

Better-Than-Chance Classification for Signal Detection

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Abstract

[TODO]

1 Introduction

A common workflow in neuroimaging consists of fitting a classifier, and estimating its predictive accuracy using cross validation. Given that the cross validated accuracy is a random quantity, it is then common to test if the cross validated accuracy is significantly better than chance using a permutation test. Examples in the neuroscientific literature include Golland and Fischl [2003], Pereira et al. [2009], Varoquaux et al. [2016], and especially the recently popularized *multivariate pattern analysis* (MVPA) framework of Kriegeskorte et al. [2006]. This practice is also observed in very high profile publications in the genetics literature: Golub et al. [1999], Slonim et al. [2000], Radmacher et al. [2002], Mukherjee et al. [2003], Juan and Iba [2004], Jiang et al. [2008].

To fix ideas, we will adhere to a concrete example. In Gilron et al. [2016], the authors seek to detect brain regions which encode differences between vocal and non-vocal stimuli. Following the MVPA workflow, the localization problem is cast as a supervised learning problem: if the type of the stimulus can be predicted from the spatial activation pattern significantly better than chance, then a region is declared to encode vocal/non-vocal information. We call this an *accuracy test*, a.k.a. *class prediction*, or *pattern discrimination*.

This same signal detection task can be also approached as a two-group multivariate test. Inferring that a region encodes vocal/non-vocal information, is essentially inferring that the spatial distribution of brain activations is different given a vocal/non-vocal stimulus. As put in Pereira et al. [2009]:

26 ... the problem of deciding whether the classifier learned to dis-
 27 criminate the classes can be subsumed into the more general ques-
 28 tion as to whether there is evidence that the underlying distribu-
 29 tions of each class are equal or not.

30 A practitioner may then call upon a two-group population test such as
 31 Hotelling’s T^2 [Anderson, 2003]. Alternatively, if the size of a brain re-
 32 gion is large compared to the number of observations, so that the spatial
 33 covariance cannot be fully estimated, then a high dimensional version of
 34 Hotelling’s test can be called upon, such as in Schäfer and Strimmer [2005]
 35 or Srivastava [2007]. For brevity, and in contrast to *accuracy tests*, we will
 36 call any two-sample multivariate tests simply *population tests*, also termed
 37 *class comparisons*. [TODO: rename to parameter test?]

38 At this point, it becomes unclear which is preferable: a population test or
 39 an accuracy test? The former with a heritage dating back to Hotelling [1931],
 40 and the latter being extremely popular, as the 959 citations¹ of Kriegeskorte
 41 et al. [2006] suggest.

42 The comparison between location and accuracy tests was precisely the
 43 goal of Ramdas et al. [2016], who compared the T^2 population test to the
 44 accuracy of *Fisher’s linear discriminant analysis* classifier (LDA). By com-
 45 paring the rates of convergence of the powers to 1, Ramdas et al. [2016]
 46 concluded that accuracy and population tests are rate equivalent.

47 Asymptotic relative efficiency measures (ARE) are typically used by statis-
 48 ticians to compare between rate-equivalent test statistics [van der Vaart,
 49 1998]. Ramdas et al. [2016] derive the asymptotic power functions of the
 50 two test statistics, which allows to compute the ARE between Hotelling’s T^2
 51 (location) test and Fisher’s LDA (accuracy) test. Theorem 14.7 of van der
 52 Vaart [1998] relates asymptotic power functions to ARE. Using the results of
 53 Ramdas et al. [2016] we deduce that the ARE is lower bounded by $2\pi \approx 6.3$.
 54 This means that Fisher’s LDA requires at least 6.3 more samples to achieve
 55 the same (asymptotic) power than the T^2 test. In this light, the accuracy
 56 test is remarkably inefficient compared to the population test. For compar-
 57 ison, the t-test is only 1.04 more (asymptotically) efficient than Wilcoxon’s
 58 rank-sum test [Lehmann, 2009], so that an ARE of 6.3 is strong evidence in
 59 favor of the population test.

60 Before discarding accuracy tests as inefficient, we recall that Ramdas
 61 et al. [2016] analyzed a *half-sample* holdout. The authors conjectured that a
 62 leave-one-out approach, which makes more efficient use of the data, may have
 63 better performance. Also, the analysis in Ramdas et al. [2016] is asymptotic.
 64 This eschews the discrete nature of the accuracy statistic, which will be

¹GoogleScholar. Accessed on Aug 4, 2016.

65 shown to have crucial impact. Since typical sample sizes in neuroscience are
66 not large, we seek to study which test is to be preferred in finite samples?
67 Our conclusion will be quite simple: *population tests almost always have more*
68 *power than accuracy tests.*

69 Our statement rests upon the observation that with typical sample sizes,
70 the accuracy test statistic is highly discrete. Permutation testing with dis-
71 crete test statistics are known to be conservative [Hemerik and Goeman,
72 2014], since they are insensitive to mild perturbations of the data, and they
73 cannot exhaust the permissible false positive rate. The degree of discretiza-
74 tion is governed by the number of samples. In our neuroscience example
75 from Gilron et al. [2016], the classification is performed based on 40 trials,
76 so that the test statistic may assume only 40 possible values. This number
77 of examples is not unusual if considering this is the number of trial-repeats,
78 or the number of subjects in an neuroimaging study.

79 The discretization effect is aggravated if the test statistic is highly concen-
80 trated. For an intuition consider the usage of a the *resubstitution accuracy*
81 as a test statistic. This statistic simply means that the accuracy is not cross
82 validated. If the data is high dimensional, the resubstitution accuracy will be
83 very high due to over fitting. In a very high dimensional model, the resubsti-
84 tution accuracy will be 1 for the observed data [McLachlan, 1976, Theorem
85 1], but also for any permutation. The concentration of resubstitution accu-
86 racy near 1, and its discreteness, render this test completely useless, with a
87 power tending to 0 for any (fixed) effect size, as the dimension of the model
88 grows.

