

Eigenvalue Algorithms

CS 292F

April 28, 2021

Lecture 8



Q orthogonal matrix: square, $Q^T Q = I$
rotations (around an axis \equiv vector)
or
reflection (through a hyperplane)
or
composition of same.

Q, V orthog. $\Rightarrow QV$ orthog.

$$\|Qx\| = \|x\| \quad \forall x$$

orthogonal transforms don't
amplify error

Given $A = A^T$ (any symm. real matrix)

Find W and Λ (diagonal)

with

$$A = W \Lambda W^T \text{ (or } W^T A W = \Lambda \text{)}$$

and $W^T W = I$



① Dense $A = A^T$.

Idea : Transform A into $W^T A W = \Lambda$
by multiplying A by orthogonal matrices
(lots of them) on left & on right.

TWO STEPS:

$$\textcircled{1} Q^T A Q = T \quad (\text{tridiagonal})$$

$$Q^T Q = I$$

$$\textcircled{2} V^T T V = \Lambda \quad (\text{diagonal})$$

$$V^T V = I$$

Then $W = QV$ and $W^T A W = \Lambda$

① looks sort of like Gaussian elimination,
zero out rows/cols of A one at a time
by Householder reflections. WORK = $O(n^3)$

② the iterative part, uses
Given rotations between just 2 rows/cols.
"bulge chasing" "toothpaste squeezing"
WORK $\sim O(n^2)$ (modulo numerics & cond num)

SPARSE $A = A^T$.

- SPARSE data structures:
Store only nonzero values.
- usually don't need all the eqns.

But DENSE step ① causes
 n^2 fill-in, n^3 work.
NEED A SPARSE ALGORITHM

Can always compute Ax from x .

THE POWER METHOD

$$b = \text{random}; \quad x_0 = b / \|b\|$$

$$\text{for } k = 0, 1, 2, \dots$$

$$A = W \Lambda W^T$$

$$\begin{cases} v = Ax_k \\ \beta_k = \|v\| \\ x_{k+1} = v / \beta_k \end{cases}$$

$$\text{Suppose } x_0 = \sum_{i=1}^n \alpha_i w_i \quad (\alpha_i = w_i^T x_0)$$

$$x_k = \frac{A^k x_0}{\|A^k x_0\|}$$

$$\text{suppose } \lambda_n \text{ is max } |\cdot|$$

$$A^k x_0 = \sum_{i=1}^n \alpha_i \lambda_i^k w_i$$

$$= \alpha_n \lambda_n^k \left(w_n + \sum_{i=1}^{n-1} \frac{\alpha_i}{\alpha_n} \cdot \left(\frac{\lambda_i}{\lambda_n} \right)^k w_i \right)$$

$$\text{now } \|A^k x_0\| = \left(\sum_i (\alpha_i \lambda_i^k)^2 \right)^{1/2} \rightarrow (\alpha_n \lambda_n^k)$$

$$\text{so } x_k \sim \underline{\underline{w_n}} + \sum_{i=1}^{n-1} (\text{as above})$$

Convergence is controlled by $\left| \frac{\lambda_{n-1}}{\lambda_n} \right|^k$ (λ_{n-1} second largest |·|)

$$\left| 1 - \frac{\lambda_n - \lambda_{n-1}}{\lambda_n} \right|^k$$

Depends on "gap" $|\lambda_n - \lambda_{n-1}|$

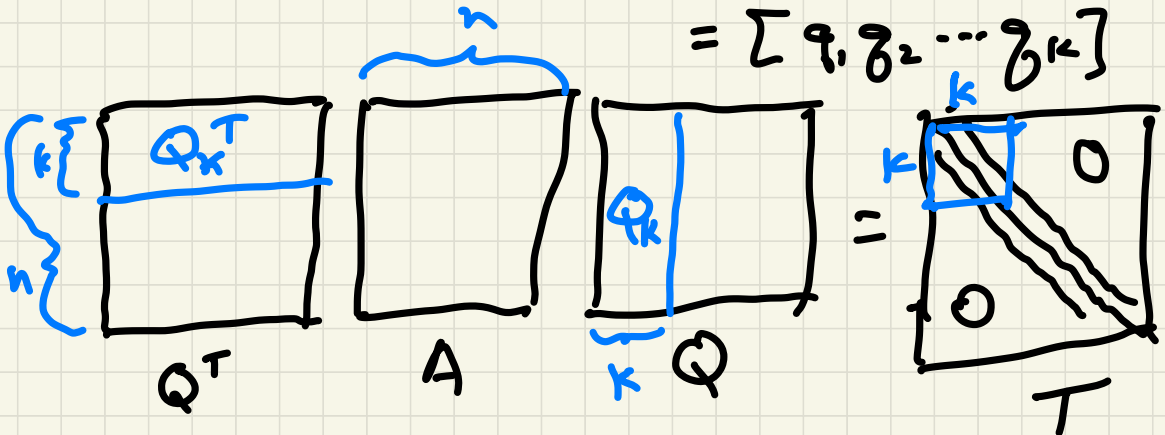
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- ① convergence depends on gap.
 - ② need $\lambda_n \neq 0$ (OK at random)
 - ③ Only get w_n .
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$K_k(A, b) = \text{span}(b, Ab, A^2b, \dots, A^{k-1}b)$
is the k^{th} Krylov subspace of
 A and b .

