still running after 3 hours. GrB using same syntax, via MATLAB @GrB interface.

## Parallel C(I,J)=A performance

Same A, I, and J as last slide. A(I,J) = 2\*A(I+1,J+1) (changes pattern).

	threads	time	speedup	speedup
		(sec)	vs MATLAB	vs GrB:1
MATLAB	1	$\infty$	-	0
GrB	1	55.25	$\infty$	1
GrB	5	14.79	$\infty$	3.74
GrB	10	9.59	$\infty$	5.76
GrB	20	7.47	$\infty$	7.39
GrB	40	7.04	$\infty$	7.84

MATLAB: first experiment still running after 3 hours.

## Parallel performance: betweenness centrality

Domininated by matrix-matrix multiply (one matrix 4-by-n and dense)

time in seconds

	threads				
matrix	1	10	20	40	
kron	1076.9	137.7	74.6	42.3	
urand	1405.8	107.2	70.3	63.2	
twitter	328.1	35.1	17.5	13.0	
web	91.3	13.4	8.3	7.8	
road	52.5	51.9	54.1	61.4	

speedup

kron	1	7.8	14.4	25.5
urand	1	13.1	20.0	22.2
twitter	1	9.3	18.7	25.2
web	1	6.8	11.0	11.7
road	1	1.0	1.0	0.9

## Parallel performance: pagerank

Domininated by matrix-vector multiply (dense vector). time in seconds

	threads				
matrix	1	10	20	40	
kron	372.7	40.8	22.2	21.8	
urand	378.9	42.2	27.7	27.8	
twitter	286.5	32.0	17.9	17.3	
web	90.0	10.9	8.9	8.9	
road	12.9	1.8	1.4	1.4	

#### speedup

kron	1	9.1	16.8	17.1
urand	1	9.0	13.7	13.6
twitter	1	9.0	16.0	16.6
web	1	8.3	10.1	10.1
road	1	7.2	9.2	9.2