

Better-Than-Chance Classification for Signal Detection

Jonathan Rosenblatt Roei Gilron Roy Mukamel

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Abstract

[TODO]

1 Introduction

A common workflow in neuroimaging consists of fitting a classifier, and estimating its predictive accuracy using cross validation. Given that the cross validated accuracy is a random quantity, it is then common to test if the cross validated accuracy is significantly better than chance using a permutation test. Examples in the neuroscientific literature include Golland and Fischl [2003], Pereira et al. [2009], Varoquaux et al. [2016], and especially the recently popularized *multivariate pattern analysis* (MVPA) framework of Kriegeskorte et al. [2006]. This practice is also observed in very high profile publications in the genetics literature: Golub et al. [1999], Slonim et al. [2000], Radmacher et al. [2002], Mukherjee et al. [2003], Juan and Iba [2004], Jiang et al. [2008].

To fix ideas, we will adhere to a concrete example. In Gilron et al. [2016], the authors seek to detect brain regions which encode differences between vocal and non-vocal stimuli. Following the MVPA workflow, the localization problem is cast as a supervised learning problem: if the type of the stimulus can be predicted from the spatial activation pattern significantly better than chance, then a region is declared to encode vocal/non-vocal information. We call this an *accuracy test*, a.k.a. *class prediction*, or *pattern discrimination*.

This same signal detection task can be also approached as a two-group multivariate test. Inferring that a region encodes vocal/non-vocal information, is essentially inferring that the spatial distribution of brain activations is different given a vocal/non-vocal stimulus. As put in Pereira et al. [2009]:

26 ... the problem of deciding whether the classifier learned to dis-
 27 criminate the classes can be subsumed into the more general ques-
 28 tion as to whether there is evidence that the underlying distribu-
 29 tions of each class are equal or not.

30 A practitioner may then call upon a two-group location test such as Hotelling’s
 31 T^2 [Anderson, 2003]. Alternatively, if the size of a brain region is large com-
 32 pared to the number of observations, so that the spatial covariance cannot
 33 be fully estimated, then a high dimensional version of Hotelling’s test can be
 34 called upon, such as in Schäfer and Strimmer [2005] or Srivastava [2007]. For
 35 brevity, and in contrast to *accuracy tests*, we will call any two-sample mul-
 36 tivariate tests simply *location tests*, also termed *class comparisons*. [TODO:
 37 rename to parameter test?]

38 At this point, it becomes unclear which is preferable: a location test or an
 39 accuracy test? The former with a heritage dating back to Hotelling [1931],
 40 and the latter being extremely popular, as the 959 citations¹ of Kriegeskorte
 41 et al. [2006] suggest.

42 The comparison between location and accuracy tests was precisely the
 43 goal of Ramdas et al. [2016], who compared the T^2 location test to the accu-
 44 racy of *Fisher’s linear discriminant analysis* classifier (LDA). By comparing
 45 the rates of convergence of the powers to 1, Ramdas et al. [2016] concluded
 46 that accuracy and location tests are rate equivalent.

47 Asymptotic relative efficiency measures (ARE) are typically used by statis-
 48 ticians to compare between rate-equivalent test statistics [van der Vaart,
 49 1998]. Ramdas et al. [2016] derive the asymptotic power functions of the
 50 two test statistics, which allows to compute the ARE between Hotelling’s T^2
 51 (location) test and Fisher’s LDA (accuracy) test. Theorem 14.7 of van der
 52 Vaart [1998] relates asymptotic power functions to ARE. Using the results of
 53 Ramdas et al. [2016] we deduce that the ARE is lower bounded by $2\pi \approx 6.3$.
 54 This means that Fisher’s LDA requires at least 6.3 more samples to achieve
 55 the same (asymptotic) power than the T^2 test. In this light, the accuracy test
 56 is remarkably inefficient compared to the location test. For comparison, the
 57 t-test is only 1.04 more (asymptotically) efficient than Wilcoxon’s rank-sum
 58 test [Lehmann, 2009], so that an ARE of 6.3 is strong evidence in favor of
 59 the location test.

60 Before discarding accuracy tests as inefficient, we recall that Ramdas
 61 et al. [2016] analyzed a *half-sample* holdout. The authors conjectured that a
 62 leave-one-out approach, which makes more efficient use of the data, may have
 63 better performance. Also, the analysis in Ramdas et al. [2016] is asymptotic.
 64 This eschews the discrete nature of the accuracy statistic, which will be

¹GoogleScholar. Accessed on Aug 4, 2016.

65 shown to have crucial impact. Since typical sample sizes in neuroscience are
 66 not large, we seek to study which test is to be preferred in finite samples?
 67 Our conclusion will be quite simple: *location tests almost always have more*
 68 *power than accuracy tests.*

69 Our statement rests upon the observation that with typical sample sizes,
 70 the accuracy test statistic is highly discrete. Permutation testing with dis-
 71 crete test statistics are known to be conservative [Hemerik and Goeman,
 72 2014], since they are insensitive to mild perturbations of the data, and they
 73 cannot exhaust the permissible false positive rate. The degree of discretiza-
 74 tion is governed by the number of samples. In our neuroscience example
 75 from Gilron et al. [2016], the classification is performed based on 40 trials,
 76 so that the test statistic may assume only 40 possible values. This number
 77 of examples is not unusual if considering this is the number of trial-repeats,
 78 or the number of subjects in an neuroimaging study.