89 To compare the power of accuracy tests and population tests in finite sam-
90 ples, we perform a simulation study of a battery of test statistics. We start
91 with formalizing the problem in Section 2. The main findings are reported
92 in Sections 4 and 5. A discussion follows in Section 6.

93 2 Problem setup

94 Let $y \in \mathcal{Y}$ be a class encoding. Let $x \in \mathcal{X}$ be a p dimensional feature vector.
95 In our vocal/non-vocal example we have $\mathcal{Y} = \{-1, 1\}$ and p , the number of
96 voxels in a brain region so that $\mathcal{X} = \mathbb{R}^{27}$.

97 Given n pairs of (x_i, y_i) , typically assumed i.i.d., a population test amounts
98 to testing whether $x|y = 1$ has the the same distribution as $x|y = -1$. I.e.,
99 we test if the multivariate voxel activation pattern has the same distribution
100 when given a vocal stimulus, as when given a non-vocal stimulus.

An accuracy test amounts to learning a predictive model and testing if its
predictions $y|x$ are better than chance. Denoting a dataset by $\mathcal{S} := (x_i, y_i)_{i=1}^n$,

the a predictor, $\mathcal{A}_{\mathcal{S}}(x) : \mathcal{X} \rightarrow \mathcal{Y}$, is the output of a learning algorithm \mathcal{A} when applied to the dataset, $\mathcal{A} : \mathcal{S} \rightarrow \mathcal{A}_{\mathcal{S}}(x)$. The accuracy of predictor $\mathcal{A}_{\mathcal{S}}(x)$ is defined as the probability of $\mathcal{A}_{\mathcal{S}}(x)$ making a correct prediction. Denoting by \mathcal{P} the probability measure of (x, y) , and by \mathcal{P}^n the same for the i.i.d sample \mathcal{S} , then

$$\mathcal{E}_{\mathcal{A}_{\mathcal{S}}(x)} := \mathcal{P}(\mathcal{A}_{\mathcal{S}}(x) = y). \quad (1)$$

The accuracy of an algorithm \mathcal{A} is defined as the average accuracy, over all possible data sets

$$\mathcal{E}_{\mathcal{A}} := \int_{\mathcal{S}} \mathcal{E}_{\mathcal{A}_{\mathcal{S}}} d\mathcal{P}^n(\mathcal{S}). \quad (2)$$

101 Denoting an estimate of $\mathcal{E}_{\mathcal{A}_{\mathcal{S}}(x)}$ by $\hat{\mathcal{E}}_{\mathcal{A}_{\mathcal{S}}(x)}$, and $\mathcal{E}_{\mathcal{A}}$ by $\hat{\mathcal{E}}_{\mathcal{A}}$, a statistically sig-
 102 nificant “better than chance” estimate of either, is evidence that the classes
 103 are distinct. In a typical application, the predictor is not fixed, so that $\hat{\mathcal{E}}_{\mathcal{A}}$,
 104 and not $\hat{\mathcal{E}}_{\mathcal{A}_{\mathcal{S}}(x)}$, will be used for the testing.

105 Two popular estimates of $\hat{\mathcal{E}}_{\mathcal{A}}$ are the *resubstitution estimate*, and the
 106 V-fold cross validation (CV) estimate [Hastie et al., 2003].

Definition 1 (Resubstitution accuracy). The resubstitution accuracy estimator, $\hat{\mathcal{E}}_{\mathcal{A}}^{resub}$, is defined as

$$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub} := \frac{1}{n} \sum_{i=1}^n \mathcal{I}\{\mathcal{A}_{\mathcal{S}}(x_i) = y_i\}, \quad (3)$$

107 where $\mathcal{I}\{A\}$ is the indicator function of event A .

Definition 2 (V-fold CV). Denoting by \mathcal{S}^v the v 'th partition of the dataset, and by $\mathcal{S}^{(v)}$ its complement, so that $\mathcal{S}^v \cup \mathcal{S}^{(v)} = \cup_{v=1}^V \mathcal{S}^v = \mathcal{S}$, the V-fold CV accuracy estimator, $\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$, is defined as

$$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold} := \frac{1}{V} \sum_{v=1}^V \frac{1}{|\mathcal{S}^v|} \sum_{i \in \mathcal{S}^v} \mathcal{I}\{\mathcal{A}_{\mathcal{S}^{(v)}}(x_i) = y_i\}, \quad (4)$$

108 2.1 Candidate Tests

109 The design of a permutation test using $\hat{\mathcal{E}}_{\mathcal{A}}$, requires the following design
 110 choices:

- 111 1. Is $\hat{\mathcal{E}}_{\mathcal{A}}$ cross validated or not?

112 2. For a V-fold cross validated test statistic:

113 (a) Should the data be refolded in each permutation?

114 (b) Should the data folding be balanced (a.k.a. stratified)?

115 (c) How many folds?

116 3. How to estimate $\hat{\mathcal{E}}_{\mathcal{A}}$?

117 We will now address these questions while bearing in mind that unlike
118 the typical supervised learning setup, we are not interested in an unbiased
119 estimate of $\mathcal{E}_{\mathcal{A}}$, but rather in its mere departure from chance level.

120 **Cross validate or not?** Given our goal, a biased estimate of $\hat{\mathcal{E}}_{\mathcal{A}}$ is not a
121 problem provided that bias is consistent over all permutations. The under-
122 lying intuition is that a permutation test will be unbiased, provided that the
123 exact same computation is performed over all permutations. We will thus
124 be considering both cross validated accuracies, and *resubstitution accuracies*,
125 where the accuracy is evaluated on the training set and not on a holdout.