LANCZOS ITERATION

$$Q^T A Q = T. \text{ Take } \underline{Q_k} = Q[:, 1:k] \quad \leftarrow n \times k \text{ matrix}$$

$$= [q_1, q_2, \dots, q_k]$$



$$\text{Let } Q_k^T A Q_k = T_k \quad (T_k \text{ is } k \times k)$$

It turns out the cols of Q_k

span $K_k(A, q_1)$.

and $Q^T A Q = T$ gives a formula for q_{k+1} in terms of q_{k-1} , q_k , and $A q_k$.

$$T = \begin{bmatrix} \alpha_1 & \beta_1 & & & 0 \\ \beta_1 & \alpha_2 & \beta_2 & & \\ & \beta_2 & \alpha_3 & \ddots & \\ 0 & & \beta_3 & \ddots & \beta_{n-1} \\ & & & \ddots & \alpha_n \end{bmatrix}$$

$$Q^T A Q = T$$

$$Q^T A q_k = k^{\text{th}} \text{ col of } T =$$

$$\begin{bmatrix} 0 \\ 0 \\ \beta_{k-1} \\ \alpha_k \\ \beta_k \\ 0 \\ 0 \end{bmatrix} \quad \text{red arrow from } t_k \text{ to } \beta_{k-1}$$

$$\text{and } A q_k = Q Q^T A q_k = Q t_k$$

$$= \beta_{k-1} q_{k-1} + \alpha_k q_k + \beta_k q_{k+1}$$

$$A g_k = Q Q^T A Q_k = Q t_k$$

$$= \beta_{k-1} g_{k-1} + \alpha_k g_k + \beta_k g_{k+1}$$

LANCZOS ITERATION

$$b = \text{random}; g_1 = b / \|b\|; g_0 = 0; \beta_0 = 0$$

for $k = 1, 2, 3, \dots$

$$\left[\begin{array}{l} v = A g_k \\ \alpha_k = g_k^T v \quad (\text{because } g_k^T A g_k = T(k, k) = \alpha_k) \\ v = v - \beta_{k-1} g_{k-1} - \alpha_k g_k \\ \beta_k = \|v\| \quad (\text{because } \|g_{k+1}\| = 1) \\ g_{k+1} = v / \beta_k \end{array} \right.$$

WE HAVE

$$\boxed{Q_k^T} \boxed{A} \boxed{Q_k} = \boxed{\begin{array}{c} \text{diagonal} \\ T_k \end{array}}$$

Do k steps of iteration. Then use phase 2 of the dense algorithm to get

$$V^T \quad T_k \quad V \stackrel{k}{=} \begin{matrix} \text{[Diagram of } T_k \text{ with } k \text{ eigenvalues circled]} \\ \text{Eigenvalues of } T_k. \end{matrix}$$

$$\Theta = \text{diag}(\theta_1, \theta_2, \dots, \theta_k)$$

$$V^T Q_{1:n}^T \quad A \quad V Q_k = \begin{matrix} \text{[Diagram of } T_k \text{ with } k \text{ eigenvalues circled]} \\ \text{Eigenvalues of } T_k. \end{matrix}$$

EVALS OF $A \approx$ EVALS OF $T \neq$ EVALS OF Θ .

The $\theta_1, \dots, \theta_k$ are called "Ritz values".
Theorem: Ritz values are approximations to eigenvalues of A . (not a subset exactly)

THEOREM: Every Ritz value is close to an eval of A .

In particular,

$$\forall_i \exists_j | \theta_i - \lambda_j | \leq \beta_k \quad \text{at step } k \text{ of Lanczos.}$$
$$1 \leq i \leq k \quad 1 \leq j \leq n$$

THEOREMISH:

The Ritz values usually converge to the extreme eigenvalues first.