79 The discretization effect is aggravated if the test statistic is highly concen-
 80 trated. For an intuition consider the usage of a the *resubstitution accuracy*
 81 as a test statistic. This statistic simply means that the accuracy is not cross
 82 validated. If the data is high dimensional, the resubstitution accuracy will be
 83 very high due to over fitting. In a very high dimensional model, the resubsti-
 84 tution accuracy will be 1 for the observed data [McLachlan, 1976, Theorem
 85 1], but also for any permutation. The concentration of resubstitution accu-
 86 racy near 1, and its discreteness, render this test completely useless, with a
 87 power tending to 0 for any (fixed) effect size, as the dimension of the model
 88 grows.

89 To compare the power of accuracy tests and location tests in finite sam-
 90 ples, we perform a simulation study of a battery of test statistics. We start
 91 with formalizing the problem in Section 2. The main findings are reported in
 92 Sections 4 and 5. A discussion follows in Section 6.

93 2 Problem setup

94 Let $y \in \mathcal{Y}$ be a class encoding. Let $x \in \mathcal{X}$ be a p dimensional feature vector.
 95 In our vocal/non-vocal example we have $\mathcal{Y} = \{-1, 1\}$ and p , the number of
 96 voxels in a brain region so that $\mathcal{X} = \mathbb{R}^{27}$.

97 Given n pairs of (x_i, y_i) , typically assumed i.i.d., a location test amounts
 98 to testing whether $x|y = 1$ has the the same distribution as $x|y = -1$. I.e.,
 99 we test if the multivariate voxel activation pattern has the same distribution
 100 when given a vocal stimulus, as when given a non-vocal stimulus.

101 An accuracy test amounts to learning a predictive model $\hat{f}(x)$ from some
 102 assumed model class $\hat{f} \in \mathcal{F}$. The prediction accuracy, denoted $\mathcal{E}_{\hat{f}}$, is de-

103 fined as the probability of a given classifier \hat{f} of making a correct predic-
 104 tion. Denoting by $I(A)$ the indicator function of the event A , we have
 105 $\mathcal{E}_{\hat{f}} := \mathbf{E} \left[I(\hat{f}(x) = y) \right]$ when given a randomly drawn data point, (x, y) . A
 106 statistically significant “better than chance” estimate of $\mathcal{E}_{\hat{f}}$ is evidence that
 107 the classes are distinct.

108 2.1 Candidate Tests

109 The design of a permutation test using the prediction accuracy, requires the
 110 following design choices:

- 111 1. Is the statistic cross validated or not?
- 112 2. For a V-fold cross validated test statistic:
 - 113 (a) Should the data be refolded in each permutation?
 - 114 (b) Should the data folding be balanced (a.k.a. stratified)?
 - 115 (c) How many folds?
- 116 3. How to estimate accuracy?

117 We will now address these questions while bearing in mind that unlike the
 118 typical supervised learning setup, we are not interested in an unbiased esti-
 119 mate of the prediction error, but rather in the mere detection of a difference
 120 between two groups.

121 **Cross validate or not?** Since we are merely interested in detecting a
 122 difference between classes, a biased error estimate is not an issue provided
 123 that bias is consistent over all permutations. The underlying intuition is
 124 that if the exact same computation is performed over all permutations, then a
 125 permutation test will be “fair”, i.e., will not inflate the false positive rate. We
 126 will thus be considering both cross validated accuracies, and resubstitution
 127 accuracies as our test statistics.

128 **Balanced folding?** The standard practice when cross validating is to con-
 129 strain the data folds to be balanced (i.e. stratified) [e.g. Ojala and Garriga,
 130 2010]. We will report results with both balanced and unbalanced data fold-
 131 ings, only to discover, it does not really matter.

132 **Refolding?** The standard practice in neuroimaging is to refold the data
 133 after each permutation, so that data folds are balanced after each label per-
 134 mutation. We will adhere, even though it can be circumvented by permuting
 135 features instead of labels, as done by Golland et al. [2005].

136 **How many folds?** Different authors suggest different rules for the number
 137 of folds. We will be varying the number of folds, and ultimately discover that
 138 the power *decreases with the number of folds*.

139 **How to estimate accuracy?** Given a predictor \hat{f} , a natural test statistic
 140 is some estimate of its accuracy $\mathcal{E}_{\hat{f}}$. Complicating matters: very low accura-
 141 cies, even 0, is evidence that the classes are separated, and we only need to
 142 invert the predictions. We can thus consider $|\mathcal{E}_{\hat{f}} - 0.5|$ as the test statistic.
 143 This, however, implies that if the classes are identical, random guessing has
 144 0.5 accuracy. This is not true if the classes are not balanced. For unbalanced
 145 data the accuracy chance level is the probability of the majority class, we
 146 denote by \hat{p}_{max} [Golland et al., 2005, Sec 4.1]. This suggests the following
 147 test statistic $|\mathcal{E}_{\hat{f}} - \hat{p}_{max}|$. Since we will be aggregating these statistics over
 148 random data sets where \hat{p}_{max} may vary, it seems appropriate to standard-
 149 ize the scale of this statistic. We thus also consider the z-scored accuracy:
 150 $|\mathcal{E}_{\hat{f}} - \hat{p}_{max}| / \sqrt{\hat{p}_{max}(1 - \hat{p}_{max})}$.