126 **Balanced folding?** The standard practice when cross validating is to con-
127 strain the data folds to be balanced, i.e. stratified [e.g. Ojala and Garriga,
128 2010]. This means that each fold has the same number of examples from
129 each class. We will report results with both balanced and unbalanced data
130 foldings, only to discover, it does not really matter.

131 **Refolding?** The standard practice in neuroimaging is to permute labels
132 and refold the data after each permutation, so that the balance of the classes
133 in each fold is preserved. We will adhere to this practice due to its popularity,
134 even though it can be simplified by permuting features instead of labels, as
135 done by Golland et al. [2005].

136 **How many folds?** Different authors suggest different rules for the number
137 of folds. We will be varying the number of folds, and ultimately discover that
138 the power *decreases with the number of folds*.

How to estimate accuracy? Low accuracies, even 0, are evidence that
the classes are separated so that for our purposes, we should consider the
departure from chance level $|\hat{\mathcal{E}}_{\mathcal{A}} - 0.5|$ as candidate test statistic. For un-
balanced classes, chance level is not 0.5, but rather the the probability of
the majority class, we denote by $\hat{\pi}$. This suggests the following test statistic

$|\hat{\mathcal{E}}_{\mathcal{A}} - \hat{\pi}|$. Since we will be aggregating these statistics over random data sets where $\hat{\pi}$ may vary, it seems appropriate to standardize the scale. We thus study, along with the naive accuracy estimate, $\hat{\mathcal{E}}_{\mathcal{A}}$, also the *z-scored accuracy* of algorithm \mathcal{A} :

$$\hat{\mathcal{Z}}_{\mathcal{A}} := \frac{|\hat{\mathcal{E}}_{\mathcal{A}} - \hat{\pi}|}{\sqrt{\hat{\pi}(1 - \hat{\pi})}}. \quad (5)$$

139 Table 1 collects an initial battery of tests we will be comparing.

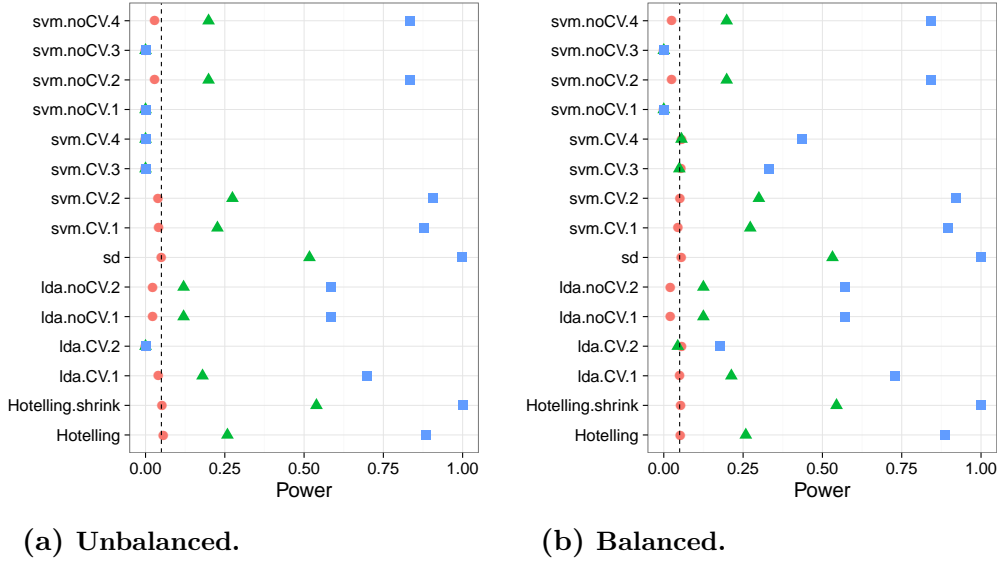
Name	Algorithm	Accuracy	Z-scored	Parameters
Hotelling	Hotelling	—	—	—
Hotelling.shrink	Hotelling	—	—	—
sd	SD	—	—	—
lda.CV.1	LDA	$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$	FALSE	—
lda.CV.2	LDA	$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$	TRUE	—
lda.noCV.1	LDA	$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub}$	FALSE	—
lda.noCV.2	LDA	$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub}$	TRUE	—
svm.CV.1	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$	FALSE	cost=1e1
svm.CV.2	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$	FALSE	cost=1e-1
svm.CV.3	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$	TRUE	cost=1e1
svm.CV.4	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Vfold}$	TRUE	cost=1e-1
svm.noCV.1	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub}$	FALSE	cost=1e1
svm.noCV.2	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub}$	FALSE	cost=1e-1
svm.noCV.3	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub}$	TRUE	cost=1e1
svm.noCV.4	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{Resub}$	TRUE	cost=1e-1

Table 1: This table collects the various test statistics we will be studying. Three are population tests: Hotelling, Hotelling.shrink, and sd. *Hotelling* is the classical two-group T^2 statistic. *Hotelling.shrink* is a high dimensional version with the regularized covariance in Schäfer and Strimmer [2005]. *sd* is another high dimensional version of the T^2 , from Srivastava et al. [2013]. The rest of the tests are variations of the linear SVM, and Fisher’s LDA, with varying accuracy measures, cross validated or not, and varying tuning parameters. For example, *svm.CV.4* is a linear SVM implemented with the *svm* R function, the cost parameter set at 0.1, and using the cross validated z-scored accuracy in Eq. 5. Another example is *lda.noCV.1*, which is Fisher’s LDA, returning the resubstitution accuracy.

3 Controlling the False Positive Rate

Figure 1 demonstrates that all of the tests considered conserve the desired 0.05 false positive rate, up to varying levels of conservatism. This can be seen from the fact that the probability of rejection is no larger than 0.05 in the absence of any effect, encoded by a red circle. This is true, in particular if: (a) the folds are balanced or not, (b) the tuning parameters of some test statistic are varied, (d) the number of folds is varied. We also observe that the most conservative tests are the resubstitution accuracy statistics. We return to this matter in the Discussion.