151 The of tests we will be comparing is collected for convenience in Table 1.

Name	Basis	CV	Accuracy	Parameters
Hotelling	Hotelling	—	—	shrink=FALSE
Hotelling.shrink	Hotelling	—	—	shrink=TRUE
lda.CV.1	LDA	TRUE	accuracy	—
lda.CV.2	LDA	TRUE	z-accuracy	—
lda.noCV.1	LDA	FALSE	accuracy	—
lda.noCV.2	LDA	FALSE	z-accuracy	—
sd	SD	—	—	—
svm.CV.1	SVM	TRUE	accuracy	cost=1e1
svm.CV.2	SVM	TRUE	accuracy	cost=1e-1
svm.CV.3	SVM	TRUE	z-accuracy	cost=1e1
svm.CV.4	SVM	TRUE	z-accuracy	cost=1e-1
svm.noCV.1	SVM	FALSE	accuracy	cost=1e1
svm.noCV.2	SVM	FALSE	accuracy	cost=1e-1
svm.noCV.3	SVM	FALSE	z-accuracy	cost=1e1
svm.noCV.4	SVM	FALSE	z-accuracy	cost=1e-1

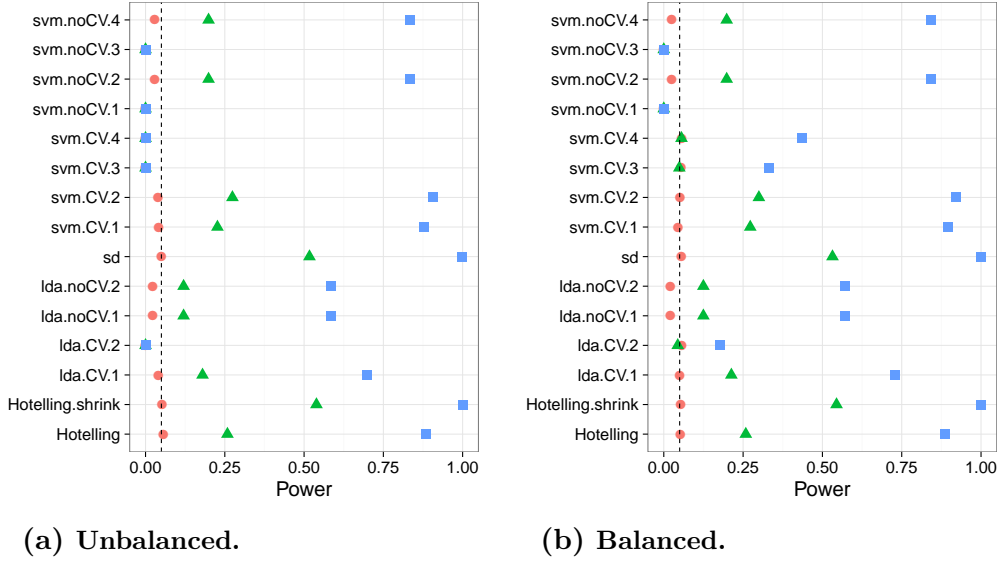
Table 1: This table enumerates the various test statistics we will be studying. Three are location tests: Hotelling, Hotelling.shrink, and sd. *Hotelling* is the classical two-group T^2 statistic. *Hotelling.shrink* is a high dimensional version with the regularized covariance in Schäfer and Strimmer [2005]. *sd* is another high dimensional version of the T^2 , from Srivastava et al. [2013]. The rest of the tests are variations of the linear SVM, and Fisher’s LDA, with varying accuracy measures, cross validated or not, and varying tuning parameters. For example, *svm.CV.4* is a linear SVM, with *libsvm*’s cost parameter set at 0.1, using the cross validated z-scored accuracy ($|\mathcal{E}_{\hat{f}} - \hat{p}_{max}|/\sqrt{\hat{p}_{max}(1 - \hat{p}_{max})}$, see Section 2.1). Another example is *lda.noCV.1*, which is Fisher’s LDA, returning the resubstitution accuracy, without cross validation, and without z-scoring.

152

153 3 Controlling the False Positive Rate

154 Figure 1 demonstrates that all of the tests considered conserve the desired
155 0.05 false positive rate, up to varying levels of conservatism. This can be
156 seen from the fact that the probability of rejection is no larger than 0.05 in
157 the absence of any effect, encoded by a red circle. This is true, in particular
158 if: (a) the folds are balanced or not, (b) the tuning parameters of some test
159 statistic are varied, (d) the number of folds is varied. We also observe that
160 the most conservative tests are the resubstitution accuracy measures. We
161 return to this matter in the Discussion.

Figure 1: The power of a permutation test with various test statistics. The power on the x axis. Effect are color and shape coded. The various statistics on the y axis. Their details are given in Table 1. Effects vary over 0 (red circle), 0.25 (green triangle), and 0.5 (blue square). Simulation details in Appendix B. Cross-validation was performed with balanced (stratified) and unbalanced data folding. See sub-captions.



4 Power

Having established that all of the tests in our battery control the false positive rate, it remains to be seen if they have similar power—especially when comparing the power of location tests to accuracy tests. From the simulation results reported in Appendix C we collect the following insights:

1. Location tests have more power than accuracy tests in all our configurations.
2. The conservativeness decays as the sample grows (Figures 8a, 8b and 9a), suggesting that concentration and/or discretization is responsible for power loss.
3. The power may increase or decrease with the number of folds (Figure 5).
4. The z-scoring of the accuracies was introduced to deal with unbalanced foldings. If the z-scoring has any effect at all, it merely kills power. There is really no reason to use it.

- 176 5. Both accuracy and location tests are inappropriate for scale alternatives
177 (Figure 7a). This was to be expected and is reported mostly as a sanity
178 check.
- 179 6. The presence of heavy tails (Figure 7b) may reduce power, but does
180 not quantitatively change results.
- 181 7. Balanced folding typically has no effect. It increased power only for
182 the z-scored statistics (Figure 1). This is surprising given they were
183 precisely designed to deal with the presence of imbalance.
- 184 8. Varying the accuracy test’s tuning parameter, such as the cost (i.e.
185 margins) has no effect on the power of the test.
- 186 9. Correlation between coordinates, mimicking temporal correlation in
187 fMRI data, has no effect on conclusions, since all test statistics account
188 for this correlation (Figure 9b).

189 The major insight from simulations is that the use of accuracy tests for
190 signal detection is underpowered compared to location tests. We now verify
191 this finding on a neuroimaging dataset.

192 5 Neuroimaging Example

193 Figure 2 is an application of both a location and an accuracy test to the data
194 of Pernet et al. [2015]. The authors of Pernet et al. [2015] collected fMRI
195 data while subjects were exposed to the sounds of human speech (vocal),
196 and other non-vocal sounds. Each subject was exposed to 20 sounds of each
197 type, totaling in $n = 40$ trials in each scan. The study was rather large and
198 consisted of about 200 subjects. The data was kindly made available by the
199 authors at the OpenfMRI website².

200 We perform group inference using within-subject permutations using the
201 pipeline of Stelzer et al. [2013], which was also reported in Gilron et al. [2016].
202 For completeness, the pipeline is described in Appendix A. To demonstrate
203 our point, we compare the *sd* location test with the *svm.cv.1* accuracy test
204 (see Table 1 for the definition of these statistics).

205 In agreement with our simulation results, the location test (*sd*) discovers
206 more brain regions when compared to an accuracy test (*svm.cv.1*). The
207 former discovers 1,232 regions, while the latter only 441, as depicted in
208 Figure 2. We emphasize that both test statistics were compared with the

²<https://openfmri.org/>

209 same permutation scheme, and the same error controls, so that any difference
 210 in detections is due to their different power.

211 Having established that accuracy tests are underpowered both in simula-
 212 tion and in application, we wish to identify the conditions under which this
 213 will occur, and discuss implications on the practice of accuracy tests.

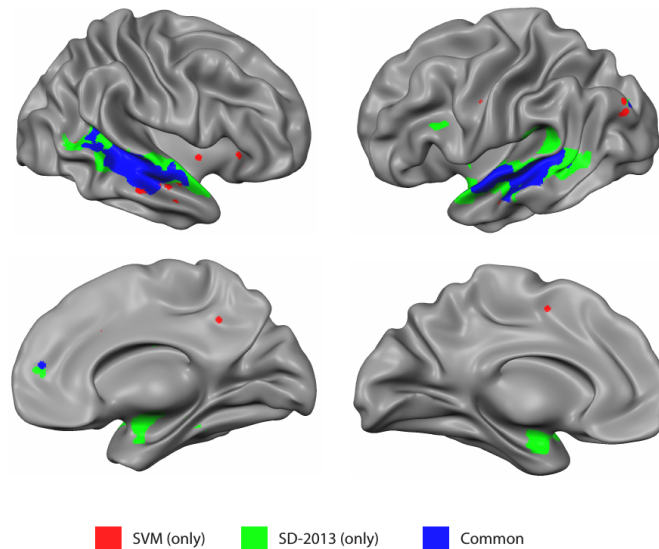


Figure 2: Brain regions encoding information discriminating between vocal and non-vocal stimuli. Map reports the centers of 27-voxel sized spherical regions, as discovered by an accuracy test (svm.cv.1), and a location test (sd). svm.cv.1 was computed using 5-fold cross validation, and a cost parameter of 1. Region-wise significance was determined using the permutation scheme of Stelzer et al. [2013], followed by region-wise $FDR \leq 0.05$ control using the Benjamini-Hochberg procedure [Benjamini and Hochberg, 1995]. Number of permutations equals 400. The location test detect 1,232 regions, and the accuracy test 441, 399 of which are common to both. For the details of the analysis see Appendix A and Gilron et al. [2016].

214 6 Discussion

215 We have set out to understand which of the tests is more powerful: the ac-
 216 curacy test or the location test. Using simulations, we have concluded that
 217 the location tests are preferable. Their high dimensional versions such as
 218 Srivastava [2007] and Schäfer and Strimmer [2005] are preferable for typical
 219 neuroimaging problems such as MVPA. We attribute this to several phe-
 220 nomena: (a) Discretization introduced in finite samples by the accuracy test

221 statistic. (b) Inefficient use of the data for the validation holdout set. The
222 presence of heavy tails shrinks the power advantage of the location tests over
223 accuracy tests.

224 The insensitivity of the power to the number of folds suggests that most
225 of the power is lost due to the discretization and not to the holdout size. The
226 degree of discretization is governed by the sample size. For this reason, an
227 asymptotic analysis such as Ramdas et al. [2016] may uncover the holdout
228 inefficiency, but will not uncover the discretization effect. The practical ad-
229 vice for the practitioner, is that for the purpose of signal detection, there
230 is typically a multivariate test (be it a location test or other), that is more
231 powerful than an accuracy test. There is also a good chance that it would
232 be easier to implement, since no cross validation will be involved.

233 6.1 Ease of implementation

234 A very important consideration is the ease of implementation. The need for
235 cross validation of the accuracy test greatly increases its computational com-
236 plexity. Moreover, anyone who has actually implemented tests with discrete
237 statistics, will attest they are more prone to programming errors. This is
238 because their unforgiveness to the type of inequalities used. Indeed, mistak-
239 enly replacing a weak inequality with a strong inequality in one's program
240 may considerably change the results. This is not the case for continuous test
241 statistics.

242 6.2 A good accuracy test

243 In Section 6.6 we discuss cases where an accuracy test cannot replace a
244 location test. For such cases we collect some conclusions from our simulations
245 on the best practices for accuracy tests.

- 246 1. The conservativeness of accuracy tests decrease with sample size.
- 247 2. Permuting features is easier than permuting labels. It allows to preserve
248 balanced folds after a permutation without refolding, thus reducing
249 computational complexity.
- 250 3. For V-fold CV, it is unclear what is the effect of the number of folds.
251 More folds increase power by reducing the number of holdout samples.
252 On the other hand, it increases the concentration of the accuracy statis-
253 tic. Compounded with the discreteness of the accuracy statistic, this
254 decreases power. This suggests that the optimal number of folds may
255 be problem specific.