Figure 1: The power of a permutation test with various test statistics. The power on the x axis. Effect are color and shape coded. The various statistics on the y axis. Their details are given in Table 1. Effects vary over 0 (red circle), 0.25 (green triangle), and 0.5 (blue square). Simulation details in Appendix B. Cross-validation was performed with balanced and unbalanced data folding. See sub-captions.



4 Power

Having established that all of the tests in our battery control the false positive rate, it remains to be seen if they have similar power—especially when comparing population tests to accuracy tests. From the simulation results reported in Appendix C we collect the following insights:

1. population tests have more power than accuracy tests in all our configurations.

- 157 2. The conservativeness decays as the sample grows (Figures 9a, 9b and
158 10a)
- 159 3. For heavy tailed distributions (Figure 8b), the extra power of the loca-
160 tion test vanishes.
- 161 4. The presence of correlations between coordinates reduces the signal to
162 noise ratio (SNR), thus reduces power. More importantly, in the pres-
163 ence of correlations the effect of regularization is amplified, increas-
164 ing the power difference between regularized and non-regularized test
165 statistics. Put differently- in low SNR regimes, regularization proves
166 crucial (Figure 10b).
- 167 5. The z-scoring of the accuracies was introduced to deal with unbalanced
168 foldings. If the z-scoring has any effect at all, it merely kills power.
- 169 6. Both accuracy and population tests are inappropriate for scale alter-
170 natives (Figure 8a). This was to be expected and is reported mostly as
171 a sanity check.
- 172 7. Balanced folding only affects the z-scored accuracy, in the opposite
173 direction than we anticipated.
- 174 8. Increasing the SVM’s cost parameter, which reduces the number of
175 support vectors entering the classifier, reduces power.

176 The major insight from simulations is that the use of accuracy tests for
177 signal detection is underpowered compared to population tests. We now
178 verify this finding on a neuroimaging dataset.

179 5 Neuroimaging Example

180 Figure 2 is an application of both a location and an accuracy test to the data
181 of Pernet et al. [2015]. The authors of Pernet et al. [2015] collected fMRI
182 data while subjects were exposed to the sounds of human speech (vocal),
183 and other non-vocal sounds. Each subject was exposed to 20 sounds of each
184 type, totaling in $n = 40$ trials in each scan. The study was rather large and
185 consisted of about 200 subjects. The data was kindly made available by the
186 authors at the OpenfMRI website².

187 We perform group inference using within-subject permutations along the
188 analysis pipeline of Stelzer et al. [2013], which was also reported in Gilron

²<https://openfmri.org/>

et al. [2016]. For completeness, the pipeline is described in Appendix A. To demonstrate our point, we compare the *sd* population test with the *svm.cv.1* accuracy test.

In agreement with our simulation results, the population test (*sd*) discovers more brain regions of interest when compared to an accuracy test (*svm.cv.1*). The former discovers 1,232 regions, while the latter only 441, as depicted in Figure 2. We emphasize that both test statistics were compared with the same permutation scheme, and the same error controls, so that any difference in detections is due to their different power.

Having established that accuracy tests are typically underpowered for signal detection compared to population tests, we wish to identify the conditions under which this will occur, and discuss practical implications.

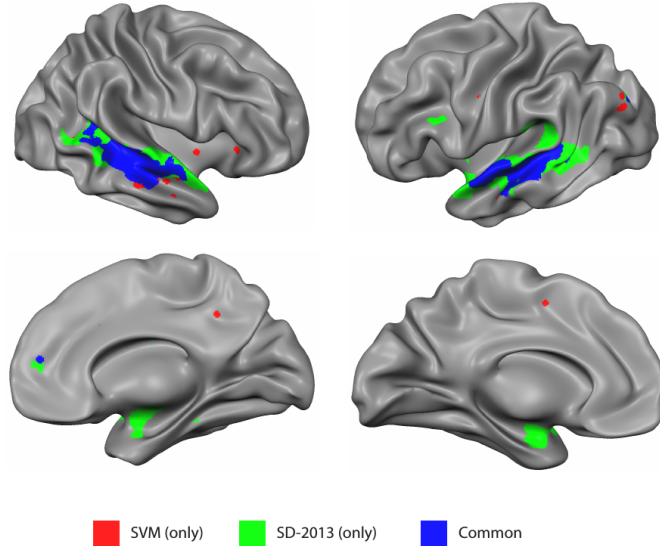


Figure 2: Brain regions encoding information discriminating between vocal and non-vocal stimuli. Map reports the centers of 27-voxel sized spherical regions, as discovered by an accuracy test (*svm.cv.1*), and a population test (*sd*). *svm.cv.1* was computed using 5-fold cross validation, and a cost parameter of 1. Region-wise significance was determined using the permutation scheme of Stelzer et al. [2013], followed by region-wise $FDR \leq 0.05$ control using the Benjamini-Hochberg procedure [Benjamini and Hochberg, 1995]. Number of permutations equals 400. The population test detect 1,232 regions, and the accuracy test 441, 399 of which are common to both. For the details of the analysis see Appendix A and Gilron et al. [2016].

201 6 Discussion

202 We have set out to understand which of the tests is more powerful: the
203 accuracy test or the population test. No amount of simulations can replace
204 the insight provided by a good closed-form analytic result. The finite sample
205 power of permutation tests is a formidable mathematical problem, so we
206 currently content ourselves with simulations. We have concluded that the
207 population tests are typically preferable. Their high dimensional versions,
208 such as Srivastava [2007] and Schäfer and Strimmer [2005], are particularly
209 well suited for neuroimaging problems such as MVPA. We attribute this
210 to several phenomena: (a) Discretization introduced in finite samples by
211 the accuracy test statistic. (b) Inefficient use of the data for the validation
212 holdout set. (c) Regularization crucial in high dimensional problems.