- 256 4. Cross validating has no less power than resubstitution. The power loss
 257 due to the training sub-samples when cross validating, is smaller than
 258 the power loss due to the concentration of the resubstitution statistic
 259 (Figure 8). For large sample sizes, discretization and concentration
 260 have weaker effects, so that the cross validated accuracy may be re-
 261 placed with the computationally more efficiency resubstitution accu-
 262 racy (Figure 9a). This also implies that there is a fundamental differ-
 263 ence between V-folding and resubstitution, so that latter should not be
 264 thought of as the limit of the former.
- 265 5. There is no gain in z-scoring the accuracy scores. Our motivating
 266 rational was clearly flawed. [TODO: why?]
- 267 6. Cross validated accuracy with balanced folds has more power than
 268 unbalanced folds. [TODO: Why?].
- 269 7. The value of the tuning parameters of a classifier have little to no
 270 effect.

271 6.3 Smoothing accuracy estimates

272 It may be possible to alleviate the effect of discretization by appropriate cross-
 273 validation. The discreteness of the accuracy statistic can be “smoothed” by
 274 allowing the test sample to be drawn with replacement. The *bootstrap* may
 275 seem like a candidate approach, but since the original data always serves as
 276 a test set, the accuracy can still only assume $1/n$ values. This is not the case,
 277 however, for the *leave-one-out bootstrap estimator* (B-LOO) and the *0.632*
 278 *bootstrap estimator* (B-0.632) [Hastie et al., 2003, Sec 7.11], which we define
 279 below for completeness. By the same rational, the degree of conservatism
 280 should decrease with the number of bootstrap samples.

Definition 1 (B-LOO). Denoting by $C^{(i)}$ the index set of bootstrap samples,
 b , where observation i is not in the train set, *leave-one-out bootstrap* estimate
 is defined as:

$$\mathcal{E}_{BLOO} := \frac{1}{n} \sum_{i=1}^n \frac{1}{|C^{(i)}|} \sum_{b \in C^{(i)}} I(\hat{f}^b(x_i) = y_i).$$

Equivalently, denoting by $S^{(b)}$ the indexes of observations, i , that are not in
 the bootstrap train sample b ,

$$\mathcal{E}_{BLOO} := \frac{1}{B} \sum_{b=1}^B \frac{1}{|S^{(b)}|} \sum_{i \in S^{(b)}} I(\hat{f}^b(x_i) = y_i).$$

Definition 2 (B-0.632). Denoting by \mathcal{E}_{resub} the resubstitution accuracy estimate, the B-0.632 accuracy estimator, $\mathcal{E}_{0.632}$, is defined as

$$\mathcal{E}_{0.632} := 0.368 \mathcal{E}_{resub} + 0.632 \mathcal{E}_{BLOO}.$$

281 The simulation results reported in Figure 3, with naming conventions in
 282 Table 2. It can be seen that selecting test sets with replacement does increase
 283 the power, when compared to V-fold cross validation, but still falls short from
 284 the power of location tests. It can also be seen that power increases with the
 285 number of Bootstrap replications, itself reducing the level of discretization.
 286 The type of Bootstrap, B-LOO versus B-0.632, does not change the power.
 287 Again, consistent with the observation that it is discretization that drives
 288 the power loss.

Name	Basis	Boot Type	B	Accuracy	Parameters
lda.Boot.1	LDA	B-0.632	10	accuracy	–
lda.Boot.2	LDA	B-LOO	10	accuracy	–
svm.Boot.1	SVM	B-0.632	10	accuracy	cost=1e1
svm.Boot.2	SVM	B-LOO	10	accuracy	cost=1e1
svm.Boot.3	SVM	B-0.632	50	accuracy	cost=1e1
svm.Boot.4	SVM	B-LOO	50	accuracy	cost=1e1

Table 2: The same as Table 1 for bootstrapped accuracy estimates. B-LOO and B-0.632 are defined in definitions 1 and 2 respectively. B denotes the number of Bootstrap samples.

290 6.4 High dimensional classifiers

291 It is known that when $p > n$ Hotelling’s T^2 , and Fisher’s LDA are not
 292 computable. In our simulations, in which $p = 23$ and $n = 40$ is “almost”
 293 high dimensional, but still allows to compute both tests. We have simulated
 294 two high dimensional versions of Hotelling’s T^2 : *sd* [Srivastava, 2007] and
 295 *Hotelling.shrink* [Schäfer and Strimmer, 2005]. The former solves the dimen-
 296 sionality problem by assuming independence over coordinates, and the latter
 297 by Tikhonov regularization of the covariance, a-la ridge regression. The cor-
 298 responding high dimensional accuracy tests would be a *naive Bayes* classifier,
 299 and l_2 regularized SVM [Ramdas et al., 2016]. We conjecture that they would
 300 not alter our conclusions, since the main force driving the conservatism is
 301 discretization, which they do not solve.