213 The presence of heavy tails shrinks the power advantage of the population
214 tests over accuracy tests. Our empirical example suggests that even if the
215 population test does not necessarily dominate the accuracy test in power,
216 empirically, it does have an advantage.

217 The degree of discretization is governed by the sample size. For this
218 reason, an asymptotic analysis such as Ramdas et al. [2016] may uncover the
219 holdout inefficiency, but will not uncover the discretization effect.

220 The practical advice for the practitioner, is that for the purpose of signal
221 detection, there is typically a population test that is more powerful than
222 an accuracy test. There is also a good chance that it would be easier to
223 implement, and faster to run, since no cross validation will be involved.

224 6.1 Ease of implementation

225 A very important consideration is the ease of implementation. The need for
226 cross validation of the accuracy test greatly increases its computational com-
227 plexity. Moreover, anyone who has actually implemented tests with discrete
228 statistics, will attest they are more prone to programming errors. This is
229 because their unforgiveness to the type of inequalities used. Indeed, mistak-
230 enly replacing a weak inequality with a strong inequality in one's program
231 may considerably change the results. This is not the case for continuous test
232 statistics.

233 6.2 Reservations

234 Some reservations to the generality of our findings are in order. Firstly,
235 not all accuracy tests are concerned with signal detection. Consider brain
236 decoding for machine interfaces, or clinical diagnosis, where the presence of

237 a medical condition is predicted from imaging data [e.g. Olivetti et al., 2012,
238 Wager et al., 2013]. In those examples, the purpose of the test is not to
239 detect a difference between classes, but to actually test the performance of a
240 particular classifier.

241 Secondly, it may be argued that accuracy tests permits the separation
242 between classes in high dimensions, such as in *reproducing kernel Hilbert*
243 *spaces* (RKHS) by using non-linear predictors. This is a false argument—
244 accuracy test do not have any more flexibility than population tests. Indeed,
245 it is possible to test for location in the same dimension the classifier is learned.
246 Gretton et al. [2012] is an example where the test for location is performed
247 in the RKHS of the data. It is also possible to test for the equality of two
248 multivariate distributions [TODO: cite vogelstein]. On the other hand, based
249 on our reported neuroimaging example, and others, we find that a population
250 test in the original feature space is indeed a simple and powerful approach
251 to signal detection.

252 6.3 A good accuracy test

253 For the cases a population test cannot replace an accuracy test, we collect
254 some conclusions and best practices from our simulations. We give particular
255 emphasis in this section to V-fold cross validation due to its popularity, but
256 note that sampling the test set with replacement is actually preferable, as
257 we discuss in Section 6.4.

258 **Sample size.** The conservativeness of accuracy tests decrease with sample
259 size.

260 **Permute features.** Permuting features is easier than permuting labels.
261 It allows to preserve balanced folds after a permutation without refolding.
262 Although we not we did not find a power difference between balanced and
263 unbalanced foldings.

264 **Use less folds.** For V-fold CV, power decreases as the number of folds
265 increases. This is quite interesting since two phenomena compete as the
266 number of folds increase: (a) the train set is larger so that better accuracies
267 are achievable. (b) The test set is smaller so that the accuracy estimate is
268 more variable. The decrease in power with increase fold number suggests
269 that the latter dominates the former. Put differently: it is easier to detect a
270 small stable departure from chance level, than a large but unstable one.

271 **Resubstitution accuracy in low dimension.** Resubstitution accuracy
 272 useful in low dimension. In high dimension, the power loss is considerable
 273 compared to a cross validated approach. We attribute this to the compound-
 274 ing of discretization and concentration effects: the difference between the
 275 sampling distribution of the resubstitution accuracy is simply indistinguish-
 276 able under the null and under the alternative. In low dimensional problems,
 277 the discretization is less impactful, and the computational burden of cross
 278 validation can be avoided by using the resubstitution accuracy. There is
 279 a fundamental difference between V-folding and resubstitution. The latter
 280 should not be thought of as the limit of the former.

281 **Regularize** Regularizing the accuracy test proves very useful in high di-
 282 mensional problems. Put differently: reducing variance by adding some bias
 283 is very useful to detect better-than-chance classification.

284 **Don't z-score.** There is no gain in z-scoring the accuracy scores. Our
 285 motivating rational was clearly flawed. [TODO: why?]

286 6.4 Smoothing accuracy estimates

287 It may be possible to alleviate the effect of discretization by appropriate
 288 cross-validation. The discreteness of the accuracy statistic is governed by
 289 the number of examples in the union (over all validation iterations) of test
 290 sets. For V-fold CV, for instance, this number is simply the sample size. This
 291 suggests that the accuracy can be “smoothed” by allowing the test sample to
 292 be drawn with replacement. The *bootstrap* may seem like a good candidate
 293 approach since it samples examples with replacement. It does so, however,
 294 for the train set, and not the test set. An algorithm that samples test sets
 295 with replacement is the *leave-one-out bootstrap estimator* (bLOO) and its
 296 derivation– the *0.632 bootstrap estimator* (b0.632) [Hastie et al., 2003, Sec
 297 7.11].

Definition 3 (bLOO). The *leave-one-out bootstrap* estimate is the average
 accuracy of the holdout observations, over all bootstrap samples. Denoting
 by \mathcal{S}^b , a bootstrap sample b , sampled with replacement from \mathcal{S} . Also denote
 by $C^{(i)}$ the index set of bootstrap samples, b , not containing observation i .
 The leave-one-out bootstrap estimate, $\hat{\mathcal{E}}_{\mathcal{A}}^{bLOO}$, is defined as:

$$\hat{\mathcal{E}}_{\mathcal{A}}^{bLOO} := \frac{1}{n} \sum_{i=1}^n \frac{1}{|C^{(i)}|} \sum_{b \in C^{(i)}} \mathcal{I}\{\mathcal{A}_{\mathcal{S}^b}(x_i) = y_i\}. \quad (6)$$

where $|A|$ is the cardinality of set A . Equivalently [TODO: verify], denoting by $S^{(b)}$ the indexes of observations, i , that are *not* in the bootstrap sample b and are not empty,

$$\hat{\mathcal{E}}_{\mathcal{A}}^{bLOO} = \frac{1}{B} \sum_{b=1}^B \frac{1}{|S^{(b)}|} \sum_{i \in S^{(b)}} \mathcal{I}\{\mathcal{A}_{S^b}(x_i) = y_i\}. \quad (7)$$

Definition 4 (b0.632). The b0.632 accuracy estimator, $\hat{\mathcal{E}}_{\mathcal{A}}^{0.632}$, is defined as

$$\hat{\mathcal{E}}_{\mathcal{A}}^{0.632} := 0.368 \hat{\mathcal{E}}_{\mathcal{A}}^{Resub} + 0.632 \hat{\mathcal{E}}_{\mathcal{A}}^{bLOO}. \quad (8)$$

Simulation results reported in Figure 3 with naming conventions in Table 2. It can be seen that selecting test sets with replacement does increase the power, when compared to V-fold cross validation, but still falls short from the power of population tests. It can also be seen that power increases with the number of bootstrap replications, itself reducing the level of discretization. The type of bootstrap, bLOO versus b0.632, does not change the power.

Name	Algorithm	Accuracy	B	Z-scored	Parameters
lda.Boot.1	LDA	$\hat{\mathcal{E}}_{\mathcal{A}}^{0.632}$	10	FALSE	–
lda.Boot.2	LDA	$\hat{\mathcal{E}}_{\mathcal{A}}^{bLOO}$	10	FALSE	–
svm.Boot.1	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{0.632}$	10	FALSE	cost=1e1
svm.Boot.2	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{bLOO}$	10	FALSE	cost=1e1
svm.Boot.3	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{0.632}$	50	FALSE	cost=1e1
svm.Boot.4	SVM	$\hat{\mathcal{E}}_{\mathcal{A}}^{bLOO}$	50	FALSE	cost=1e1

Table 2: The same as Table 1 for bootstrapped accuracy estimates. bLOO and b0.632 are defined in definitions 3 and 4 respectively. B denotes the number of Bootstrap samples.

6.5 High dimensional classifiers

Inspecting Figure 1a (for instance), it can be seen that Hotelling’s T^2 test has similar power to accuracy tests. It should thus be argued that the real advantage of the population tests is due to their adaptation to high dimension by regularization (*sd* and *Hotelling.shrink*), and not only to discretization. To study this, we call upon several regularized classifiers, designed for high dimensional problems. In the spirit of the regularized covariance of



Figure 3: Bootstrap— The power of a permutation test with various test statistics. The power on the x axis. Effect are color and shape coded. The various statistics on the y axis. Their details are given in tables 1 and 2. Effects vary over 0 (red circle), 0.25 (green triangle), and 0.5 (blue square). Simulation details in Appendix B.

313 *Hotelling.shrink*, we try an l_2 regularized svm Friedman et al. [2010], and
314 shrinkage based LDA [Pang et al., 2009, Ramey et al., 2016]. In the spirit of
315 the diagonalized covariance of *sd*, we try a diagonalized LDA [Dudoit et al.,
316 2002], which can be thought of a method intersecting Fisher’s LDA and Naive
317 Bayes.

318 Simulation results reported in Figure 4 with naming conventions in Ta-
319 ble 3. It can be seen that regularizing a classifier in high dimension, just
320 like a parameter test, improves power. It can also be seen that (regularized)
321 parameter tests are still more powerful than (regularized) accuracy tests.
322 This was to be expected, since we already saw in (e.g. Figure 1a) that the
323 unregularized parameter test, *Hotelling*, is slightly more powerful than the
324 regularized accuracy test, *svm.CV.1* for instance.

325 We can compound regularization in this section with the bootstrapping
326 from Section 6.4, to improve finite sample power of the accuracy tests. This
327 is done in the *svm.highdim.2* test, which still falls short from the power of the
328 location tests, but is a much more powerful accuracy test than the original

329 non-regularized, V-fold validated, version of *svm.CV.1*.

Name	Basis	CV	Accuracy	Parameters
svm.highdim.1	SVM	V-fold	accuracy	cost=1e-1
svm.highdim.2	SVM	B=50	accuracy	cost=1e-1
lda.highdim.1	LDA	V-fold	accuracy	—
lda.highdim.2	LDA	V-fold	accuracy	—
lda.highdim.3	LDA	V-fold	accuracy	—

Table 3: The same as Table 1 for regularized (high dimensional) predictors. *svm.highdim.1* is an l_2 regularized SVM Friedman et al. [2010]. *svm.highdim.2* is the same with b0.632 instead of V-fold cross validation. *lda.highdim.1* is the Diagonal Linear Discriminant Analysis of Dudoit et al. [2002]. *lda.highdim.2* is the High-Dimensional Regularized Discriminant Analysis of Ramey et al. [2016]. *lda.highdim.3* is the Shrinkage-based Diagonal Linear Discriminant Analysis of Pang et al. [2009].

330

331 6.6 Related Literature

332 Ojala and Garriga [2010] study the power of two accuracy tests: one test-
 333 ing the “no signal” null hypothesis, and the other testing the “independent
 334 features” null hypothesis. They perform an asymptotic analysis, and a sim-
 335 ulation study. They also apply various classifiers to various data sets. Their
 336 emphasis is the effect of the underlying classifier on the power, and the po-
 337 tential of the “independent features” test for feature selection. This is a very
 338 different emphasis from our own.