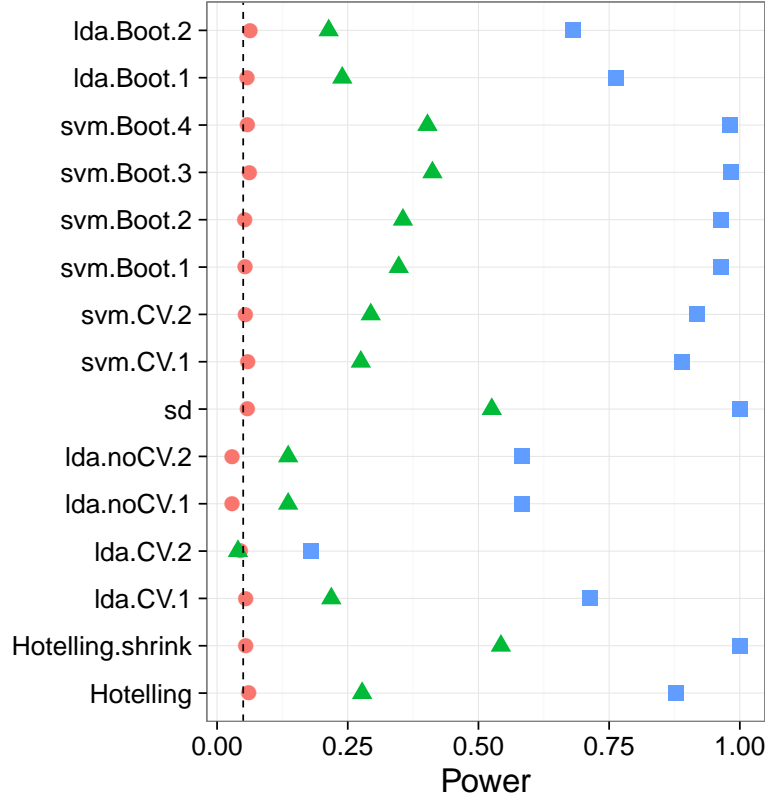


Figure 3: *Bootstrap: The power of a permutation test with various test statistics. The power on the x axis. Effect are color and shape coded. The various statistics on the y axis. Their details are given in tables 1 and 2. Effects vary over 0 (red circle), 0.25 (green triangle), and 0.5 (blue square). Simulation details in Appendix B.*

6.5 Related Literature

Olivetti et al. [2012] and Olivetti et al. [2014] looked into the problem of choosing a good accuracy test. They propose a new test they call an *independence test*, and demonstrate by simulation that it has more power than other accuracy tests, and can deal with non-balanced data sets. We did not include this test in the battery we compared, but we note the following: (a) The independence test of Olivetti et al. [2012] relies on a discrete test statistic. This means that in the cases that the accuracy test is called upon for discriminating populations, it will probably be underpowered compared to location tests. (b) In contrast with the underlying motivation of Olivetti

et al. [2012]’s independence test, we did not find that balancing the data folds is crucial for an accuracy test.

Golland et al. [2005] study accuracy tests using simulation, neuroimaging data, genetic data, and analytically. Their analytic results formalize our intuition from Section 1 on the effect of concentration of the accuracy statistic: The finite Vapnik–Chervonenkis (VC) dimension requirement [Golland and Fischl, 2003, Sec 4.3] prevents the permutation p-value from (asymptotically) concentrating. They also find that the power decreases with the level of discretization of the statistic. This is seen in their Figure 4, where the size of the test-set, K , governs the discretization. Since they permute features, and not labels, then all their permutation samples are balanced, and there is no issue of refolding.

Golland et al. [2005] simulate the power of an accuracy test using a multivariate Gaussian mixture, with a parameter p governing the separation between classes. Under their model $(x_i|y_i = 1) \sim p\mathcal{N}(\mu_1, I) + (1 - p)\mathcal{N}(\mu_2, I)$ and $(x_i|y_i = -1) \sim (1 - p)\mathcal{N}(\mu_1, I) + p\mathcal{N}(\mu_2, I)$. Varying p interpolates between the null distribution ($p = 0.5$) and a location shift model ($p = 0$). We perform the same simulation as Golland et al. [2005], after reparametrizing p so that $p = 0$ corresponds to the null model, and $p = 23$ to be comparable to our other simulations. We find that in this mixture class of models, like the location class of models, a location test has more power than an accuracy test (Figure 4).

6.6 Reservations

Some reservations to the generality of our findings are in order. Firstly, not all accuracy tests are concerned with signal detection. Consider brain decoding for machine interfaces, and clinical diagnosis, where the presence of a medical condition is predicted from imaging data [e.g. Olivetti et al., 2012, Wager et al., 2013]. In those examples, the purpose of the test is not to detect a difference between classes, but to actually test the performance of a particular classifier. As put by Ojala and Garriga [2010]:

... these tests study whether the classifier is using the described properties and not whether the plain data contain such properties. For studying the characteristics of a population represented by the data, standard statistical test could be used.

This is because classification is harder than detection. We may be able to detect a difference between classes, but not be able to classify examples significantly better than chance.