339 Olivetti et al. [2012] and Olivetti et al. [2014] looked into the problem of
 340 choosing a good accuracy test. They propose a new test they call an *independ-*
 341 *ence test*, and demonstrate by simulation that it has more power than other
 342 accuracy tests, and can deal with non-balanced data sets. We did not include
 343 this test in the battery we compared, but we note the following: (a) The in-
 344 dependence test of Olivetti et al. [2012] relies on a discrete test statistic. It
 345 may thus be improved with the methods discussed in this section, before the
 346 application of Olivetti et al. [2012]’s independence test. (b) In contrast with
 347 the underlying motivation of Olivetti et al. [2012]’s independence test, we
 348 did not find that balancing the data folds is crucial for an accuracy test.

349 Golland et al. [2005] study accuracy tests using simulation, neuroimaging
 350 data, genetic data, and analytically. Their analytic results formalize our in-

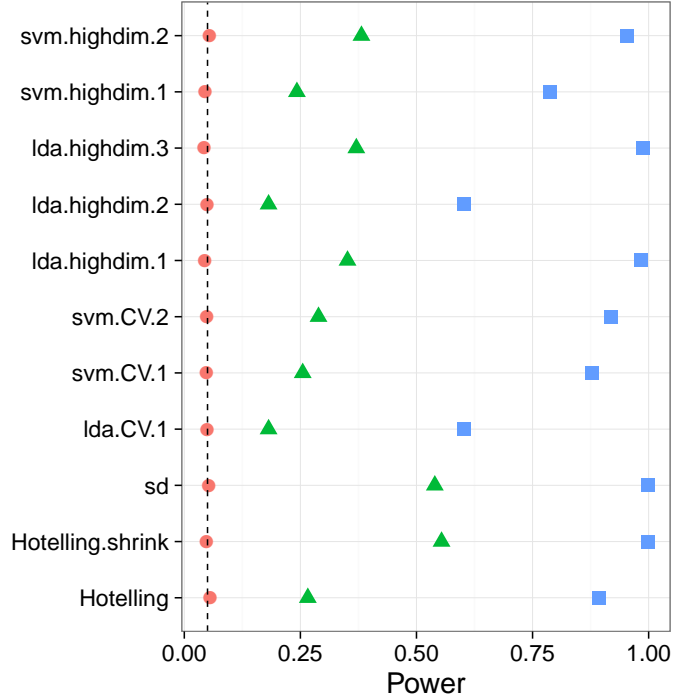


Figure 4: HighDim Classifier— The power of a permutation test with various test statistics. The power on the x axis. Effect are color and shape coded. The various statistics on the y axis. Their details are given in tables 1 and 3. Effects vary over 0 (red circle), 0.25 (green triangle), and 0.5 (blue square). Simulation details in Appendix B.

351 tuition from Section 1 on the effect of concentration of the accuracy statistic:
352 The finite Vapnik–Chervonenkis (VC) dimension requirement [Golland and
353 Fischl, 2003, Sec 4.3] prevents the permutation p-value from (asymptotically)
354 concentrating near 1. Like ourselves, they also find that the power increases
355 with the size of the test set (Figure 4, middle). This is seen in their Figure 4,
356 where the size of the test-set, K , governs the discretization. Since they per-
357 mutate features, not labels, then all their permutation samples are balanced,
358 and there is no issue of refolding.

359 Golland et al. [2005] simulate the power of accuracy tests by sampling
360 from a Gaussian mixture family of models, and not from a location family
361 as our own simulations. Under their model $(x_i|y_i = 1) \sim p\mathcal{N}(\mu_1, I) +$
362 $(1 - p)\mathcal{N}(\mu_2, I)$ and $(x_i|y_i = -1) \sim (1 - p)\mathcal{N}(\mu_1, I) + p\mathcal{N}(\mu_2, I)$. Varying p
363 interpolates between the null distribution ($p = 0.5$) and a location shift model
364 ($p = 0$). We now perform the same simulation as Golland et al. [2005], after
365 parameterizing p so that $p = 0$ corresponds to the null model, and in the
366 same dimensionality as our previous simulations We find that also in this

367 mixture class of models a population test has more power than an accuracy
 368 test (Figure 5).

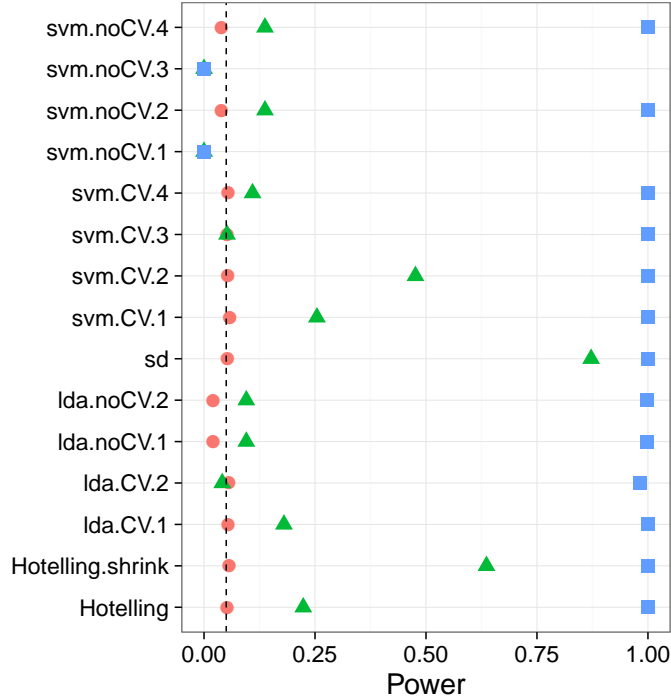


Figure 5: **Mixture**— $\mathbf{x}_i = \chi_i \mu + \eta_i$; $\chi_i = \{-1, 1\}$ and $Prob(\chi_i = 1) = (1/2 - p)^{y_i^*} (1/2 + p)^{1-y_i^*}$. μ is a p -vector with $3/\sqrt{p}$ in all coordinates. The effect, p , is color and shape coded and varies over 0 (red circle), $1/4$ (green triangle) and $1/2$ (blue square).