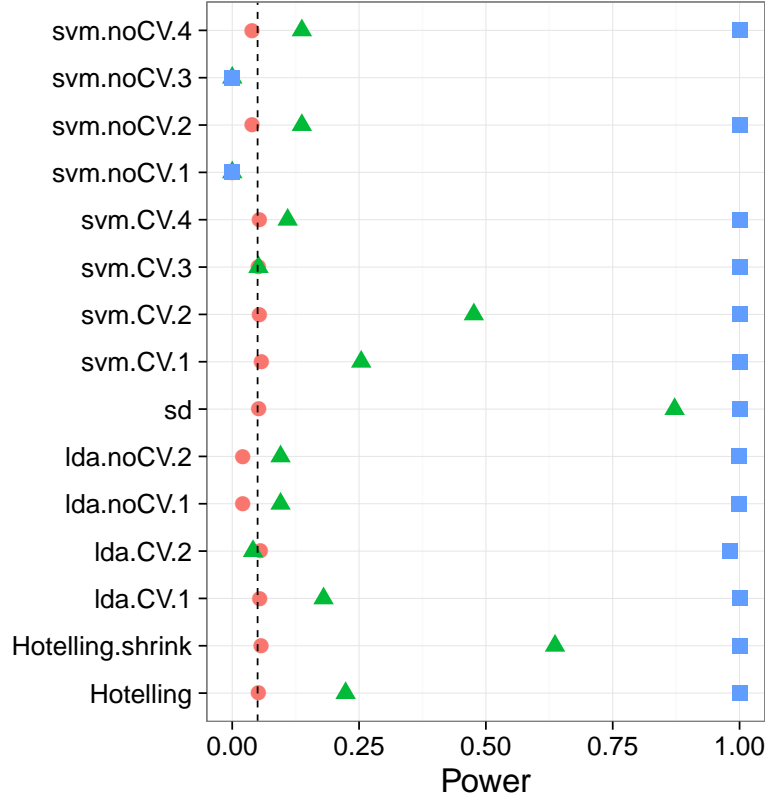


Figure 4: **Mixture:** $\mathbf{x}_i = \chi_i \mu + \eta_i$; $\chi_i = \{-1, 1\}$ and $\text{Prob}(\chi_i = 1) = (1/2 - p)^{y_i^*} (1/2 + p)^{1 - y_i^*}$. μ is a p -vector with $3/\sqrt{p}$ in all coordinates. The effect, p , is color and shape coded and varies over 0 (red circle), $1/4$ (green triangle) and $1/2$ (blue square).

Secondly, it may be argued that accuracy tests permits the separation between classes in high dimensions, such as in *reproducing kernel Hilbert spaces* (RKHS) by using non-linear predictors. This is a false argument—accuracy test do not have any more flexibility than location tests. Indeed, it is possible to test for location in the same dimension the classifier is learned. Gretton et al. [2012] is an example where the test for location is performed in the RKHS of the data. It is also possible to test for the equality of two multivariate distributions without specifying any a-priori alternative [e.g. ?]). On the other hand, based on our reported neuroimaging example, and others, we find that a location test in the original feature space is indeed a simple and powerful approach to signal detection.

360 6.7 Epilogue

361 Given all the above, we find the popularity of accuracy tests quite puzzling.
362 We believe this is due to a reversal of the inference cascade. Researchers
363 first fit a classifier, and then ask if the classes are any different. Were they
364 to start by asking if classes are any different, and only then try to classify,
365 then location tests would naturally arise as the preferred method. As put by
366 Ramdas et al. [2016]:

367 The recent popularity of machine learning has resulted in the ex-
368 tensive teaching and use of prediction in theoretical and applied
369 communities and the relative lack of awareness or popularity of
370 the topic of Neyman-Pearson style hypothesis testing in the com-
371 puter science and related “data science” communities.

372 And more simply by Frank Harrell in the `CrossValidated` Q&A site³:

373 ... your use of proportion classified correctly as your accuracy
374 score. This is a discontinuous improper scoring rule that can be
375 easily manipulated because it is arbitrary and insensitive.

376 7 Acknowledgments

³[http://stats.stackexchange.com/questions/17408/
how-to-assess-statistical-significance-of-the-accuracy-of-a-classifier](http://stats.stackexchange.com/questions/17408/how-to-assess-statistical-significance-of-the-accuracy-of-a-classifier).

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487 A Analysis pipeline

488 Here is the analysis pipeline of Stelzer et al. [2013] we for the auditory data in
 489 Gilron et al. [2016]. Denoting by $i = 1, \dots, I$ the subject index, $v = 1, \dots, V$
 490 the voxel index, and $s = 1, \dots, S$ the permutation index. Since regions⁴ are
 491 centered around a unique voxel, the voxel index v also serves as a unique
 492 region index. Algorithm 1 computes a region-wise test statistic, which is
 493 compared to its permutation null distribution computed by Algorithm 2.

Algorithm 1: Compute a group parametric map.

Data: fMRI scans, and experimental design.
Result: Brain map of group statistics: $\{\bar{T}_v\}_{v=1}^V$

```

1 for  $v \in 1, \dots, V$  do
2   for  $i \in 1, \dots, I$  do
3      $T_{i,v} \leftarrow$  test statistic for subject  $i$  in a region centered at  $v$ .
4    $\bar{T}_v \leftarrow \frac{1}{I} \sum_{i=1}^I T_{i,v}$ .
```

Algorithm 2: Compute a permutation p-value map.

Data: fMRI scans of 20 subjects, experimental design.
Result: Brain map of permutation p-values: $\{p_v\}_{v=1}^V$

```

1 for  $s \in 1, \dots, S$  do
2   permute labels;
3    $\bar{T}_v^s \leftarrow$  parametric map
```

⁴*searchlight* or *sphere* in the MVPA parlance

496 B Simulation Details

497 The following details are common to all the reported simulations, unless stated
498 otherwise in a figure’s caption. The R code for the simulations can be found
499 in [TODO].

500 Each simulation is based on 4,000 replications. In each replication, we
501 generate n i.i.d. samples from a shift model $\mathbf{x}_i = \mu \mathbf{y}_i^* + \eta_i$. Where $y_i^* = \{0, 1\}$
502 is the class of subject i in dummy coding. Recalling that $y_i = \{-1, 1\}$ is the
503 class in effect coding, then clearly $y_i = 2y_i^* - 1$. The noise is distributed as
504 $\eta_i \sim \mathcal{N}_p(0, \Sigma)$. The sample size $n = 40$. The dimension of the data is $p = 23$.
505 The covariance $\Sigma = I$. Effects, i.e. shifts μ , are equal coordinate p -vectors
506 with coordinates that vary over $\mu \in \{0, 1/4, 1/2\}$.