369 6.7 Epilogue

370 Given all the above, we find the popularity of accuracy tests quite puzzling.
 371 We believe this is due to a reversal of the inference cascade. Researchers first
 372 fit a classifier, and then ask if the classes are any different. Were they to
 373 start by asking if classes are any different, and only then try to classify, then
 374 population tests would naturally arise as the preferred method. As put by
 375 Ramdas et al. [2016]:

376 The recent popularity of machine learning has resulted in the ex-
 377 tensive teaching and use of prediction in theoretical and applied
 378 communities and the relative lack of awareness or popularity of
 379 the topic of Neyman-Pearson style hypothesis testing in the com-
 380 puter science and related “data science” communities.

381 And more simply by Frank Harrell in the CrossValidated Q&A site³:
382 ... your use of proportion classified correctly as your accuracy
383 score. This is a discontinuous improper scoring rule that can be
384 easily manipulated because it is arbitrary and insensitive.

385 **7 Acknowledgments**

³[http://stats.stackexchange.com/questions/17408/
how-to-assess-statistical-significance-of-the-accuracy-of-a-classifier](http://stats.stackexchange.com/questions/17408/how-to-assess-statistical-significance-of-the-accuracy-of-a-classifier).

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510 A Analysis pipeline

511 Here is the analysis pipeline of Stelzer et al. [2013] we for the auditory data in
 512 Gilron et al. [2016]. Denoting by $i = 1, \dots, I$ the subject index, $v = 1, \dots, V$
 513 the voxel index, and $s = 1, \dots, S$ the permutation index. Since regions⁴ are
 514 centered around a unique voxel, the voxel index v also serves as a unique
 515 region index. Algorithm 1 computes a region-wise test statistic, which is
 516 compared to its permutation null distribution computed by Algorithm 2.

Algorithm 1: Compute a group parametric map.

Data: fMRI scans, and experimental design.
Result: Brain map of group statistics: $\{\bar{T}_v\}_{v=1}^V$

```

1 for  $v \in 1, \dots, V$  do
2   for  $i \in 1, \dots, I$  do
3      $T_{i,v} \leftarrow$  test statistic for subject  $i$  in a region centered at  $v$ .
4    $\bar{T}_v \leftarrow \frac{1}{I} \sum_{i=1}^I T_{i,v}$ .
```

Algorithm 2: Compute a permutation p-value map.

Data: fMRI scans of 20 subjects, experimental design.
Result: Brain map of permutation p-values: $\{p_v\}_{v=1}^V$

```

1 for  $s \in 1, \dots, S$  do
2   permute labels;
3    $\bar{T}_v^s \leftarrow$  parametric map
```

⁴*searchlight* or *sphere* in the MVPA parlance

519 B Simulation Details

520 The following details are common to all the reported simulations, unless
521 stated otherwise in a figure’s caption. The R code for the simulations can be
522 found in [TODO].

523 Each simulation is based on 4,000 replications. In each replication, we
524 generate n i.i.d. samples from a shift model $\mathbf{x}_i = \mu \mathbf{y}_i^* + \eta_i$. Where $y_i^* = \{0, 1\}$
525 is the class of subject i in dummy coding. Recalling that $y_i = \{-1, 1\}$ is the
526 class in effect coding, then clearly $y_i = 2y_i^* - 1$. The noise is distributed as
527 $\eta_i \sim \mathcal{N}_p(0, \Sigma)$. The sample size $n = 40$. The dimension of the data is $p = 23$.
528 The covariance $\Sigma = I$. Effects, i.e. shifts μ , are equal coordinate p -vectors
529 with coordinates that vary over $\mu \in \{0, 1/4, 1/2\}$.

530 Having generated the data, we compute each of the test statistics in Ta-
531 ble 1. For test statistics that require data folding, we used 8 folds. We then
532 compute a permutation p-value by permuting the class labels, and recomput-
533 ing each test statistic. We perform 400 such permutations. We then reject
534 the $\mu_i = 0$ null hypothesis if the permutation p-value is smaller than 0.05.
535 The reported power is the proportion of replication where the permutation
536 p-value falls below 0.05.

C Simulation Results

Figure 6: Simulation details in Appendix B except the changes in the sub-captions.



Figure 7: Simulation details in Appendix B except the changes in the sub-captions.



Figure 8: Simulation details in Appendix B except the changes in the sub-captions.



Figure 9: Simulation details in Appendix B except the changes in the sub-captions.

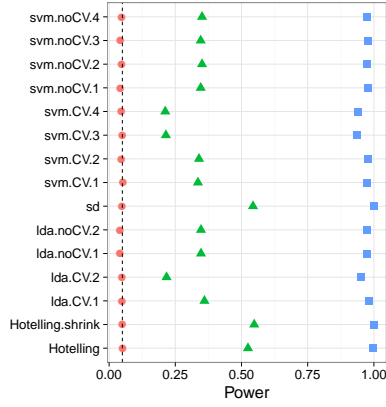


(a) Low-Dimension— False positive rates for $n = 40$.



(b) High-Dimension— False positive rates for $n = 400$.

Figure 10: Simulation details in Appendix B except the changes in the sub-captions.



(a) High-Dimension, local alternative—
 $n = 400$,
 $\mu \in \frac{1}{\sqrt{10}} \times \{0, 1/4, 1/2\}$.



(b) AR(1) dependence—
 $\Sigma_{k,l} = \rho^{|k-l|}; \rho = 0.8$.