507 Having generated the data, we compute each of the test statistics in Ta-
508 ble 1. For test statistics that require data folding, we used 8 folds. We then
509 compute a permutation p-value by permuting the class labels, and recomput-
510 ing each test statistic. We perform 400 such permutations. We then reject
511 the $\mu_i = 0$ null hypothesis if the permutation p-value is smaller than 0.05.
512 The reported power is the proportion of replication where the permutation
513 p-value falls below 0.05.

C Simulation Results

Figure 5: Simulation details in Appendix B except the changes in the sub-captions.



(a) 2-fold cross validation.
Balanced folding.



(b) 20-fold cross validation.
Balanced folding

Figure 6: *Simulation details in Appendix B except the changes in the sub-captions.*

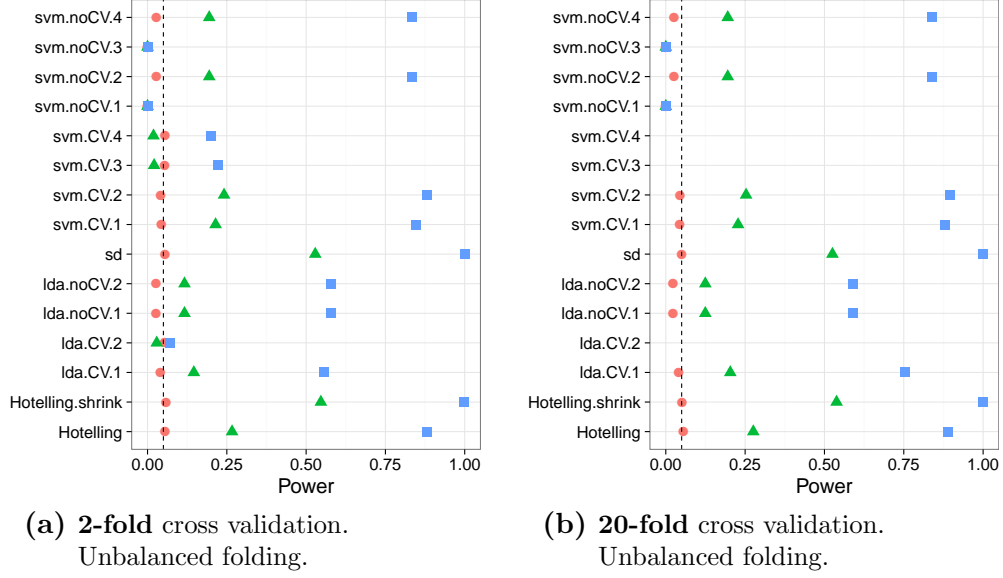
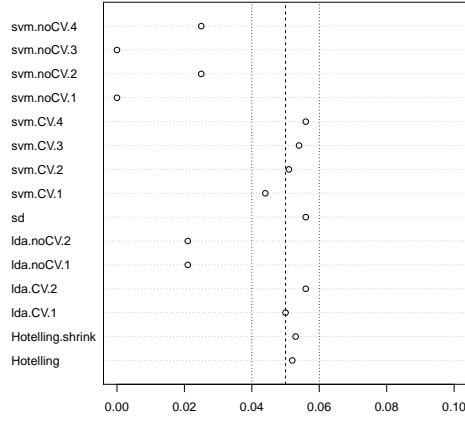


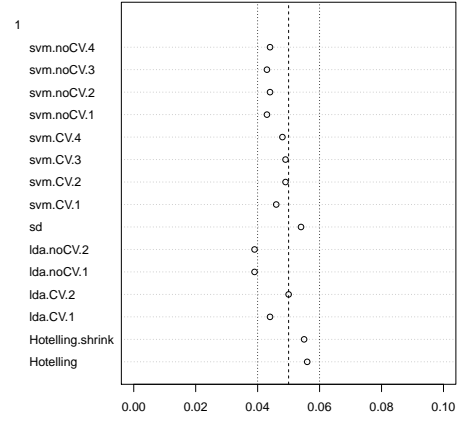
Figure 7: *Simulation details in Appendix B except the changes in the sub-captions.*



Figure 8: *Simulation details in Appendix B except the changes in the sub-captions.*

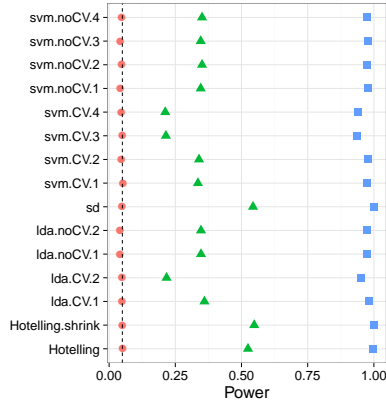


(a) **Low-Dimension:** False positive rates for $n = 40$.

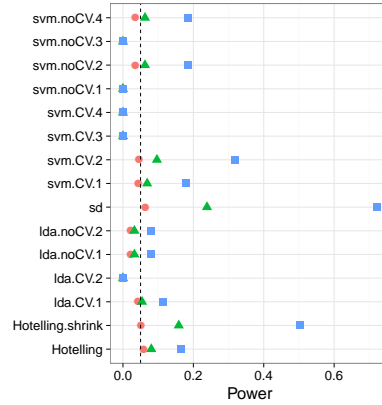


(b) **High-Dimension:** False positive rates for $n = 400$.

Figure 9: *Simulation details in Appendix B except the changes in the sub-captions.*



(a) **High-Dimension, local alternative:**
 $n = 400$,
 $\mu \in \frac{1}{\sqrt{10}} \times \{0, 1/4, 1/2\}$.



(b) **AR(1) dependence:**
 $\Sigma_{k,l} = \rho^{|k-l|}; \rho = 0.8$.